

Lecture X. Enhancing Sparse Signal Recovery

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Severance

In Lecture IX

- Review of Transform Sparsity
 - Sparse signal recovery for actual images
 - Transform sparsity with total-variation minimization (ADMM, Chambolle-Pock algorithms)
 - Various transforms available for image reconstruction and denoising
- Today, Let's take a look at **how to enhance sparse signal recovery**

Enhancing Time Efficiency

Accelerating Strategy

Accelerating Strategy

- Unconstrained Minimization
 - f is **convex** and **differentiable**
 - ∇f is **Lipschitz constant L** $\|\nabla f(x) - \nabla f(y)\|_2 \leq L\|x - y\|_2$

$$t \leq \frac{1}{L} : \quad f(x_k) - f^* \leq \frac{\|x_0 - x^*\|_2^2}{2tk} \quad \text{Linear convergence}$$

- Method to make the convergence faster

$$x_{k+1} = x_k - t_k \nabla f(x_k) + s_k (x_k - x_{k-1})$$

Utilizing 'previous iterates'

FISTA -- Accelerating ISTA

- FISTA (Fast Iterative Soft-Thresholding Algorithm)

$$\begin{aligned} x_{k+1} &= y_k - t_k \nabla f(y_k) \\ y_{k+1} &= x_{k+1} + \frac{k}{k+3} (x_{k+1} - x_k) \end{aligned} \quad \Rightarrow \quad f(x_k) - f^* \leq \frac{2 \|x_0 - x^*\|_2^2}{t(k+1)^2}$$

Quadratic convergence

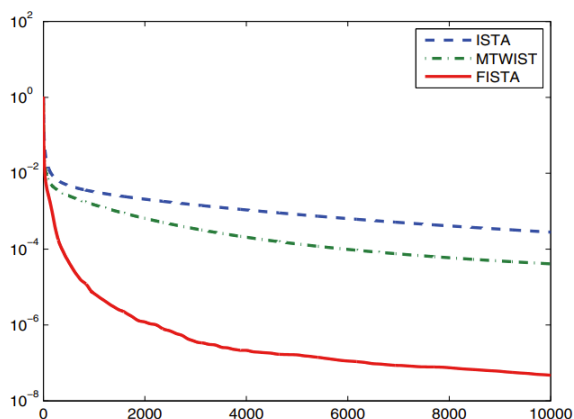
$$\begin{aligned} \underset{x}{\text{minimize}} \quad & f(x) = \|Ax - b\|_2^2 + \lambda \|x\|_1 = g(x) + h(x) \\ \Rightarrow \quad & x_{k+1} = \text{SoftThreshold}(y_k - t_k \nabla g(y_k), \lambda t_k) = \text{SoftThreshold}(y_k - t_k A^T (Ay_k - b), \lambda t_k) \\ & y_{k+1} = x_{k+1} + \frac{k}{k+3} (x_{k+1} - x_k) \end{aligned}$$

FISTA -- Accelerating ISTA

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A Fast Iterative Shrinkage-Thresholding Algorithm for ...

by A Beck · 2009 · Cited by 12694 — We consider the class of iterative shrinkage-thresholding algorithms (ISTA) for solving **linear inverse problems** arising in signal/image processing.



$F(\mathbf{x}_k) - F(\mathbf{x}^*)$ of ISTA, MTWIST, and FISTA.

Enhancing Recovery Accuracy

L_p -norm ($p < 1$) Minimization

Revisiting L_k -norm, but $k < 1$

- L_k -norm

Definition:	$\ x\ _k = (x_1 ^k + x_2 ^k + x_3 ^k + \dots + x_n ^k)^{\frac{1}{k}}$
L2-norm:	$\ x\ _2 = \sqrt{ x_1 ^2 + x_2 ^2 + x_3 ^2 + \dots + x_n ^2}$
L1-norm:	$\ x\ _1 = x_1 + x_2 + x_3 + \dots + x_n $

- Theoretically, however, the ideal solver for sparse signal processing is **L0-norm** (counting # of non-zero elements)

$$L0\text{-norm: } \|x\|_0 = \sum_j 1_{\{x_j \neq 0\}}$$



→ Minimizing L0-norm is a **non-convex** optimization (**Hard to implement** in practice)

Proximity Operator for L_0 Minimization

- Proximity (Thesholding) operator for L_0 -norm

$$\begin{aligned}
 & \underset{x}{\text{minimize}} \quad f(x) = \|Ax - b\|_2^2 + \lambda \|x\|_0 = g(x) + h(x) \\
 \Rightarrow & \quad x_{k+1} = \underset{x}{\text{argmin}} \left[g(x_k) + \frac{1}{2t_k} \|x - (x_k - t_k \nabla g(x_k))\|_2^2 + h(x) \right] \\
 & = \underset{x}{\text{argmin}} \left[\frac{1}{2t_k} \|x - (x_k - t_k \nabla g(x_k))\|_2^2 + \lambda \|x\|_0 \right] \\
 & = \underset{x}{\text{argmin}} \left[\frac{1}{2\lambda t_k} \|x - (x_k - t_k \nabla g(x_k))\|_2^2 + \|x\|_0 \right] \\
 & = \text{HardThreshold}(x_k - t_k \nabla g(x_k), \lambda t_k) = \text{HardThreshold}(x_k - t_k A^T (Ax_k - b), \sqrt{2\lambda t_k}) \\
 & = \begin{cases} x_k - t_k A^T (Ax_k - b) & (|x_k - t_k A^T (Ax_k - b)| \geq \sqrt{2\lambda t_k}) \\ 0 & (|x_k - t_k A^T (Ax_k - b)| < \sqrt{2\lambda t_k}) \end{cases}
 \end{aligned}$$

Approximation to L_0 -norm -- Reweighted L_1 -norm

- Approximated L_0 -norm by **reweighted L_1 -norm**

$$\begin{aligned}
 \text{L0-norm:} \quad & \underset{x}{\text{minimize}} \quad \|x\|_0 = \sum_j 1_{\{x_j \neq 0\}} \\
 \text{L1-norm with W:} \quad & \underset{x}{\text{minimize}} \quad \|Wx\|_1 = \sum_j w_j \cdot |x_j| \quad \text{where } w_j = \frac{1}{|x_j| + \delta} \quad (\delta > 0) \\
 & \underset{x}{\text{minimize}} \quad \|Wx\|_1 = \sum_j \frac{|x_j|}{|x_j| + \delta} \approx \sum_j 1_{\{x_j \neq 0\}}
 \end{aligned}$$

Graphical Interpretation of Reweighted L_1 -norm

- Approximated L_0 -norm by **reweighted L_1 -norm**

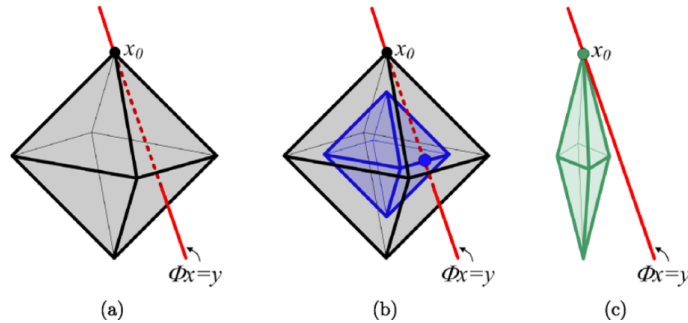


Fig. 1 Weighting ℓ_1 minimization to improve sparse signal recovery. (a) Sparse signal x_0 , feasible set $\Phi x = y$, and ℓ_1 ball of radius $\|x_0\|_{\ell_1}$. (b) There exists an $x \neq x_0$ for which $\|x\|_{\ell_1} < \|x_0\|_{\ell_1}$. (c) Weighted ℓ_1 ball. There exists no $x \neq x_0$ for which $\|Wx\|_{\ell_1} \leq \|Wx_0\|_{\ell_1}$

S. Boyd, "Enhancing Sparsity by Reweighted ℓ_1 Minimization", J Fourier Anal Appl (2008) 14:877-905

Implementation of Reweighted L_1 -norm

- Pseudo-code of **reweighted L_1 -norm**

Step 1. Implement conventional L_1 -norm
 $w_j = 1$

$$\begin{aligned} \underset{x}{\text{minimize}} \quad & \|Ax - b\|_2^2 + \lambda \|x\|_1 \\ & = \|Ax - b\|_2^2 + \lambda \sum_j |x_j| \end{aligned}$$

Step 2. With resulting x from step 1 ($x^{(l)}$),
compute reweighting matrix W

$$w_j^{(l)} = \frac{1}{|x_j^{(l)}| + \delta} \quad (\delta > 0)$$

Step 3. Execute L_1 Minimization with W
(initial guess : $x^{(l)}$)

$$\begin{aligned} \underset{x}{\text{minimize}} \quad & \|Ax - b\|_2^2 + \lambda \|W^{(l)} x\|_1 \\ & = \|Ax - b\|_2^2 + \lambda \sum_j w_j^{(l)} |x_j| \end{aligned}$$

Step 4. Repeat [Step 2] to [Step 3]
until convergence

$$\begin{aligned} w_j^{(k)} &= \frac{1}{|x_j^{(k)}| + \delta} \quad (\delta > 0) \\ \underset{x}{\text{minimize}} \quad & \|Ax - b\|_2^2 + \lambda \|W^{(k)} x\|_1 \end{aligned}$$

L_p-norm (p < 1) Minimization for Total-Variation

Implementation of Total-Variation Minimization by Reweighted L₁-norm

• Pseudo-code of Total-Variation reweighted L₁-norm

Step 1. Implement conventional L₁-norm

$$\underset{x}{\text{minimize}} \quad \frac{\mu}{2} \|Ax - b\|_2^2 + \|D_h x\|_1 + \|D_v x\|_1$$

Step 2. With resulting x from step 1 ($x^{(l)}$),
compute reweighting matrix W

$$w_{h,j}^{(l)} = \frac{1}{|D_h x_j^{(l)}| + \delta} \quad (\delta > 0), \quad w_{v,j}^{(l)} = \frac{1}{|D_v x_j^{(l)}| + \delta} \quad (\delta > 0)$$

Step 3. Execute L₁ Minimization with W
(initial guess : $x^{(l)}$)

$$\underset{x}{\text{minimize}} \quad \frac{\mu}{2} \|Ax - b\|_2^2 + \|W_h^{(l)}(D_h x)\|_1 + \|W_v^{(l)}(D_v x)\|_1$$

Step 4. Repeat [Step 2] to [Step 3]
until convergence

$$w_{h,j}^{(k)} = \frac{1}{|D_h x_j^{(k)}| + \delta} \quad (\delta > 0), \quad w_{v,j}^{(k)} = \frac{1}{|D_v x_j^{(k)}| + \delta} \quad (\delta > 0)$$

$$\underset{x}{\text{minimize}} \quad \frac{\mu}{2} \|Ax - b\|_2^2 + \|W_h^{(k)}(D_h x)\|_1 + \|W_v^{(k)}(D_v x)\|_1$$

L₀-norm with ADMM -- Reweighting Process

- Denoising with TV min.

$$\begin{aligned} \underset{x}{\text{minimize}} \quad & f(x) = g(x) + h_h(x) + h_v(x) = \frac{\mu}{2} \|x - f\|_2^2 + \|W_h(D_h x)\|_1 + \|W_v(D_v x)\|_1 \\ \Rightarrow \underset{x, d_h, d_v, b_h, b_v}{\text{minimize}} \quad & \frac{\mu}{2} \|x - f\|_2^2 + |d_h| + |d_v| + \frac{\lambda}{2} \|d_h - W_h(D_h x) - q_h\|_2^2 + \frac{\lambda}{2} \|d_v - W_v(D_v x) - q_v\|_2^2 \end{aligned}$$

Step 1. Update x : $\underset{x}{\text{minimize}} \quad \frac{\mu}{2} \|x - f\|_2^2 + \frac{\lambda}{2} \|d_h - W_h(D_h x) - q_h\|_2^2 + \frac{\lambda}{2} \|d_v - W_v(D_v x) - q_v\|_2^2$

Step 2. Update d_u, d_v :

$$\underset{d_h}{\text{minimize}} \quad |d_h| + \frac{\lambda}{2} \|d_h - W_h(D_h x) - q_h\|_2^2 \Rightarrow d_h^{k+1} = \text{SoftThreshold}\left(W_h(D_h x^{k+1}) + q_h^k, \frac{1}{\lambda}\right)$$

Step 3. Update q_h, q_v :

$$\underset{q_h}{\text{minimize}} \quad \frac{\lambda}{2} \|d_h - W_h(D_h x) - q_h\|_2^2 \Rightarrow q_h^{k+1} = q_h^k + (W_h(D_h x^{k+1}) - d_h^{k+1})$$

L₀-norm with Chambolle-Pock -- Reweighting Process

- Modifying the primal-dual solution (Chambolle-Pock algorithm)

$\begin{aligned} F(Kx) &= f_1(Ax) + f_2(D_h x) + f_3(D_v x), \quad G(x) = [x]_+ \\ f_1(y_1) &= \frac{\lambda}{2} \ y_1 - b\ _2^2 \quad (y_1 = Ax), \\ f_2(y_2) &= \ W_h \cdot y_2\ _1 \quad (y_2 = D_h x), \\ f_3(y_3) &= \ W_v \cdot y_3\ _1 \quad (y_3 = D_v x) \end{aligned}$	$\begin{aligned} y_l^{n+1} &= \text{prox}_{\sigma F^*}(y_l^n + \sigma \cdot K \tilde{x}^n) \\ x^{n+1} &= \text{prox}_{\tau G}(x^n - \tau \sum_l K^T y_l^{n+1}) \\ \tilde{x}^{n+1} &= x^{n+1} + \theta(x^{n+1} - x^n) \end{aligned}$
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$$\begin{aligned} y_2^{n+1} &= \text{prox}_{\sigma f_2^*}(y_2^n + \sigma \cdot W_h \cdot (D_h \tilde{x}^n)) = \text{Truncate}(y_2^n + \sigma \cdot W_h \cdot (D_h \tilde{x}^n), \sigma) \\ &= \begin{cases} y_2^n + \sigma \cdot W_h \cdot (D_h \tilde{x}^n) & (|y_2^n + \sigma \cdot W_h \cdot (D_h \tilde{x}^n)| < \sigma) \\ \sigma & (|y_2^n + \sigma \cdot W_h \cdot (D_h \tilde{x}^n)| > \sigma) \end{cases} \end{aligned}$$

$$\begin{aligned} x^{n+1} &= \text{prox}_{\tau G}(x^n - \tau \sum_l K^T y_l^{n+1}) \\ &= \left[x^n - \tau (A^T y_1^{n+1} + W_h(D_h^T y_2^{n+1}) + W_v(D_v^T y_3^{n+1})) \right]_+ \end{aligned}$$

L₀-norm with Chambolle-Pock

- Modifying the primal-dual solution (Chambolle-Pock algorithm)

$$\begin{aligned} & \underset{x}{\text{minimize}} \quad F(Kx) + G(x) \\ & y_l^{n+1} = \text{prox}_{\sigma F^*}(y_l^n + \sigma \cdot K\tilde{x}^n) \\ & x^{n+1} = \text{prox}_{\tau G}(x^n - \tau \sum_l K^T y_l^{n+1}) \Rightarrow \begin{aligned} & y^{n+1} = \text{prox}_{\sigma^{-1}F}(\sigma^{-1}y^n + Kx^n) \\ & z^{n+1} = z^n + \sigma(Kx^n - y^{n+1}) \\ & x^{n+1} = \text{prox}_{\tau G}(x^n - \tau \sum_l K^T y_l^{n+1}) \\ & \tilde{x}^{n+1} = x^{n+1} + \theta(x^{n+1} - x^n) \end{aligned} \end{aligned}$$

*Moreau's decomposition

$$\begin{aligned} x &= \text{prox}_{\sigma F}(x) + \sigma \cdot \text{prox}_{\sigma^{-1}F^*}(\sigma^{-1}x) \\ \Rightarrow \quad \text{prox}_{\sigma F^*}(\tilde{y}) &= \tilde{y} - \sigma \cdot \text{prox}_{\sigma^{-1}F}(\sigma^{-1}\tilde{y}) \end{aligned}$$

T. Mollenhoff et al, Low Rank Priors for Color Image Regularization. EMMCVPR 2015

Example of L₀ Minimization by Chambolle-Pock

$$\begin{aligned} & \underset{x}{\text{minimize}} \quad F(Kx) + G(x) = \frac{\mu}{2} \|Ax - b\|_2^2 + \|x\|_0 \quad (x \geq 0) \\ & F(Kx) = F\left(\begin{bmatrix} A \\ I \end{bmatrix} x\right) = f_1(Ax) + f_2(x), \quad G(x) = [x]_+ \\ & f_1(y_1) = \frac{\mu}{2} \|y_1 - b\|_2^2 \quad (y_1 = Ax), \quad f_2(y_2) = \|y_2\|_1 \quad (y_2 = x) \end{aligned}$$

Step 1. Update z 's:

$$\begin{aligned} z_1^{n+1} &= \text{prox}_{\sigma^{-1}F}(\sigma^{-1}y_1^n + A\tilde{x}^n) = \frac{(\sigma^{-1}y_1^n + A\tilde{x}^n) + \mu b / \sigma}{1 + (\mu / \sigma)} \\ z_2^{n+1} &= \text{prox}_{\sigma^{-1}F}(\sigma^{-1}y_2^n + \tilde{x}^n) = \begin{cases} \sigma^{-1}y_2^n + \tilde{x}^n & (|\sigma^{-1}y_2^n + \tilde{x}^n| \geq \sigma^{-1}) \\ 0 & (|\sigma^{-1}y_2^n + \tilde{x}^n| < \sigma^{-1}) \end{cases} \end{aligned}$$

Step 2. Update y 's:

$$\begin{aligned} y_1^{n+1} &= y_1^n + \sigma(Ax^n - z_1^{n+1}) \\ y_2^{n+1} &= y_2^n + \sigma(x^n - z_2^{n+1}) \end{aligned}$$

Step 3. Update x and \tilde{x} :

$$\begin{aligned} x^{n+1} &= \text{prox}_{\tau G}(x^n - \tau \sum_l K^T y_l^{n+1}) = \left[x^n - \tau(A^T y_1^{n+1} + y_2^{n+1}) \right]_+ \\ \tilde{x}^{n+1} &= x^{n+1} + \theta(x^{n+1} - x^n) \end{aligned}$$

Example of Total-Variation L_0 Minimization by Chambolle-Pock

$$F(Kx) = F\left(\begin{bmatrix} A \\ D_h \\ D_v \end{bmatrix} x\right) = f_1(Ax) + f_2(D_h x) + f_3(D_v x), \quad G(x) = [x]_+$$

$$f_1(y_1) = \frac{\mu}{2} \|y_1 - b\|_2^2 \quad (y_1 = Ax),$$

$$f_2(y_2) = \|y_2\|_1 \quad (y_2 = D_h x), \quad f_3(y_3) = \|y_3\|_1 \quad (y_3 = D_v x)$$

$$z^{n+1} = \text{prox}_{\sigma^{-1}F}(\sigma^{-1}y^n + Kx^n)$$

$$y^{n+1} = y^n + \sigma(Kx^n - z^{n+1})$$

$$x^{n+1} = \text{prox}_{\tau G}(x^n - \tau \sum_l K^T y_l^{n+1})$$

$$x^{n+1} = x^{n+1} + \theta(x^{n+1} - x^n)$$

Step 1. Update z 's:

$$z_1^{n+1} = \text{prox}_{\sigma^{-1}F}(\sigma^{-1}y_1^n + A\tilde{x}^n) = \frac{(\sigma^{-1}y_1^n + A\tilde{x}^n) + \mu b / \sigma}{1 + (\mu / \sigma)}$$

$$z_2^{n+1} = \text{prox}_{\sigma^{-1}F}(\sigma^{-1}y_2^n + D_h \tilde{x}^n) = \begin{cases} \sigma^{-1}y_2^n + D_h \tilde{x}^n & (|\sigma^{-1}y_2^n + D_h \tilde{x}^n| \geq \sigma^{-1}) \\ 0 & (|\sigma^{-1}y_2^n + D_h \tilde{x}^n| < \sigma^{-1}) \end{cases}$$

$$z_3^{n+1} = \text{prox}_{\sigma^{-1}f_3}(\sigma^{-1}y_3^n + D_v \tilde{x}^n) = \begin{cases} \sigma^{-1}y_3^n + D_v \tilde{x}^n & (|\sigma^{-1}y_3^n + D_v \tilde{x}^n| \geq \sigma^{-1}) \\ 0 & (|\sigma^{-1}y_3^n + D_v \tilde{x}^n| < \sigma^{-1}) \end{cases}$$

Example of Total-Variation L_0 Minimization by Chambolle-Pock

$$F(Kx) = F\left(\begin{bmatrix} A \\ D_h \\ D_v \end{bmatrix} x\right) = f_1(Ax) + f_2(D_h x) + f_3(D_v x), \quad G(x) = [x]_+$$

$$f_1(y_1) = \frac{\mu}{2} \|y_1 - b\|_2^2 \quad (y_1 = Ax),$$

$$f_2(y_2) = \|y_2\|_1 \quad (y_2 = D_h x), \quad f_3(y_3) = \|y_3\|_1 \quad (y_3 = D_v x)$$

$$z^{n+1} = \text{prox}_{\sigma^{-1}F}(\sigma^{-1}y^n + Kx^n)$$

$$y^{n+1} = y^n + \sigma(Kx^n - z^{n+1})$$

$$x^{n+1} = \text{prox}_{\tau G}(x^n - \tau \sum_l K^T y_l^{n+1})$$

$$x^{n+1} = x^{n+1} + \theta(x^{n+1} - x^n)$$

Step 2. Update y 's:

$$y_1^{n+1} = y_1^n + \sigma(Ax^n - z_1^{n+1})$$

$$y_2^{n+1} = y_2^n + \sigma(D_h x^n - z_2^{n+1})$$

$$y_3^{n+1} = y_3^n + \sigma(D_v x^n - z_3^{n+1})$$

Step 3. Update x and \tilde{x} :

$$x^{n+1} = \text{prox}_{\tau G}(x^n - \tau \sum_l K^T y_l^{n+1}) = [x^n - \tau(A^T y_1^{n+1} + y_2^{n+1} + y_3^{n+1})]_+$$

$$\tilde{x}^{n+1} = x^{n+1} + \theta(x^{n+1} - x^n)$$



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