

## Multiple Tasks Assignment

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1) When Task\_one and Task\_two has equal priority = PRIORITY\_LOW

output:

[illegible]

Solution:

From the above output observation we could see that, characters A is printed 3-4 times and character b is printed same way. This is because:

- The baudrate is 38400, i.e. the serial communication can transfer 38400 bits per second.
- One character needs 10 bit transfer, thus transfer rate is 3840 characters per second
- As, Task\_one and Task\_two has same priority == LOW, RTOS will jump between these two tasks for every tick time = (1/1kHz = 1mSec). Thus, each task would run to transfer 3.8 characters i.e. 3-4 characters before switching to other task.

2) When priority of Task\_one = PRIORITY\_LOW, and Task\_two = PRIORITY\_MEDIUM

Output:

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peripherals_init(): Low level startup
WARNING: SD card could not be mounted

I2C slave detected at address: 0x38
I2C slave detected at address: 0x64
I2C slave detected at address: 0x72

entry_point(): Entering main()
bbbbbbbbbbbbAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAA
AAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbb
bbAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbb
bbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAA
AAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbA
AAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbb
bbbbbbAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAA
AbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAA
AAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbb
bbAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbbbbbbbbbbAAAAAAAAAAAAAbbb
bbbbbbbbbbAAAAAAAAAAAAA
```

Solution:

The above output observation we can see that,

- character b is printed 4 times and then switched to Task\_one
  - Task\_two with priority 2 ran for 1 mSec, then the higher priority task (UART\_TASK) preempted it (Task\_two went to sleep for 1 sec) to print data. UART\_TASK went to sleep after printing data.
- character A is printed 12 times, .i.e. Task\_one ran fully without preemption, as other tasks were sleeping.
- character b is printed 12 times .i.e. Task\_two ran fully without preemption as other tasks were sleeping.
- pattern repeated same way.

3) When priority of Task\_one = PRIORITY\_MEDIUM, and Task\_two = PRIORITY\_LOW

Output:

[illegible]

**Analysis:**

From the above output, I found the following observations:

- Initial 4 characters printed from Task\_one, Because:
  - It has higher priority than the task printing character b
  - It only printed 4 characters, as after 1 tick time RTOS preempted this task to run higher priority task of UART\_TASK
- next characters printed are b, 12 times. i.e. Task\_two ran fully without preemption
  - As, other tasks were sleeping, no task was available to preempt
- next characters printed are A, 12 times, i.e. Task\_one ran fully without preemption
  - As other tasks were sleeping, no one was available to preempt this one
- This pattern repeated throughout processing