

Hochschild 2-cocycles as the space of infinitesimal deformations

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July 21, 2020

1 Introduction

This note explores the relationship between Hochschild cohomology and the theory of deformation of algebras. We explore ideas showing how you can draw a one-to-one correspondence between equivalent classes of infinitesimal deformations and Hochschild 2-cocycles. These ideas can be found in several literatures such as [1, 2]. The definition of an infinitesimal deformation is given as Definition 18 with reference to Definition 7 and the main theorem is Theorem 19. This note is NOT self contained. Feel free to contact/email me if you have any questions or if you find any typos!

2 Preliminaries

Let k be a field of characteristics 0 and R a ring with unit 1_R . By a ring, we mean a commutative associative k -algebra. We take $\otimes = \otimes_k$ unless otherwise specified.

Definition 1. Let R be a ring with unit and $s : k \rightarrow R$, a homomorphism with $s(1) = 1_R$. A map $\epsilon : R \rightarrow k$ is an augmentation of R if $\epsilon s = 1_k$.

Examples

1. The ring $R = k[[t]]$ of formal power series with coefficients in k is augmented with $\epsilon : R \rightarrow k$ given by $\sum_i r_i t^i \mapsto r_0$.
2. Let A be an algebra, and let $R = A[[t]]$ be the ring of formal power series with coefficients in A . R is augmented with $\epsilon : R \rightarrow k$ given by $\sum_i a_i t^i \mapsto a_0$.
3. The group ring $k[G]$ of a finite group G is the space of all formal linear combination $\sum_{g \in G} a_g g$, $a_g \in k$ with multiplication

$$\left(\sum_{g \in G} a_g g\right) \left(\sum_{g \in G} b_g g\right) = \sum_{g \in G} \sum_{xy=g} a_x b_y g.$$

$k[G]$ is augmented with $\epsilon : k[G] \rightarrow k$ given by $\sum_{g \in G} a_g g \mapsto \sum_{g \in G} a_g$.

Remark 2. The subspace $\text{Ker}(\epsilon)$ is a two sided ideal of R called the augmentation ideal.

Observe that k is an R bimodule with the structure induced by ϵ . Since R an associative k -algebra, R is automatically a k -module. We will now discuss how to pass from k -modules to R -modules and vice versa.

Definition 3. Let V be a k -vector space and R a unital ring (or a k -algebra). The free R -module generated by V is an R -module $R\langle V \rangle$ together with a k -linear map $\iota : V \rightarrow R\langle V \rangle$ with the property that for every R -module and module homomorphism $V \xrightarrow{f} W$ there exists a module homomorphism $R\langle V \rangle \xrightarrow{\phi} W$ for which

the following diagram commutes.

$$\begin{array}{ccc} V & \xrightarrow{\iota} & R\langle V \rangle \\ & \searrow f & \downarrow \psi \\ & & W \end{array}$$

Remark 4. This universal property determines the free module $R\langle V \rangle$ uniquely up to isomorphism. A concrete model which will later be used is the module $R\langle V \rangle = R \otimes V$.

The above describes how we pass from a k -vector space V to an R -module $R\langle V \rangle$ (with model in mind being $R \otimes V$). How then do we pass from an R -module to a vector space over k .

Definition 5. Let W be an R -module. The reduction of W is the k -module $\overline{W} := k \otimes_R W$, with a k -action given by

$$t(t' \otimes w) = tt' \otimes w \quad \text{for all } t, t' \in k, w \in W$$

It is clear that there are k -module isomorphisms $\overline{W} \cong W/\overline{R}W$ and $\overline{R\langle V \rangle} \cong V$. This reduction clearly defines a functor from the category of R -modules to the category of k -modules. Note that for the R -module R , the reduction $\overline{R} := k \otimes_R R \cong k$. Let the map $W \rightarrow \overline{W}$ be defined by $rx \mapsto \bar{r} \otimes x$. Since this tensor product is taken over R we realize that $\bar{r} \otimes x = 1 \otimes \bar{r}x$, so the kernel of this map is the set $\overline{R}W := \{\bar{r}w \mid r \in R, w \in W\}$. Notice that for any $\lambda \in k$, $s(\lambda) \in R$, so $\lambda \otimes w \mapsto s(\lambda)w$ implies the surjectivity of the map $W \rightarrow \overline{W}$. The first isomorphism theorem implies that $\overline{W} \cong W/\overline{R}W$. It is also straight forward to see that $\overline{R\langle V \rangle} \cong \overline{R} \otimes \overline{V} \cong \overline{R} \otimes V \cong k \otimes_k V \cong V$.

Proposition 6. If B is an associative R -algebra, then the reduction \overline{B} is a k -algebra with the structure induced by the algebra structure on B .

Proof. \overline{B} by definition is a k -algebra. Since $\overline{B} \cong B/\overline{R}B$, it is enough to show that $\overline{R}B$ is a two sided ideal of B , so it inherits the algebra structure on B . For any $r \in \overline{R}, b, b_1 \in B$, the multiplication $(rb, b_1) = r(b, b_1)$ showing that $(\overline{R}B, B) \subseteq \overline{R}B$. \square

3 Deformation theory

We now delve into the classical definition of deformation theory and how this connects with Hochschild 2-cocycles.

Definition 7. Let A be an associative k -algebra and R an augmental unital ring. An R -deformation of A is an associative R -algebra B and a module homomorphism ϕ such that $\phi : \overline{B} \rightarrow A$ is an isomorphism of k -algebras.

The following is a pictorial representation of the information given in Definition 7.

$$\begin{array}{ccc}
 A & \xrightarrow[\text{passing to}]{} & R\langle A \rangle (\text{e.g. } \cong R \otimes A) \\
 \uparrow \phi \text{ (isomorphism)} & & \downarrow \text{deformation problem} \\
 \overline{B} & \xleftarrow[\text{reduction module}]{} & B
 \end{array}$$

We denote a deformation of the algebra A by the pair $(B, \overline{B} \xrightarrow{\phi} A)$. There is a notion of equivalence classes of deformations of an algebra A . Two R -deformations of an algebra A given by $(B_1, \overline{B}_1 \xrightarrow{\phi_1} A)$ and $(B_2, \overline{B}_2 \xrightarrow{\phi_2} A)$ are equivalent if there is a map $w : B_1 \rightarrow B_2$ such that $w = (\phi_2)^{-1}\phi_1$.

Remark 8.

- In the foregoing, we assume that $R\langle A \rangle$ of the above diagram is $R \otimes A$ and is isomorphic to B as an R -module.
- The isomorphism $B \cong R \otimes A$ identifies A with the submodule $1 \otimes A$ of B and $A \otimes A$ with the submodule $(1 \otimes A) \otimes (1 \otimes A)$ of $B \otimes B$.

Lemma 9. For an R -deformation $(B, \overline{B} \xrightarrow{\phi} A)$ the multiplication ϕ in B is determined by its restriction to $A \otimes A \subset B \otimes B$. Every deformation $w : B \rightarrow B'$ that is equivalent to ϕ is determined by its restriction to $A \subset B$.

Proof. Using the fact that $B \cong R \otimes A$, each element of B is a finite sum of elements of the form $ra, r \in R, a \in A$. Since $\phi : \overline{B} \rightarrow A$, is an isomorphism of k -algebras, for all $\lambda_i \in k, x, y \in \overline{B}$, k -bilinearity of ϕ as a map on \overline{B} implies that $\phi(\lambda_1 x, \lambda_2 y) = \lambda_1 \lambda_2 \phi(x, y)$. Now suppose $x = ra_1, y = sa_2, r, s \in R, a_1, a_2 \in A$, R -bilinearity of ϕ as a multiplicative map $B \times B \rightarrow B$, implies that $\phi(x, y) = \phi(ra_1, sa_2) = rs\phi(a_1, a_2)$, showing that with the multiplication $\phi(a_1, a_2)$ in $A \otimes A$, we can determine the multiplication of ϕ in B . The equivalence of w and ϕ implies there is a deformation $(B', \overline{B'} \xrightarrow{\phi'} A)$ such that $w = (\phi')^{-1}\phi$. Since the multiplication of ϕ and ϕ' in B are determined by their restriction to $A \otimes A$, w is determined by its restriction to $A \otimes A$. \square

4 Formal and Infinitesimal deformations

Definition 10. By a formal deformation, we mean a deformation in the sense of Definition 7 over the complete local augmented ring $R = k[[t]]$.

Notice that in this case if $(A_t, \overline{A_t} \xrightarrow{\mu} A)$ is a formal deformation of A , then we identify the reduction of A_t $\overline{A_t}$ with $A \otimes A_t$ so that according to Lemma 9 the multiplication of μ in A_t is determined by its restriction to $A \otimes A$. All such formal deformation are given by the map $\mu : A \otimes A \rightarrow A$ satisfying certain conditions.

Theorem 11. A formal deformation A_t of a k -algebra A is given by the family

$$\{\mu_i : A \otimes A \rightarrow A \mid i \in \mathbb{N}\}$$

such that $\mu_0(a, b) = ab$ (the multiplication on A) and

$$(D_k) \quad \sum_{\substack{i+j=k \\ i,j \geq 0}} \mu_i(\mu_j(a, b), c) = \sum_{\substack{i+j=k \\ i,j \geq 0}} \mu_i(a, \mu_j(b, c))$$

for all $a, b, c \in A$ and $k \geq 1$.

Proof. By Lemma 9, the multiplication of μ_t is determined by its restriction to $A \otimes A$. For $a, b \in A$, expanding $\mu(a, b)$ into the power series

$$\mu(a, b) = \mu_0(a, b) + t\mu_1(a, b) + t^2\mu_2(a, b) + \dots \quad (12)$$

for some k -bilinear functions μ_i . It is obvious that μ_0 corresponds with multiplication in A . It is also verifiable that μ is associative if and only if (D_k) are satisfied for each $k \geq 1$. \square

Remark 13. We observe that by taking $\mu_0(a, b) = 0$, the associativity of μ implies the associativity in A (that is D_0) and (D_1) means that

$$a\mu_1(b, c) - \mu_1(ab, c) + \mu_1(a, bc) - \mu_1(a, b)c = 0 \quad (14)$$

Hochschild cohomology: For a k -algebra A , Hochschild cohomology was originally defined using the following projective resolution known as the bar resolution.

$$B(A)_\bullet := \dots \rightarrow A^{\otimes(n+2)} \xrightarrow{\delta_n} A^{\otimes(n+1)} \xrightarrow{\delta_{n-1}} \dots \xrightarrow{\delta_2} A^{\otimes 3} \xrightarrow{\delta_1} A^{\otimes 2} (\rightarrow A) \quad (15)$$

where the differentials δ_i are given by

$$\delta_n(a_0 \otimes a_1 \otimes \dots \otimes a_{n+1}) = \sum_{i=0}^n (-1)^i a_0 \otimes \dots \otimes a_i a_{i+1} \otimes \dots \otimes a_{n+1}$$

for each element $a_i \in A$, for all $i = 0, 1, 2, \dots, n+1$. Let $f \in \text{Hom}_{A^e}(A^{m+2}, A) \cong \text{Hom}_k(A^{\otimes m}, A)$, satisfying $\delta^* f = 0$, where $\delta^* f(a_0 \otimes a_1 \otimes \dots \otimes a_{m+2}) = f(\delta(a_0 \otimes a_1 \otimes \dots \otimes a_{m+2}))$.

Definition 16. An Hochschild 2-cocycle is a map $f : A \otimes A \rightarrow A$, (which can also be viewed as a module homomorphism $f \in \text{Hom}_{A^e}(A^4, A)$) satisfying $\delta^* f(1 \otimes a \otimes b \otimes c \otimes 1) = 0$. This means that

$$\begin{aligned} fd(1 \otimes a \otimes b \otimes c \otimes 1) &= f(a \otimes b \otimes c \otimes 1) - f(1 \otimes ab \otimes c \otimes 1) \\ &+ f(1 \otimes a \otimes bc \otimes 1) - f(1 \otimes a \otimes b \otimes c) = 0 \\ &\text{which is equivalent to} \\ af(b \otimes c) - f(ab \otimes c) + f(a \otimes bc) - f(a \otimes b)c &= 0. \end{aligned} \quad (17)$$

Definition 18. By an infinitesimal deformation, we mean a deformation in the sense of Definition 7 over the complete local augmented ring $R = k[[t]]/(t^2)$.

Theorem 19. There is a one-to-one correspondence between the space of equivalence classes of infinitesimal deformations of A and the space of Hochschild 2-cocycles of A with coefficients in A .

Proof. By an infinitesimal deformation, the multiplication $*$ in B reduces to

$$a * b = \mu_0(a, b) + t\mu_1(a, b) = ab + t\mu_1(a, b).$$

Then associativity of $*$ implies Equation 14, that is

$$a\mu_1(b, c) - \mu_1(ab, c) + \mu_1(a, bc) - \mu_1(a, b)c = 0$$

where $\mu_0(a, b) = ab$. Comparing this with Equation (17), we realize that μ_1 is a Hochschild 2-cocycle with $\mu_1(x, y) = \mu_1(x \otimes y)$.

Now suppose that $(B, \overline{B} \xrightarrow{*} A)$ and $(B', \overline{B'} \xrightarrow{\bar{*}} A)$ are two equivalent deformations. Lets associate Hochschild 2-cocycles $\mu_1, \bar{\mu}_1$ to each deformation $*$ and $\bar{*}$ and express for $a, b \in A$,

$$\begin{aligned} a * b &= ab + t\mu_1(a, b) \\ a\bar{*}b &= ab + t\bar{\mu}_1(a, b). \end{aligned} \tag{20}$$

By Lemma 9 every equivalence of deformations $w : B \rightarrow B'$ is determined by its restriction to A . In this case $w = (\bar{*}^{-1})(*)$, is determined by a k -linear map $w_1 : A \rightarrow A$ satisfying $w(a) = a + tw_1(a)$ for all $a \in A$. w is invertible and satisfies

$$w(a * b) = w(a)\bar{*}w(b) \tag{21}$$

Substituting Equation (20) into (21), we obtain

$$\begin{aligned} w(ab + t\mu_1(a, b)) &= (a + tw_1(a))\bar{*}(b + tw_1(b)) \\ ab + t\mu_1(a, b) + tw_1(ab + t\mu_1(a, b)) &= (a + tw_1(a))(b + tw_1(b)) + t\bar{\mu}_1(a + tw_1(a), b + tw_1(b)) \\ ab + t\mu_1(a, b) + tw_1(ab) + t^2w_1\mu_1(a, b) &= ab + t[aw_1(b) + w_1(a)b] \\ &\quad + t[\bar{\mu}_1(a, b) + t\bar{\mu}_1(a, w_1(b)) + t\bar{\mu}_1(w_1(a), b) + t^2\bar{\mu}_1(w_1(a), w_1(b))] \end{aligned}$$

since $t^2 = 0$, we obtain

$$ab + t[\mu_1(a, b) + w_1(ab)] = ab + t[aw_1(b) + w_1(a)b + \bar{\mu}_1(a, b)]$$

showing that

$$\mu_1(a, b) - \bar{\mu}_1(a, b) = aw_1(b) - w_1(ab) + w_1(a)b = \delta^*w(a, b)$$

that is, the two infinitesimal deformations $\mu_1, \bar{\mu}_1$ are equivalent if and only if they differ by a coboundary. \square

References

- [1] M. DOUBEK, M. MARKL, P. ZIMA, *Deformation Theory (Lecture notes)*, arXiv:0705.3719.
- [2] S. WITHERSPOON, *Hochschild Cohomology for Algebras*, Graduate Studies in Mathematics, American Mathematical Society.