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761 760 u=1 u+84
rector in the target
space at X(1)
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ain: see what this vector becomes upon parallel transport.

ni(u) - known (say)

ni(u+du) - calculate

Goto Z(u) le find a new coordinale sys Z' s.t. d'égis =0 at Z' = Z'(0)

n'i (u+du)= n'i (u) + O(Su2) (by rules of parallel transport) -

line you don't want to keep changing coordinates (its inconvenient), in we see what

parallel transport amounts in some arbitrary frame

Translate to 2

$$N^{i}(u) = \frac{\partial x^{i}}{\partial x^{i}} | \frac{1}{x^{i}} | \frac{1}{x^{i$$

 $n^{i}(u+\delta u) = \frac{\partial x^{i}}{\partial x^{i}R} |x^{i}(u+\delta u)$ $n^{i}R(u) + O(\delta u^{2})$ $n^{i}R(u) + O(\delta u^{2})$

 $\frac{\partial x^i}{\partial x^i} | \overline{x}^i(u) + \frac{\partial^2 x^i}{\partial x^i} \delta x^i + \dots \qquad \begin{cases} \delta x^{il} = \frac{\partial x^{il}}{\partial x^{il}} \delta u \end{cases}$

 $\Rightarrow n'(u+du) = h'(u) + \frac{\partial^2 x'}{\partial x'^2 \partial x'} \frac{\partial x'^2 \partial u}{\partial x'} \frac{\partial u}{\partial x'} \frac{\partial$

 $\frac{du}{dv_i} = \frac{3x_i}{3x_i} \frac{3x_i}{3x_i} \frac{3x_i}{3x_i} \frac{3x_i}{3x_i} \frac{3x_i}{3x_i} \frac{3x_i}{3x_i}$

We still have dependence on the givened coordinate. We wish to get rid of it

 $\Gamma_{mn}^{il}(\vec{x}') = \frac{\partial x^{i}}{\partial x^{i}} \frac{\partial x^{j}}{\partial x^{im}} \frac{\partial x^{k}}{\partial x^{in}} \Gamma_{jk}^{ik}(\vec{x}) + \frac{\partial x^{i}}{\partial x^{k}} \frac{\partial^{2}x^{k}}{\partial x^{im}\partial x^{in}} = 0 \quad (for the primed)$ primed frame)

 $\frac{9x_{ij}}{9x_{b}} L_{ij}^{wv}(\underline{x}_{i}) = \frac{9x_{iw}}{9x_{b}} \frac{9x_{iw}}{9x_{b}} L_{b}^{ik}(\underline{x}) + \frac{9x_{iw}}{9x_{b}} = 0$

also, sciell: $n^{1}k(u) = \frac{\partial x^{1}k}{\partial x^{1}} n^{3}(u)$ $\frac{dx'}{dy} = \frac{\partial x'}{\partial x} \frac{\partial x'}{\partial x}$

Using Twe (Ex: check) we get

 $\frac{dn^i}{du} + \Gamma pq \left(\vec{x}(u) \right) n P \frac{dx^q}{du} = 0$

(The primes will dissippear (as knowner delta))

for a d-dimensional space, there're d- first order d.e. Thus given the initial vector, you can toln it for u.

MB: U needn't describe a geodesie. clain: The egn is parametrization independent. $\frac{dn^{i}}{du} = \frac{dv}{du} \cdot \frac{dn^{i}}{dv}$ $= \frac{dv^{g}}{du} = \frac{dv^{g}}{dv} \cdot \frac{dv}{du}$ $= \frac{dv^{g}}{du} = \frac{dv^{g}}{dv} \cdot \frac{dv}{du}$ NB: unlike the geodesiie of which works in a specific parametrication. Now choose an arbitrary coordinate sys \(\vec{x}''\) (where \(\Gamma''\) needn't be zero) Recallini = n" R Dxik substitute in $\frac{\partial x'}{\partial x'} = \frac{\partial x'}{\partial x'$ MB: dx = 3x9 dx"x Therefore its evident that the parallel transport eg's don't depend on the coordinate frame: NB: Its not surprising: ne coordinate sys to start with, was arbitrary. Therefore infact its a consistency check. Ex: du (gi; (x(u)) ni(u) ni(u)) = in o vic. norm is present under parallel transport. Proof sketch: (direct) and is known now, & gi; dxk = dgi; d that known. (reat) the quantity is invariant under coordinate transformations. Thus, goto the primed coordinates. Now first derivative of g is zero (by def' of the primed coordinate). Also, for a primed coordinate, $\frac{dn'}{dy} = 0$. So that does it. Perall: Geodesie eg^ de xi du du = 0; Z. Dy": n'(u) = dz' (he tangent rector) . So now, dri + Tiknidxk = 0 NB!: This is exactly the parallel transport egn

Alternate def of geodesic: curre s.t. its tangent vectors are transported from

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Her after parallel transport
               NB: The transport y' is linear.

The transport y' is linear.

The transport y' is linear.

The transport y' is linear.
                                   no) = Mi, (\(\frac{1}{2}\alpha\), \(\frac{1}{2}\alpha\), \(\frac{1}\alpha\), \(\frac{1}{2}\alpha\), \(\frac{1}{2}\
   Dy': - C: = Path cin the reverse direction.
Q: What can we say about Mi; ( To, , To, -c)?
NB: The parallel transport eg'. is rescribbe (independent of parametergation)
                   We reparametrize: V:=1-U; this will do the feb. U=1 \Leftrightarrow V=0
                                  \frac{dn^i}{dv} + \prod_{j \neq i} n^j(v) \frac{dx^k}{dv} = 0 \quad \Rightarrow \quad \frac{dn^i}{du} + \prod_{j \neq i} n^j(u) \frac{dx^k}{du} = 0
                      So we solve the same old ego with boundary conditions reserved.
                    Thus we must have
                                     N_{\alpha\beta} := \left(M_{\alpha\beta} \left(\vec{x}_{\alpha\beta}, \vec{z}_{\alpha\beta}, c\right)^{-1}\right)^{i}, \quad N_{\alpha\beta}^{i}
                                                        by Dy' M (\(\fix\) \(\fix\) \(
                                                                                                                                                                                                                                                         M(xa), xa), -()=M(xa), xa, ()
   NB: If we had dri + Fix n' dxi = 0, the eg want be reversible.
  Take 2 curses faining xu, l xo, , c, d cz
                                                                                                                                                                                                                               x(1) 26)
 In general, M(\vec{x}_0, \vec{x}_0), C_1) \neq M(\vec{x}_0, \vec{x}_0), C_2)
 lonsidu: M(\vec{x}_0, \vec{x}_0), C_1-C_2) = M(\vec{x}_0, \vec{x}_0), -C_2). M(\vec{x}_0, \vec{x}_0), C_1)
                                                                                                                                   = M(\vec{x}_0, \vec{x}_0, (z)) M(\vec{x}_0, \vec{x}_0, (z))
Dy. Monodroms Matrix around ( & 1 in general.
                             := M(x, x, c) for some closed curse C
                                                                           final rector, after coming back to \vec{x}.
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Now lets change be coordinate system: $y_{ij} = \frac{g_{xb}}{g_{xij}} \bigvee_{b} = \frac{g_{xb}}{g_{xij}} \bigvee_{b} \bigvee_{i} \bigvee_{j} \bigvee_{$ Recall:

'As M was s, then you'd get vie. It will remain identity even in The new coordinate sys. NB: This can be proved the other way also. If n'i an'i then M must be NB 2: This analysis will not work for M(\$\vec{x}_1, \vec{x}_2, c) :: We DX M &X' factor won't become kronecker (they're evaluated at different points), even if M= I. Claim: When R=0, M=1; the reserve is true when there're we singularities (& simply connected) Proof: Start with a small curve; length ~ O(E) Convention: 0< u< f so that dri ~1 dni = - Tik ni (u) dxi idea: Keep terms of order u & Then integrate, you get the result to order E. Then plugin the result be re-evaluate to get order corect to order t order , can't take it at its 7 original value dni = - [ik (20) Nio dxk $\frac{dn^{i}}{du} = -\left\{ \prod_{j \in (\vec{x}_{0j})}^{i} + \partial_{j} \prod_{j \in (\vec{x}_{0j})}^{i} (\vec{x}_{0j}) \left(\vec{x}_{0j} - \vec{x}_{0j} \right) \right\} \times \left\{ \vec{x}_{0j} - \vec{x}_{0j} - \vec{x}_{0j} \right\} \times \left\{ \vec{x}_{0j} - \vec{x}_{0j} - \vec{x}_{0j} - \vec{x}_{0j} \right\} \times \left\{ \vec{x}_{0j} - \vec{x}_{0j} - \vec{x}_{0j} - \vec{x}_{0j} - \vec{x}_{0j} - \vec{x}_{0j} - \vec{x}_{0j} \right\} \times \left\{ \vec{x}_{0j} - \vec{x}_{0j} -$ $(x^{2}-x^{2})$ $\frac{dx^{k}}{du}$ keeping upto O(E), we have dni = - { Lik Lib ub (x & - xigi) qx k

+ 30 [18. (22-26) . NO) . NO) . dx R } + O(62)

Integrating from (0, E), we note that term I is zero. $n^{i}(u) = n_{(0)}^{i} + \partial_{i}\Gamma_{ijk}^{i} n_{(0)}^{i}$ $\int_{0}^{\epsilon} (x^{0} - x^{0}) d(x^{k} - x^{k}_{0}) - \Gamma_{ik}^{i} \Gamma_{ijk}^{k} n^{k} \int_{0}^{\epsilon} (x^{3} - x^{0})$ (Lets try to match indices for aesthetics)

NB: The boundary turns are zero. The derivative can be -. shifted with a ninus sign.

NB2: This means the indices of lk are anti-symmetric

NB3: Thus only the symmetric part of the remaining part must contribute