

## 2025.1 Multicore Computing Project #4

### -problem 2-

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#### 1. Environment

A. Google Colab(T4 GPU)

#### 2. Source Code

A. thrust\_ex.cu

```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
#include <thrust/transform.h>
#include <thrust/reduce.h>
#include <thrust/functional.h>
#include <thrust/iterator/counting_iterator.h>
#include <thrust/iterator/transform_iterator.h>
#include <stdio.h>
#include <time.h>
#include <cuda_runtime.h>
```

```
struct pi_functor {
    const double step;

    pi_functor(double _step) : step(_step) {}

    __host__ __device__
    double operator()(const long& i) const {
        double x = (i + 0.5) * step;
        return 4.0 / (1.0 + x * x);
    }
};
```

```
int main() {
    const long num_steps = 1000000000L;
```

```

const double step = 1.0 / (double)num_steps; //width

printf("Thrust Pi Calculation Started...\n");
printf("Number of steps: %ld\n", num_steps);

// calculate execution time
clock_t start_time = clock();
// make counting iterator 0 ~ (num steps -1)
thrust::counting_iterator<long> first(0);
thrust::counting_iterator<long> last = first + num_steps;
//make transform iterator that apply pi functor to each index
thrust::transform_iterator<pi_functor, thrust::counting_iterator<long>>
    transform_first(first, pi_functor(step));
thrust::transform_iterator<pi_functor, thrust::counting_iterator<long>>
    transform_last(last, pi_functor(step));
// add all transformed values
double sum = thrust::reduce(transform_first, transform_last, 0.0,
thrust::plus<double>());

double pi = step * sum;

clock_t end_time = clock();
double elapsed_time = ((double)(end_time - start_time)) /
CLOCKS_PER_SEC;

printf("Execution Time : %.10lfsec\n", elapsed_time);
printf("pi=%.10lf\n", pi);

return 0;
}

```

### 3. Compilation and Execution

- %%writefile thrust\_ex.cu
- [total code]
- !nvcc -arch=sm\_75 -o thrust\_ex thrust\_ex.cu
- !./thrust\_ex

#### 4. Result

##### A. capture image

###### i. omp\_pi\_one

```
[ ] !gcc -fopenmp -o omp_pi_one omp_pi_one.c

[ ] !./omp_pi_one

🔄 Execution Time : 3.1910440210sec
pi=3.1415926536
```

###### ii. thrust\_ex

```
[2] !nvcc -arch=sm_75 -o thrust_ex thrust_ex.cu

[3] !./thrust_ex

🔄 Number of steps: 1000000000
Execution Time : 0.3452060000sec
pi=3.1415926536
```

##### B. Performance

Implementation	Execution Time	Performance
1 thread (CPU)	3.191 sec	0.313
Thrust GPU	0.345 sec	2.899

##### C. Result Analysis

The Thrust implementation was better than 1 thread version. The improvement was achieved because GPU can process thousands of calculations simultaneously, and Thrust libraries provides optimized parallel algorithms.