

DEEP LEARNING AND INVERSE PROBLEMS
SUMMER 2024
Lecturer: Reinhard Heckel

Problem Set 10

Issued: Tuesday July 2, 2024, 1:00 pm.
Due: Tuesday July 9, 2024, 1:00 pm.

Problem 1 (Robustness of regularized least squares). Suppose our goal is to recover a vector \mathbf{x} from a noisy measurement $\mathbf{y} = \mathbf{A}\mathbf{x} + \mathbf{e}$, where $\mathbf{A} \in \mathbb{R}^{m \times n}$, $m < n$, is a generic measurement matrix and \mathbf{e} is additive noise. In this problem, we numerically study the behavior of the ℓ_2 -regularized least-squares estimator

$$\hat{\mathbf{x}}_{2,\lambda}(\mathbf{y}) = \arg \min_{\mathbf{x}} \frac{1}{2} \|\mathbf{A}\mathbf{x} - \mathbf{y}\|_2^2 + \frac{\lambda}{2} \|\mathbf{x}\|_2^2,$$

and the ℓ_1 -regularized least-squares estimator

$$\hat{\mathbf{x}}_{1,\lambda}(\mathbf{y}) = \arg \min_{\mathbf{x}} \frac{1}{2} \|\mathbf{A}\mathbf{x} - \mathbf{y}\|_2^2 + \lambda \|\mathbf{x}\|_1,$$

under random (average-case) perturbations.

- (a) Give a closed form expression of $\hat{\mathbf{x}}_{2,\lambda}$ in terms of the singular values and vectors of the matrix \mathbf{A} .
- (b) Now we want to numerically investigate the reconstruction error of the estimator $\hat{\mathbf{x}}_{2,\lambda}$ under random perturbations. Towards this end, choose $\mathbf{A} \in \mathbb{R}^{500 \times 2000}$ as a Gaussian random matrix with $\mathcal{N}(0, 1/500)$ iid entries, and choose \mathbf{x} as an 50-sparse vector with non-zeros drawn from the distribution $\mathcal{N}(0, 1/50)$. Plot the reconstruction mean-squared error $\|\hat{\mathbf{x}}_{2,\lambda}(\mathbf{A}\mathbf{x} + \mathbf{e}) - \mathbf{x}\|_2^2$ for a random noise vector \mathbf{e} with iid $\mathcal{N}(0, 0.5/500)$ entries as a function of the regularization parameter λ .
- (c) Repeat the steps from part (b) for the ℓ_1 -regularized least-squares estimator $\hat{\mathbf{x}}_{1,\lambda}$. Note that there is no closed-form expression of the estimator $\hat{\mathbf{x}}_{1,\lambda}$ (why?), so you have to resort to optimization to approximate it. To this end, you can for example use the ISTA method as discussed in Problem 2 of Homework 2.

Problem 1 (Robustness of regularized least squares). Suppose our goal is to recover a vector \mathbf{x} from a noisy measurement $\mathbf{y} = \mathbf{A}\mathbf{x} + \mathbf{e}$, where $\mathbf{A} \in \mathbb{R}^{m \times n}$, $m < n$, is a generic measurement matrix and \mathbf{e} is additive noise. In this problem, we numerically study the behavior of the ℓ_2 -regularized least-squares estimator

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- (a) Give a closed form expression of $\hat{\mathbf{x}}_{2,\lambda}$ in terms of the singular values and vectors of the matrix \mathbf{A} .

$$L(x) = \frac{1}{2} \|\mathbf{A}x - \mathbf{y}\|_2^2 + \frac{\lambda}{2} \|x\|_2^2$$

$$\nabla_x L(x) = \mathbf{A}^T (\mathbf{A}x - \mathbf{y}) + \lambda x \stackrel{!}{=} 0$$

$$(\mathbf{A}^T \mathbf{A} + \lambda \mathbf{I}) x = \mathbf{A}^T \mathbf{y}$$

$$x = (\mathbf{A}^T \mathbf{A} + \lambda \mathbf{I})^{-1} \mathbf{A}^T \mathbf{y}$$

Assume $\mathbf{A} = \mathbf{U} \Sigma \mathbf{V}^T$

$$\mathbf{A}^T \mathbf{A} = \mathbf{U} \Sigma^2 \mathbf{U}^T$$

$$x = (\mathbf{U} \Sigma^2 \mathbf{U}^T + \lambda \mathbf{I})^{-1} \mathbf{V} \Sigma \mathbf{U}^T \mathbf{y}$$

assume $\mathbf{I} = \mathbf{U} \mathbf{U}^T$: $x = (\mathbf{U} (\Sigma^2 + \lambda \mathbf{I}) \mathbf{U}^T)^{-1} \mathbf{V} \Sigma \mathbf{U}^T \mathbf{y}$

b) See notebook

(c) Repeat the steps from part (b) for the ℓ_1 -regularized least-squares estimator $\hat{\mathbf{x}}_{1,\lambda}$. Note that there is no closed-form expression of the estimator $\hat{\mathbf{x}}_{1,\lambda}$ (why?), so you have to resort to optimization to approximate it. To this end, you can for example use the ISTA method as discussed in Problem 2 of Homework 2.

It doesn't have a closed-form solution because $\|\cdot\|_1$ norm is not differentiable.

$$\Rightarrow g(x) = \lambda \|x\|_1 = \lambda \sum_{i=1}^n |x_i|$$

The absolute value is not differentiable at $x_i = 0$

$$\frac{d|x_i|}{dx_i} = \begin{cases} 1 & x_i > 0 \\ -1 & x_i < 0 \\ 0 & x_i = 0 \end{cases}$$

(See notebook)