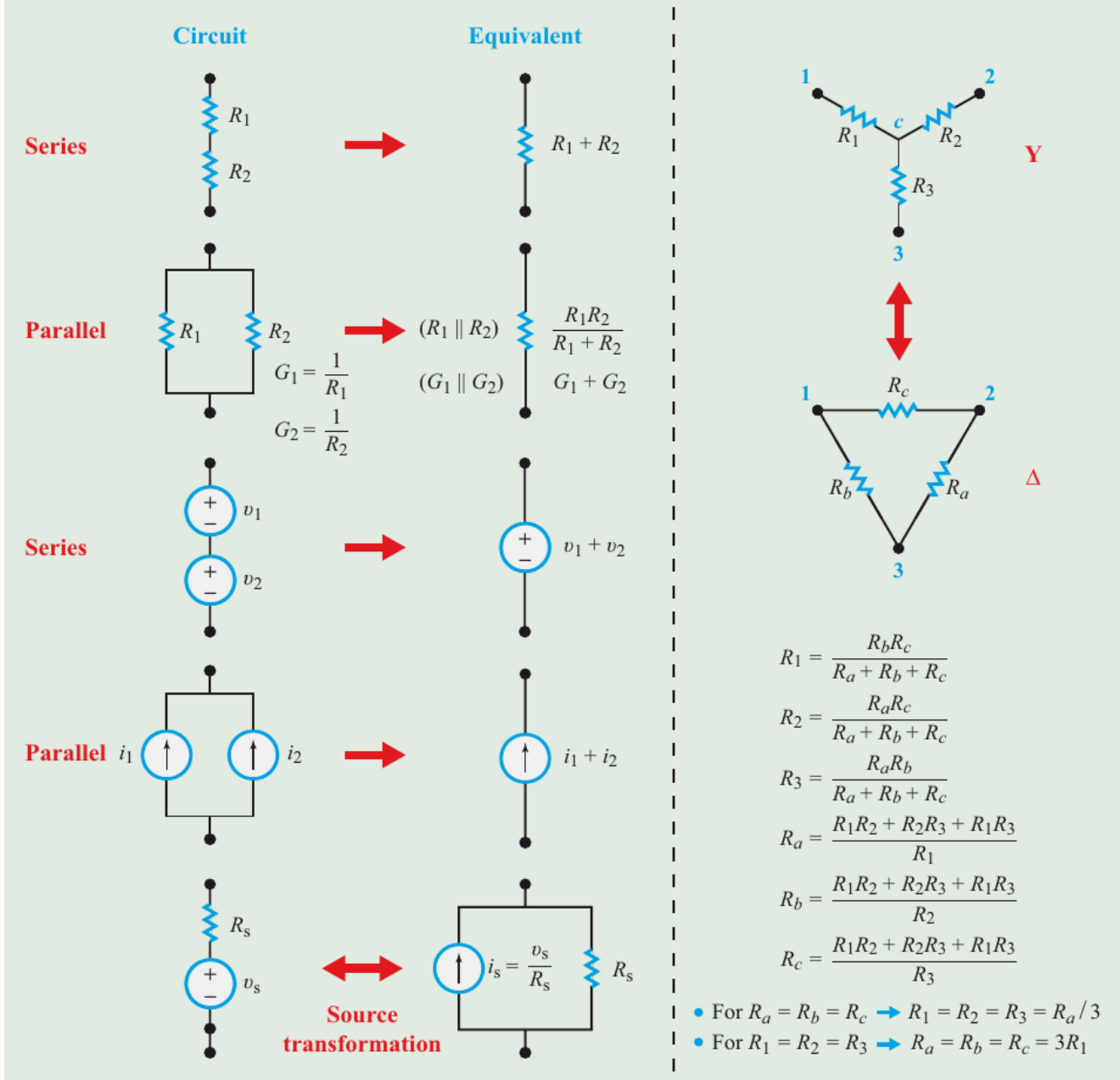


Table 2-5: Equivalent circuits.

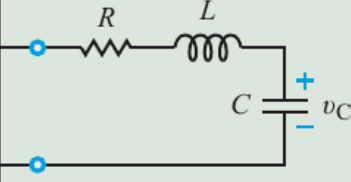
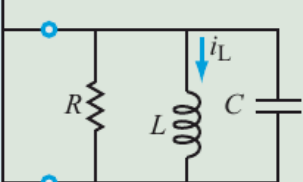


To Determine	Method	Can Circuit Contain Dependent Sources?	Relationship
v_{Th}	Open-circuit v	Yes	$v_{Th} = v_{oc}$
v_{Th}	Short-circuit i (if R_{Th} is known)	Yes	$v_{Th} = R_{Th} i_{sc}$
R_{Th}	Open/short	Yes	$R_{Th} = v_{oc} / i_{sc}$
R_{Th}	Equivalent R	No	$R_{Th} = R_{eq}$
R_{Th}	External source	Yes	$R_{Th} = v_{ex} / i_{ex}$
$i_N = v_{Th} / R_{Th}; R_N = R_{Th}$			


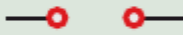
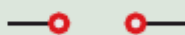

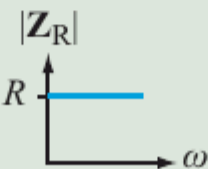

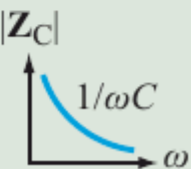
$$\frac{R_{Th}^2}{4V_{Th}} = P_{max}$$

Method	Common Use
Ohm's law	Relates V , I , R . Used with all other methods to convert $V \Leftrightarrow I$.
R , G in series and \parallel	Combine to simplify circuits. R in series adds, and is most often used. G in \parallel adds, so may be used when much of the circuit is in parallel.
Y- Δ or Π -T	Convert resistive networks that are not in series or in \parallel into forms that can often be combined in series or in \parallel . Also simplifies analysis of bridge circuits.
Voltage/current dividers	Common circuit configurations used for many applications, as well as handy analysis tools. Dividers can also be used as combiners when used "backwards."
Kirchhoff's laws (KVL/KCL)	Solve for branch currents. Often used to derive other methods.
Node-voltage method	Solves for node voltages. Probably the most commonly used method because (1) node voltages are easy to measure, and (2) there are usually fewer nodes than branches and therefore fewer unknowns (smaller matrix) than KVL/KCL.
Mesh-current method	Solves for mesh currents. Fewer unknowns than KVL/KCL, approximately the same number of unknowns as node voltage method. Less commonly used, because mesh currents seem less intuitive, but useful when combining additional blocks in cascade.
Node-voltage by-inspection method	Quick, simplified way of analyzing circuits. Very commonly used for quick analysis in practice. Limited to circuits containing only independent current sources.
Mesh-current by-inspection method	Quick, simplified way of analyzing circuits. Very commonly used for quick analysis in practice. Limited to circuits containing only independent voltage sources.
Superposition	Simplifies circuits with multiple sources. Commonly used for both calculation and measurement.
Source transformation	Simplifies circuits with multiple sources. Commonly used for both calculation/design and measurement/test applications.
Thévenin and Norton equivalents	Very often used to simplify circuits in both calculation and measurement applications. Also used to analyze cascaded systems. Thévenin is the more commonly used form, but Norton is often handy for analyzing parallel circuits. Source transformation allows easy conversion between Thévenin and Norton.
Input/output resistance (R_{in}/R_{out})	Commonly used to evaluate when cascaded circuits can be analyzed individually or when full circuit analysis or a buffer is needed.

Table 6-1: Step response of RLC circuits for $t \geq 0$.

<p style="text-align: center;">Series RLC</p> <div style="border: 1px solid black; padding: 5px; width: fit-content;"> <p>Input: dc circuit with switch action at $t = 0$</p> </div> 	<p style="text-align: center;">Parallel RLC</p> <div style="border: 1px solid black; padding: 5px; width: fit-content;"> <p>Input: dc circuit with switch action at $t = 0$</p> </div> 
Total Response	Total Response
<p>Overdamped ($\alpha > \omega_0$)</p> $v_C(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} + v_C(\infty)$ $A_1 = \frac{\frac{1}{C} i_C(0) - s_2 [v_C(0) - v_C(\infty)]}{s_1 - s_2}$ $A_2 = \frac{\frac{1}{C} i_C(0) - s_1 [v_C(0) - v_C(\infty)]}{s_2 - s_1}$	<p>Overdamped ($\alpha > \omega_0$)</p> $i_L(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} + i_L(\infty)$ $A_1 = \frac{\frac{1}{L} v_L(0) - s_2 [i_L(0) - i_L(\infty)]}{s_1 - s_2}$ $A_2 = \frac{\frac{1}{L} v_L(0) - s_1 [i_L(0) - i_L(\infty)]}{s_2 - s_1}$
<p>Critically Damped ($\alpha = \omega_0$)</p> $v_C(t) = (B_1 + B_2 t) e^{-\alpha t} + v_C(\infty)$ $B_1 = v_C(0) - v_C(\infty)$ $B_2 = \frac{1}{C} i_C(0) + \alpha [v_C(0) - v_C(\infty)]$	<p>Critically Damped ($\alpha = \omega_0$)</p> $i_L(t) = (B_1 + B_2 t) e^{-\alpha t} + i_L(\infty)$ $B_1 = i_L(0) - i_L(\infty)$ $B_2 = \frac{1}{L} v_L(0) + \alpha [i_L(0) - i_L(\infty)]$
<p>Underdamped ($\alpha < \omega_0$)</p> $v_C(t) = e^{-\alpha t} (D_1 \cos \omega_d t + D_2 \sin \omega_d t) + v_C(\infty)$ $D_1 = v_C(0) - v_C(\infty)$ $D_2 = \frac{\frac{1}{C} i_C(0) + \alpha [v_C(0) - v_C(\infty)]}{\omega_d}$	<p>Underdamped ($\alpha < \omega_0$)</p> $i_L(t) = e^{-\alpha t} (D_1 \cos \omega_d t + D_2 \sin \omega_d t) + i_L(\infty)$ $D_1 = i_L(0) - i_L(\infty)$ $D_2 = \frac{\frac{1}{L} v_L(0) + \alpha [i_L(0) - i_L(\infty)]}{\omega_d}$
<p style="text-align: center;">Auxiliary Relations</p> <div style="display: flex; justify-content: space-between;"> <div style="width: 45%;"> $\alpha = \begin{cases} \frac{R}{2L} & \text{Series RLC} \\ \frac{1}{2RC} & \text{Parallel RLC} \end{cases}$ $s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}$ </div> <div style="width: 45%;"> $\omega_0 = \frac{1}{\sqrt{LC}}$ $\omega_d = \sqrt{\omega_0^2 - \alpha^2}$ $s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$ </div> </div>	

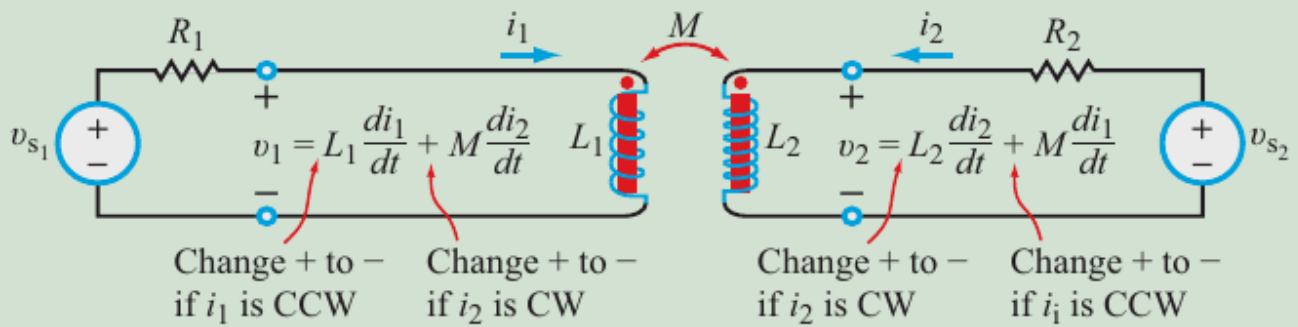
$x(t)$		\mathbf{X}
$A \cos \omega t$	\longleftrightarrow	A
$A \cos(\omega t + \phi)$	\longleftrightarrow	$Ae^{j\phi}$
$-A \cos(\omega t + \phi)$	\longleftrightarrow	$Ae^{j(\phi \pm \pi)}$
$A \sin \omega t$	\longleftrightarrow	$Ae^{-j\pi/2} = -jA$
$A \sin(\omega t + \phi)$	\longleftrightarrow	$Ae^{j(\phi - \pi/2)}$
$-A \sin(\omega t + \phi)$	\longleftrightarrow	$Ae^{j(\phi + \pi/2)}$
$\frac{d}{dt}(x(t))$	\longleftrightarrow	$j\omega \mathbf{X}$
$\frac{d}{dt}[A \cos(\omega t + \phi)]$	\longleftrightarrow	$j\omega Ae^{j\phi}$
$\int x(t) dt$	\longleftrightarrow	$\frac{1}{j\omega} \mathbf{X}$
$\int A \cos(\omega t + \phi) dt$	\longleftrightarrow	$\frac{1}{j\omega} Ae^{j\phi}$

Property	R	L	C
$v-i$	$v = Ri$	$v = L \frac{di}{dt}$	$i = C \frac{dv}{dt}$
$\mathbf{V-I}$	$\mathbf{V} = R\mathbf{I}$	$\mathbf{V} = j\omega L\mathbf{I}$	$\mathbf{V} = \frac{\mathbf{I}}{j\omega C}$
\mathbf{Z}	R	$j\omega L$	$\frac{1}{j\omega C}$
dc equivalent	R	 Short circuit	 Open circuit
High-frequency equivalent	R	 Open circuit	 Short circuit
Frequency response			

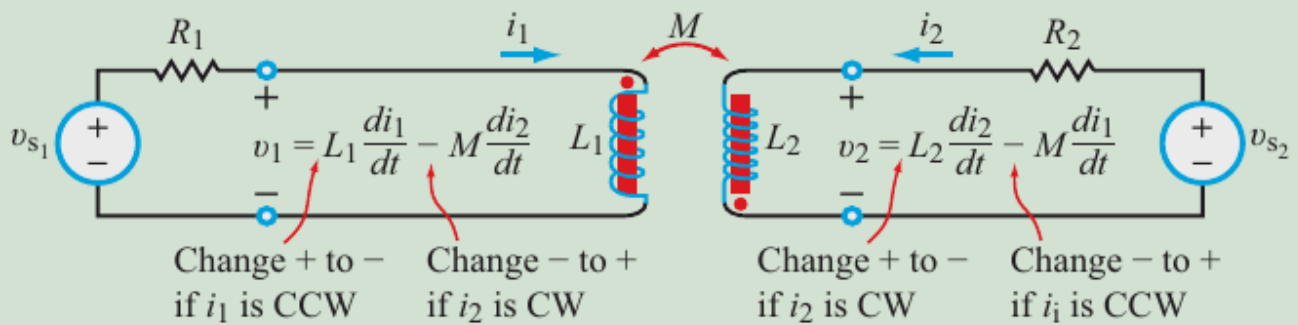
Time Domain		Phasor Domain
<p> $v(t) = V_m \cos(\omega t + \phi_v)$ $i(t) = I_m \cos(\omega t + \phi_i)$ $V_{rms} = V_m / \sqrt{2}$ $I_{rms} = I_m / \sqrt{2}$ </p>	\longleftrightarrow	<p> $\mathbf{V} = V_m e^{j\phi_v}$ $\mathbf{I} = I_m e^{j\phi_i}$ $\mathbf{V}_{rms} = V_{rms} e^{j\phi_v}$ $\mathbf{I}_{rms} = I_{rms} e^{j\phi_i}$ </p>
<h3>Complex Power</h3> $\mathbf{S} = \frac{1}{2} \mathbf{V} \mathbf{I}^* = \mathbf{V}_{rms} \mathbf{I}_{rms}^* = P_{av} + jQ$		
Real Average Power $P_{av} = \Re \{ \mathbf{S} \}$ $= V_{rms} I_{rms} \cos(\phi_v - \phi_i)$ $= I_{rms}^2 R = V_{rms}^2 R / Z ^2$		Reactive Power $Q = \Im \{ \mathbf{S} \}$ $= V_{rms} I_{rms} \sin(\phi_v - \phi_i)$ $= I_{rms}^2 X = V_{rms}^2 X / Z ^2$
Apparent Power $S = \mathbf{S} = \sqrt{P_{av}^2 + Q^2}$ $= V_{rms} I_{rms}$ $= I_{rms}^2 Z = V_{rms}^2 / Z $	$\mathbf{S} = S e^{j(\phi_v - \phi_i)} = S e^{j\phi_z}$ $\phi_z = \phi_v - \phi_i$	Power Factor $pf = \frac{P_{av}}{S}$ $= \cos(\phi_v - \phi_i)$ $= \cos \phi_z$

Factor	Bode Magnitude	Bode Phase
Constant K	$20 \log K$ 0 dB	$\pm 180^\circ$ if $K < 0$ 0° if $K > 0$
Zero @ Origin $(j\omega)^N$	0 dB 1 $\text{slope} = 20N \text{ dB/decade}$	$(90N)^\circ$ 0°
Pole @ Origin $(j\omega)^{-N}$	0 dB 1 $\text{slope} = -20N \text{ dB/decade}$	$(-90N)^\circ$ 0°
Simple Zero $(1 + j\omega/\omega_c)^N$	0 dB ω_c $\text{slope} = 20N \text{ dB/decade}$	$(90N)^\circ$ 0° $0.1\omega_c$ ω_c $10\omega_c$
Simple Pole $\left(\frac{1}{1 + j\omega/\omega_c} \right)^N$	0 dB ω_c $\text{slope} = -20N \text{ dB/decade}$	$(-90N)^\circ$ 0° $0.1\omega_c$ ω_c $10\omega_c$
Quadratic Zero $[1 + j2\zeta\omega/\omega_c + (j\omega/\omega_c)^2]^N$	0 dB ω_c $\text{slope} = 40N \text{ dB/decade}$	$(180N)^\circ$ 0° $0.1\omega_c$ ω_c $10\omega_c$
Quadratic Pole $\frac{1}{[1 + j2\zeta\omega/\omega_c + (j\omega/\omega_c)^2]^N}$	0 dB ω_c $\text{slope} = -40N \text{ dB/decade}$	$(-180N)^\circ$ 0° $0.1\omega_c$ ω_c $10\omega_c$

Magnetic Coupling



(a) Dots on same ends

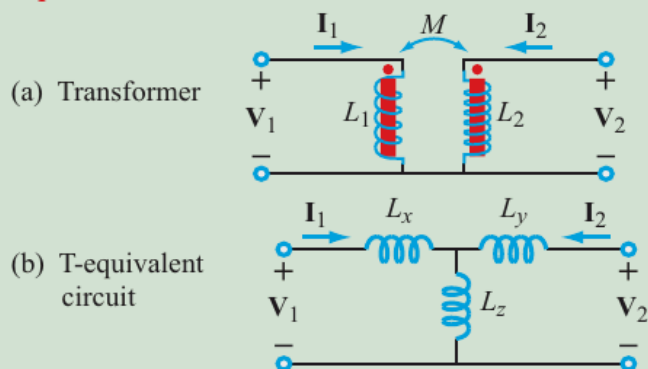


(b) Dots on opposite ends

$$k = \frac{M}{\sqrt{L_1 L_2}}$$

Mathematical and Physical Models (continued)

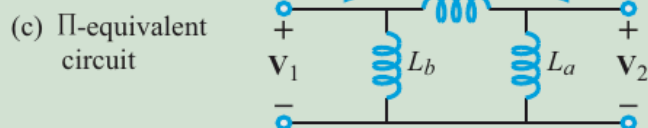
Equivalent Circuits



$$L_x = L_1 - M$$

$$L_y = L_2 - M$$

$$L_z = M$$



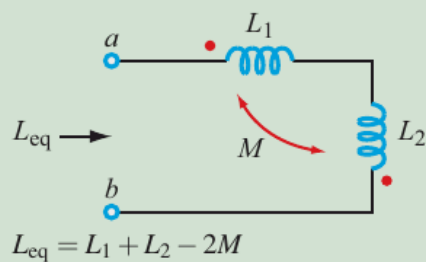
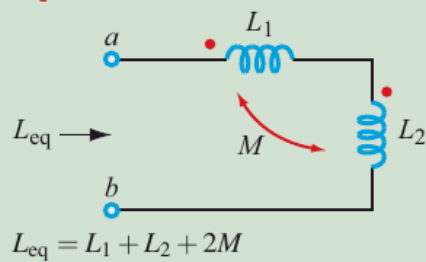
$$L_a = \frac{L_1 L_2 - M^2}{L_1 - M}$$

$$L_b = \frac{L_1 L_2 - M^2}{L_2 - M}$$

$$L_c = \frac{L_1 L_2 - M^2}{M}$$

Replace M with $-M$ if dots are on opposite ends.

Equivalent Inductance



Ideal Transformer

$$\frac{V_2}{V_1} = n$$

$$\frac{I_2}{I_1} = \frac{1}{n}$$

$$Z_{in} = \frac{V_1}{I_1} = \frac{1}{n^2} \frac{V_2}{I_2} = \frac{Z_L}{n^2}$$