

UNIVERSITY OF ABERDEEN

SESSION 2017–18

EM40JN

Degree Examination in EM40JN Heat and Momentum Transfer

8th December 2017

9 am – 11 am

PLEASE NOTE THE FOLLOWING

- (i) You **must not** have in your possession any material other than that expressly permitted in the rules appropriate to this examination. Where this is permitted, such material **must not** be amended, annotated or modified in any way.
- (ii) You **must not** have in your possession any material that could be determined as giving you an advantage in the examination.
- (iii) You **must not** attempt to communicate with any candidate during the exam, either orally or by passing written material, or by showing material to another candidate, nor must you attempt to view another candidate's work.
- (iv) You **must not** take to your examination desk any electronic devices such as mobile phones or other "smart" devices. The only exception to this rule is an approved calculator.

Failure to comply with the above will be regarded as cheating and may lead to disciplinary action as indicated in the Academic Quality Handbook.

Notes:

- (i) Candidates ARE permitted to use an approved calculator.*
- (ii) Candidates ARE NOT permitted to use the Engineering Mathematics Handbook.*
- (iii) Candidates ARE NOT permitted to use GREEN or RED pen in their exam booklet.*
- (iv) Data sheets are attached to the paper.*

Candidates must attempt ALL questions. Question 1 and 3 are worth 33 marks. Question 2 is worth 34 marks.

Question 1

Water is overflowing a dam and down an inclined slope (see Fig. 1). The surface of the dam can be idealised as a rectangular plane which is symmetric in the z -direction, and (for now) only laminar flow is being considered.

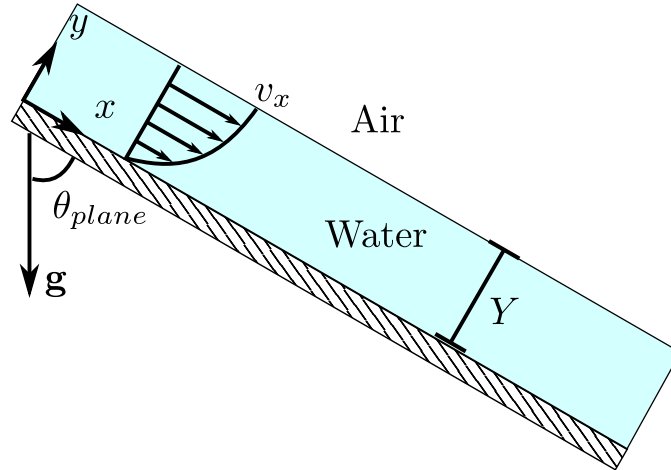


Figure 1: Water flowing down an inclined plane.

- a) Simplify the continuity equation for this system and state any assumptions you make. **[6 marks]**
- b) Derive the following results from the Cauchy momentum equation and the general form of Newton's law of viscosity: **[10 marks]**

$$\frac{\partial \tau_{yx}}{\partial y} = \rho g_x \qquad \tau_{yx} = -\mu \frac{\partial v_x}{\partial y}.$$

- c) Define your boundary conditions and derive the following expression for the velocity profile, **[9 marks]**

$$v_x = \frac{\rho g_x}{\mu} \left(Y y - \frac{y^2}{2} \right)$$

- d) Use an integration of the velocity over the flow area to determine the following expression for the volumetric flow rate, **[6 marks]**

$$\dot{V}_x = \frac{\rho g_x Y^3 Z}{3 \mu}.$$

- e) Provide an expression for the maximum flow velocity. **[2 marks]**

[Question total: 33marks]

Question 2

In prilling towers, molten fertilizer slurry is dripped to form frozen spherical pellets called prills. As a first approximation to understanding the heat transfer from the falling prills, consider a heated sphere of radius, R , and fixed surface temperature, T_R , suspended in a large, motionless body of fluid.

- a) Set up the differential equation describing the temperature, T , in the surrounding fluid as a function of r , the distance from the center of the sphere. The thermal conductivity, k , of the fluid is considered constant. **[14 marks]**
- b) Integrate the differential equation and use these boundary conditions to determine the integration constants: at $r = R$, $T = T_R$; and at $r = \infty$, $T = T_\infty$. **[8 marks]**
- c) From the temperature profile, obtain an expression for the heat flux at the surface. Equate this result to the heat flux given by “Newton’s law of cooling” and show that a dimensionless heat transfer coefficient (known as the Nusselt number) is given by,

$$\text{Nu} = \frac{hD}{k} = 2,$$

in which D is the sphere diameter.

[12 marks]

[Question total: 34marks]

Question 3

- a) Consider a large aluminium plate of thickness 0.12 m with initial uniform temperature of 85°C. Suddenly, the temperature of one of the faces is lowered to 20°C, while the other face is perfectly insulated. Assuming that the plate can be modelled as a 1D problem, the following thermal energy conservative equation can be used,

$$\rho C_p \frac{\partial T}{\partial t} = \kappa \frac{\partial^2 T}{\partial x^2} + S,$$

where ρ , C_p , t are density, heat capacity and time, respectively. κ and S are thermal conductivity coefficient and source term. Using the finite difference method (FDM) with spatial (Δx) and temporal (Δt) increments of 0.03 m and 300 s, respectively,

- i) Determine the number of nodes necessary to discretise the problem; **[2 marks]**
- ii) Describe the boundary and initial conditions for this problem; **[5 marks]**
- iii) Determine the temperature distribution of the plate at $t = 10$ minutes using the FDM, **[16 marks]**

Thermal diffusivity ($\alpha = \kappa \rho^{-1} C_p^{-1}$) of the plate is $1.5 \times 10^{-6} \text{ m}^2 \cdot \text{s}^{-1}$. The discretised form of the thermal energy equation is

$$\rho C_p \frac{T_i^{j+1} - T_i^j}{\Delta t} = \kappa \frac{T_{i+1}^j - 2T_i^j + T_{i-1}^j}{(\Delta x)^2} + S_i^j,$$

where i and j are spatial and temporal indices.

- b) A double-pipe (shell-and-tube) heat exchanger is constructed of a stainless steel ($\kappa = 15.1 \text{ W} \cdot \text{m}^{-1} \cdot ^\circ\text{C}^{-1}$) inner tube of inner diameter $D_i = 1.5 \text{ cm}$ and outer diameter $D_o = 1.9 \text{ cm}$ and an outer shell of inner diameter 3.2 cm. The convective heat transfer coefficient is $h_i = 800 \text{ W} \cdot \text{m}^{-2} \cdot ^\circ\text{C}^{-1}$ on the inner surface of the tube and $h_o = 1200 \text{ W} \cdot \text{m}^{-2} \cdot ^\circ\text{C}^{-1}$ on the outer surface. For a fouling factor $R_{f,i} = 0.0004 \text{ m}^2 \cdot ^\circ\text{C} \cdot \text{W}^{-1}$ on the tube side and $R_{f,o} = 0.0001 \text{ m}^2 \cdot ^\circ\text{C} \cdot \text{W}^{-1}$ on the shell side, determine:
- i) The thermal resistance of the heat exchanger per unit length (in $^\circ\text{C} \cdot \text{W}^{-1}$) and; **[3 marks]**
 - ii) The overall heat transfer coefficients, U_i and U_o (in $\text{W} \cdot \text{m}^{-2} \cdot ^\circ\text{C}^{-1}$) based on the inner and outer surface areas of the tube, respectively. **[7 marks]**

[Question total: 33marks]

END OF PAPER

DATASHEET

General balance equations:

$$\frac{\partial \rho}{\partial t} = -\nabla \cdot \rho \mathbf{v} \quad (\text{Mass/Continuity}) \quad (1)$$

$$\frac{\partial C_A}{\partial t} = -\nabla \cdot \mathbf{N}_A + \sigma_A \quad (\text{Species}) \quad (2)$$

$$\rho \frac{\partial \mathbf{v}}{\partial t} = -\rho \mathbf{v} \cdot \nabla \mathbf{v} - \nabla \cdot \boldsymbol{\tau} - \nabla p + \rho \mathbf{g} \quad (\text{Momentum}) \quad (3)$$

$$\rho C_p \frac{\partial T}{\partial t} = -\rho C_p \mathbf{v} \cdot \nabla T - \nabla \cdot \mathbf{q} - \boldsymbol{\tau} : \nabla \mathbf{v} - p \nabla \cdot \mathbf{v} + \sigma_{\text{energy}} \quad (\text{Heat/Energy}) \quad (4)$$

In Cartesian coordinate systems, ∇ can be treated as a vector of derivatives. In curve-linear coordinate systems, the directions $\hat{\mathbf{r}}$, $\hat{\boldsymbol{\theta}}$, and $\hat{\boldsymbol{\phi}}$ depend on the position. For convenience in these systems, look-up tables are provided for common terms involving ∇ .

Cartesian coordinates (with index notation examples)

where s is a scalar, \mathbf{v} is a vector, and $\boldsymbol{\tau}$ is a tensor.

$$\begin{aligned} \nabla s &= \nabla_i s = \left[\frac{\partial s}{\partial x}, \frac{\partial s}{\partial y}, \frac{\partial s}{\partial z} \right] \\ \nabla^2 s &= \nabla_i \nabla_i s = \frac{\partial^2 s}{\partial x^2} + \frac{\partial^2 s}{\partial y^2} + \frac{\partial^2 s}{\partial z^2} \\ \nabla \cdot \mathbf{v} &= \nabla_i v_i = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \\ \nabla \cdot \boldsymbol{\tau} &= \nabla_i \tau_{ij} \\ [\nabla \cdot \boldsymbol{\tau}]_x &= \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} \\ [\nabla \cdot \boldsymbol{\tau}]_y &= \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} \\ [\nabla \cdot \boldsymbol{\tau}]_z &= \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} \\ \mathbf{v} \cdot \nabla \mathbf{v} &= v_i \nabla_i v_j \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_x &= v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_y &= v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_z &= v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \end{aligned}$$

Cylindrical coordinates

where s is a scalar, \mathbf{v} is a vector, and τ is a tensor. All expressions involving τ are for symmetrical τ only.

$$\begin{aligned}\nabla s &= \left[\frac{\partial s}{\partial r}, \frac{1}{r} \frac{\partial s}{\partial \theta}, \frac{\partial s}{\partial z} \right] \\ \nabla^2 s &= \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial s}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 s}{\partial \theta^2} + \frac{\partial^2 s}{\partial z^2} \\ \nabla \cdot \mathbf{v} &= \frac{1}{r} \frac{\partial}{\partial r} (r v_r) + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_z}{\partial z} \\ [\nabla \cdot \tau]_r &= \frac{1}{r} \frac{\partial}{\partial r} (r \tau_{rr}) + \frac{1}{r} \frac{\partial \tau_{r\theta}}{\partial \theta} - \frac{1}{r} \tau_{\theta\theta} + \frac{\partial \tau_{rz}}{\partial z} \\ [\nabla \cdot \tau]_\theta &= \frac{1}{r} \frac{\partial \tau_{\theta\theta}}{\partial \theta} + \frac{\partial \tau_{r\theta}}{\partial r} + \frac{2}{r} \tau_{r\theta} + \frac{\partial \tau_{\theta z}}{\partial z} \\ [\nabla \cdot \tau]_z &= \frac{1}{r} \frac{\partial}{\partial r} (r \tau_{rz}) + \frac{1}{r} \frac{\partial \tau_{\theta z}}{\partial \theta} + \frac{\partial \tau_{zz}}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_r &= v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_\theta &= v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_z &= v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z}\end{aligned}$$

Spherical coordinates

where s is a scalar, \mathbf{v} is a vector, and τ is a tensor. All expressions involving τ are for symmetrical τ only.

$$\begin{aligned}\nabla s &= \left[\frac{\partial s}{\partial r}, \frac{1}{r} \frac{\partial s}{\partial \theta}, \frac{1}{r \sin \theta} \frac{\partial s}{\partial \phi} \right] \\ \nabla^2 s &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial s}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial s}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 s}{\partial \phi^2} \\ \nabla \cdot \mathbf{v} &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} \\ [\nabla \cdot \tau]_r &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_{rr}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\tau_{r\theta} \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial \tau_{r\phi}}{\partial \phi} - \frac{\tau_{\theta\theta} + \tau_{\phi\phi}}{r} \\ [\nabla \cdot \tau]_\theta &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_{r\theta}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\tau_{\theta\theta} \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial \tau_{\theta\phi}}{\partial \phi} + \frac{\tau_{r\theta}}{r} - \frac{\cot \theta}{r} \tau_{\phi\phi} \\ [\nabla \cdot \tau]_\phi &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \tau_{r\phi}) + \frac{1}{r} \frac{\partial \tau_{\theta\phi}}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial \tau_{\phi\phi}}{\partial \phi} + \frac{\tau_{r\theta}}{r} + \frac{2 \cot \theta}{r} \tau_{\theta\phi} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_r &= v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_\theta &= v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta - v_\phi^2 \cot \theta}{r} \\ [\mathbf{v} \cdot \nabla \mathbf{v}]_\phi &= v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r v_\phi + v_\theta v_\phi \cot \theta}{r}\end{aligned}$$

Rectangular		Cylindrical		Spherical	
q_x	$-k \frac{\partial T}{\partial x}$	q_r	$-k \frac{\partial T}{\partial r}$	q_r	$-k \frac{\partial T}{\partial r}$
q_y	$-k \frac{\partial T}{\partial y}$	q_θ	$-k \frac{1}{r} \frac{\partial T}{\partial \theta}$	q_θ	$-k \frac{1}{r} \frac{\partial T}{\partial \theta}$
q_z	$-k \frac{\partial T}{\partial z}$	q_z	$-k \frac{\partial T}{\partial z}$	q_ϕ	$-k \frac{1}{r \sin \theta} \frac{\partial T}{\partial \phi}$
τ_{xx}	$-2\mu \frac{\partial v_x}{\partial x} + \mu^B \nabla \cdot \mathbf{v}$	τ_{rr}	$-2\mu \frac{\partial v_r}{\partial r} + \mu^B \nabla \cdot \mathbf{v}$	τ_{rr}	$-2\mu \frac{\partial v_r}{\partial r} + \mu^B \nabla \cdot \mathbf{v}$
τ_{yy}	$-2\mu \frac{\partial v_y}{\partial y} + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{\theta\theta}$	$-2\mu \left(\frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r} \right) + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{\theta\theta}$	$-2\mu \left(\frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r} \right) + \mu^B \nabla \cdot \mathbf{v}$
τ_{zz}	$-2\mu \frac{\partial v_z}{\partial z} + \mu^B \nabla \cdot \mathbf{v}$	τ_{zz}	$-2\mu \frac{\partial v_z}{\partial z} + \mu^B \nabla \cdot \mathbf{v}$	$\tau_{\phi\phi}$	$-2\mu \left(\frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + \frac{v_r + v_\theta \cot \theta}{r} \right) + \mu^B \nabla \cdot \mathbf{v}$
τ_{xy}	$-\mu \left(\frac{\partial v_x}{\partial y} + \frac{\partial v_y}{\partial x} \right)$	$\tau_{r\theta}$	$-\mu \left(r \frac{\partial}{\partial r} \left(\frac{v_\theta}{r} \right) + \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right)$	$\tau_{r\theta}$	$-\mu \left(r \frac{\partial}{\partial r} \left(\frac{v_\theta}{r} \right) + \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right)$
τ_{yz}	$-\mu \left(\frac{\partial v_y}{\partial z} + \frac{\partial v_z}{\partial y} \right)$	$\tau_{\theta z}$	$-\mu \left(\frac{1}{r} \frac{\partial v_z}{\partial \theta} + \frac{\partial v_\theta}{\partial z} \right)$	$\tau_{\theta\phi}$	$-\mu \left(\frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \left(\frac{v_\phi}{\sin \theta} \right) + \frac{1}{r \sin \theta} \frac{\partial v_\theta}{\partial \phi} \right)$
τ_{xz}	$-\mu \left(\frac{\partial v_x}{\partial z} + \frac{\partial v_z}{\partial x} \right)$	τ_{zr}	$-\mu \left(\frac{\partial v_r}{\partial z} + \frac{\partial v_z}{\partial r} \right)$	$\tau_{\phi r}$	$-\mu \left(\frac{1}{r \sin \theta} \frac{\partial v_r}{\partial \phi} + r \frac{\partial}{\partial r} \left(\frac{v_\phi}{r} \right) \right)$

Table 1: Fourier's law for the heat flux and Newton's law for the stress in several coordinate systems. Please remember that the stress is symmetric, so $\tau_{ij} = \tau_{ji}$.

Viscous models:

Power-Law Fluid:

$$|\tau_{xy}| = k \left| \frac{\partial v_x}{\partial y} \right|^n \quad (5)$$

Bingham-Plastic Fluid:

$$\frac{\partial v_x}{\partial y} = \begin{cases} -\mu^{-1} (\tau_{xy} - \tau_0) & \text{if } \tau_{xy} > \tau_0 \\ 0 & \text{if } \tau_{xy} \leq \tau_0 \end{cases}$$

Dimensionless Numbers

$$\text{Re} = \frac{\rho \langle v \rangle D}{\mu} \quad \text{Re}_H = \frac{\rho \langle v \rangle D_H}{\mu} \quad \text{Re}_{MR} = -\frac{16 L \rho \langle v \rangle^2}{R \Delta p} \quad (6)$$

The hydraulic diameter is defined as $D_H = 4 A / P_w$.

Single phase pressure drop calculations in pipes:

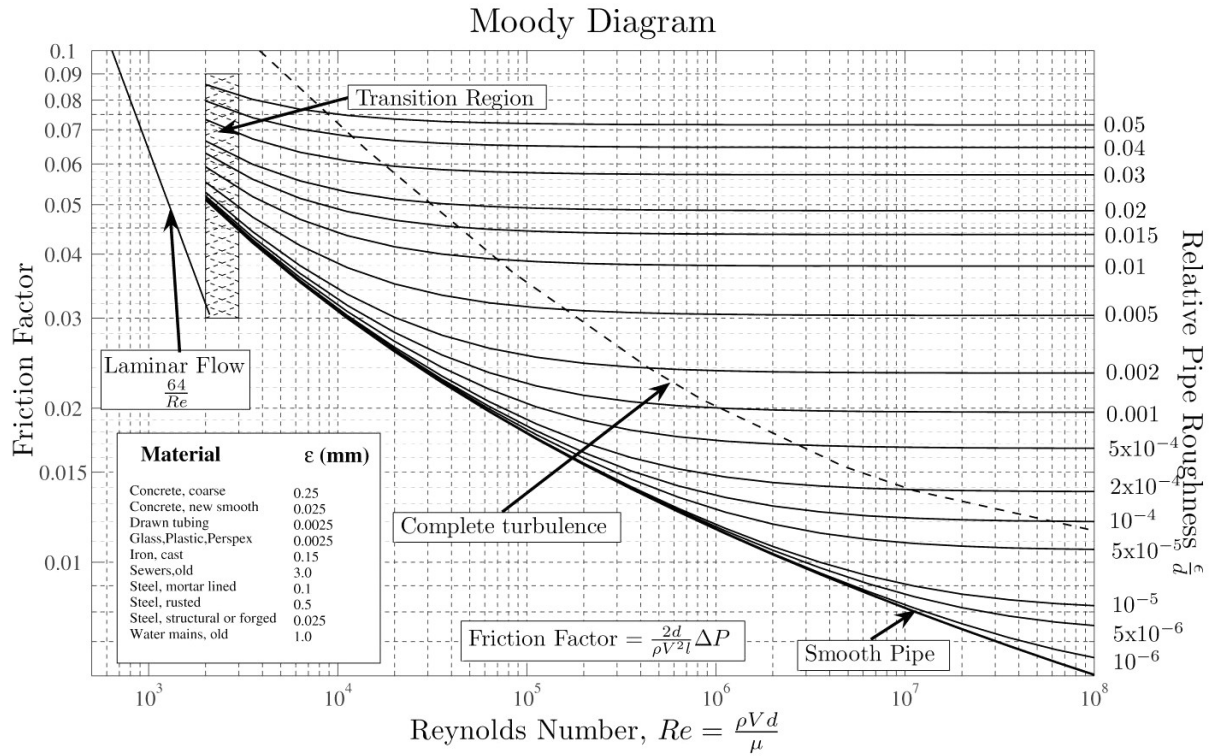
Darcy-Weisbach equation:

$$\frac{\Delta p}{L} = -\frac{C_f \rho \langle v \rangle^2}{R} \quad (7)$$

where $C_f = 16/Re$ for laminar Newtonian flow. For turbulent flow of Newtonian fluids in smooth pipes, we have the Blasius correlation:

$$C_f = 0.079 Re^{-1/4} \quad \text{for } 2.5 \times 10^3 < Re < 10^5 \text{ and smooth pipes.}$$

Otherwise, you may refer to the Moody diagram.



Laminar Power-Law fluid:

$$\dot{V} = \frac{n \pi R^3}{3n+1} \left(\frac{R}{2k} \right)^{\frac{1}{n}} \left(-\frac{\Delta p}{L} \right)^{\frac{1}{n}}$$

Two-Phase Flow:

Lockhart-Martinelli parameter:

$$X^2 = \frac{\Delta p_{liq.-only}}{\Delta p_{gas-only}}$$

Pressure drop calculation:

$$\Delta p_{two-phase} = \Phi_{liq.}^2 \Delta p_{liq.-only} = \Phi_{gas}^2 \Delta p_{gas-only}$$

Chisholm's relation:

$$\Phi_{gas}^2 = 1 + cX + X^2$$

$$\Phi_{liq.}^2 = 1 + \frac{c}{X} + \frac{1}{X^2}$$

$$c = \begin{cases} 20 & \text{turbulent liquid \& turbulent gas} \\ 12 & \text{laminar liquid \& turbulent gas} \\ 10 & \text{turbulent liquid \& laminar gas} \\ 5 & \text{laminar liquid \& laminar gas} \end{cases}$$

Farooqi and Richardson expression for liquid hold-up in co-current flows of Newtonian fluids and air in horizontal pipes:

$$h = \begin{cases} 0.186 + 0.0191 X & 1 < X < 5 \\ 0.143 X^{0.42} & 5 < X < 50 \\ 1 / (0.97 + 19/X) & 50 < X < 500 \end{cases}$$

Heat Transfer Dimensionless numbers:

$$\text{Nu} = \frac{hL}{k} \quad \text{Pr} = \frac{\mu C_p}{k} \quad \text{Gr} = \frac{g \beta (T_w - T_\infty) L^3}{\nu^2}$$

where $\beta = V^{-1}(\partial V / \partial T)$.

Heat transfer: Resistances

$$Q = U_T A_T \Delta T = R_T^{-1} \Delta T$$

	Conduction Shell Resistances			Radiation
	Rect.	Cyl.	Sph.	
R	$\frac{X}{kA}$	$\frac{\ln(R_{outer}/R_{inner})}{2\pi Lk}$	$\frac{R_{inner}^{-1} - R_{outer}^{-1}}{4\pi k}$	$\left[A \varepsilon \sigma (T_j^2 + T_i^2) (T_j + T_i) \right]^{-1}$

Radiation Heat Transfer:

Stefan-Boltzmann constant $\sigma = 5.6703 \times 10^{-8} \text{ W m}^{-2} \text{ K}^{-4}$.

Summation relationship, $\sum_j F_{i \rightarrow j} = 1$, and reciprocity relationship, $F_{i \rightarrow j} A_i = F_{j \rightarrow i} A_j$.

Radiation shielding factor $1/(N+1)$.

$$Q_{rad., i \rightarrow j} = \sigma \varepsilon F_{i \rightarrow j} A_i (T_j^4 - T_i^4) = h_{rad.} A (T_\infty - T_w)$$

Natural Convection

Ra = Gr Pr	C	m
$< 10^4$	1.36	1/5
$10^4 - 10^9$	0.59	1/4
$> 10^9$	0.13	1/3

Table 2: Natural convection coefficients for isothermal vertical plates in the empirical relation $Nu \approx C (Gr Pr)^m$.

For isothermal vertical cylinders, the above expressions for isothermal vertical plates may be used but must be scaled by a factor, F (i.e., $Nu_{v.cyl.} = F Nu_{v.plate}$):

$$F = \begin{cases} 1 & \text{for } (D/H) \geq 35 Gr_H^{-1/4} \\ 1.3 [H D^{-1} Gr_D^{-1}]^{1/4} + 1 & \text{for } (D/H) < 35 Gr_H^{-1/4} \end{cases}$$

where D is the diameter and H is the height of the cylinder. The subscript on Gr indicates which length is to be used as the critical length to calculate the Grashof number.

Churchill and Chu expression for natural convection from a horizontal pipe:

$$Nu^{1/2} = 0.6 + 0.387 \left\{ \frac{Gr Pr}{[1 + (0.559/Pr)^{9/16}]^{16/9}} \right\}^{1/6} \quad \text{for } 10^{-5} < Gr Pr < 10^{12}$$

Forced Convection:

Laminar flows:

$$Nu \approx 0.332 Re^{1/2} Pr^{1/3}$$

Well-Developed turbulent flows in smooth pipes:

$$Nu \approx \frac{(C_f/2) Re Pr}{1.07 + 12.7(C_f/2)^{1/2} (Pr^{2/3} - 1)} \left(\frac{\mu_b}{\mu_w} \right)^{0.14}$$

Boiling:

Forster-Zuber pool-boiling coefficient:

$$h_{nb} = 0.00122 \frac{k_L^{0.79} C_{p,L}^{0.45} \rho_L^{0.49}}{\gamma^{0.5} \mu_L^{0.29} h_{fg}^{0.24} \rho_G^{0.24}} (T_w - T_{sat})^{0.24} (p_w - p_{sat})^{0.75}$$

Mostinski correlations:

$$h_{nb} = 0.104 p_c^{0.69} q^{0.7} \left[1.8 \left(\frac{p}{p_c} \right)^{0.17} + 4 \left(\frac{p}{p_c} \right)^{1.2} + 10 \left(\frac{p}{p_c} \right)^{10} \right]$$

$$q_c = 3.67 \times 10^4 p_c \left(\frac{p}{p_c} \right)^{0.35} \left[1 - \frac{p}{p_c} \right]^{0.9}$$

(Note: for the Mostinski correlations, the pressures are in units of bar)

Condensing:

Horizontal pipes

$$h = 0.72 \left(\frac{k^3 \rho^2 g_x E_{latent}}{D \mu (T_w - T_\infty)} \right)^{1/4}$$

Lumped capacitance method:

$$\text{Bi} = \frac{h L_c}{\kappa}$$

$$L_c = V/A \quad \text{for Bi} < 0.1$$

$$\frac{T(t) - T_\infty}{T_0 - T_\infty} = e^{-bt} \quad b = \frac{hA_s}{\rho V C_p}$$

1-D Transient Heat Conduction:

$$Fo = \frac{\alpha \Delta t}{(\Delta x)^2} = \tau, \quad \alpha = \kappa (\rho C_p)^{-1}$$

$$\theta_{\text{wall}} = \frac{T(x, t) - T_\infty}{T_i - T_\infty} = A_1 e^{-\lambda_1^2 \tau} \cos\left(\frac{\lambda_1 x}{L}\right), \quad \theta_{\text{cyl}} = \frac{T(r, t) - T_\infty}{T_i - T_\infty} = A_1 e^{-\lambda_1^2 \tau} \mathbf{J}_0\left(\frac{\lambda_1 r}{r_0}\right)$$

$$\theta_{\text{sph}} = \frac{T(r, t) - T_\infty}{T_i - T_\infty} = A_1 e^{-\lambda_1^2 \tau} \frac{\sin\left(\frac{\lambda_1 r}{r_0}\right)}{\frac{\lambda_1 r}{r_0}}$$

$$\theta_{0,\text{wall}} = \theta_{0,\text{cyl}} = \theta_{0,\text{sph}} = \frac{T_0 - T_\infty}{T_i - T_\infty} = A_1 e^{-\lambda_1^2 \tau}$$

$$\left(\frac{Q}{Q_{\text{max}}}\right)_{\text{wall}} = 1 - \theta_{0,\text{wall}} \frac{\sin \lambda_1}{\lambda_1}, \quad \left(\frac{Q}{Q_{\text{max}}}\right)_{\text{cyl}} = 1 - 2\theta_{0,\text{cyl}} \frac{\mathbf{J}_1(\lambda_1)}{\lambda_1}$$

$$\left(\frac{Q}{Q_{\text{max}}}\right)_{\text{sph}} = 1 - 3\theta_{0,\text{sph}} \frac{\sin \lambda_1 - \lambda_1 \cos \lambda_1}{\lambda_1^3}$$

Finite-Difference Method:

$$\frac{\partial}{\partial t}(\rho \phi) + \frac{\partial}{\partial x}(\rho \mathbf{v} \phi) = \nabla \cdot (\Gamma \nabla \phi) + \mathcal{S} \quad (1D \text{ transport equation})$$

$$\left(\frac{d\phi}{dx}\right)_i = \frac{\phi_{i+1} - \phi_{i-1}}{2\Delta x} \quad \text{and} \quad \left(\frac{d^2\phi}{dx^2}\right)_i = \frac{\phi_{i-1} + \phi_{i+1} - 2\phi_i}{(\Delta x)^2}$$

$$T_i^{j+1} = (1 - 2\tau) T_i^j + \tau (T_{i+1}^j + T_{i-1}^j) + \frac{\tau (\Delta x)^2}{\kappa} S_i^j$$

Overall Heat Transfer Coefficient:

$$\dot{Q} = \frac{\Delta T}{\mathcal{R}} = UA\Delta T = U_i A_i \Delta T = U_o A_o \Delta T$$

$$\mathcal{R} = R_i + R_{\text{wall}} + R_o = \frac{1}{h_i A_i} + \frac{\ln D_o/D_i}{2\pi\kappa L} + \frac{1}{h_o A_o}$$

Fouling Factor:

$$\mathcal{R} = \frac{1}{h_i A_i} + \frac{R_{f,i}}{A_i} + R_{\text{wall}} + \frac{R_{f,o}}{A_o} + \frac{1}{h_o A_o}$$

LMTD Method:

$$\dot{Q} = UA_s \Delta T_{\text{lm}} \quad \text{with} \quad \Delta T_{\text{lm}} = \frac{\Delta T_2 - \Delta T_1}{\ln \frac{\Delta T_2}{\Delta T_1}} = \frac{\Delta T_1 - \Delta T_2}{\ln \frac{\Delta T_1}{\Delta T_2}}$$

$$\text{Parallel flows: } \begin{cases} \Delta T_1 = T_{\text{hot,in}} - T_{\text{cold,in}} \\ \Delta T_2 = T_{\text{hot,out}} - T_{\text{cold,out}} \end{cases}$$

$$\text{Counter flows: } \begin{cases} \Delta T_1 = T_{\text{hot,in}} - T_{\text{cold,out}} \\ \Delta T_2 = T_{\text{hot,out}} - T_{\text{cold,in}} \end{cases}$$

ϵ -NTU Method:

$$\epsilon = \frac{\dot{Q}}{\dot{Q}_{\text{max}}}, \quad \text{with } \dot{Q}_{\text{max}} = C_{\min} (T_{\text{hot,in}} - T_{\text{cold,in}}) \quad \text{and} \quad C_{\min} = \text{Min} \{ \dot{m}_{\text{hot}} C_{p,\text{hot}}, \dot{m}_{\text{cold}} C_{p,\text{cold}} \}$$

$$\text{NTU} = \frac{UA_s}{C_{\min}}$$

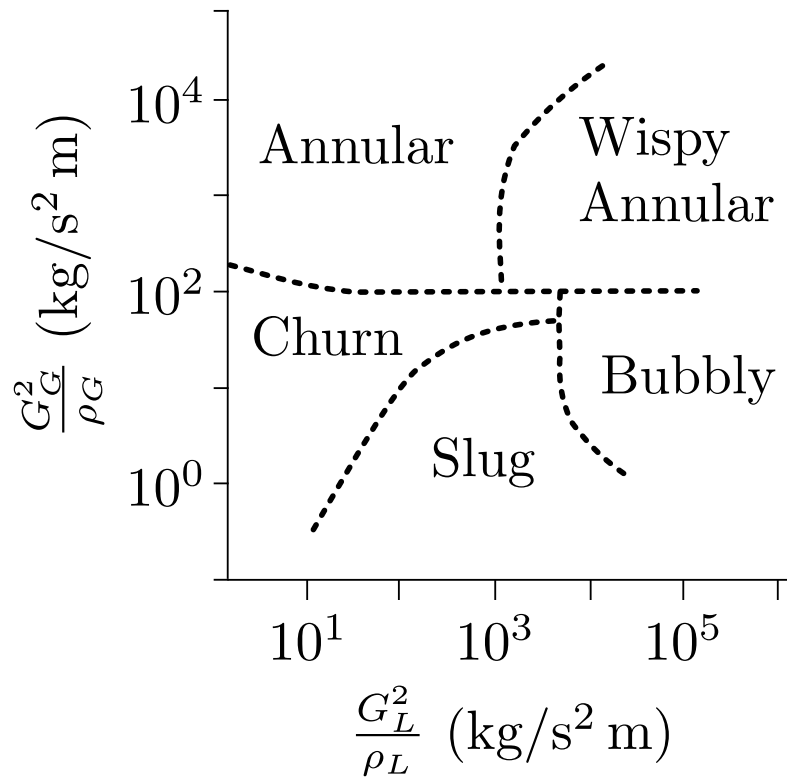


Figure 2: *Hewitt-Taylor flow pattern map for multiphase flows in vertical pipes.*

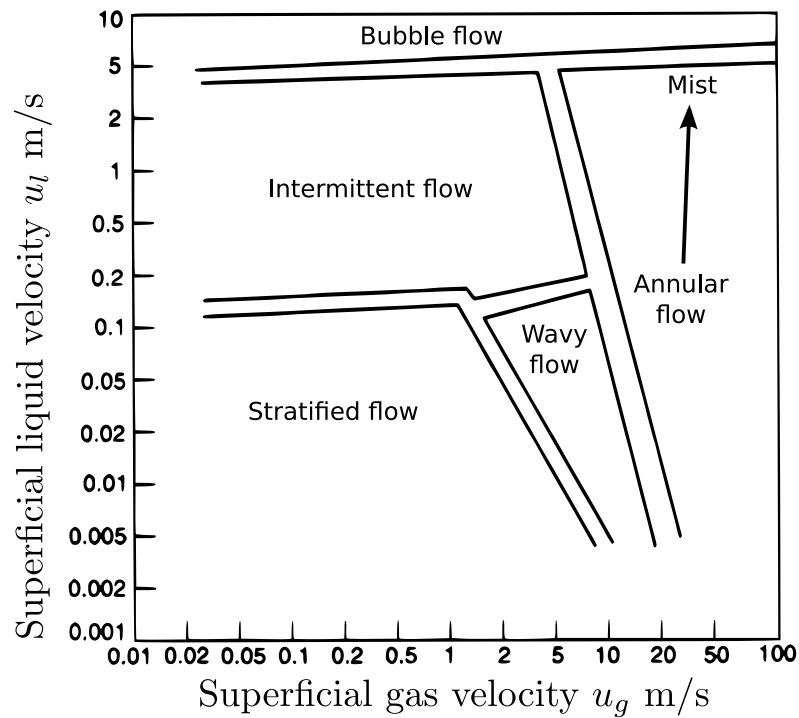


Figure 3: *Chhabra and Richardson flow pattern map for horizontal pipes.*

TABLE 4–2

Coefficients used in the one-term approximate solution of transient one-dimensional heat conduction in plane walls, cylinders, and spheres ($Bi = hL/k$ for a plane wall of thickness $2L$, and $Bi = hr_o/k$ for a cylinder or sphere of radius r_o)

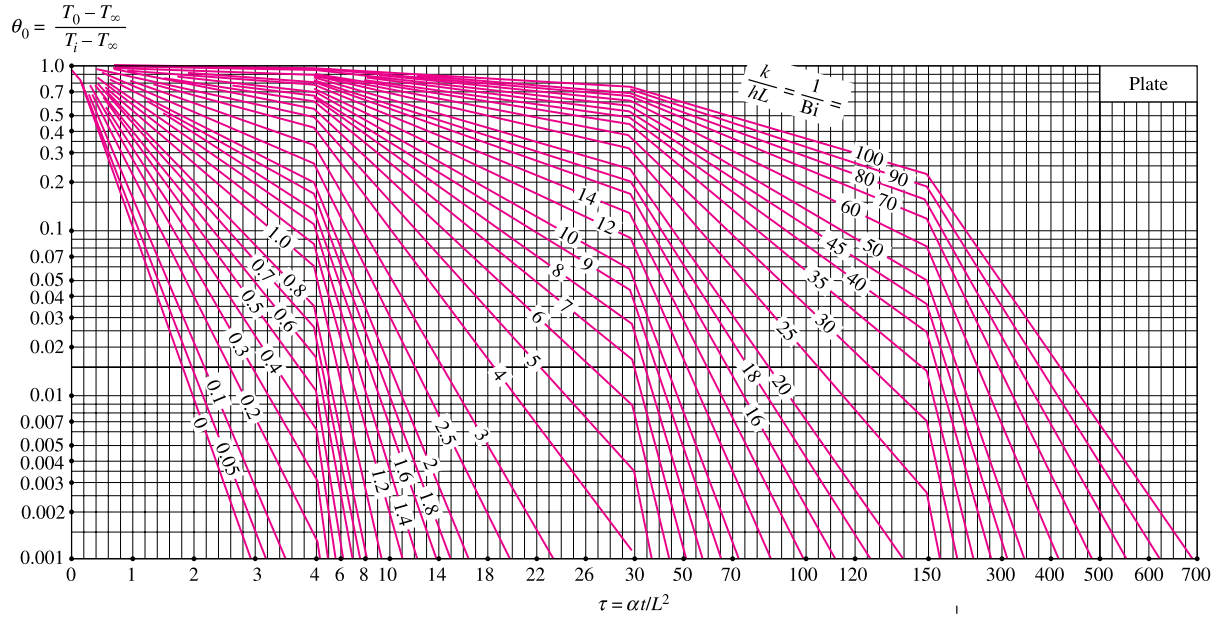
Bi	Plane Wall		Cylinder		Sphere	
	λ_1	A_1	λ_1	A_1	λ_1	A_1
0.01	0.0998	1.0017	0.1412	1.0025	0.1730	1.0030
0.02	0.1410	1.0033	0.1995	1.0050	0.2445	1.0060
0.04	0.1987	1.0066	0.2814	1.0099	0.3450	1.0120
0.06	0.2425	1.0098	0.3438	1.0148	0.4217	1.0179
0.08	0.2791	1.0130	0.3960	1.0197	0.4860	1.0239
0.1	0.3111	1.0161	0.4417	1.0246	0.5423	1.0298
0.2	0.4328	1.0311	0.6170	1.0483	0.7593	1.0592
0.3	0.5218	1.0450	0.7465	1.0712	0.9208	1.0880
0.4	0.5932	1.0580	0.8516	1.0931	1.0528	1.1164
0.5	0.6533	1.0701	0.9408	1.1143	1.1656	1.1441
0.6	0.7051	1.0814	1.0184	1.1345	1.2644	1.1713
0.7	0.7506	1.0918	1.0873	1.1539	1.3525	1.1978
0.8	0.7910	1.1016	1.1490	1.1724	1.4320	1.2236
0.9	0.8274	1.1107	1.2048	1.1902	1.5044	1.2488
1.0	0.8603	1.1191	1.2558	1.2071	1.5708	1.2732
2.0	1.0769	1.1785	1.5995	1.3384	2.0288	1.4793
3.0	1.1925	1.2102	1.7887	1.4191	2.2889	1.6227
4.0	1.2646	1.2287	1.9081	1.4698	2.4556	1.7202
5.0	1.3138	1.2403	1.9898	1.5029	2.5704	1.7870
6.0	1.3496	1.2479	2.0490	1.5253	2.6537	1.8338
7.0	1.3766	1.2532	2.0937	1.5411	2.7165	1.8673
8.0	1.3978	1.2570	2.1286	1.5526	2.7654	1.8920
9.0	1.4149	1.2598	2.1566	1.5611	2.8044	1.9106
10.0	1.4289	1.2620	2.1795	1.5677	2.8363	1.9249
20.0	1.4961	1.2699	2.2880	1.5919	2.9857	1.9781
30.0	1.5202	1.2717	2.3261	1.5973	3.0372	1.9898
40.0	1.5325	1.2723	2.3455	1.5993	3.0632	1.9942
50.0	1.5400	1.2727	2.3572	1.6002	3.0788	1.9962
100.0	1.5552	1.2731	2.3809	1.6015	3.1102	1.9990
∞	1.5708	1.2732	2.4048	1.6021	3.1416	2.0000

TABLE 4–3

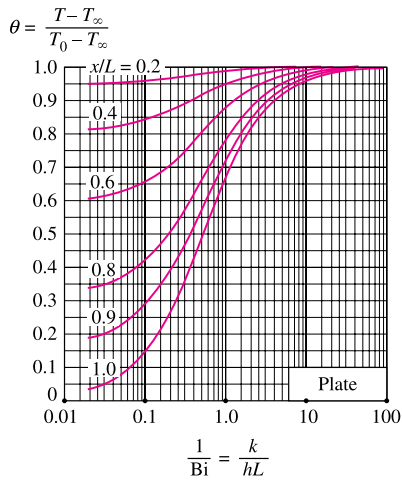
The zeroth- and first-order Bessel functions of the first kind

η	$J_0(\eta)$	$J_1(\eta)$
0.0	1.0000	0.0000
0.1	0.9975	0.0499
0.2	0.9900	0.0995
0.3	0.9776	0.1483
0.4	0.9604	0.1960
0.5	0.9385	0.2423
0.6	0.9120	0.2867
0.7	0.8812	0.3290
0.8	0.8463	0.3688
0.9	0.8075	0.4059
1.0	0.7652	0.4400
1.1	0.7196	0.4709
1.2	0.6711	0.4983
1.3	0.6201	0.5220
1.4	0.5669	0.5419
1.5	0.5118	0.5579
1.6	0.4554	0.5699
1.7	0.3980	0.5778
1.8	0.3400	0.5815
1.9	0.2818	0.5812
2.0	0.2239	0.5767
2.1	0.1666	0.5683
2.2	0.1104	0.5560
2.3	0.0555	0.5399
2.4	0.0025	0.5202
2.6	−0.0968	−0.4708
2.8	−0.1850	−0.4097
3.0	−0.2601	−0.3391
3.2	−0.3202	−0.2613

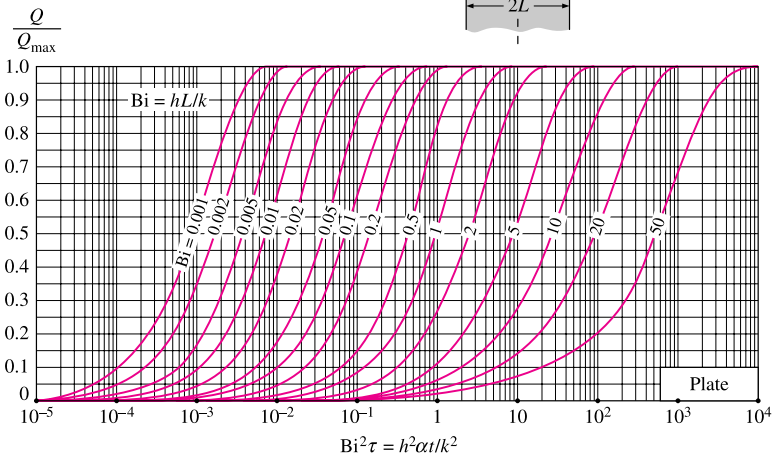
Figure 4: Coefficients for the 1D transient equations.



(a) Midplane temperature (from M. P. Heisler, "Temperature Charts for Induction and Constant Temperature Heating," *Trans. ASME* 69, 1947, pp. 227-36. Reprinted by permission of ASME International.)



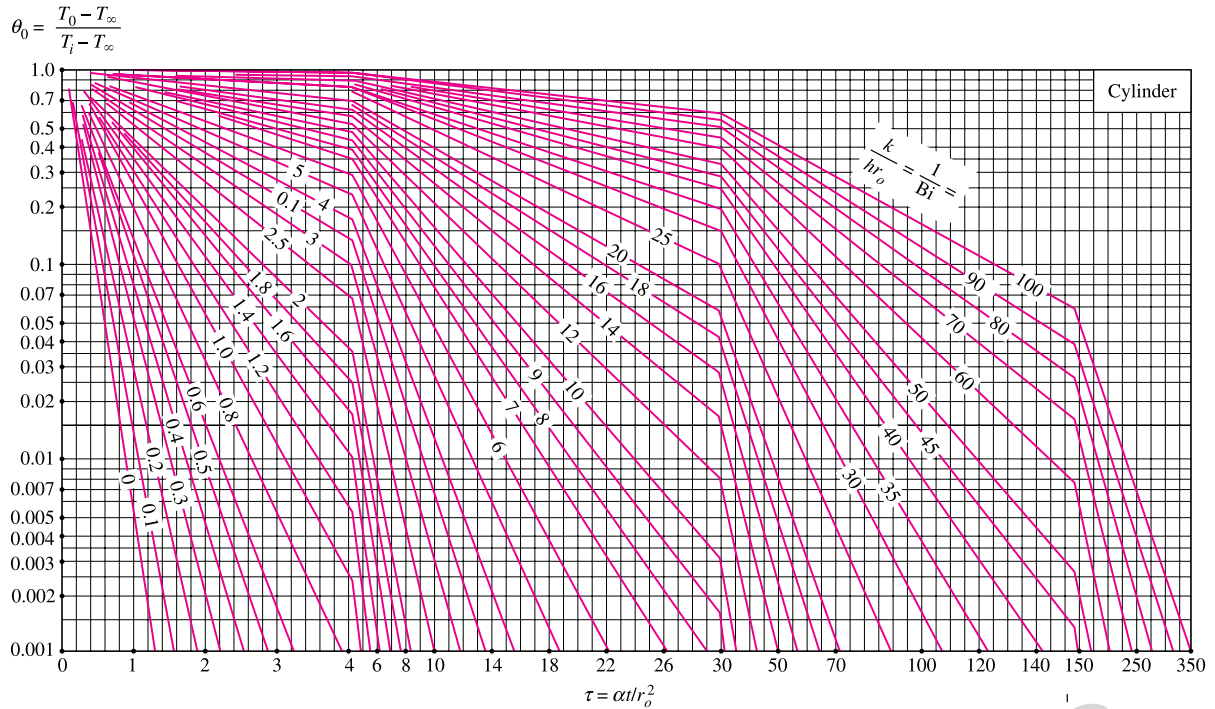
(b) Temperature distribution (from M. P. Heisler, "Temperature Charts for Induction and Constant Temperature Heating," *Trans. ASME* 69, 1947, pp. 227-36. Reprinted by permission of ASME International.)



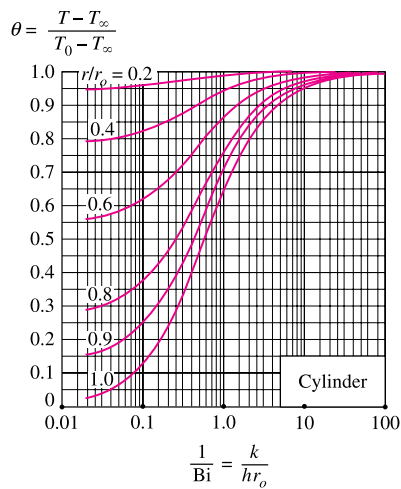
(c) Heat transfer (from H. Gröber et al.)

Transient temperature and heat transfer charts for a plane wall of thickness $2L$ initially at a uniform temperature T_i subjected to convection from both sides to an environment at temperature T_∞ with a convection coefficient of h .

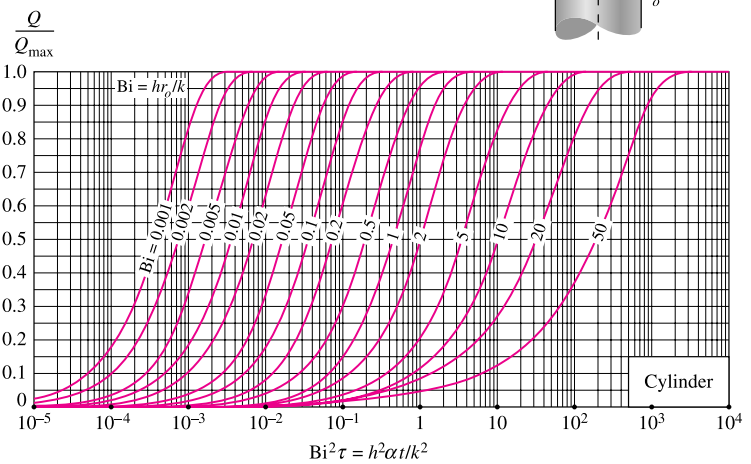
Figure 5:



(a) Centerline temperature (from M. P. Heisler, "Temperature Charts for Induction and Constant Temperature Heating," *Trans. ASME* 69, 1947, pp. 227–36. Reprinted by permission of ASME International.)



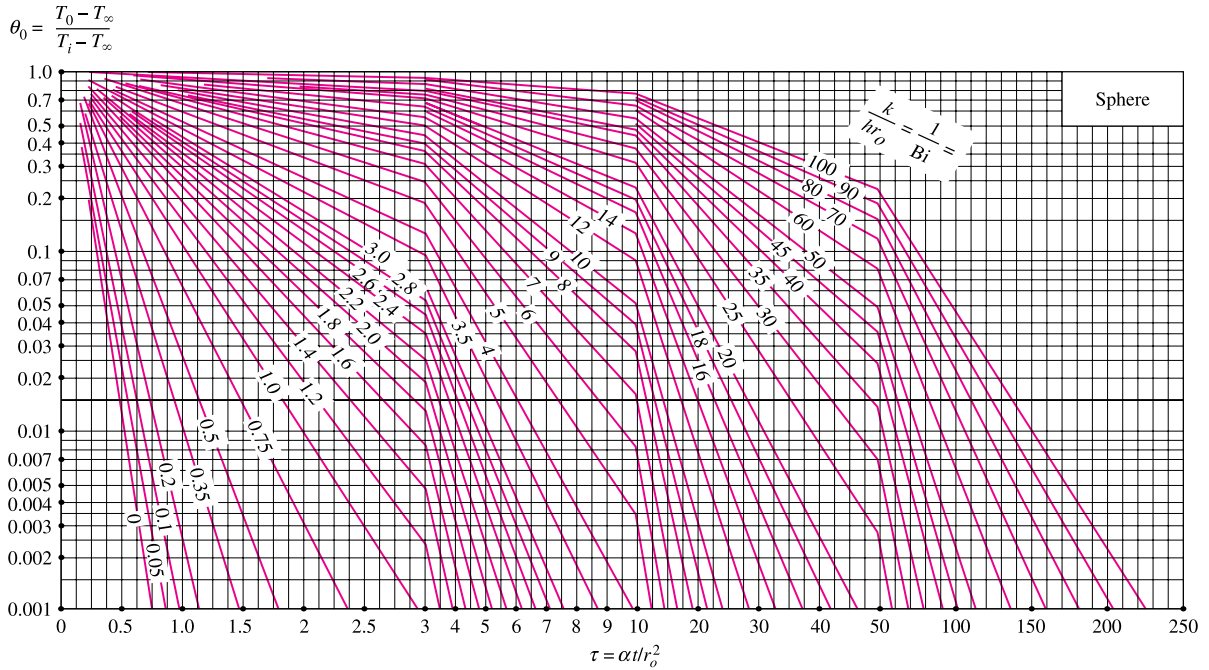
(b) Temperature distribution (from M. P. Heisler, "Temperature Charts for Induction and Constant Temperature Heating," *Trans. ASME* 69, 1947, pp. 227–36. Reprinted by permission of ASME International.)



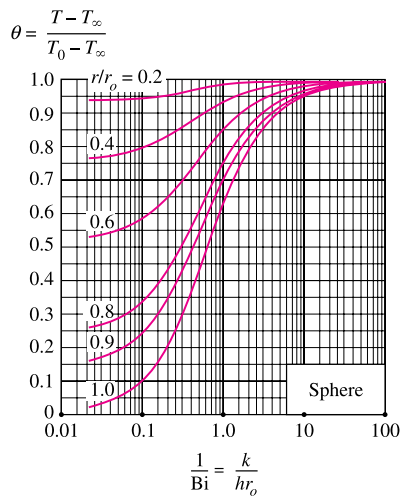
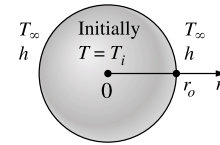
(c) Heat transfer (from H. Gröber et al.)

Transient temperature and heat transfer charts for a long cylinder of radius r_o initially at a uniform temperature T_i subjected to convection from all sides to an environment at temperature T_∞ with a convection coefficient of h .

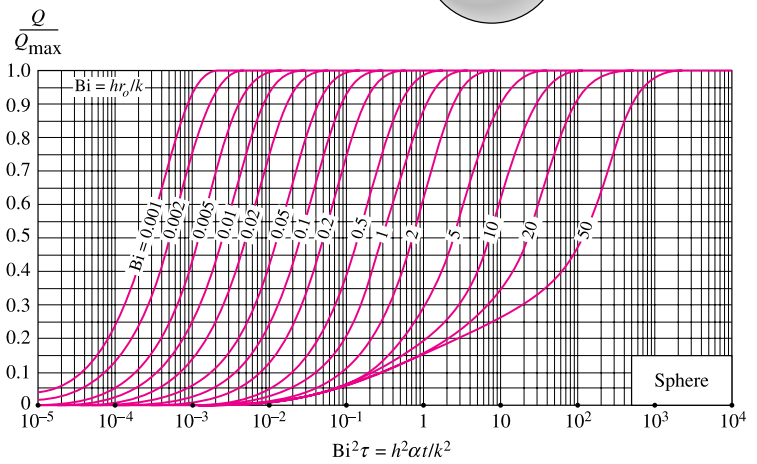
Figure 6:



(a) Midpoint temperature (from M. P. Heisler, "Temperature Charts for Induction and Constant Temperature Heating," *Trans. ASME* 69, 1947, pp. 227–36. Reprinted by permission of ASME International.)



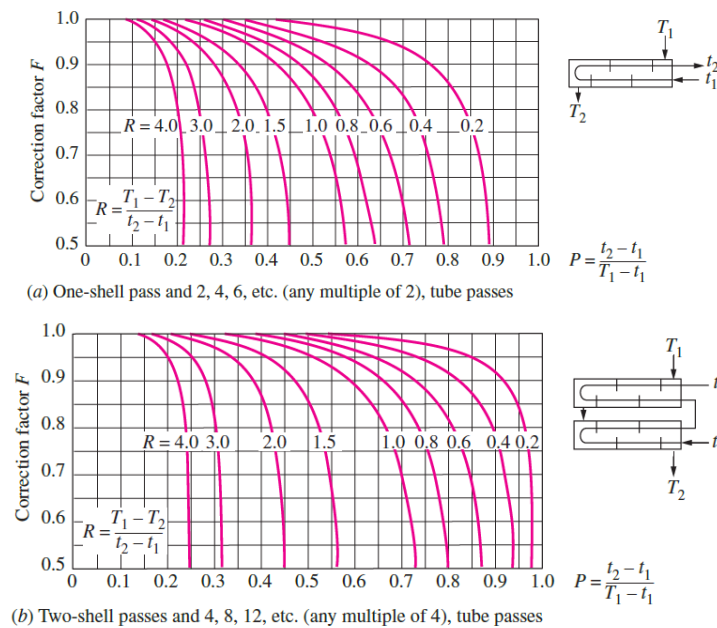
(b) Temperature distribution (from M. P. Heisler, "Temperature Charts for Induction and Constant Temperature Heating," *Trans. ASME* 69, 1947,



(c) Heat transfer (from H. Gröber et al.)

Transient temperature and heat transfer charts for a sphere of radius r_o initially at a uniform temperature T_i subjected to convection from all sides to an environment at temperature T_∞ with a convection coefficient of h .

Figure 7:

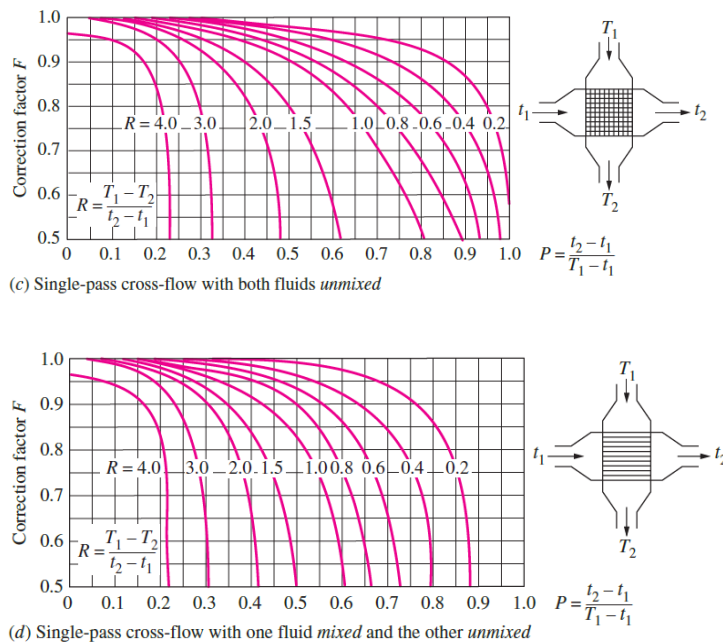


Extracted from Y.A. Cengel, "Heat Transfer: A Practical Approach", 2nd Edition.

Figure 10.8

Correction factor F charts for common shell-and-tube and cross-flow heat exchangers (from Bowman, Mueller, and Nagle, Ref. 2).

Figure 8: Correction-factors for LMTD Method, extracted from Y. A. Cengel, "Heat transfer:A practical approach", 2nd Ed.



Extracted from Y.A. Cengel, "Heat Transfer: A Practical Approach", 2nd Edition.

Figure 10.8

Correction factor F charts for common shell-and-tube and cross-flow heat exchangers (from Bowman, Mueller, and Nagle, Ref. 2).

Figure 9: Correction-factors for LMTD Method, extracted from Y. A. Cengel, "Heat transfer:A practical approach", 2nd Ed.

Effectiveness relations for heat exchangers: $NTU = UA_s/C_{\min}$ and $c = C_{\min}/C_{\max} = (\dot{m}C_p)_{\min}/(\dot{m}C_p)_{\max}$ (Kays and London, Ref. 5.)

Heat exchanger type	Effectiveness relation
1 Double-pipe: Parallel-flow	$\varepsilon = \frac{1 - \exp[-NTU(1+c)]}{1+c}$
Counter-flow	$\varepsilon = \frac{1 - \exp[-NTU(1-c)]}{1-c \exp[-NTU(1-c)]}$
2 Shell and tube: One-shell pass 2, 4, ... tube passes	$\varepsilon = 2 \left\{ 1 + c + \sqrt{1+c^2} \frac{1 + \exp[-NTU\sqrt{1+c^2}]}{1 - \exp[-NTU\sqrt{1+c^2}]} \right\}^{-1}$
3 Cross-flow (single-pass) Both fluids unmixed	$\varepsilon = 1 - \exp \left\{ \frac{NTU^{0.22}}{c} [\exp(-c NTU^{0.78}) - 1] \right\}$
C_{\max} mixed, C_{\min} unmixed	$\varepsilon = \frac{1}{c} (1 - \exp[1-c(1 - \exp(-NTU))])$
C_{\min} mixed, C_{\max} unmixed	$\varepsilon = 1 - \exp \left\{ -\frac{1}{c} [1 - \exp(-c NTU)] \right\}$
4 All heat exchangers with $c = 0$	$\varepsilon = 1 - \exp(-NTU)$

NTU relations for heat exchangers $NTU = UA_s/C_{\min}$ and $c = C_{\min}/C_{\max} = (\dot{m}C_p)_{\min}/(\dot{m}C_p)_{\max}$ (Kays and London, Ref. 5.)

Heat exchanger type	NTU relation
1 Double-pipe: Parallel-flow	$NTU = -\frac{\ln[1 - \varepsilon(1+c)]}{1+c}$
Counter-flow	$NTU = \frac{1}{c-1} \ln \left(\frac{\varepsilon-1}{\varepsilon c-1} \right)$
2 Shell and tube: One-shell pass 2, 4, ... tube passes	$NTU = -\frac{1}{\sqrt{1+c^2}} \ln \left(\frac{2/\varepsilon - 1 - c - \sqrt{1+c^2}}{2/\varepsilon - 1 - c + \sqrt{1+c^2}} \right)$
3 Cross-flow (single-pass) C_{\max} mixed, C_{\min} unmixed	$NTU = -\ln \left[1 + \frac{\ln(1-\varepsilon c)}{c} \right]$
C_{\min} mixed, C_{\max} unmixed	$NTU = \frac{\ln[c \ln(1-\varepsilon) + 1]}{c}$
4 All heat exchangers with $c = 0$	$NTU = -\ln(1-\varepsilon)$

Figure 10: NTU relations extracted from Y. A. Cengel, "Heat transfer: A practical approach", 2nd Ed.

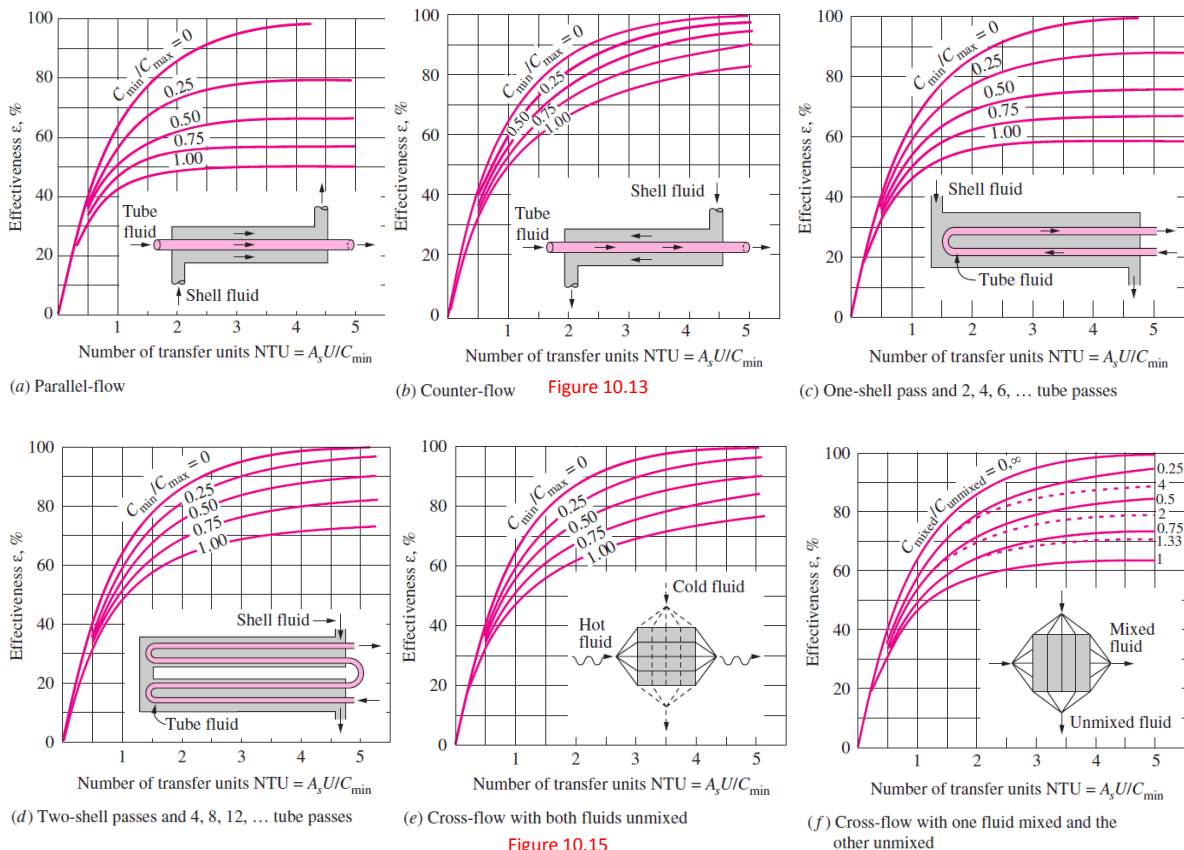


Figure 10.13

Extracted from Y.A. Cengel, "Heat Transfer: A Practical Approach", 2nd Edition.

Figure 11: NTU plots extracted from Y. A. Cengel, "Heat transfer: A practical approach", 2nd Ed.

Diffusion Dimensionless Numbers

$$Sc = \frac{\mu}{\rho D_{AB}}$$

$$Le = \frac{k}{\rho C_p D_{AB}}$$

Diffusion

General expression for the flux:

$$\mathbf{N}_A = \mathbf{J}_A + x_A \sum_B \mathbf{N}_B$$

Fick's law:

$$\mathbf{J}_A = -D_{AB} \nabla C_A$$

Stefan's law:

$$N_{s,r} = -D \frac{c}{1-x} \frac{\partial x}{\partial r}$$

Ideal Gas

$$P V = n R T$$

$$R \approx 8.314598 \text{ J K}^{-1} \text{ mol}^{-1}$$

Geometry

$$P_{\text{circle}} = 2 \pi r$$

$$A_{\text{circle}} = \pi r^2$$

$$A_{\text{sphere}} = 4 \pi r^2$$

$$V_{\text{sphere}} = \frac{4}{3} \pi r^3$$

$$A_{\text{cylinder}} = P_{\text{circle}} L$$

$$V_{\text{cylinder}} = A_{\text{circle}} L$$