

Coverage



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Outline



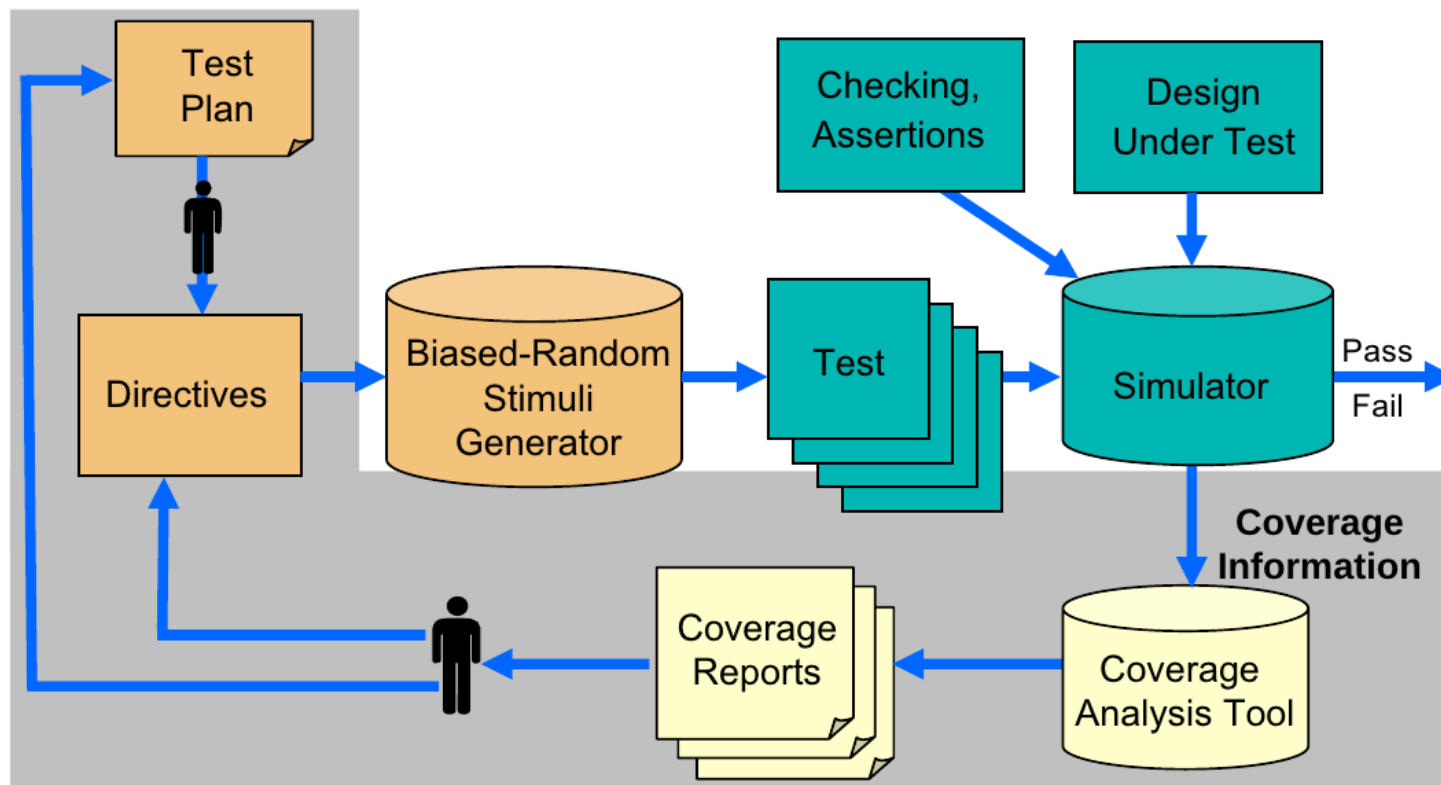
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- Introduction to coverage
- Code coverage models
- Structural coverage models
- Functional coverage
- Coverage closure

Simulation-based Verification Environment



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Why Coverage?



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- Simulation is based on limited execution samples
 - Cannot run all possible scenarios, but
 - Need to know that all (important) areas of the DUV are verified
- Solution: Coverage measurement and analysis
- The main ideas behind coverage
 - Features (of the specification and implementation) are identified
 - Coverage models written to quantify their behavioral spaces

Coverage Goals



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- Measure the "quality" of a set of tests
- Supplement test specifications by pointing to untested areas
 - NOTE: Coverage gives ability to see what has not been verified!
 - Coverage completeness does not imply functional correctness of the design!
- Help create regression suites
 - Ensure that all parts of the DUV are covered by regression suite
- Provide a stopping criteria for unit testing
- Improve understanding of the design

Coverage Types



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- Code coverage
- Structural coverage
- Functional coverage

- Other classifications
 - Implicit vs. explicit
 - Specification vs. implementation

Code Coverage - Basics



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- Coverage models are based on the HDL code
 - Implicit, implementation coverage
- Coverage models are syntactic
 - Model definition is based on syntax and structure of the HDL
- Generic models – fit (almost) any programming language
 - Both software and hardware

Code Coverage - Limitations



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Code coverage can answer the question:

“Is there a piece of code that has not been verified?”

- Method used in software engineering for some time.

Main problem:

- False positive answers can look identical to true positive answers.

False positive: A bad design is thought to be good.

- Useful for profiling:
 - Run coverage on testbench to indicate what areas are executed most often.
 - Gives insight on what to optimize!
- Many types of code coverage report metrics/models.

Types of Code Coverage Models



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- Control flow
 - Check that the control flow of the program has been fully exercised
- Data flow
 - Models that look at the flow of data in, and between, programs
- Mutation
 - Models that check directly for common bugs

Control Flow Models



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- Routine (function entry)
 - Each function / procedure is called
- Function call
 - Each function is called from every possible location
- Function return
 - Each return statement is executed
- **Statement (block)**
 - Each statement in the code is executed
- **Branch/Path**
 - Each branch in branching statement is taken
 - If, switch, case, when, ...
- **Expression/Condition**
 - Each (sub-)expression in Boolean expression takes true and false values
- Loop
 - All possible number of iterations in (Bounded) loops are executed

Statement/Block Coverage



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Measures which lines (statements) have been executed by the verification suite.

```

✓ if (parity==ODD || parity==EVEN) begin
❑ parity_bit = compute_parity(data,parity);
  end
✓ else begin
✓ parity_bit = 1'b0;
  end
✓ #(delay_time);
✓ if (stop_bits==2) begin
✓ end_bits = 2'b11;
✓ #(delay_time);
  end

```

What do we need to do to get the statement coverage to 100%?

- Why has this never occurred?
- Is it a condition that can never occur? Was is simply forgotten?
- (Dead code can be “ok”!) WHY?

Expression/Condition Coverage



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Measures the various ways paths through the code are executed.

- Where a branch condition is made up of a Boolean expression, want to know which of the subexpressions have been covered.

```

✓ if (parity==ODD || parity==EVEN) begin
✓ parity_bit = compute_parity(data,parity);
end
✓ else begin
✓ parity_bit = 1'b0;
end
✓ #(delay_time);
✓ if (stop_bits==2) begin
✓ end_bits = 2'b11;
✓ #(delay_time);
end

```

Diagram illustrating expression coverage analysis. A green line traces the execution path through the first `if` statement and the `if (stop_bits==2)` statement, ending with a green checkmark. A red line traces the execution path through the `else` block and the `if (stop_bits==2)` statement, ending with a red square. This indicates that the `if (stop_bits==2)` condition was covered, but the `else` branch of the first `if` statement was not.

Note: Only 50%
expression
coverage!

- Analysis: Understand WHY part of an expression was not executed
- Reaching 100% expression coverage is extremely difficult.

Data Flow Models



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- Coverage models that are based on flow of data during execution
- Each coverage task has two attributes
 - Define – where a value is assigned to a variable (signal, register, ...)
 - Use – where the value is being used

```

process (a, b)
begin
  s <= a + b;
end process
process (clk)
begin
  if (reset)
    a <= 0; b <= 0;
  else
    a <= in1; b <= in2;
  end if
end process

```

Mutation Coverage



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- Mutation coverage is designed to detect simple (typing) mistakes in the code
 - Wrong operator
 - + instead of –
 - >= instead of >
 - Wrong variable
 - Offset in loop boundaries
- A mutation is considered covered if we found a test that can distinguish between the mutation and the original code
 - Strong mutation – the difference is visible in the primary outputs
 - Weak mutation – the difference is visible inside the DUV

Code Coverage Models for Hardware



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- Toggle coverage
 - Each (bit) signal changed its value from 0 to 1 and from 1 to 0
- All-values coverage
 - Each (multi-bit) signal got all possible values
 - Used only for signals with small number of values
 - For example, state variables of FSMs

Code Coverage Strategy



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- Set minimum % of code coverage depending on available verification resources and importance of preventing post tape-out bugs.
 - A failure in low-level code may affect multiple high-level callers.
 - Hence, set a higher level of code coverage for unit testing than for system testing.
- Generally, 90% goal for statement, branch or expression coverage.
 - Some feel that less than 100% does not ensure quality.
 - Beware: Reaching full code coverage closure can cost a lot of effort!
 - This effort could be more wisely invested into other verification techniques.
- Avoid setting a goal lower than 80%.

Literature: [J Barkley. Why Statement Coverage Is Not Enough. A practical strategy for coverage closure., TransEDA.]

Structural Coverage



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- Implicit coverage models that are based on common structures in the code
 - FSMs, Queues, Pipelines, ...
- The structures are extracted automatically from the design and pre-defined coverage models are applied to them
- Users may refine the models
 - Define illegal events

State-Machine Coverage



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- State-machines are the essence of RTL design
- FSM coverage models are the most commonly used structural coverage models
- Types of models
 - State
 - Transition (or arc)
 - Path

Code Coverage - Limitations



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- Coverage questions not answered by code coverage tools
 - Did every instruction take every exception?
 - Did two instructions accessed the register at the same time?
 - How many times did cache miss take more than 10 cycles?
 - Does the implementation cover the functionality specified?
 - ... (and many more)
- Code coverage indicates how thoroughly the test suite exercises the source code!
 - Can be used to identify outstanding corner cases
- Code coverage lets you know if you are not done!
 - It does not indicate anything about the functional correctness of the code!
- 100% code coverage does not mean very much.
- Need another form of coverage!

Functional Coverage



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- It is important to cover the functionality of the DUV.
 - Most functional requirements can't easily be mapped into lines of code!
- Functional coverage models are designed to assure that various aspects of the functionality of the design are verified properly
- Functional coverage models are specific to a given design or family of designs
- Models cover
 - The inputs and the outputs
 - Internal states
 - Scenarios
 - Parallel properties
 - Bug Models

Functional Coverage Model Types



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- Discrete set of coverage tasks
 - Set of unrelated or loosely related coverage tasks
 - In many cases, natural extension of assertions into coverage
 - Often used for corner cases
- Structured coverage models
 - The coverage tasks are defined in a structure that defines relations between the coverage tasks
 - Allow definition of similarity and distance between tasks
 - Most commonly used model types
 - Cross-product
 - Trees
 - Hybrid structures

Cross-Product Coverage Model



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[O Lachish, E Marcus, S Ur and A Ziv. Hole Analysis for Functional Coverage Data. In proceedings of the 2002 Design Automation Conference (DAC), June 10-14, 2002, New Orleans, Louisiana, USA.]

A cross-product coverage model is composed of the following parts:

1. A semantic description of the model (story)
2. A list of the attributes mentioned in the story
3. A set of all the possible values for each attribute (the attribute value domains)
4. A list of restrictions on the legal combinations in the cross-product of attribute values

Example: Cross-Product Coverage Model 1



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Design: switch/cache unit

[G Nativ, S Mittermaier, S Ur and A Ziv. Cost Evaluation of Coverage Directed Test Generation for the IBM Mainframe. In Proceedings of the 2001 International Test Conference, pages 793-802, October 2001.]

Motivation: Interactions of core processor unit command-response sequences can create complex and potentially unexpected conditions causing contention within the pipes in the switch/cache unit when many core processors are active.

All conditions must be tested to gain confidence in design correctness.

Attributes relevant to command-response events:

- Commands - CPs to switch/cache [31]
- Responses - switch/cache to CPs [16]
- Pipes in each switch/cache [2]
- CPs in the system [8]
- (Command generators per CP chip [2])

How big is the coverage space, i.e. how many coverage tasks?

Example: Cross-Product Coverage Model 2



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Size of coverage space:

- Coverage space is formed by cross-product over all attribute value domains.
- Size of cross-product is product of domain sizes:
 - $31 \times 16 \times 2 \times 8 \times 2 = 15872$
- Hence, there are 15872 coverage tasks.

Example coverage task:

(Command=20, Response=01, Pipe=1, CP=5, CG=0)

Are all of these tasks reachable/legal?

- Restrictions on the coverage model are:
 - possible responses for each command
 - unimplemented command/response combinations
 - some commands are only executed in pipe 1
- After applying restrictions, there are 1968 legal coverage tasks left.
- Make sure you identify & apply restrictions before you start!

Defining the Legal and Interesting Spaces



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In Practice:

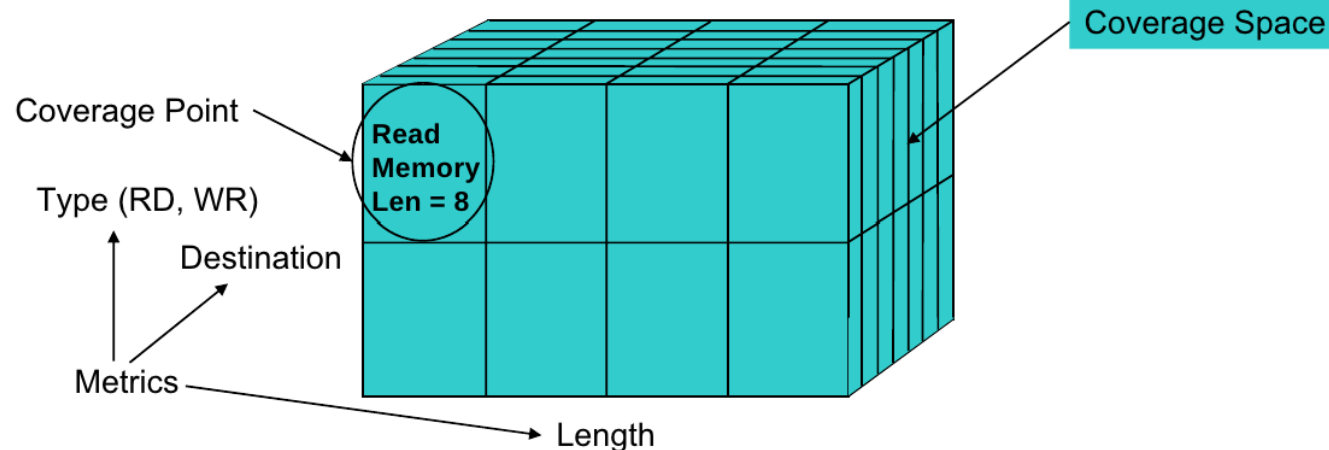
- The design and verification team create initial spaces based on their understanding of the design
 - Boundaries between legal and illegal are often not well understood
- Coverage feedback modifies the space definition
- Sub-models are used to economically check and refine the spaces
 - Easy to define as these are sub-crosses!
- Interesting spaces tend to change often due to shift in focus in the verification process

Coverage Terminology



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- coverage model: *A set of legal and interesting coverage points in the coverage space.*
- coverage point:
 1. *A point within a multi-dimensional coverage space.*
 2. *An event of interest that can be observed during simulation.*



Summary: Functional Coverage



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Determines whether the functionality of the DUV was verified.

- Functional coverage models are user-defined.
 - (specification driven)
 - This is a skill. It needs (lots of) experience!
 - Focus on control signals. WHY?
- Strengths:
 - High expressiveness: cross-correlation and multi-cycle scenarios.
 - Objective measure of progress against verification plan.
 - Can identify coverage holes by crossing existing items.
 - Results are easy to interpret.
- Weaknesses:
 - Only as good as the coverage metrics.
 - To implement the metrics, manual effort is required.

Summary: Code Coverage



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- Determines if all the implementation was verified.
- Models are implicitly defined by the source code.
 - (implementation driven)
 - statement, path, expression, toggle, etc.
 - Strengths:
 - Reveals unexercised parts of design.
 - May reveal gaps in functional verification plan.
 - No manual effort is required to implement the metrics. (Comes for free!)
 - Weaknesses:
 - No cross correlations.
 - Can't see multi-cycle/concurrent scenarios.
 - Manual effort required to interpret results.

Summary: Coverage Models



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Do we need both code and functional coverage? YES!!

Functional Coverage	Code Coverage	Interpretation
Low	Low	There is verification work to do.
Low	High	Multi-cycle scenarios, corner cases, cross-correlations still to be covered.
High	Low	Verification plan/or functional coverage metrics inadequate. Check for “dead” code.
High	High	High confidence of quality.

- Coverage models complement each other!
- No single coverage model is complete on its own.



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Coverage Closure

Risks of Using Coverage



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- Low coverage goals
- Some coverage models are ill-suited to deal with common problems
 - Missing code
- Generating simple tests to cover specific uncovered tasks
 - There is merit in generating tests outside the coverage!
- Using coverage without commitment to using the results

Coverage Closure



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Coverage closure is the process of:

- Finding areas of coverage not exercised by a set of tests.
 - Coverage Holes!
- Creating additional tests to increase coverage by targeting these holes.

Controllability Problems



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If the cases to be hit contain internal states/signals of the DUV, directed tests that exercise all combinations are hard to find.

- Processor pipeline verification: Control logic, Internal FSMs
- Generate biased random tests automatically. [RTPG]
 - Typically tests are filtered to retain only those that add to coverage.
 - Coverage analysis indicates hard-to-reach cases.
 - Don't waste engineers time on what automation can achieve.
- Combine automatically generated stimulus with coverage.
- Gives rise to Coverage DRIVEN Verification Methodology

BUT:

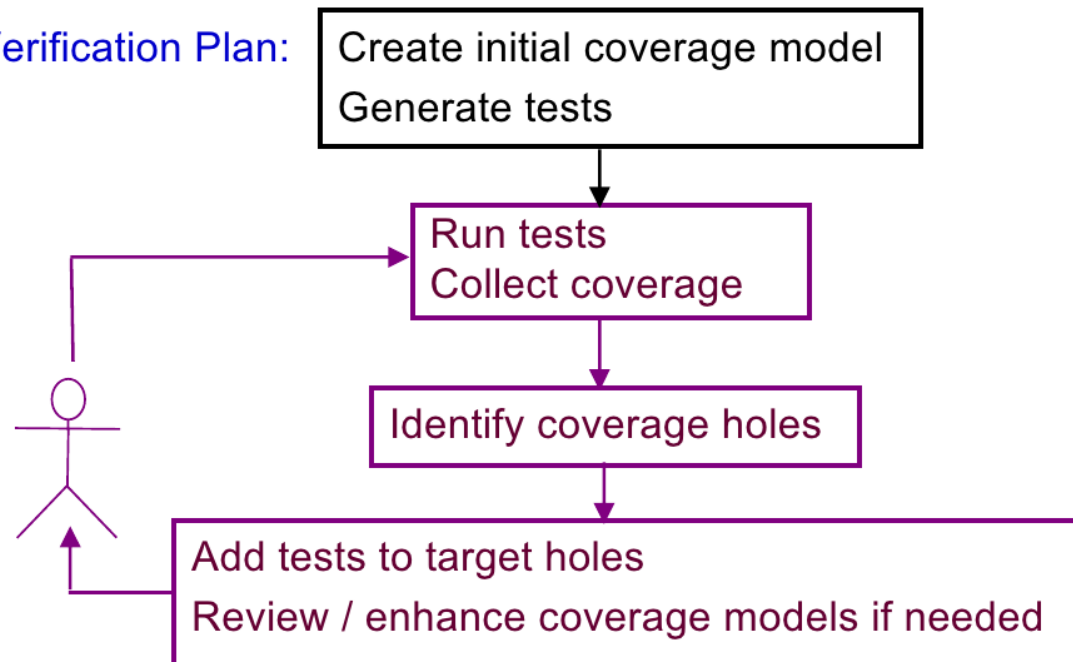
- Hard-to-reach cases (may) need manual attention.
 - Bias tests towards certain conditions or corner cases.
 - Supplying bias requires significant engineering skill.
 - Often only trial-and-error approach.

Coverage DRIVEN Verification Methodology



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From Verification Plan:



Current research: How can we automate this further?

80/20 Split



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In practice: 80/20 (20/80) split wrt coverage progress.

Good news:)

- 80% of coverage is achieved (relatively quickly/easily) driving randomly generated tests.
- This takes about 20% of total time/effort/sim runs spent on verification.

Bad news:(

- Gaining the remaining 20% coverage,
 - i.e. filling the remaining coverage holes (which often needs to be done manually and requires a lot of skill plus design understanding),
- can take as much as 80% of the total time/effort/sim runs spent on verification.

Benefits of Coverage DRIVEN Verification Methodology



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- Shortens implementation time
 - (Initial setup time)
 - Random generation covers many “easy” cases
- Improves quality
 - Focus on goals in verification plan
 - Encourages exploration/refinement of coverage models
- Accelerates verification closure
 - Refine/tighten constraints to target coverage holes

Summary: Coverage



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- Coverage is an important verification tool.
 - Code coverage: statement, path, expression
 - Structural coverage: FSM
 - Functional coverage models: story, attributes, values, restrictions
 - Assertion coverage was introduced during the lecture on Assertion-based Verification.
- Combination of coverage models required in practice.
 - Code coverage alone does not mean anything!
- Verification Methodology should be coverage driven.
- Automation: Research into coverage directed test generation
- Delays in coverage closure are the main reason why verification projects fall behind schedule!