

Introduction to general relativity: curvature cont.

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Action of $(\nabla_a \nabla_b - \nabla_b \nabla_a)$ ($\equiv [\nabla_a, \nabla_b]$)
on vectors & tensors may be obtained as follows

Let t^a & w_a are arbitrary vector & dual
vector fields. Consider $t^a w_a$:

$$0 = (\nabla_a \nabla_b - \nabla_b \nabla_a)(t^c w_c) = \nabla_a(w_c \nabla_b t^c + t^c \nabla_b w_c) - \nabla_b(w_c \nabla_a t^c + t^c \nabla_a w_c)$$

$$= w_c(\nabla_a \nabla_b - \nabla_b \nabla_a)t^c + t^c(\nabla_a \nabla_b - \nabla_b \nabla_a)w_c$$

$$0 = w_c(\underline{\quad})t^c + t^c w_d R_{abc}^d$$

\Rightarrow

$$(\nabla_a \nabla_b - \nabla_b \nabla_a)t^c = -R_{abd}^c t^d$$

Similarly, ex1: we find $T_{b_1 \dots b_k}^{a_1 \dots a_k}$:

$$\textcircled{A} \quad (\nabla_a \nabla_b - \nabla_b \nabla_a)T_{d_1 \dots d_k}^{c_1 \dots c_k} = -\sum_{j=1}^k R_{abc}^j T_{d_1 \dots d_k}^{c_1 \dots c_{j-1} e c_j \dots c_k} + \sum_{j=1}^k R_{abd_j}^e T_{d_1 \dots e \dots d_k}^{c_1 \dots c_k}$$

The Riemann tensor has four important properties:

$$1. \quad R_{abc}^d = -R_{bac}^d$$

$$2. \quad R_{[abc]}^d = 0$$

$$3. \quad \text{For } \nabla_a \text{ defined by metric } \nabla_a g_{bc} = 0: \quad R_{abcd} = -R_{abdc}$$

$$4. \quad \nabla_{[a} R_{bc]d}^e = 0 \quad (\text{Bianchi identity})$$

Proof: 1. follows by definition

2. Note for arbitrary w_a & ∇_a we have

$$\nabla_{[a} \nabla_{b]} w_c = 0$$

check this as follows:

LHS:

$$\text{LHS} = \nabla_{[a} \nabla_{b]} w_c + \nabla_{[a} C_{b]c}^d w_d$$

$$= \partial_{[a} \partial_{b]} w_c + C_{[ab]}^d \partial_{[d} w_{c]} + C_{[ac]}^d \partial_{[b} w_{d]}$$

Antisymmetric over
abc, leave d alone.

$$+ 2\sigma_{ab}^{\gamma} \omega^d + C_{[ab}^e \tilde{C}_{|elc]}^d \omega^d + C_{[alc]}^e \tilde{C}_{bje}^d \omega^d$$

= 0 Thus

$$0 = 2 \nabla_a \nabla_b \omega_c = \nabla_{[a} \nabla_{b]} \omega_c - \nabla_{[b} \nabla_{a]} \omega_c = R_{[abc]}^d \omega^d$$

3. Consider:

$$0 = (\nabla_a \nabla_b - \nabla_b \nabla_a) g_{cd} \stackrel{!}{=} R_{abc}^e g_{ed} + R_{bcd}^e g_{ce} = R_{abcd} + R_{bac}$$

4. Consider

$$(i) = (\nabla_a \nabla_b - \nabla_b \nabla_a) \nabla_c \omega_d \stackrel{!}{=} R_{abc}^e \nabla_e \omega_d + R_{abd}^f \nabla_c \omega_f$$

vs.

$$(ii) = \nabla_a (\nabla_b \nabla_c \omega_d - \nabla_c \nabla_b \omega_d) = \nabla_a (R_{bcd}^e \omega_e) = \omega_e \nabla_a R_{bcd}^e + R_{bcd}^e \nabla_a \omega_e$$

Analogously (i) & (ii) over abc \Rightarrow both expressions become equal:

$$R_{[abc]}^e \nabla_e \omega_d + R_{[abd]}^f \nabla_c \omega_f = \omega_e \nabla_{[a} R_{bc]}^e + R_{[bcd]}^e \nabla_a \omega_e$$

Thus, for all ω_e . $\omega_e \nabla_{[a} R_{bc]}^e = 0$

□

Riemann curvature tensor:

$$R(v, w, u, v)$$

vector vector vector dual vector

This argument defines
one coordinate of 20 subspace
of \mathbb{R}^n

defines 2nd
coordinate axis

$$R(v, w, u, v) \approx M_a^b$$

... linear combination

$$R(v, w, \cdot, \cdot) \cong M_a^b$$

a matrix or linear transformation
of v_p

Defn:

Ricci tensor:

$$R_{ac} = R_{abc}^b$$

Note:

$$R_{ab} = R_{ba}$$

(by 3.)

Scalar curvature

$$R = R_a^a$$

Contract Bianchi identity:

$$\nabla_a R_{bcd}^a + \nabla_b R_{acd} - \nabla_c R_{abd} = 0$$

Contract with g^{bd} :

$$\nabla_a R_c^a + \nabla_b R_c^b - \nabla_c R = 0$$

Written

$$\nabla^a G_{ab} = 0$$

("Divergence")
definition of

where:

$$G_{ab} = R_{ab} - \frac{1}{2} R g_{ab}$$

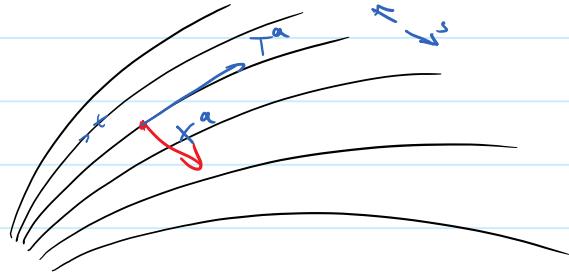
Is the Einstein tensor.

Geodesic deviation equation

- Tells us how nearby geodesics accelerate away or toward each other.

Suppose we have a smooth one-parameter family $\gamma_s(t)$ of geodesics. That is, γ_s is a geodesic $\forall s \in \mathbb{R}$, and $(s, t) \mapsto \gamma_s(t)$ is smooth, one-to-one map with smooth inverse. Let Σ be 2-D submanifold described by $\gamma_s(t)$; (s, t) are a coord system of Σ

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$T^a = (\partial/\partial t)^a$ is tangent to $\gamma_s(t)$, we have

$$T^a \nabla_a T^b = 0$$

The vector field $X^a = (\beta_s)^a$ is displacement to infinitesimally close geodesic $\gamma_{s+\delta}(t)$

Rescale t with a s -dependent factor so that

$\text{does not vary with } s$. Since X^a, T^a are coordinate fields so

$$T^b \nabla_b X^a = X^b \nabla_b T^a$$

$\rightarrow X^a T_a$ is constant. A reparametrisation by addition of (s -dependent) constant

$$X^a T_a = 0$$

The quantity $v^a = T^b \nabla_b X^a$ measures rate of change of displacement X^a along geodesic; "relative velocity"
"relative acceleration"

$$\begin{aligned} A^a &= T^c \nabla_c v^a = T^c \nabla_c (T^b \nabla_b X^a) \\ &= T^c \nabla_c (X^b \nabla_b T^a) \quad (X^a \text{ & } T^a \text{ commute}) \\ &= (T^c \nabla_c X^b) (\nabla_b T^a) + X^b T^c \nabla_c \nabla_b T^a \\ &= (X^c \nabla_c T^b) (\nabla_b T^a) + X^b T^c \nabla_c \nabla_b T^a - R_{c b d}{}^a X^b T^c T^d \\ &= X^c \nabla_c (T^b \nabla_b T^a) - R_{c b d}{}^a X^b T^c T^d \\ &= -R_{c b d}{}^a X^b T^c T^d \end{aligned}$$

\rightarrow Geodesic deviation equation

If

$$A^a = 0 \quad \text{for all geodesic families } \gamma_s(t) \Leftrightarrow R_{abc}{}^d = 0$$

If \exists relatively accelerating geodesics (families)
 $\Rightarrow R_{abc}^d \neq 0$

Computing curvature

Given manifold M with metric g_{ab} then R_{abc}^d is determined uniquely by ∇_a

In practice we choose coordinates (ψ, x^n)
 determined by ψ .

$$\nabla_b w_c = \partial_b w_c - \Gamma_{bc}^d w_d$$

So

$$\nabla_a \nabla_b w_c = \partial_a (\partial_b w_c - \Gamma_{bc}^d w_d) - \Gamma_{ab}^e (\partial_e w_c - \Gamma_{ec}^d w_d) - \Gamma_{ac}^e (\partial_b w_c - \Gamma_{bc}^d w_d)$$

Thus,

$$R_{abc}^d w_d = 2 \nabla_{[a} \nabla_{b]} w_c \quad (\text{ex.})$$

$$R_{abc}^d w_d = (-2 \partial_{[a} \Gamma_{b]}^d + 2 \Gamma_{c[a}^e \Gamma_{b]e}^d) w_d$$

This holds for all w_d , so in coordinates ψ :

$$R_{\mu\nu\rho}^\sigma = \frac{\partial}{\partial x^\nu} \Gamma_{\rho\rho}^\sigma - \frac{\partial}{\partial x^\mu} \Gamma_{\nu\rho}^\sigma + \sum_a \left(\Gamma_{\mu\rho}^a \Gamma_{\alpha\nu}^\sigma - \Gamma_{\nu\rho}^a \Gamma_{\alpha\mu}^\sigma \right)$$

Ricci tensor is simply $R_{\mu\rho} \equiv \sum_\nu R_{\mu\nu\rho}^\nu$

Some useful formulae

Define $g = \det(g_{\mu\nu})$

Use formula for inverse of matrix: (ex)

$$\sum_{\nu,\alpha} g^{\nu\alpha} \frac{\partial g_{\nu\alpha}}{\partial x^\mu} = \frac{1}{g} \frac{\partial g}{\partial x^\mu}$$

and $= 2 \log(|g|)$

∂x^μ

This equation appears in formula for Christoffel symbols

$$\Gamma_{\alpha\mu}^{\nu} = \sum_{\lambda} \Gamma_{\lambda\mu}^{\nu} = \frac{1}{2} \sum_{\lambda,\mu} g^{\nu\lambda} \frac{\partial g_{\lambda\mu}}{\partial x^\nu}$$

$$\Rightarrow \text{by above} \Rightarrow = \frac{1}{2} \frac{1}{g} \frac{\partial g}{\partial x^\mu} = \frac{1}{2} \frac{\partial \log(\sqrt{|g|})}{\partial x^\mu}$$

Appears as well in divergence $\nabla_a T^a$ of vector field T^a

$$\begin{aligned}\nabla_a T^a &= \partial_a T^a + \Gamma_{ab}^a T^b \\ &= \sum_a \frac{1}{\sqrt{g}} \frac{\partial}{\partial x^a} (\sqrt{g} T^a)\end{aligned}$$