

# Bag #3.1

## Linear Algebra

System of Linear Eq<sup>s</sup>:

$$\begin{aligned} a_{11}x + a_{12}y &= b_1 \\ a_{21}x + a_{22}y &= b_2 \end{aligned}$$

represent lines.

$$A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}; A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$$

$$A\vec{x} = \vec{b}$$

Round off errors: If the determinant is  $\sim 0$ , i.e. when the lines are almost parallel

Gauss Elimination: Upper triangular form  
Gauss-Seidel Elimination: Diagonal form

In general the operations needed

$$\begin{aligned} n-1 &= 1+2+\dots+(n-1) \\ n-2 &= 2+\dots+(n-1) \\ &\vdots \\ 1 &= 1 \end{aligned}$$

ASK Prashansa

$$\approx 4 O(n^2)$$

for diagonal final

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}$$

Methods of evaluation (baby stuff)

$$(a_{21} \cdot a_{11} - a_{21} \cdot a_{11})x + (a_{22} \cdot a_{11} - a_{12} \cdot a_{21})y = b_2 \cdot a_{11} - b_1 \cdot a_{21}$$

$$(a_{21} - a_{11} \frac{a_{21}}{a_{11}})x + (a_{22} - a_{12} \frac{a_{21}}{a_{11}})y = b_2 - b_1 \frac{a_{21}}{a_{11}}$$

$$\begin{pmatrix} a_{11} & a_{12} \\ 0 & a_{22} - a_{12} \frac{a_{21}}{a_{11}} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 - b_1 \frac{a_{21}}{a_{11}} \end{pmatrix}$$

The second approach will take  $\sim 10$  steps, for 2 equations. This can cause problems if  $a_{11} \sim 0$ . So instead iterate through the rows & put the largest (called pivot) pivot row first

Case:  $a_{22} \ll a_{21} \sim \epsilon$

$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \rightarrow \begin{pmatrix} a_{11} & a_{12} \\ 0 & a_{22} - a_{12} \frac{a_{21}}{a_{11}} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 - b_1 \frac{a_{21}}{a_{11}} \end{pmatrix}$$

Eg:

$$\begin{aligned} x + \epsilon y &= 1 \\ \epsilon x + y &= 1 \end{aligned} \Rightarrow \begin{aligned} y &= -\frac{x}{\epsilon} + \frac{1}{\epsilon} \\ y &= 1 - \epsilon x \end{aligned}$$

This  $\sim \epsilon^2$  maybe the round off error of  $a_{22}$  & not affect it this may!

$$\begin{aligned} x + \epsilon y &= 1 \\ 0 + y &= 1 - \epsilon \end{aligned} \Rightarrow \begin{aligned} x &= 1 - \epsilon y \\ &= 1 - \epsilon(1 - \epsilon) \\ &= 1 - \epsilon + O(\epsilon^2) \end{aligned}$$

(neglecting  $\epsilon^2$ )

These things can come back & hit you.

The issue is that you have no handle on the errors. The solution is SDD

ASK: Amdahl's Law: if  $s$ : seq. fraction,  $p$ : parallel fraction } if  $s+p=1$ , then the speedup =  $1/s$



# Bagla # 3.2

(N)  
Gauss-Jordan  
Gauss Elimination ( $O(n^2)$ )

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \\ a_{41} & a_{42} & a_{43} & a_{44} \end{bmatrix}$$

$A\vec{x} = \vec{b}$

Row equilibration  
 $|a_{ij}| \leq 1 \forall i$   
divide an entire row by the largest.

columns eg.  
 $|a_{ij}| \leq 1, \max |a_{ij}| = 1$   
for each  $j$

These help to avoid comparisons/operations of largely different #s.

Then:  $A = LU$  (condition on  $A$ ?)

upper triangular  
lower triangular.  
Demand  $L$  to be of the form

$$L = \begin{bmatrix} 1 & 0 & 0 & 0 \\ l_{21} & 1 & 0 & 0 \\ l_{31} & l_{32} & 1 & 0 \\ l_{41} & l_{42} & l_{43} & 1 \end{bmatrix}$$

can verify that

$$L^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -l_{21} & 1 & 0 & 0 \\ -l_{31} & -l_{32} & 1 & 0 \\ -l_{41} & -l_{42} & -l_{43} & 1 \end{bmatrix}$$

where  $l_{ij}^{-1}$  is the mat element of  $L^{-1}$  & can be obtained by

Methods

$$A\vec{x} = \vec{b}$$

$$U\vec{x} = \vec{b}$$

our old form

we do

$$L U \vec{x} = \vec{b}$$

$$U \vec{x} = L^{-1} \vec{b}$$

1) Unit Diag  $L$

Doolittle

2) Unit Diag  $U$

Cront's algorithm

$$L = \begin{bmatrix} 1 & 0 & 0 & 0 \\ \frac{a_{21}}{a_{11}} & 1 & 0 & 0 \\ \frac{a_{31}}{a_{11}} & \frac{a_{32}}{a_{11}} & 1 & 0 \\ \frac{a_{41}}{a_{11}} & \frac{a_{42}}{a_{11}} & \frac{a_{43}}{a_{11}} & 1 \end{bmatrix}$$

So for a given  $A$

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & & & \\ & & & \\ & & & \end{bmatrix}$$

$$A = U \Sigma V^T$$

$$U^T U = I$$

$$V V^T = I$$

$$\Sigma = \text{diag}\{\sigma_1, \dots, \sigma_n\}$$

$U$  = eigen-vectors of  $A^T A$  (put in a column)

$V$  =  $A^T A$  (put in a row)

$$\sigma_i = \sqrt{\lambda_i(A^T A)}$$

not multiplication  
 $\lambda_i$  is the eigenvalue of  $A^T A$

$$\sigma_1 \geq \sigma_2 \geq \sigma_3 \geq \dots \geq \sigma_n \geq 0$$

I'll have  $a_{22} = \frac{a_{21}}{a_{11}} \cdot a_{12} + x \Rightarrow x = a_{22} - \frac{a_{21}}{a_{11}} \cdot a_{12}$

In general,  $l_{i1} = \frac{a_{i1}}{a_{11}}; U_{kj} = a_{kj} - \sum_{i=1}^{k-1} l_{ki} U_{ij}$

Other algorithm is  $l_{ik} = \frac{a_{ik} - \sum_{j=1}^{k-1} l_{ij} U_{jk}}{U_{kk}}$

the issue is that you may have  $U_{kk} = 0$