

ICommander

- # startPositionLBR
- # TCP
- # RCM
- # apertureLimit
- # heightSafety
- # buttons
- # velocitySub
- # Q4StateSub
- # Q5StateSub
- # Q6pStateSub
- und 33 mehr ...

- + setGripperStatus()
- + configurationCallback()
- # statemachineThread()
- # calcQ6()
- # commandVelocities()
- # loop()
- # QuaternionFromEuler()