

# Bell type test with a double slit setup

## The setup

- Consider the double slit setup as shown [TODO: add an image]
- In a typical Bell test, we have Alice and Bob who measure along  $[x, x']$  or  $[z, z']$ . However, this can be equivalently stated as: Alice and Bob apply a unitary, given as  $U(\theta) = e^{i\sigma_y \theta}$  with setting  $[\theta_1, \theta_2]$  and  $[\phi_1, \phi_2]$  respectively, while both measure along  $x$ .  
NB: A measurement along  $x$  for instance, means  $\sigma_x$  is measured.
- In this setup, Alice and Bob, both measure the modular momentum. They can as before, use the different settings. These apply a relative phase.
- The target is to see if in this setup, we can violate the corresponding inequality:  
 $E(x[z - z'] + x'[z + z']) \leq 2$ , given that  $-1 \leq z, z', x, x' \leq 1$ 
  - So we start with inputting the setting, one from Alice, one from Bob. Call it  $\gamma_A, \gamma_B$ . Given these, I find the resultant state, which is essentially just  $(q_1 p_1 + \text{Exp}[\phi] q_2 p_2) / \sqrt{2}$  with  $\phi = \gamma_A + \gamma_B$ .
  - To measure  $x_{\text{mod}}$  I simply measure  $e^{i \hat{x} 2\pi/L}$ , whose operation is simply to shift the lumps.

## The Code

### Approach one (only phases, doesn't violate | as intuitively expected)

This has been matched with analytic results for  $m=2,3$  and the rest seem to be correct also.

```
In[104]:= m = 50;
ex[α_, β_] := (
  (*Print["Initial state:"];*)
  (*stateEntangled =  $\frac{q_1 p_1 + \text{Exp}[i(\alpha + \beta)] q_2 p_2}{\sqrt{2}}$ ;*)
  stateEntangled =  $\frac{\text{Exp}[i(\alpha + \beta)] q_1 p_1 + \text{Sum}[q_n p_n, \{n, 2, m\}]}{\sqrt{m}}$ ;
  (*state =  $\frac{p_1 + \text{Exp}[\phi] p_2}{\sqrt{2}}$ ;*)
  state = stateEntangled;
  (*Print[state];*)
  (*dispRuleP = {p_n -> p_{n+1}};*)
)
```

```

dispRule= {pn -> pn+1, qn -> qn+1};
eispRule= {pn -> pn+1, qn -> qn-1};
conjDispRule= {pn -> pn-1, qn -> qn-1};
conjEispRule= {pn -> pn-1, qn -> qn+1};
orthRule= {pm pn -> 0, qm qn -> 0};
normRule = {pn pn -> 1, qn qn -> 1};
conjRule = {Exp[φ-] -> Exp[-φ]};

(*Print["So the expectation for identity is"]*);
(*newState =state ; (*/. dispRuleP*);*)
(*ans=Expand[ (state /. conjRule) newState] /. normRule /. orthRule;*)
(*Print[ans, " so no surprises there!"]*);

(*Print["And the expectation for modular x is "]*);
newState1 = state /. dispRule;
newState2 = state /. eispRule;
(*Print[newState1];*)
newState3 = state /. conjEispRule; (*Analytically, these are zero*)
newState4 = state /. conjDispRule;
(*newState2 and 3 are zero | Look at your notes for the calculations*)
newState = (newState1 + newState2 + newState3 + newState4) / 4;
ans = Expand[ (state /. conjRule) newState] /. normRule /. orthRule;
Return[ans]
)
chsh[x_, y_, u_, v_] := ex[x, u] - ex[x, v] + ex[y, u] + ex[y, v]

Print["Expectation for arbitrary φ and δ, for n=", m, ":"]
ExpToTrig[ex[φ, δ]]
Print["CHSH/Bell:"]
ExpToTrig[chsh[x, y, u, v]] (*/. {u+x -> A, v+x -> B}*)

(*ExpToTrig[chsh[0,0,0,0]] *)
(*Plot3D[ $\frac{1}{2} \cos[1+x] - \frac{1}{2} \cos[x] + \frac{1}{2} \cos[1+y] + \frac{1}{2} \cos[y]$ , {x, -π, π}, {y, -π, π}]*)
(*Maximize[ $\left\{\frac{1}{2} \cos[u+x] - \frac{1}{2} \cos[v+x] + \frac{1}{2} \cos[u+y] + \frac{1}{2} \cos[v+y],\right.$ 
 $\left. -\pi \leq u \ \&\& \ u \leq \pi \ \&\& \ -\pi \leq v \ \&\& \ v \leq \pi \ \&\& \ -\pi \leq x \ \&\& \ x \leq \pi \ \&\& \ -\pi \leq y \ \&\& \ y \leq \pi\right\}, \{u, v, x, y\}]$ *)
(*Maximize[ $\left\{\frac{1}{2} \cos[(u+v)], u < \pi \ \&\& \ -\pi < u \ \&\& \ v < \pi \ \&\& \ -\pi < v\right\}, \{u, v\}]$ *)
(*Maximize[{1/(u+1), u > 0}, {u}]*)
(*Maximize[{1/(x+1), x > 0}, {x}]*)

(*
Just testing if the substitution I'm
doing is indeed linearly independent, its not..;
a={{1,0,1,0},{1,0,0,1},{0,1,1,0},{0,1,0,1}};
a={{1,0,0,0},{0,1,0,0},{0,0,1,0},{0,0,0,1}};
Det[a]
*)

Expectation for arbitrary φ and δ, for n=50:

```

$$\text{Out}[108] = \frac{12}{25} + \frac{1}{100} \cos[\delta + \phi]$$

CHSH/Bell:

$$\text{Out}[110]= \frac{24}{25} + \frac{1}{100} \cos[u+x] - \frac{1}{100} \cos[v+x] + \frac{1}{100} \cos[u+y] + \frac{1}{100} \cos[v+y]$$

## Approach two [use a different but closer to the bell situation state]

So far, this is miserable. The expectation of a Hermitian operator is turning up to be complex. So again, I'll have to calculate the whole thing analytically first and then check. Worst part, is that it is not even obvious yet how this should be scaled.

```

In[138]:= m = 2; (*This is the number of lumps *)

ex[α_, β_] := (
  (*Print["Initial state:"];*)
  (*stateEntangled= $\frac{q_1 p_1 + \text{Exp}[i(\alpha+\beta)] q_2 p_2}{\sqrt{2}}$ ;*)
  stateEntangled =  $\frac{1}{\sqrt{m}}$  (Exp[i (α+β)] q1 p1 + Sum [qn pn, {n, 2, m }]);
  ψ = Simplify [
     $\frac{1}{\sqrt{2}} \left( \left( \frac{\text{Exp}[i\alpha] q_1 + q_2}{\sqrt{2}} \right) \left( \frac{\text{Exp}[i\beta] p_1 - p_2}{\sqrt{2}} \right) - \left( \frac{\text{Exp}[i\alpha] q_1 - q_2}{\sqrt{2}} \right) \left( \frac{\text{Exp}[i\beta] p_1 + p_2}{\sqrt{2}} \right) \right)$ ;
    Print[ψ];
    (*state= $\frac{p_1 + \text{Exp}[\phi] p_2}{\sqrt{2}}$ ;*)
    state = ψ;
    (*state=stateEntangled;*)
    (*Print[state];*)
    (* dispRuleP={pn→pn+1};*)
    dispRule = {pn → pn+1, qn → qn+1};
    eispRule = {pn → pn+1, qn → qn-1};
    conjDispRule = {pn → pn-1, qn → qn-1};
    conjEispRule = {pn → pn-1, qn → qn+1};
    orthRule = {pm pn → 0, qm qn → 0};
    normRule = {pn pn → 1, qn qn → 1};
    conjRule = {Exp[φ] → Exp[-φ]};
    Print[state /. conjRule];
    (*conjRule = {α→ -α, β→ -β};*)

    (*Print["So the expectation for identity is"];
    newState = state ; (*/. dispRuleP*);
    ans=Expand[ (state /. conjRule) newState] /. normRule /. orthRule;
    Print[ans, " so no surprises there!"];
    *)
    (*Print["And the expectation for modular x is "];*)
    newState1 = state /. dispRule;
    newState2 = state /. eispRule;
    (*Print[newState1];*)
    newState3 = state /. conjEispRule; (*Analytically, these are zero*)
    newState4 = state /. conjDispRule;
    (*newState2 and 3 are zero | Look at your notes for the calculations*)
    newState = (newState1 + newState2 + newState3 + newState4) / 4;
    ans = Expand[ (state /. conjRule) newState] /. normRule /. orthRule;

    Return[ans]
  )

chsh[x_, y_, u_, v_] := ex[x, u] - ex[x, v] + ex[y, u] + ex[y, v]

(*Print["Expectation for arbitrary φ and δ, for n=", m, " :"]*)
ex[φ, δ]
(*Print["CHSH/Bell:"]
  ExpToTrig[chsh[x, y, u, v]] (*/. {u+x → A, v+x → B}*)
*)

```

$$\text{Out}[140]= -\frac{\frac{-e^{i\alpha} p_2 q_1 + e^{i\beta} p_1 q_2}{\sqrt{2}}}{\frac{-e^{-i\alpha} p_2 q_1 + e^{-i\beta} p_1 q_2}{\sqrt{2}}} - \frac{e^{i\alpha-i\beta}}{8} - \frac{e^{-i\alpha+i\beta}}{8}$$