2025.1 Multicore Computing Project #4

-problem 2-

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1. Envorinment
    A. Google Colab(T4 GPU)
2. Source Code
    A. thrust_ex.cu
        #include <thrust/host_vector.h>
        #include <thrust/device_vector.h>
        #include <thrust/transform.h>
        #include <thrust/reduce.h>
        #include <thrust/functional.h>
        #include <thrust/iterator/counting_iterator.h>
        #include <thrust/iterator/transform_iterator.h>
        #include <stdio.h>
        #include <time.h>
        #include <cuda_runtime.h>
        struct pi_functor {
             const double step;
             pi_functor(double _step) : step(_step) {}
             _host_ _device_
             double operator()(const long& i) const {
                 double x = (i + 0.5) * step;
                 return 4.0 / (1.0 + x * x);
            }
        };
        int main() {
```

const long num_steps = 1000000000L;

```
printf("Thrust Pi Calculation Started...₩n");
             printf("Number of steps: %ld₩n", num_steps);
             // calculate execution time
             clock_t start_time = clock();
             // make counting iterator 0 ~ (num steps -1)
             thrust::counting_iterator<long> first(0);
             thrust::counting_iterator<long> last = first + num_steps;
             //make transform iterator that apply pi functor to each index
             thrust::transform_iterator<pi_functor, thrust::counting_iterator<long>>
                 transform_first(first, pi_functor(step));
             thrust::transform_iterator<pi_functor, thrust::counting_iterator<long>>
                 transform_last(last, pi_functor(step));
             // add all transformed values
             double sum = thrust::reduce(transform_first, transform_last, 0.0,
        thrust::plus < double > ());
             double pi = step * sum;
             clock_t end_time = clock();
             double elapsed_time = ((double)(end_time - start_time)) /
         CLOCKS_PER_SEC;
             printf("Execution Time: %.10lfsec₩n", elapsed_time);
             printf("pi=%.10lf₩n", pi);
             return 0;
        }
3. Compilation and Execution
   - %%writefile thrust ex.cu
       [total code]
   - !nvcc -arch=sm_75 -o thrust_ex thrust_ex.cu
     !./thrust_ex
```

const double step = 1.0 / (double)num_steps; //width

4. Result

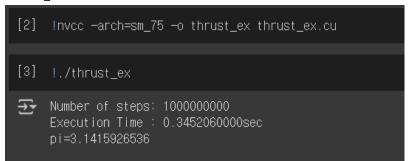
- A. capture image
 - i. omp_pi_one

```
[] !gcc -fopenmp -o omp_pi_one omp_pi_one.c

[] !./omp_pi_one

Execution Time : 3.1910440210sec
pi=3.1415926536
```

ii. thrust_ex



B. Performance

| Implementation | Execution Time | Performance |
|----------------|----------------|-------------|
| 1 thread (CPU) | 3.191 sec | 0.313 |
| Thrust GPU | 0.345 sec | 2.899 |

C. Result Analysis

The Thrust implementation was better than 1 thread version. The improvement was achieved because GPU can process thousands of calculations simultaneously, and Thrust libraries provides optimized parallel algorithms.