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Park
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Circle  $(\vec{x}')$   $\partial_{\mathbf{k}_{1}} \mathbf{x}'^{i} \cdot ... \partial_{\mathbf{k}_{p}} \mathbf{x}'^{i} \cdot ... \partial_{\mathbf{q}_{q}} \mathbf{x}'^{i} \cdot .$ 

(1,0) Contravariant ridos

(0,1) Coverient vector

(P+8, q+s) tons Action in Branch - This transforms as a

A: (7) 3k, x': 3'; x'. A R, (7)

3x'i 3x'i = 3x'i = 5x'k,

= ARI R. (X) which is consistent

Claim. Take some point p on the manifold. To is the coordinate of p in some coordinate system. Then  $\exists$  a coordinate transf  $\vec{x} \rightarrow \vec{x}'$  s.t.  $g':j(x'o) = diag(\pm 1, \pm 1)$ .

NB: For continuous metrics, the number of + 6 - entries will be constant.

= t; (z,) 70 x, = t; (z,0)

 $x^{i} = x_{(0)}^{i} + A_{k}^{i}(x^{i} - x^{i}) + B_{k,i}^{i}(x^{i} - x^{i})(x^{i} - x^{i}) + \dots$ 

Here we expand about to

g'el (z'o) = 3'ex 3'ex 3'ex 3'il z'= z'o = A' A' P Dij (To) (Take o' & should be clear) = (At g A) & (in matrix notation)

Notition: Regard 3i; as matrix; i as now index, i as column index

Recall: S is symmetrie; Thus can be diagonalized with orthogonal matrices.

viz. g = 5 d 5 s.t. 5'S=II

( ) ( ) ( ) non-singular metric only, in eigenvalues are non-zero.  $D_{\gamma}^{A} : R = R^{T} = \left( \overline{M}_{1} \right) , \Rightarrow R^{T} \gamma R = \left( \overline{M}_{1} \right)$   $where \gamma = \left( \frac{\lambda_{1}}{|\lambda_{1}|} \right) .$   $\frac{\lambda_{n}}{|\lambda_{n}|}$ 

g = stat = stropes

g'el = (ATgA)el = (ATSTRT NRCA)Rd , = (ES) " well get g'el (zio) = NRA

This is not unique; eg. 2=1, then + A = (URS) will get the right form, where Signature: When all + , then encledian when one - , then lorentgian NB: (1) Locally then, there's no more information (3) This will not distinguish How place I the surface of a sphere.
(B) This is more than diagonalization; A is more than just a PTR like matrix. Dyn: Kijk = digik K'inizis = d'i, (g'izis (7')) = 9; (3; 2, 2, 5; 8; x, 3 8; 3; (x,)) = 3'1,3'1, x'2 3'1,3'3 gizi3 + 3'1,3'1,3'1,3'1,3'1,3'3 gizi3 + وندين ان و ونع ون و دند عن و الم This is the term or want (why? we'll see soon) chain sule
= d'iz x<sup>j</sup>² d'iz x<sup>j</sup> d'i, x<sup>j</sup> di, g'iziz = d'i, x', d'iz x', d'iz x', d'ig x', d'iz iz x', d'iz x', d This is how kijk should transform if kijk was a tensor. However, since the other tirms are non-zero, as Kijk is not a tensor under general coordinate transformation. Idea: Take a linear combination of Kijk to construct a tensor.

This is not possible. "Caren polynomials of Kijk) Proof sketch: Issume we can show that given a point, I a coordinate transformation (CT) s.t. K variables. Therefore, it must varish in all coordinates (: Cersors trensform in that way). Therefore its impossible to find such a tensor (itill be zero essentially), (if this argument is repeated for all points.)

We went K'ijk = 0, so (N(n+1). In eg's are required to be zero.

# constants is also (N(n+1). In (:: B'; k also has similar symmetric aspects as Kijk)

Accell: xi = xio + Ai; (x'i - x'i) + Bix (x'i - x'i)(x'k - x'k) + ....

Idea: Take 2 derivatives of gij

(Claim: This itself is not a tensor.)

: Use the old argument. Lee if it can be shown to be zero in some coordinate yes.

At to, # of components of Si; ke = n(n+1) n(n+1)

Vecall: 2i=xi + Ai; (...) + Bije (...) + Cijke (...) ikt

Now # of paremeters in ( isee =  $n \cdot \frac{n(n+1)(n+2)}{31}$  & (for large N)

I there're more constraints than parameters. This means one can't in general get

lesult. So  $\frac{n^2(n+1)^2}{4} = \frac{n^2(n+1)(n+2)}{6} = \frac{1}{12} \frac{n^2(n^2-1)}{12} - \frac{1}{12} \frac{for n=2}{70 \text{ for } n=3}$ 

which means the tensor so constructed will have the oforesaid # of free

parameters.

Defn: Die =: 1 gil (diger + dre gei - de gir) := Christoffel tymbol/Ronnection

Riske =: de Pik - de Pil + Pik Pim - Ja Pikm: = Riemann Tensos

Exercise: ['mn (z') = dix'ld'mx'd'nxk [ik (z) + dxxld'md'n2k

NB: This is not a tensor -: of the second term

: Pike is a terror of rank (1,3)

: Rijke has to n2(n2-1) independent parameters.