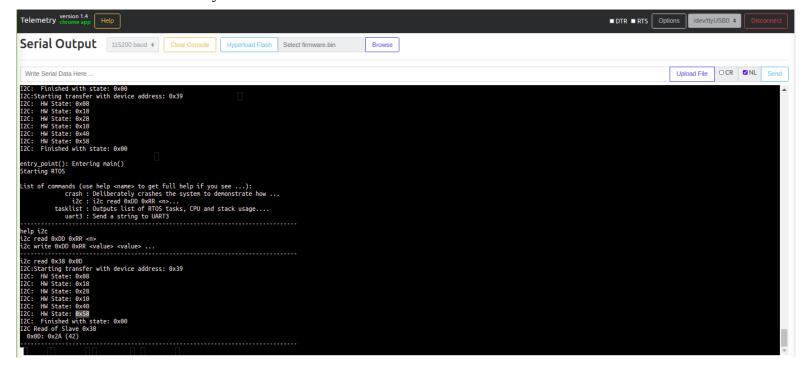
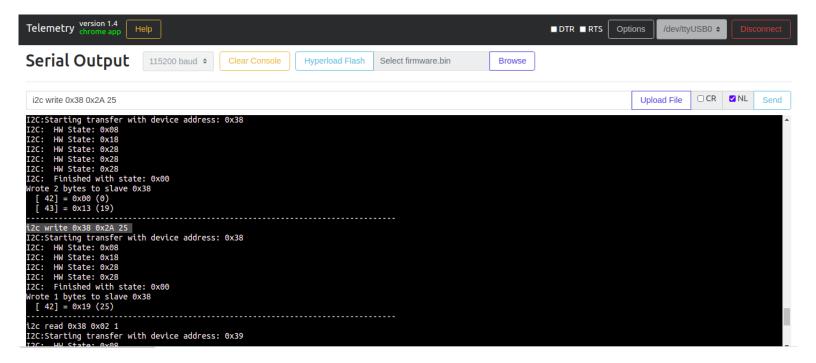
## I2C Part 1

- 1) To read WHO\_AM\_I register:
- → Sent "i2c read 0x38 0x0D" CLI command
- → Below the Telemtry screenshot of same



- 2) To write to CTRL\_REG1 register of Accelerometer sensor:
- → Sent "i2c write 0x38 0x2A 25" CLI command



## I2C Part 1

- 3) To read X and Z axis value of accelerometer:
- → sent "i2c read 0x38 0x01 2" CLI command to read X axis data
- → sent "i2c read 0x38 0x05 2" CLI command to read Z axis data

