

Addressing Bias in Algorithmic Solutions: Exploring Vertex Cover and Feedback Vertex Set

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What is Parameterised Complexity

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What do we know about NP-COMPLETENESS

For NP-COMplete problems, in general instances, one does not **expect** exact deterministic algorithms which run in polynomial time.

↓
approximation

→ Randomisation

Parameter
↓
V.E.

Exact Expon.
 $(1.6)^n \leftarrow 2^n$
 $(\sqrt{n})^n \leftarrow 10^n$

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Parameterised Complexity deals with algorithms which run efficiently for some instances.

FIXED-PARAMETER TRACTABLE

$$n, k \quad |n.c.| \leq k$$

Definition of a parameterised problem

A *parameterised problem* is a language $L \subseteq \Sigma^* \times \mathbb{N}$, where Σ is a fixed, finite alphabet. For an instance $(x, k) \in \Sigma^* \times \mathbb{N}$, k is called the *parameter*.

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FIXED-PARAMETER TRACTABLE

A parameterised problem $L \subseteq \Sigma^* \times \mathbb{N}$ is called *fixed-parameter tractable* (FPT) if there exists an algorithm \mathcal{A} (called a *fixed-parameter algorithm*), a computable function $f : \mathbb{N} \rightarrow \mathbb{N}$, and a constant c such that, given $(x, k) \in \Sigma^* \times \mathbb{N}$, the algorithm \mathcal{A} correctly decides whether $(x, k) \in L$ in time bounded by $f(k) \cdot |(x, k)|^c$. The complexity class containing all fixed-parameter tractable problems is called FPT.

Π G n k $\Pi \in \text{FPT}$ $f(n) \leq n^c$ $n^c \times f(k)$

$$t \quad \underline{[t] := \{1, 2, \dots, t\}}$$

Let t be constant positive integer. We will refer to members of $\{1, 2, \dots, t\}$ as colours. A graph G is said to be t -coloured if there exists a function $c : V(G) \rightarrow 2^{\{1, 2, \dots, t\}} \setminus \emptyset$. Given a t -tuple of non-negative integers, $\mathbb{T} = (k_i)_{i=1}^t$, a set $S \subseteq V(G)$ is said to be \mathbb{T} -fair if for each $i \in [t]$, we have $|\{v \in S \mid i \in c(v)\}| = k_i$.

$$\begin{matrix} 2 & 3, 4 \\ \bullet & \bullet \\ & \bullet \end{matrix}$$

$$\mathbb{T} = (k_1, k_2, \dots, k_t)$$

$$S = \underbrace{\{v_1, v_2, \dots, v_{10}\}}_{k_1, \quad k_2}$$

\mathbb{T} -FAIR PROBLEMS(CONTD.)

We will discuss the following problems

\mathbb{T} -FAIR VERTEX COVER

Input: An undirected t -coloured graph $G = (V, E)$ and t -tuple of integers, $\mathbb{T} = (k_i)_{i=1}^t$.

Parameter: $\sum_{i=1}^t k_i$.

Question: Does G have a \mathbb{T} -fair vertex cover?

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Kernelisation

$$\Pi. (I, k) \xrightarrow{\mathcal{A}} (I', k') \in \text{kernel}$$

A *kernelisation algorithm* for a parameterised problem Π is a deterministic algorithm \mathcal{A} that, given an instance (I, k) of Π , works in polynomial time and returns an equivalent instance (I', k') , such that $|I'| + k' \leq g(k)$, where $g : \mathbb{N} \rightarrow \mathbb{N}$ is a computable function. The instance (I', k') is called a *kernel*.

\mathcal{A} in $n^{O(1)}$ time

FPT $|I'| + k' \leq \underbrace{g(k)}_{T(k)}$

$$n^{O(1)} + T(k) \leq \underline{\underline{n^{O(1)} \cdot T(k)}}$$

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Kernelisation

$$\Pi \longrightarrow \underline{g(k)}$$

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Theorem

A problem Π is in FPT if and only if it admits a kernelisation algorithm.

Hint

$$\text{in } \underline{g(k)}$$

\mathcal{A}

$$n^{L+1}$$

Polynomial Kernel for \mathbb{T} -FAIR VERTEX COVER

We apply the following rules once at the beginning.

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- If $|\{v \in V(G) | c(i) \in v\}| < k_i$ holds for at least one $i \in [t]$ then return No.

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$\sum k_i 2^t$

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- Let $k_{\max} = \max_{1 \leq i \leq t} k_i$. For each non-empty $X \subseteq [t]$, $V_X = \{v \in V(G) | \deg(v) = 0 \wedge \underline{c}(v) = X\}$. If $|V_X| > k_{\max}$, then keep any k_{\max} of them and remove the rest from V_X . Finally, let $I^* = \bigcup_{X \subseteq [t] \wedge X \neq \emptyset} V_X$.

$$|I^*| \leq k_{\max} 2^t \leq \sum k_i 2^t$$

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We then apply the following rules in order, until they can't be applied any more.

Polynomial Kernel for \mathbb{T} -FAIR VERTEX COVER(contd.)

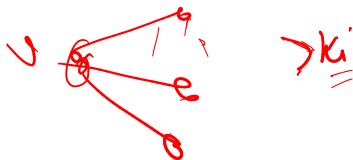
- $\exists (i, j) \in [t] \times [t]$, such that (i) $k_i = k_j = 0$ and (ii) $\exists uv \in E(G)$, such that $i \in c(u) \wedge j \in c(v)$. Return No.

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- $\exists v \in V(G)$, such that for some $i \in [t]$, $|\{w \in N(v) \mid i \in c(w)\}| > k_i$, then return $(G - v, c', k')$, where c' is the restriction of c on $V(G) \setminus \{v\}$ and for each $i \in [t]$, $k'_i = k_i - |\{w \in \{v\} \mid i \in c(w)\}|$.



Polynomial Kernel for \mathbb{T} -FAIR VERTEX COVER(contd.)

- $\exists (i, j) \in [t] \times [t]$, such that (i) $k_i = k_j = 0$ and (ii) $\exists uv \in E(G)$, such that $i \in c(u) \wedge j \in c(v)$. Return No.
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- $\exists v \in V(G)$, such that for some $i \in [t]$, $|\{w \in N(v) | i \in c(w)\}| > k_i$, then return $(G - v, c', k'_i)$, where c' is the restriction of c on $V(G) \setminus \{v\}$ and for each $i \in [t]$, $k'_i = k_i - |\{w \in \{v\} | i \in c(w)\}|$.

Return a kernel

If none of the above rules are applicable, then return No, if $|V(G)| \geq (\sum_{i=1}^t k_i)^2 + \sum_{i=1}^t k_i \times (1 + 2^t)$ or $|E(G)| \geq (\sum_{i=1}^t k_i)^2$. Otherwise, we return the instance (G, c, \mathbb{T}) .

$|F| = n$
 $\nrightarrow \dots$
 $|V(G - F)| \leq K |F|$
 $|V(G)| \leq n^2 + n$
 $|E(G)| \leq n^2$

Tree Decomposition of a Graph

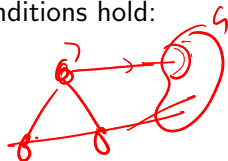
Given a graph, its *treewidth* is a measure of how “tree-like” it is. Forests have treewidth 1, whereas cycles have treewidth 2.

$n-1$

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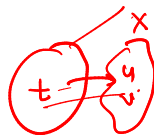
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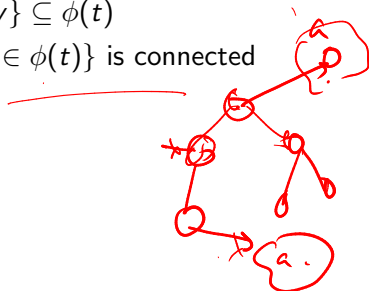


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node

sub

For any $t \in V(T)$, $\phi(t)$ is called the bag of the node t . The width of tree decomposition (T, ϕ) equals $\max_{t \in V(T)} |\phi(t)| - 1$, that is, the maximum size of its bag minus 1. The treewidth of a graph G , denoted by $tw(G)$, is the minimum possible width of a tree decomposition of G .

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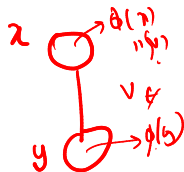
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 - **Introduce vertex node:** This is a node x of T , with exactly one child y such that $\phi(x) = \phi(y) \cup \{v\}$ for some $v \notin \phi(y)$; we say that v is *introduced* at x .



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- **Forget node:** This is a node x of T , with exactly one child y such that $\phi(x) = \phi(y) \setminus \{v\}$ for some $v \in \phi(y)$; we say that v is *forgotten* at x .

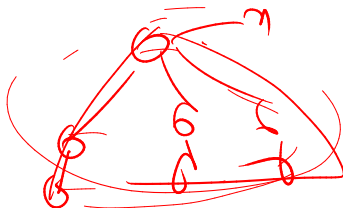


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For a node x of T , we define $G_x = (V_x, E_x)$ as follows:

- $V_x = \bigcup_{y \text{ is a descendant of } x} \phi(y)$
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If a graph G has a tree decomposition of width k , then it admits a nice tree decomposition of width at most k . Moreover, given a tree decomposition (T, ϕ) of width k , one can find a nice tree decomposition of width k , in time $O(k^2 \cdot \max(|V(T)|, |V(G)|))$ that has $O(k|V(G)|)$ nodes.

Revisit the problems

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Parameter: width of (T, ϕ)

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$t_w := \text{width of } (T, \phi).$

FAIR VERTEX COVER FOR GRAPHS WITH BOUNDED TREewidth

$$\pi = (k_i)_{i=1}^t$$

We will use dynamic programming to solve FAIR VERTEX COVER FOR GRAPHS WITH BOUNDED TREewidth.

For a node x of T , a subset S of $\phi(x)$, a t -tuple of integers $(r_i)_{i=1}^t$, where for each $i \in [t]$, $0 \leq r_i \leq k_i$, we define $I_x[S, (r_i)_{i=1}^t]$ as follows:

- $I_x[S, (r_i)_{i=1}^t] = 1$, if G_x has an $(r_i)_{i=1}^t$ -fair vertex cover which intersects $\phi(x)$ at S .
- $I_x[S, (r_i)_{i=1}^t] = 0$, otherwise

If all of the above entries are correctly evaluated, then G has \mathbb{T} -fair vertex cover if and only if $I_r[\emptyset, \mathbb{T}] = 1$.



FAIR VC FOR GRAPHS WITH BOUNDED TREewidth(CONTD.)



$$(r_i)_{i=1}^t = 0$$

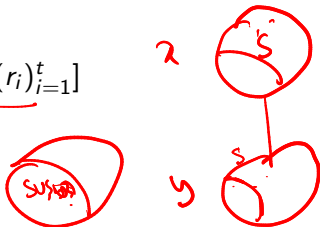
We will now compute the entries of DP table. For a node x of T , a subset S of $\phi(x)$, and a t -tuple of integers $(r_i)_{i=1}^t$, we determine the value of $I_x[S, (r_i)_{i=1}^t]$ as follows.

- x is a leaf node. If $\forall i \in [t], r_i = 0$, then $I_x[\emptyset, (r_i)_{i=1}^t] = 1$, otherwise $I_x[\emptyset, (r_i)_{i=1}^t] = 0$.

- x has a child y and forgets vertex v .

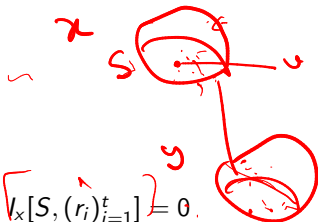
$$I_x[S, (r_i)_{i=1}^t] = I_y[S, (r_i)_{i=1}^t] \oplus I_y[S \cup \{v\}, (r_i)_{i=1}^t]$$

$T \subseteq U$



FAIR VC FOR GRAPHS WITH BOUNDED TREewidth(CONTD.)

$$I_x[S, (r_i)_{i=1}^t]$$



- x has a child y and introduces vertex v .
 - If $v \notin S$, $I_x[S, (r_i)_{i=1}^t] = I_y[S, (r_i)_{i=1}^t]$
 - $v \in S$ and for some $j \in c(v)$, $r_j = 0$, then $I_x[S, (r_i)_{i=1}^t] = 0$.
 - In all other cases, $I_x[S, (r_i)_{i=1}^t] = I_y[S \setminus \{v\}, (r'_i)_{i=1}^t]$, where for $i \in [t]$, $r'_i = |\{w \in \{v\} \mid i \in c(w)\}|$

$v \in S$

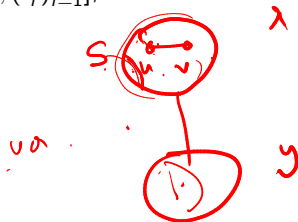
0

$$r'_i = r_i - 1$$

$$r'_i = \delta_i$$

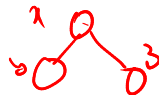
FAIR VC FOR GRAPHS WITH BOUNDED TREewidth(CONTD.)

- x has a child y and introduces vertex v .
 - If $v \notin S$, $I_x[S, (r_i)_{i=1}^t] = I_y[S, (r_i)_{i=1}^t]$
 - $v \in S$ and for some $j \in c(v)$, $r_j = 0$, then $I_x[S, (r_i)_{i=1}^t] = 0$
 - In all other cases, $I_x[S, (r_i)_{i=1}^t] = I_y[S \setminus \{v\}, (r'_i)_{i=1}^t]$, where for $i \in [t]$, $r'_i = |\{w \in \{v\} | i \in c(w)\}|$
- x has a child y and introduces edge uv .
 - $S \cap \{u, v\} = \emptyset$, then $I_x[S, (r_i)_{i=1}^t] = 0$
 - Otherwise, $I_x[S, (r_i)_{i=1}^t] = I_y[S, (r_i)_{i=1}^t]$



FAIR VC FOR GRAPHS WITH BOUNDED TREEWIDTH(CONTD.)

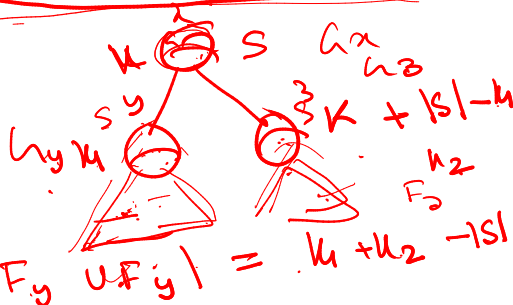
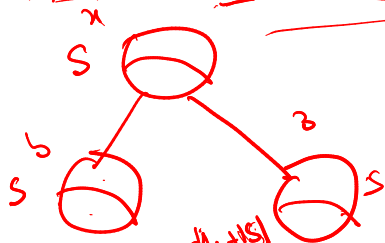
$$S \subseteq \phi(x)$$



If x is a join node with children y and z , we do as follows:

Consider all tuples $(a_i)_{i=1}^t$, such that $0 \leq a_i \leq r_i$. Evaluate the following.

$$I_x[S, (r_i)_{i=1}^t] \leftarrow I_x[S, (r_i)_{i=1}^t] \oplus (I_y[S, (a_i)_{i=1}^t] \odot I_z[S, (r_i)_{i=1}^t - |\{w \in S \mid i \in c(w)\}| - a_i]_{i=1}^t))$$



FAIR VC FOR GRAPHS WITH BOUNDED TREewidth(CONTD.)

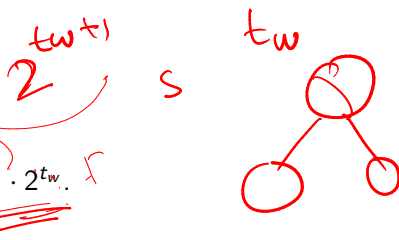
If x is a join node with children y and z , we do as follows:

Consider all tuples $(a_i)_{i=1}^t$, such that $0 \leq a_i \leq r_i$. Evaluate the following.

$$I_x[S, (r_i)_{i=1}^t] \leftarrow$$

$$(I_x[S, (r_i)_{i=1}^t] \oplus (I_y[S, (a_i)_{i=1}^t] \odot I_z[S, (r_i + |\{w \in S \mid i \in c(w)\}| - a_i)_{i=1}^t]))$$

The running time of the algorithm is $n^{O(1)} \cdot 2^{tw}$.



FPT ALGORITHM FOR FAIR VERTEX COVER



Let v be a vertex of degree 3 or more. Let H' be the graph obtained by deleting the vertex v from G , c' be the function obtained by restricting c to $V(H') = (V(G) \setminus \{v\})$, and let $\mathbb{T}' = \{k'_1, k'_2, \dots, k'_t\}$ where for each $i \in [t]$ we have $k'_i = k_i - |\{w \in \{v\} \mid i \in c(w)\}|$.

$$u_i = u_i - 1 \quad (G, c, \pi)$$

$$(G - v, c', \pi')$$

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Let H'' be the graph obtained by deleting the open neighbourhood $N(v)$ from G , let c'' be the function obtained by restricting c to $V(H'') = (V(G) \setminus N(v))$, and let $\mathbb{T}'' = \{k''_1, k''_2, \dots, k''_t\}$ where for each $i \in [t]$ we have $k''_i = k_i - |\{w \in N(v) | i \in c(w)\}|$.

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Let v be a vertex of degree 3 or more. Let H' be the graph obtained by deleting the vertex v from G , c' be the function obtained by restricting c to $V(H') = (V(G) \setminus \{v\})$, and let $\mathbb{T}' = \{k'_1, k'_2, \dots, k'_t\}$ where for each $i \in [t]$ we have $k'_i = k_i - |\{w \in \{v\} | i \in c(w)\}|$.

Let H'' be the graph obtained by deleting the open neighbourhood $N(v)$ from G , let c'' be the function obtained by restricting c to $V(H'') = (V(G) \setminus N(v))$, and let $\mathbb{T}'' = \{k''_1, k''_2, \dots, k''_t\}$ where for each $i \in [t]$ we have $k''_i = k_i - |\{w \in N(v) | i \in c(w)\}|$.

The branching rule recursively solves the two instances (H', c', \mathbb{T}') and (H'', c'', \mathbb{T}'') . If at least one of these recursive calls returns YES, then the rule returns YES; otherwise it returns NO.

FPT ALGORITHM FOR FAIR VERTEX COVER(contd.)

For solving the base case, use the bounded treewidth algorithm as a routine.

FPT ALGORITHM FOR FAIR VERTEX COVER(contd.)

1 vs 3

Branches

θ $\alpha(k)$ $f(k)$

For solving the base case, use the bounded treewidth algorithm as a routine.

The branching algorithm follows the relation

$T(k) \leq T(k-1) + T(k-3)$, when $k \geq 3$. Substituting $\sum_{i=1}^t k_i$ for k , we can get an upper bound on the number of recursive calls. Thus, the total time taken by the algorithm is $n^{O(1)} \cdot \underline{\underline{1.4656^{\sum_{i=1}^t k_i}}}$.

$\alpha(k) \underline{\underline{1.4656^{\sum k_i}}}$