ICommander # startPositionLBR # TCP # RCM # apertureLimit # heightSafety # buttons # velocitySub # Q4StateSub # Q5StateSub # Q6pStateSub und 33 mehr ... + setGripperStatus() + configurationCallback() # statemachineThread() # calcQ6() # commandVelocities() # loop() # QuaternionFromEuler() NumericKinematicCommander IbrJointAnglePub IbrJointAngleSub startPositionLBR IbrJointAngles + NumericKinematicCommander() statemachineThread() configurationCallback() buttonCheck() getControlDevice() calcQ6() commandVelocities() IbrJointAngleCallback() Q4StateCallback() Q5StateCallback() Q6nStateCallback()

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 Q6pStateCallback() buttonCallback()

loop()