RCM # T_FL_EE # T_0_EE # T_0_Q4 # T_FL_Q4 # T_FL_Q5 # T_FL_Q6 # jointAnglesTar # jointAnglesAct # DEG_TO_RAD und 9 mehr ... # checkTCP() # calcInvKin()

buildAffine3d()

toolDescriptionParameters

- + X_0_Q4 + Y_0_Q4 + Z_0_Q4 + A_0_Q4 + B_0_Q4 + C_0_Q4
- + L_Q5_Q6 + L_Q6_EE + X_RCM

/-TOOL_PARAMETERS

GeometricKinematic

- nh_
- T 0 FL
- rcmServer
- directKinematicsServer
- inverseKinematicsServer
- + GeometricKinematic()
- + getT_0_FL()
- + getT_0_Q4() + setAngles()
- calcDirKin()
- calcbirKin()
- rcmCallback()
- directKinematicsCallback()
- inverseKinematicsCallback()
- buildAffine3d()