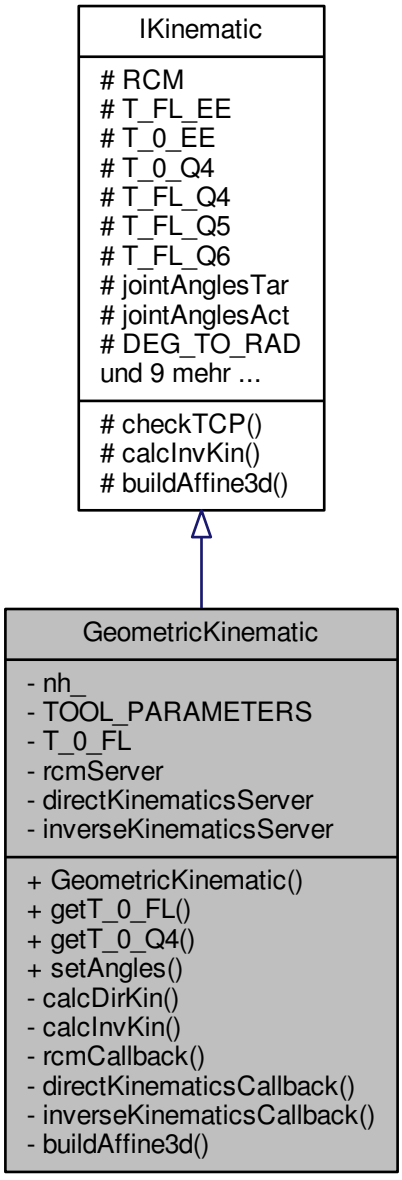
IKinematic
RCM
T_FL_EE
T_0_EE
T_0_Q4
T_FL_Q4
T_FL_Q5
T_FL_Q6
jointAnglesTar
jointAnglesAct
DEG_TO_RAD
und 9 mehr ...
checkTCP()
calcInvKin()
buildAffine3d()
GeometricKinematic
- nh_
- TOOL_PARAMETERS
- T_0_FL
- rcmServer
- directKinematicsServer
- inverseKinematicsServer
+ GeometricKinematic()
+ getT_0_FL()
+ getT_0_Q4()
+ setAngles()
- calcDirKin()
- calcInvKin()
- rcmCallback()
- directKinematicsCallback()
- inverseKinematicsCallback()
- buildAffine3d()