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Lab F	Partner(s) Kathema Chen		
Date	Performed <b>21/02/2024</b>	Date Submitted 28/02/wee	
Lab (	such as #1: UNC) <b>\ \ 3: LME</b>		
	Philip		
		our TA) See your TA for detailed feedback. you need to improve this aspect of your work.	
Pape	er Subtotals (points)	( ) Discussion & Conclusions (6	<b>)</b>
( )	) General (6)	Numerical comparison of results Logical conclusions	
	Sig. figs. Units	Discussion of pos. errors	
	Clarity of Presentation	Suggestions to reduce errors	
	Format		
		( ) Paper Total (60 points)	
(	Abstract (4)	(30 points for CME or EPF)	)
	Quantity or principle	( ) Notebook (10 points)	
	How measurement was made	Format (proper style, following dire	
	Numerical Results Conclusion	Apparatus (brief description of equi	ipment,
		including sketches)	a and
( )	) Intro & Theory (9)	Data (including computer file name manually recorded data)	s una
	Basic principle	Experimental Technique (describin,	g vour
=	Main equations to be used	procedures; stating & justifying und	- ·
	Apparatus	Analysis (results and errors)	
	What will be plotted Fitting parameters related		
		( ) Worksheet(s)/Fill-in-the-Blan	nk-
(	) Exp. Procedures (15)	Report (30 points) if applicable	
	Description (18)		
	Stating and justifying uncertainties	( ) Adjustments – late submissions	,
	Data Record Quality of Lab Work	improper procedures, etc. – or bonu for exceptional work.	s points
( )	) Analysis & Error Analysis (20)		
	Discussion	( ) Total Grade	
	Equations & Calculations	,	
	Presentation inc. Graphs, Tables Results Reported & Reasonable	Graded by (TA's in	itial)
	Underlined items addressed	Traded by(1A s in	mai)

## **Abstract**

The purpose for this lab is to establish whether energy is truly conserved when stored and transferred between springs, gravity (height), and motion.

Expected energy loss in GPE: 
$$\frac{\Delta E}{\Delta y} = -0.033 \pm 0.003 \; \frac{J}{m}$$

Actual energy loss in GPE: 
$$\frac{\Delta E}{\Delta y} = -0.056 \pm 0.002 \; \frac{J}{m}$$

Expected friction loss in spring movement: 
$$\Delta E = -0.017 \pm 0.002~J$$
  
Actual friction loss in spring movement:  $\Delta E = -0.029 \pm 0.001~J$ 

Total energy lost: 
$$\Delta E = -0.081 \pm 0.01~J$$

Total energy lost: 
$$\epsilon = -16 \pm 2\%$$

Our expected values for energy loss and actual values slightly differed, with the system losing more energy than we expected. We ultimately attributed this to additional unmeasured friction and spring dampening, thus not disproving the theory of energy conservation.

## **Gravitational Potential Energy**

## **Finding Friction**

#### **Method**

- Ensure Plane is level
- Gradually add weight until the cart has constant velocity
- Measure the mass needed to offset the friction

#### **Data**

Trial	$m_c\left(g ight)$	$m_p\left(g ight)$
1	988.0	3.4
2	987.4	3.4
3	987.3	3.3
4	987.6	3.4
5	987.8	3.3
6	988.0	3.4
7	987.6	3.4
8	987.6	3.3
9	987.7	3.4
10	987.9	3.4

Trial	$m_c\left(g ight)$	$m_p\left(g ight)$
Mean	987.74	3.37
STD.	10.1	0.3

## **Analysis**

#### Finding W

$$egin{aligned} F_f &pprox m_p g \ W &pprox W_f = F_f \cdot d \ &= -m_p g d \ W &= -0.0330597 d \ \delta_W &= \delta_{Wm_p} = \delta_{m_p} g d = 0.002943 d \ W &= d (-0.0330597 \pm 0.002943) \end{aligned}$$

## **Analytical Conclusion**

We estimate the energy lost to friction will be equal to  $\frac{\Delta E}{\Delta y}=-0.033\pm0.003\,rac{J}{m}$ 

Where  $\Delta y$  is the distance traveled

## **Checking energy loss**

#### **Method**

- Add 50g of weight to a system that is already in balance
- Record position, velocity, acceleration
- Calculate energies and energy loss

#### **Data**

Time	Distance	Velocity	Acceleration	Kinetic Energy	Potential Energy	Total Energy
0.1517	0					
0.23995	0.015	0.19139	0.48532	0.01907	-0.00785	0.01121
0.31179	0.03	0.22557	0.46638	0.02649	-0.01571	0.01078
0.37425	0.045	0.25461	0.46362	0.03375	-0.02356	0.01019
0.4303	0.06	0.28013	0.44698	0.04085	-0.03141	0.00944
0.48174	0.075	0.30293	0.43929	0.04777	-0.03927	0.0085
0.52959	0.09	0.32366	0.42702	0.05453	-0.04712	0.00741

Time	Distance	Velocity	Acceleration	Kinetic Energy	Potential Energy	Total Energy
0.5746	0.105	0.34269	0.41856	0.06113	-0.05497	0.00616
0.61726	0.12	0.36069	0.42563	0.06772	-0.06283	0.0049
0.65788	0.135	0.37853	0.45298	0.07459	-0.07068	0.00391
0.69661	0.15	0.39723	0.5125	0.08214	-0.07853	0.00361
0.73349	0.165	0.41593	0.5012	0.09005	-0.08639	0.00367
0.7688	0.18	0.43341	0.4893	0.09779	-0.09424	0.00354
0.80276	0.195	0.45011	0.49413	0.10546	-0.10209	0.00337
0.8355	0.21	0.46477	0.40156	0.11245	-0.10995	0.0025
0.86733	0.225	0.4768	0.35424	0.11834	-0.1178	0.000543
0.89843	0.24	0.48828	0.38362	0.12411	-0.12565	-0.00155
0.92879	0.255	0.50038	0.41339	0.13033	-0.13351	-0.00317
0.95841	0.27	0.5127	0.41874	0.13683	-0.14136	-0.00453
0.98732	0.285	0.52495	0.42854	0.14345	-0.14921	-0.00577
1.01557	0.3	0.53901	0.56704	0.15124	-0.15707	-0.00583
1.043	0.315	0.55435	0.55176	0.15997	-0.16492	-0.00495
1.06971	0.33	0.56816	0.48226	0.16804	-0.17277	-0.00474
1.09582	0.345	0.58104	0.50449	0.17575	-0.18063	-0.00488

## **Analysis**

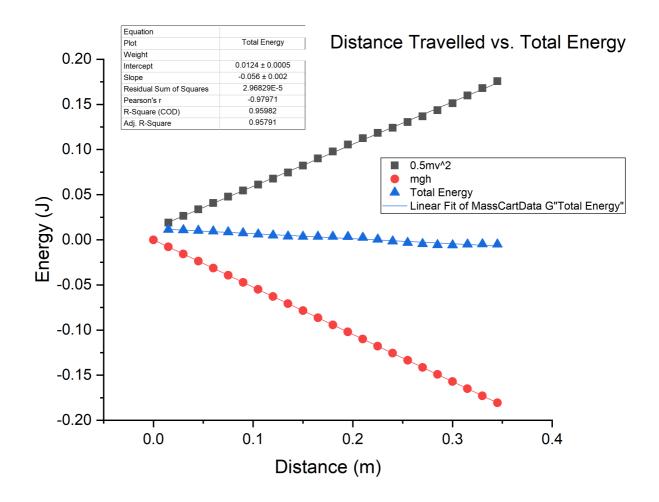


Fig 1: Kinetic, Gravitational Potential, and Total Energy vs. distance traveled

### Finding W

W = -0.0330597d

W = -0.0330597(0.345)

 $W = -0.0114055965 \; J$ 

 $\delta_W=0.002943d$ 

 $\delta_W = 0.002943(0.345)$ 

 $\delta_W = 0.001~J$ 

 $W = -0.011 \pm 0.001 \; J$ 

### **Estimating energy loss**

From the graph, our slope is

$$rac{dE}{dy} = -0.056 \pm 0.002$$

$$\Delta E = rac{d\Delta E}{dy}d$$

=-0.056(0.345)

= -0.01932 J

$$egin{aligned} \delta_{\Delta E} &= \delta_{rac{d\Delta E}{dy}} d \ &= 0.002 (0.345) \ &= 0.00069 \ J \end{aligned}$$

$$\Delta E = -0.01932 \pm 0.0007 J$$

#### **Analytical Conclusion**

From our prior estimate of energy lost to friction, we estimate that

$$\Delta E = -0.011 \pm 0.001~J$$

Experimentally, we have instead determined that we lost

$$\Delta E = -0.01932 \pm 0.0007 \ J$$

We deduced that there is likely significantly more friction in the system due to the nonnegligible increase of force on the pulley, as well as significantly more air-resistance due to the larger weight.

## **Spring Potential Energy**

## **Finding the Spring Constant**

#### **Method**

- Put a meter stick next to the string, parallel, with numbering visible from the side through the string
- Measure the tip of the hook of the spring at different weights

#### **Data**

Weight (g)	Position (cm)
50.0	82.25
55.0	80.90
60.0	79.15
65.0	77.35
70.0	75.75
75.0	74.35
80.0	72.85
85.0	71.70
90.0	69.65
95.0	68.25
100.0	66.50

## **Analysis**

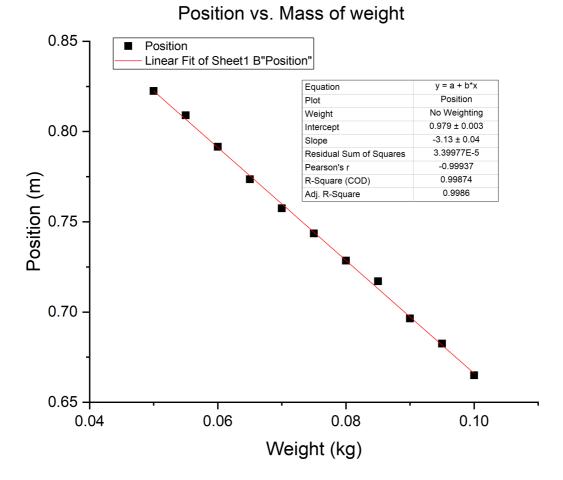


Fig 2: Position of the end of the spring vs. mass hung upon it

### Finding k

The force on the spring can be calculated by the amount of mass hanging on it.

$$F_s = F_g = mg$$
  $F_s = k\Delta x$ 

The slope represents:  $\frac{d\Delta x}{dm}$ 

$$mg=k\Delta x$$
  $g=krac{d\Delta x}{dm}$   $k=rac{g}{rac{d\Delta x}{dm}}$   $k=rac{9.81}{3.13}$   $k=3.134~rac{N}{m}$ 

$$k=rac{g}{rac{d\Delta x}{dm}}$$

The variance in g is negligible compared to that of  $\frac{d\Delta x}{dm}$ 

Let 
$$s=rac{d\Delta x}{dm}$$

$$\delta_k = \delta_{ks} = \delta_s \frac{g}{s^2}$$

$$= 0.04 \left(\frac{9.81}{3.13^2}\right)$$

$$= 0.04 \frac{N}{m}$$

$$k=3.13\pm0.04\,rac{N}{m}$$

### **Analytical Conclusion**

Experimentally, we can deduce that the spring constant for our given spring is  $k=3.13\pm0.04\,rac{N}{m}$ 

## **Finding Energy loss in the Spring**

#### **Data**

At 100g of weight:

Trial	<b>Max Excursion</b>	<b>Resting Position</b>
1	42.80	66.55
2	42.25	66.55
3	40.35	66.55
4	41.10	66.55
Mean	41.8	
STD.	0.6	

Unstretched Spring = 93.90 cm

### **Analysis**

#### **Finding Energy Values**

In all cases, the uncertainty of the hanging mass is negligible at around  $0.00001\ kg$  as the other uncertainties are multiple orders of magnitude larger

$$U_{ki}$$

$$U_{ki}=rac{1}{2}kx^2=0~J$$

$$egin{aligned} \delta_{U_{ki}} &= \delta_{U_{ki}k} = \delta_k rac{1}{2} x^2 \ &= 0 \end{aligned}$$

$$U_{ki}=0\pm 0~J$$

$$U_{kf}$$

$$U_{kf} = \frac{1}{2}kx^2$$
  
=  $\frac{1}{2}3.134(0.9390 - 0.418)^2$   
=  $0.4253 J$ 

$$egin{aligned} \delta_{U_{kf}} &= \sqrt{\delta_{U_{kf}k}^2 + \delta_{U_{kf}x}^2} = \sqrt{(\delta_k rac{1}{2} x^2)^2 + (\delta_x k x)^2} \ &= \sqrt{(0.04(0.5)(0.9390 - 0.418)^2)^2 + (0.006(3.134)(0.9390 - 0.418))^2} \ &= 0.01\ J \end{aligned}$$

$$U_{kf}=0.43\pm0.01~J$$

 $U_{gi}$ 

$$U_{gi}=mgh=0\ J$$

$$\delta_{U_{gi}} = \delta_{U_{gi}h} = \delta_h mg$$

$$U_{gi}=0\pm 0~J$$

 $U_{gf}$ 

$$egin{aligned} U_{fg} &= mgh \ &= -0.1(9.81)(0.9390 - 0.418) \ &= -0.5111\ J \end{aligned}$$

$$egin{aligned} \delta_{U_{gf}} &= \delta_{U_{gf}h} = \delta_h mg \ &= 0.006(0.1)(9.81) \ &= 0.006 \end{aligned}$$

$$U_{gf} = -0.511 \pm 0.006~J$$

#### $\Delta E$

$$\Delta E = U_{gf} + U_{kf} - U_{gi} - U_{ki}$$
  
= 0.43 - 0.511 = -0.081 J

$$egin{aligned} \delta_{\Delta_E} &= \sqrt{\delta_{U_{gf}}^2 + \delta_{U_{kf}}^2} \ &= \sqrt{0.01^2 + 0.006^2} \ &= 0.01\ J \end{aligned}$$

$$\Delta E = -0.081 \pm 0.01~J$$

#### $W_f$ Estimated

$$W_f = d(-0.0330597 \pm 0.002943) \ W_f = (0.9390 - 0.418)(-0.0330597 \pm 0.002943)$$

$$W_f = -0.0172241037 \pm 0.001533303$$
  $W_f = -0.017 \pm 0.002~J$   $rac{dW_f}{d\Delta E} pprox 20.99\%$ 

#### $W_f$ Experimental

$$egin{aligned} W_f &= d(-0.056 \pm 0.002) \ W_f &= (0.9390 - 0.418)(-0.056 \pm 0.002) \ W_f &= -0.029176 \pm 0.001042 \ W_f &= -0.029 \pm 0.001 \ & rac{dW_f}{d\Delta E} pprox 35.80\% \end{aligned}$$

#### Finding $\epsilon$

$$\epsilon = rac{\Delta U_k + \Delta U_g}{|\Delta U_g|} \ = rac{0.43 - 0.511}{0.511} \ = -0.1585$$

$$egin{align} \delta_{\epsilon} &= \sqrt{\delta_{\epsilon U_{kf}}^2 + \delta_{\epsilon U_{gf}}^2} = \sqrt{\left(rac{\delta_{U_{kf}}}{|U_{gf}|}
ight)^2 + \left(-rac{\delta_{U_{gf}}U_{kf}}{U_{gf}^2}
ight)^2} \ &= \sqrt{\left(rac{0.01}{0.511}
ight)^2 + \left(rac{0.006(0.43)}{0.511^2}
ight)^2} \ &= 0.02 \end{array}$$

$$\epsilon = -0.16 \pm 0.02$$
  $\epsilon = -16 \pm 2\%$ 

#### **Analytical Conclusion**

We experimentally determined that in this system, we lose about  $\epsilon=-16\pm2\%$  of the energy when transferred from Gravitational potential to kinetic and finally to spring potential energy. We also attribute the loss in energy mainly to the dampening of the spring, as our expected friction due to the system calculated in the first part of the lab only accounts for a loss of  $W_f=-0.017\pm0.002~J$  while our total energy loss is  $\Delta E=-0.081\pm0.01~J$ 

## **Conclusion**

We conclude that energy is conserved as our estimated values for friction and actual energy loss in the first section of this lab line up pretty closely. Although they are not within the statistical limits to be likely equal, we determined that the additional energy loss in the first lab was due to additional friction due to the substantial increase in weight, and thus normal force upon the pulley. In the second half of the lab, we determined we lose about  $16 \pm 2\%$  of the energy when the energy is transferring from gravitational potential to kinetic and finally to spring potential. Although roughly 21% of the energy lost could be explained by the same

frictional constant we determined in the first part of the lab, we deduce that the remaining energy loss is due to dampening in the spring and other additional frictions due to and even more substantially increased weight from the first lab and a higher tension due to the spring as well. If we use the experimental value for friction from the first lab, we can estimate energy lost to friction to be about 36% of all energy lost. This leaves us with approximately 10% of energy transferred lost due to spring dampening, which is a very rational loss for a spring.

Although we do lose more energy compared to what theoretically should be happening, we deduce that the additional energy loss is due to our imperfect system and measurement techniques, leading to marginally more energy lost overall. Since the number is not drastically inequivalent, we conclude that energy is indeed conserved.

Expected energy loss in GPE: 
$$\frac{\Delta E}{\Delta y} = -0.033 \pm 0.003 \; rac{J}{m}$$

Actual energy loss in GPE: 
$$\frac{\Delta E}{\Delta y} = -0.056 \pm 0.002 \; \frac{J}{m}$$

Expected friction loss in spring movement: 
$$\Delta E = -0.017 \pm 0.002~J$$

Actual friction loss in spring movement: 
$$\Delta E = -0.029 \pm 0.001~J$$

Total energy lost: 
$$\Delta E = -0.081 \pm 0.01 \ J$$

Total energy lost: 
$$\epsilon = -16 \pm 2\%$$

## **Acknowledgements and info**

Lab #3

21/02/2024

Station 14 Rockefeller 404

PHYS 121

Lab Partner: Katherine Chen

Lab Manual: Lab 3 CME PHYS 121