

Introduction to general relativity: derivative operators and parallel transport

03 May 2021 11:38

Covariant derivative operator ∇ } notation
 \equiv affine connections

Notation: Let M be a manifold, denote by $\mathcal{X}(M)$ the space of smooth vector fields on M .

Definition: an affine connection ∇ is a map

$$\nabla: \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathcal{X}(M)$$

We immediately extend domain of definition of ∇ to

$$\nabla: \mathcal{X}(M) \times J^{(k,l)} \rightarrow J^{(k,l)}$$



(0) Let $X, Y \in \mathcal{X}(M)$ $Z \in J^{(k,l)}$:

$$\boxed{\nabla_{(X+Y)} Z = \nabla_X Z + \nabla_Y Z}$$

(0') If $f \in \mathcal{F}(M)$, $X \in \mathcal{X}(M)$, $Y \in J^{(k,l)}$

$$\boxed{\nabla_f X Y = f \nabla_X Y}$$

(1) Linearity: $A, B \in J^{(k,l)}$

$$\boxed{\nabla_X (A+B) = \nabla_X A + \nabla_X B}$$

In AIN: note $\nabla_X \equiv \underline{X^a \nabla_a}$)

$$\nabla_c (A_{b_1 \dots b_k}^{a_1 \dots a_k} + B_{b_1 \dots b_k}^{a_1 \dots a_k}) = \nabla_c A_{b_1 \dots b_k}^{a_1 \dots a_k} + \nabla_c B_{b_1 \dots b_k}^{a_1 \dots a_k}$$

2. Leibniz rule: For all $A \in J^{(k,l)}$, $B \in J^{(l',m')}$

$$\boxed{\nabla_X (A \otimes B) = (\nabla_X A) \otimes B + A \otimes (\nabla_X B)}$$

In AIN:

$$\nabla_e (A_{b_1 \dots b_k}^{a_1 \dots a_k} B_{d_1 \dots d_l'}^{c_1 \dots c_{l'}}) = (\nabla_e A_{b_1 \dots b_k}^{a_1 \dots a_k}) B_{d_1 \dots d_l'}^{c_1 \dots c_{l'}} + A_{b_1 \dots b_k}^{a_1 \dots a_k} (\nabla_e B_{d_1 \dots d_l'}^{c_1 \dots c_{l'}})$$

In AIN:

$$\nabla_e \left(A_{b_1 \dots b_k}^{a_1 \dots a_n} B_{d_1 \dots d_l}^{c_1 \dots c_m} \right) = (\nabla_e A_{b_1 \dots b_k}^{a_1 \dots a_n}) B_{d_1 \dots d_l}^{c_1 \dots c_m} + A_{b_1 \dots b_k}^{a_1 \dots a_n} (\nabla_e B_{d_1 \dots d_l}^{c_1 \dots c_m})$$

(3) Commutativity with contractions: For all $A \in J(k, l)$

$$\nabla_x (\epsilon_{j_1 \dots j_n} A) = \epsilon_{j_1 \dots j_n} (\nabla_x A)$$

In AIN:

$$\nabla_d \left(A_{b_1 \dots b_n}^{a_1 \dots a_n} \right) = (\nabla_d A)_{b_1 \dots b_n}^{a_1 \dots a_n}$$

(4) Reduction to vector fields on scalar functions

Let $f \in \mathcal{F}(n)$ then

$$\nabla_x(f) = X(f)$$

AIN:

$$X(f) = X^a \nabla_a f$$

(5) Torsion free:

$$\nabla_x Y - \nabla_y X - [X, Y] = 0$$

\Rightarrow

In AIN (ex). $\forall f \in \mathcal{F}(n)$

$$\nabla_a \nabla_b f = \nabla_b \nabla_a f$$

Simple consequences: $\forall X \in \mathcal{X}(n)$, $Y \in \mathcal{X}(n)$, $f \in \mathcal{F}(n)$

$$(k) \quad \nabla_X(fY) = X(f)Y + f\nabla_X Y$$

$$\begin{aligned} (k+1) \quad [v, w](f) &= v(w(f)) - w(v(f)) \\ &= \underline{v^a \nabla_a} (\underline{w^b \nabla_b} (f)) - \underline{w^a \nabla_a} (\underline{v^b \nabla_b} (f)) \\ &= v^a (\nabla_a w^b) \nabla_b f - w^a (\nabla_a v^b) \nabla_b f \\ &\quad + v^a w^b \nabla_a \nabla_b f - v^a w^b \nabla_b \nabla_a f \end{aligned}$$

So vector field $[v, w]$ is given by

$$[v, w]^b = v^a \nabla_a w^b - w^a \nabla_a v^b$$

There are many derivative operators obeying (0), ..., (5)

The simplest example is the ordinary derivative operator

∂_a defined as follows. Let ψ be a chart & $T \in J(k,1)$ with components $T_{v_1 \dots v_k}^{m_1 \dots m_k}$ in coord. basis
 ∂_a acts via

$$\partial_a T_{b_1 \dots b_k}^{a_1 \dots a_k} \xrightarrow[\text{coord. basis } \psi]{\text{in}} \frac{\partial}{\partial x^a} (T_{v_1 \dots v_k}^{m_1 \dots m_k})$$

→ obviously defined only in chart ψ . (ex check
 ∂_a obeys (4) → (5))

Suppose ∇_a & $\tilde{\nabla}_a$ are two derivative operators
 obeying (4) - (5). As a map on $f \in \mathcal{F}(r)$

$$(\tilde{\nabla}_a - \nabla_a)(f) = \tilde{\nabla}_a f - \nabla_a f = 0$$

Now consider

$$(\tilde{\nabla}_a - \nabla_a) \text{ on } J(0,1)$$

$$(\tilde{\nabla}_a - \nabla_a) : J(0,1) \rightarrow J(0,2)$$

Let $f \in \mathcal{F}(m)$ & $w \in J(0,1)$. Then $fw_a \in J(0,1)$

We find

$$\underbrace{(\tilde{\nabla}_a - \nabla_a)}_{\text{ex}} (fw_b) = f \underbrace{(\tilde{\nabla}_a - \nabla_a)(w_b)}_{\text{ex}} \quad \textcircled{A}$$

(via Leibniz & (4))

Claim: (4) implies that $\tilde{\nabla}_a w_b - \nabla_a w_b$
 only depends on w_b at p . Strategy:
 Let $w'_b \in J(0,1)$ have property

$$w'_b|_p = w_b|_p$$

we will argue:

$$\tilde{\nabla}_a w_b - \nabla_a w_b = \tilde{\nabla}_a w'_b - \nabla_a w'_b$$

One can find (ex) smooth functions f_α which vanish
 at p and smooth $\mu_b(\alpha) \in J(0,1)$ such that

$$w'_b - w_b = \sum_{\alpha=1}^n (f_\alpha) \mu_b(\alpha) \quad f_\alpha|_p = 0$$

Apply $(\tilde{\nabla}_a - \nabla_a)$:

$$(\tilde{\nabla}_a - \nabla_a)(w'_b - w_b) = \sum_{\alpha=1}^n f_\alpha (\tilde{\nabla}_a - \nabla_a) \mu_b(\alpha)$$

$$= 0 \text{ at } r \text{ because } f_a \underset{r}{=} 0$$

Hence

$$\underbrace{(\tilde{\nabla}_a - \nabla_a) w_b^c}_{\text{doesn't depend on } w_b \text{ away from } r} = \underbrace{(\tilde{\nabla}_a - \nabla_a) w_b^c}_{\text{at } r} \text{ at } r$$

$(\tilde{\nabla}_a - \nabla_a)$: as a map of tensors of type (α_1) at r to $\mathcal{T}(\alpha_2)$

C

$$C: V_p^k \rightarrow V_p^* \otimes V_p^*$$

By duality $V_p^{tk} \cong V_p$, C can be interpreted as a map

$$\text{from } V_p^* \otimes V_p \otimes V_p \rightarrow \mathbb{R} \text{ or}$$

element of $V_p \otimes V_p^k \otimes V_p^*$. We write C_{ab}^c for free

ATN of C

$$\boxed{\nabla_a w_b = \tilde{\nabla}_a w_b - C_{ab}^c w_c}$$

WARNING!
BUT C_{ab}^c does

not transform as a tensor field of

type $J(1,2)$

we choose $\tilde{\nabla}_a = \partial_a$

$$\text{Consider } w_b = \nabla_r f \stackrel{(5)}{=} \tilde{\nabla}_r f \quad f \in \mathcal{F}(m)$$

$$\underbrace{\nabla_a \nabla_b f}_{\text{symmetric}} = \tilde{\nabla}_a \tilde{\nabla}_b f - C_{ab}^c \nabla_c f$$

symmetric symmetric

$$C_{ab}^c = C_{ba}^c$$

The Leibniz property & (4) now determines $(\tilde{\nabla}_a - \nabla_a)$ on all tensor fields: let $w \in \mathcal{T}(\alpha_1)$ and $t \in \mathcal{F}(1,0) \cong \mathcal{X}(m)$.

$$\omega_a t^a \in \mathcal{F}(m)$$

(4):

$$(\tilde{\nabla}_a - \nabla_a)(w_b t^b) = 0$$

Leibniz k (3):

$$t^b (\tilde{\nabla}_a - \nabla_a) w_b + w_b (\tilde{\nabla}_a - \nabla_a) t^b = 0$$

$$\Rightarrow \underbrace{t^b C_{ab}^c w_c}_{\text{c}} + w_b (\tilde{\nabla}_a - \nabla_a) t^b = 0$$

$$\Rightarrow w_b ((\tilde{\nabla}_a - \nabla_a) t^b + t^c C_{ac}^b) = 0$$

or

$$\boxed{\nabla_a t^b = \tilde{\nabla}_a t^b + C_{ac}^b t^c}$$

$$\nabla_a t^b = \tilde{\nabla}_a t^b + C_{ac}^b t^c$$

ex: for $T \in J(k, l)$

$$\begin{aligned}\nabla_a T_{c_1 \dots c_k}^{b_1 \dots b_k} &= \tilde{\nabla}_a T_{c_1 \dots c_k}^{b_1 \dots b_k} + \sum_i C_{ad}^{b_i} T_{c_1 \dots c_k}^{b_1 \dots d \dots b_k} \\ &\quad - \sum_j C_{ac_j}^d T_{c_1 \dots d \dots c_k}^{b_1 \dots b_k} \quad (\text{A})\end{aligned}$$

In other words action $\tilde{\nabla}_a - T_a$ or arbitrary $J(k, l)$
is determined by $C_{ab}^c \leftarrow [V_p \otimes V_p^* \otimes V_p^*]$

Converse: $C_{ab}^c \in V_p \otimes V_p^* \otimes V_p^*$ and a derivative operator
 $\tilde{\nabla}_a$ then ∇_a defined by (A) is also a derivative operator

C_{ab}^c doesn't always transform as a tensor field
of type $J(1, 2)$ under change of
coords (e.g. when $\tilde{\nabla}_a \equiv \partial_a$)

Most important example : let $\tilde{\nabla}_a = \partial_a$. In this
case $C_{ab}^c \mapsto \Gamma_{ab}^c$, called Christoffel symbols :

$$\nabla_a t^b = \partial_a t^b + \Gamma_{ac}^b t^c$$

in coords.

$$\nabla_\mu t^\nu = \partial_\mu t^\nu + \Gamma_{\mu\nu}^\lambda t^\nu$$