

THE CANONICAL EQUATIONS

§40 Hamilton's Equations

Motivatⁿ: We assumed that the mechanical state is described by $\{x_i, v_i\}$.
Sometimes it is better described as $\{x_i, p_i\}$ canonical momentum.

\therefore equations in x, p ?

Lagandre Transfⁿ: Means by which one passes from one set of independent variables to another.

Conversion (in this case):

$$\text{NB: } dL = \sum_i \frac{\partial L}{\partial q_i} dq_i + \sum_i \frac{\partial L}{\partial \dot{q}_i} d\dot{q}_i$$

$$\text{Recall: } p_i = \frac{\partial L}{\partial \dot{q}_i} \quad (\text{by def}^n)$$

$$\frac{\partial L}{\partial q_i} = \dot{p}_i \quad (\text{by Lagrange eqs})$$

$$\Rightarrow dL = \sum \dot{p}_i dq_i + \sum p_i d\dot{q}_i \quad (*)$$

$$\text{NB: } \sum p_i d\dot{q}_i = d(\sum p_i \dot{q}_i) - \sum \dot{q}_i dp_i$$

$$\Rightarrow -\sum \dot{p}_i dq_i + \sum \dot{q}_i dp_i = d(p_i \dot{q}_i - L) \quad (1)$$

Recall: $H = \sum p_i \dot{q}_i - L$ is the energy of the syst.

Defⁿ: Hamiltonian := Energy expressed in terms of (q, p) .
or
Hamilton's Eqⁿ

NB from (1): $dH = - \sum \dot{p}_i \underbrace{dq_i} + \sum \dot{q}_i \underbrace{dp_i}$

$$\left. \begin{aligned} - \frac{\partial H}{\partial q_i} &= \dot{p}_i \\ \frac{\partial H}{\partial \dot{q}_i} &= \dot{q}_i \end{aligned} \right\} \begin{array}{l} \text{Hamilton's} \\ \text{Eqⁿs} \end{array}$$

Remark 1: Form 2s first-order eqⁿ for 2s unknowns (p, q)
compared to s second-order eqⁿs earlier.

Remark 2: Also called "canonical eqⁿs" due to symmetry & simplicity.

NB: We didn't include an explicit time dependence in L (will do something more general shortly).

NB 2:
$$\frac{dH}{dt} = \frac{\partial H}{\partial t} + \underbrace{\frac{\partial H}{\partial q_i} \dot{q}_i + \frac{\partial H}{\partial p_i} \dot{p}_i}_{\text{This using Hamilton's eqⁿ}}$$

$\Rightarrow \frac{dH}{dt} = \frac{\partial H}{\partial t}$
manifestly, if no explicit time dependence, Energy is conserved.

Consider: Some additional parameter λ (encoding e.g. an external field etc.)

$$dL = \sum p_i dq_i + \sum p_i d\dot{q}_i + \frac{\partial L}{\partial \lambda} d\lambda$$

using this instead of (*) I would get

$$dH = -\sum p_i dq_i + \sum \dot{q}_i dp_i - \frac{\partial L}{\partial \lambda} d\lambda$$

$$\Rightarrow \left. \frac{\partial H}{\partial \lambda} \right|_{p, q} = - \left. \frac{\partial L}{\partial \lambda} \right|_{q, \dot{q}}$$

NB: λ could even be explicit time dependence

$$\Rightarrow \left. \frac{\partial H}{\partial t} \right|_{p, q} = - \left. \frac{\partial L}{\partial t} \right|_{q, \dot{q}} .$$