```
[]: %run utils.py
    %run helper.py
[]: import os
    import cv2 as cv
    import argparse
    from sklearn.svm import LinearSVC
    from skimage import feature
    import pandas as pd
    import os
    from skimage.transform import resize
    from skimage.io import imread
    import numpy as np
    import matplotlib.pyplot as plt
    from utils import read_img
    from sklearn.metrics import f1_score
    import joblib
    from scipy.spatial.distance import cdist
    from sklearn.preprocessing import StandardScaler
    import helper
    from sklearn.metrics import f1_score
[]: train_image_paths = []
    train_labels = []
     # get all the image folder paths
    Categories=['american_football', 'baseball', 'basketball', 'billiard_ball', '
     →'bowling_ball', 'cricket_ball', 'football', 'golf_ball',
                'hockey_ball', 'hockey_puck', 'rugby_ball', 'shuttlecock', \(
     datadir='dataset/train'
    for i in Categories:
        print(f'loading... category : {i}')
        path=os.path.join(datadir,i)
        for img in os.listdir(path):
            train_image_paths.append(os.path.join(path,img))
            train_labels.append(Categories.index(i))
        print(f'loaded category:{i} successfully')
[]: test_image_paths = []
    test_labels = []
     # get all the image folder paths
    Categories=['american_football', 'baseball', 'basketball', 'billiard_ball', '
     →'bowling_ball', 'cricket_ball', 'football', 'golf_ball',
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'hockey_ball', 'hockey_puck', 'rugby_ball', 'shuttlecock', __
      datadir='dataset/test'
     for i in Categories:
         print(f'loading... category : {i}')
         path=os.path.join(datadir,i)
         for img in os.listdir(path):
             test_image_paths.append(os.path.join(path,img))
             test_labels.append(Categories.index(i))
         print(f'loaded category:{i} successfully')
[]: \# generates Baq-of-Words features using SIFT descriptors for a given list of
     → image paths and a pre-computed codebook (visual vocabulary).
     # initializes a SIFT object, Iterates through each image path, Reads the image, \Box
     →converts it to grayscale, and detects keypoints and computes SIFT descriptors.
     # For each descriptor, it computes distances to the codebook centroids and \Box
     \hookrightarrow assigns it to the nearest centroid.
     # Accumulates the histogram of visual words (BoW) for each image. Returns a_{f \sqcup}
     →matrix of BoW features for all images
     scaler = StandardScaler() #scale the features before feeding them to the SVML
     \hookrightarrow classifier
     def bag_of_words_SIFT(image_paths, codebook):
         sift = cv.SIFT_create(nfeatures=300)
         codebook_size = codebook.shape[0]
         image_features = []
         for image_path in image_paths:
             img = read_img(image_path, mono=True)
             keypoints, descriptors = sift.detectAndCompute(img, None)
             bow = np.zeros(codebook_size)
             if descriptors is not None:
                 distances = cdist(descriptors, codebook)
                 for d in distances:
                     bow[np.argmin(d)] += 1
             image_features.append(bow.reshape(1, codebook_size))
         image_features = np.concatenate(image_features)
         return image_features
[]: codebook_SIFT = joblib.load('Saved_Models_SVM/codebook_SIFT.joblib')
     svm_SIFT = joblib.load('Saved_Models_SVM/svm_bow_SIFT.joblib')
[]: \#compute BoW features for the training images using SIFT descriptors and the \sqcup
      →pre-computed codebook. Scales the BoW features.
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print('Generating BOW features for training set...')
     train_images_SIFT = bag_of_words_SIFT(train_image_paths, codebook_SIFT)
     train_images_scaled_SIFT = scaler.fit_transform(train_images_SIFT)
     print('Train images:', train_images_SIFT.shape)
[]: # Initializes a SIFT object, Loops over each image path, Reads the image,
      →converts it to grayscale, and applies Gaussian pixel noise with increasing
     \rightarrow intensity (i).
     # Normalizes the pixel values to the range [0, 255], Detects keypoints and \Box
      →computes SIFT descriptors for the noisy image,
     # Computes BoW features for the image by assigning each descriptor to the \Box
      →nearest centroid in the codebook and accumulating the counts,
     # Appends the computed BoW features for the image to the image_features list and \Box
      \rightarrow After processing all images, concatenates the BoW features into a single \sqcup
      \hookrightarrow array.
     def bag_of_words_SIFT_GPN(image_paths, codebook, i):
         sift = cv.SIFT_create(nfeatures=300)
         codebook_size = codebook.shape[0]
         image_features = []
         for image_path in image_paths:
             img = read_img(image_path, mono=True)
             img = helper.gaussian_pixel_noise(img, i)
             img = cv.normalize(img, None, 0, 255, cv.NORM_MINMAX).astype('uint8')
             keypoints, descriptors = sift.detectAndCompute(img, None)
             bow = np.zeros(codebook_size)
             if descriptors is not None:
                 distances = cdist(descriptors, codebook)
                 for d in distances:
                     bow[np.argmin(d)] += 1
             image_features.append(bow.reshape(1, codebook_size))
         image_features = np.concatenate(image_features)
         return image_features
[]: #list l containing intensity values for Gaussian pixel noise.
     1 = [0, 2, 4, 6, 8, 10, 12, 14, 16, 18]
[]: #creates a pandas DataFrame of from the accuracies stored in the list res, with \Box
      → the intensity levels of Gaussian pixel noise (1) as the index
     #DataFrame provides a structured representation of accuracies corresponding to \Box
     → different intensity levels of Gaussian pixel noise,
     #making it easier to analyze and visualize the results to understand how the \Box
      →performance of the SVM classifier varies with different levels of noise.
     res = []
     for i in range(len(1)):
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print(l[i])
         test_images = bag_of_words_SIFT_GPN(test_image_paths, codebook_SIFT, 1[i])
         test_images_scaled = scaler.transform(test_images)
         test_predictions = svm_SIFT.predict(test_images_scaled)
         res.append(accuracy_score(test_labels, test_predictions))
     d = {'Accuracy': res}
     df = pd.DataFrame(data=d, index = 1)
     df.to_csv("Robustness_Testing_Results_SVM/Gaussian pixel noise ACCURACY.csv")
[]: def bag_of_words_SIFT_GB(image_paths, codebook, i):
         sift = cv.SIFT_create(nfeatures=300)
         codebook_size = codebook.shape[0]
         image_features = []
         for image_path in image_paths:
             img = read_img(image_path, mono=True)
             img = helper.gaussian_blur(img, i)
             img = cv.normalize(img, None, 0, 255, cv.NORM_MINMAX).astype('uint8')
             keypoints, descriptors = sift.detectAndCompute(img, None)
             bow = np.zeros(codebook_size)
             if descriptors is not None:
                 distances = cdist(descriptors, codebook)
                 for d in distances:
                     bow[np.argmin(d)] += 1
             image_features.append(bow.reshape(1, codebook_size))
         image_features = np.concatenate(image_features)
         return image_features
[]: res = []
     for i in range(10):
         print(i)
         test_images = bag_of_words_SIFT_GB(test_image_paths, codebook_SIFT, i)
         test_images_scaled = scaler.transform(test_images)
         test_predictions = svm_SIFT.predict(test_images_scaled)
         res.append(accuracy_score(test_labels, test_predictions))
     d = {'Accuracy': res}
     df = pd.DataFrame(data=d, index = 1)
     df.to_csv("Robustness_Testing_Results_SVM/Gaussian blurring ACCURACY.csv")
[]: #Detects keypoints and computes descriptors using SIFT on the contrast-scaled
      → image, Computes the BoW histogram using the codebook
     #and distances between descriptors and codebook centroids, populates the BoW_{f L}
      \hookrightarrowhistogram for each image and Returns the concatenated BoW histograms of all
      \rightarrow images
     def bag_of_words_SIFT_ICI(image_paths, codebook, i):
         sift = cv.SIFT_create(nfeatures=300)
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codebook_size = codebook.shape[0]
         image_features = []
         for image_path in image_paths:
             img = read_img(image_path, mono=True)
             img = helper.scale_contrast(img, i)
             img = cv.normalize(img, None, 0, 255, cv.NORM_MINMAX).astype('uint8')
             keypoints, descriptors = sift.detectAndCompute(img, None)
             bow = np.zeros(codebook_size)
             if descriptors is not None:
                 distances = cdist(descriptors, codebook)
                 for d in distances:
                     bow[np.argmin(d)] += 1
             image_features.append(bow.reshape(1, codebook_size))
         image_features = np.concatenate(image_features)
         return image_features
[]: 1 = [1.0, 1.01, 1.02, 1.03, 1.04, 1.05, 1.1, 1.15, 1.20, 1.25]
[]: res = []
     for i in range(len(1)):
         print(l[i])
         test_images = bag_of_words_SIFT_ICI(test_image_paths, codebook_SIFT, 1[i])
         test_images_scaled = scaler.transform(test_images)
         test_predictions = svm_SIFT.predict(test_images_scaled)
         res.append(accuracy_score(test_labels, test_predictions))
     d = {'Accuracy': res}
     df = pd.DataFrame(data=d, index = 1)
     df.to_csv("Robustness_Testing_Results_SVM/Image Contrast Increase ACCURACY.csv")
     df
[]: 1 = [1.0, 0.95, 0.90, 0.85, 0.80, 0.60, 0.40, 0.30, 0.20, 0.10]
[]: res = []
     for i in range(len(1)):
         print(1[i])
         test_images = bag_of_words_SIFT_ICI(test_image_paths, codebook_SIFT, 1[i])
         test_images_scaled = scaler.transform(test_images)
         test_predictions = svm_SIFT.predict(test_images_scaled)
         res.append(accuracy_score(test_labels, test_predictions))
     d = {'Accuracy': res}
     df = pd.DataFrame(data=d, index = 1)
     df.to_csv("Robustness_Testing_Results_SVM/Image Contrast Decrease ACCURACY.csv")
     df
[]: def bag_of_words_SIFT_IB(image_paths, codebook, i):
         sift = cv.SIFT_create(nfeatures=300)
         codebook_size = codebook.shape[0]
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```
image_features = []
         for image_path in image_paths:
             img = read_img(image_path, mono=True)
             img = helper.change_brightness(img, i)
             img = cv.normalize(img, None, 0, 255, cv.NORM_MINMAX).astype('uint8')
             keypoints, descriptors = sift.detectAndCompute(img, None)
             bow = np.zeros(codebook_size)
             if descriptors is not None:
                 distances = cdist(descriptors, codebook)
                 for d in distances:
                     bow[np.argmin(d)] += 1
             image_features.append(bow.reshape(1, codebook_size))
         image_features = np.concatenate(image_features)
         return image_features
[]: 1 = [0, 5, 10, 15, 20, 25, 30, 35, 40, 45]
[]: res = []
     for i in range(len(1)):
         print(l[i])
         test_images = bag_of_words_SIFT_IB(test_image_paths, codebook_SIFT, 1[i])
         test_images_scaled = scaler.transform(test_images)
         test_predictions = svm_SIFT.predict(test_images_scaled)
         res.append(accuracy_score(test_labels, test_predictions))
     d = {'Accuracy': res}
     df = pd.DataFrame(data=d, index = 1)
     df.to_csv("Robustness_Testing_Results_SVM/Image Brightness Increase ACCURACY.
     ⇔csv")
     df
[]: def bag_of_words_SIFT_IB(image_paths, codebook, i):
         sift = cv.SIFT_create(nfeatures=300)
         codebook_size = codebook.shape[0]
         image_features = []
         for image_path in image_paths:
             img = read_img(image_path, mono=True)
             img = helper.change_brightness(img, i)
             img = cv.normalize(img, None, 0, 255, cv.NORM_MINMAX).astype('uint8')
             keypoints, descriptors = sift.detectAndCompute(img, None)
             bow = np.zeros(codebook_size)
             if descriptors is not None:
                 distances = cdist(descriptors, codebook)
                 for d in distances:
                     bow[np.argmin(d)] += 1
             image_features.append(bow.reshape(1, codebook_size))
         image_features = np.concatenate(image_features)
         return image_features
```

```
[]: 1 = [0, -5, -10, -15, -20, -25, -30, -35, -40, -45]
[]: res = []
     for i in range(len(1)):
        print(l[i])
         test_images = bag_of_words_SIFT_IB(test_image_paths, codebook_SIFT, 1[i])
         test_images_scaled = scaler.transform(test_images)
         test_predictions = svm_SIFT.predict(test_images_scaled)
         res.append(accuracy_score(test_labels, test_predictions))
     d = {'Accuracy': res}
     df = pd.DataFrame(data=d, index = 1)
     df.to_csv("Robustness_Testing_Results_SVM/Image Brightness Decrease ACCURACY.
      ⇔csv")
     df
[]: def bag_of_words_SIFT_OII(image_paths, codebook, i):
         sift = cv.SIFT_create(nfeatures=300)
         codebook_size = codebook.shape[0]
         image_features = []
         for image_path in image_paths:
             img = read_img(image_path, mono=True)
             img = helper.occlusion(img, i)
             img = cv.normalize(img, None, 0, 255, cv.NORM_MINMAX).astype('uint8')
             keypoints, descriptors = sift.detectAndCompute(img, None)
             bow = np.zeros(codebook_size)
             if descriptors is not None:
                 distances = cdist(descriptors, codebook)
                 for d in distances:
                     bow[np.argmin(d)] += 1
             image_features.append(bow.reshape(1, codebook_size))
         image_features = np.concatenate(image_features)
         return image_features
[]: 1 = [0, 5, 10, 15, 20, 25, 30, 35, 40, 45]
[]: res = []
     for i in range(len(1)):
         print(l[i])
         test_images = bag_of_words_SIFT_OII(test_image_paths, codebook_SIFT, 1[i])
         test_images_scaled = scaler.transform(test_images)
         test_predictions = svm_SIFT.predict(test_images_scaled)
         res.append(accuracy_score(test_labels, test_predictions))
     d = {'Accuracy': res}
     df = pd.DataFrame(data=d, index = 1)
     df.to_csv("Robustness_Testing_Results_SVM/Occlusion of the Image Increase_
     →ACCURACY.csv")
     df
```

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[]: def bag_of_words_SIFT_SPN(image_paths, codebook, i):
         sift = cv.SIFT_create(nfeatures=300)
         codebook_size = codebook.shape[0]
         image_features = []
         for image_path in image_paths:
             img = read_img(image_path, mono=True)
             img = helper.salt_and_pepper(img, i)
             img = cv.normalize(img, None, 0, 255, cv.NORM_MINMAX).astype('uint8')
             keypoints, descriptors = sift.detectAndCompute(img, None)
             bow = np.zeros(codebook_size)
             if descriptors is not None:
                 distances = cdist(descriptors, codebook)
                 for d in distances:
                     bow[np.argmin(d)] += 1
             image_features.append(bow.reshape(1, codebook_size))
         image_features = np.concatenate(image_features)
         return image_features
[]: 1 = [0.00, 0.02, 0.04, 0.06, 0.08, 0.10, 0.12, 0.14, 0.16, 0.18]
[]: res = []
     for i in range(len(1)):
         print(l[i])
         test_images = bag_of_words_SIFT_SPN(test_image_paths, codebook_SIFT, 1[i])
         test_images_scaled = scaler.transform(test_images)
         test_predictions = svm_SIFT.predict(test_images_scaled)
         res.append(accuracy_score(test_labels, test_predictions))
     d = {'Accuracy': res}
     df = pd.DataFrame(data=d, index = 1)
     df.to_csv("Robustness_Testing_Results_SVM/Salt and Pepper Noise ACCURACY.csv")
     df
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