ICommander

startPositionLBR
TCP
RCM
apertureLimit
heightSafety
buttons
velocitySub
Q4StateSub
Q5StateSub
Q6pStateSub
und 33 mehr ...

+ setGripperStatus()
+ configurationCallback()
# statemachineThread()
# calcQ6()
# commandVelocities()
# loop()
# QuaternionFromEuler()

GeometricKinematicCommander

- lbrTargetPositionPub
- velocity_
- nh_
- T_0_FL

+ GeometricKinematicCommander()
- statemachineThread()
- calcQ6()
- commandVelocities()
- buttonCheck()
- getControlDevice()
- flangeCallback()
- loop()
- Q4StateCallback()
- Q5StateCallback()
- Q6nStateCallback()
- Q6pStateCallback()
- velocityCallback()
- buttonCallback()