mín
$$F(kx) + G(x) = \frac{k^{2}}{2} [|Ax - b||_{2}^{2} + ||D_{h}x||_{0} + ||D_{h}x||_{0}$$
 $x \text{ step } ||D_{h}x||_{1}^{2} = ||D_{h}x||_{1}^{2} + ||D_{h}x||_{1$

× Normest
$$\rightarrow$$
 5822 A27778
$$T = \frac{1}{(\text{normest})^2}$$

$$G = \frac{1}{\text{T.}(\text{normest})^2}$$

$$G^{-1} = \frac{1}{\sqrt{(1+2\cdot h)}}$$

$$\Theta = \frac{1}{\sqrt{(1+2\cdot h)}}$$

hw3-prob3-l0-norm

February 13, 2024

```
[1]: #
     import numpy as np
     import scipy.io
     import matplotlib.pyplot as plt
[2]: # MAT
    mat_path = r"../HW3_package/hw3_prob3.mat"
     mat_data = scipy.io.loadmat(mat_path)
     A = mat_data['A']
     b = mat_data['b']
     x_orig = mat_data['x_orig']
[3]: def normest_numpy(A):
         nnn
                    A 2-
         NumPy
         HHHH
         # SVD . full_matrices=False
         U, s, V = scipy.sparse.linalg.svds(A)
         return s[0]
     def Dh(u):
         rows, cols = u.shape
         d = np.zeros((rows, cols))
         d[:, 1:cols] = u[:, 1:cols] - u[:, 0:cols-1]
         d[:, 0] = u[:, 0] - u[:, cols-1]
         return d
     def Dht(u):
         rows, cols = u.shape
         d = np.zeros((rows, cols))
         d[:, 0:cols-1] = u[:, 0:cols-1] - u[:, 1:cols]
         d[:, cols-1] = u[:, cols-1] - u[:, 0]
         return d
     def Dv(u):
```

```
rows, cols = u.shape
d = np.zeros((rows, cols))
d[1:rows, :] = u[1:rows, :] - u[0:rows-1, :]
d[0, :] = u[0, :] - u[rows-1, :]
return d

def Dvt(u):
   rows, cols = u.shape
   d = np.zeros((rows, cols))
   d[0:rows-1, :] = u[0:rows-1, :] - u[1:rows, :]
   d[rows-1, :] = u[rows-1, :] - u[0, :]
   return d
```

```
[4]: mu = 1
    stopping_point = 2e-4

# # normest    tau sigma
    norm_est = normest_numpy(A)
    tau = 1 / norm_est**2
    sigma = 1 / (tau * norm_est**2)
    sigma_1 = (tau * norm_est**2)

theta = 1/np.sqrt(1 + 2 * mu)
```

```
[5]: y1 = np.zeros(b.shape)
     y2 = np.zeros((256, 256))
     y3 = np.zeros((256, 256))
     x = np.zeros((256, 256))
     z1 = np.zeros(b.shape)
     z2 = np.zeros((256, 256))
     z3 = np.zeros((256,256))
     y2 = Dh(x)
     y3 = Dv(x)
     x = x.reshape(65536, 1)
     y1 = A @ x
     x = x.reshape(256,256)
     for idx in range(10000):
         # step 1
         Dhx = Dh(x)
         Dvx = Dv(x)
         # step 2
```

```
# HardThresholding
    z2 = sigma_1 * y2 + Dhx
    z3 = sigma_1 * y3 + Dvx
    z2[np.abs(sigma_1 * y2 + Dhx) < sigma_1] = 0
    z3[np.abs(sigma_1 * y3 + Dvx) < sigma_1] = 0
    x = x.reshape(65536, 1)
    z1 = ((sigma_1 * y1 + A @ x) + (mu * b/ sigma)) / (1 + mu / sigma)
    # step 3
    x_minus1 = x
    y1 = y1 + sigma * (A @ x - z1)
    y2 = y2 + sigma * (Dhx - z2)
    y3 = y3 + sigma * (Dvx - z3)
    y2 = y2.reshape(65536, 1)
    y3 = y3.reshape(65536, 1)
    x = x - (tau * (A.T @ y1 + y2 + y3))
    x[x<0] = 0
    x = x + theta * (x - x_minus1)
    x = x.reshape(256, 256)
    y2 = y2.reshape(256, 256)
    y3 = y3.reshape(256, 256)
    x_{minus1} = x_{minus1.reshape}(256,256)
    print(idx, np.linalg.norm((x - x_minus1), 2) / np.linalg.norm(x, 2))
    if (np.linalg.norm((x - x_minus1), 2) / np.linalg.norm(x, 2)) <
  →stopping_point:
        break
0 1.0
```

```
1 3.5274576204341277
2 1.3557814728326099
3 4.753474126239157
4 1.2435827896935654
5 3.817060833425024
6 0.9097140113056035
7 1.3939271807967724
8 0.5159256306848036
9 0.41495220115601467
```

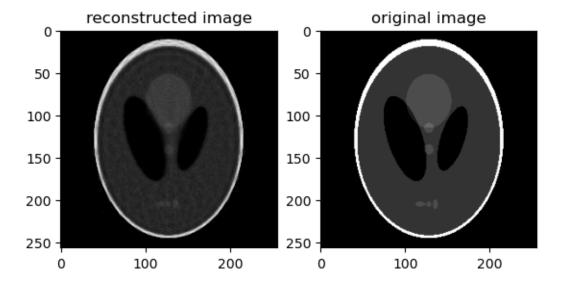
10 0.18905458077982387

```
155 0.00021407338829309585
156 0.00021183643092429058
157 0.00020968856933822777
158 0.00020746446445694437
159 0.00020498247548997444
160 0.00020304495866980073
161 0.0002007890858422375
162 0.0001988301007671573
```

```
[6]: # original f
    x = x.reshape((256, 256))
    plt.subplot(121)
    plt.imshow(x.T, cmap = "gray")
    plt.title( label = "reconstructed image")

    x = x.reshape((256, 256))
    plt.subplot(122)
    plt.imshow(x_orig, cmap = "gray")
    plt.title( label = "original image")

    plt.show()
```



[]: