

Introduction to general relativity: derivative operators and parallel transport

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Covariant derivative operator ∇ } notation
 \equiv affine connections

Notation: Let M be a manifold, denote by $\mathcal{X}(M)$ the space of smooth vector fields on M .

Definition an affine connection ∇ is a map

$$\nabla: \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathcal{X}(M)$$

It immediately extend domain of definition of ∇ to

$$\nabla: \mathcal{X}(M) \times \mathcal{J}(k,l) \rightarrow \mathcal{J}(k,l) \quad \Downarrow$$

(0) Let $X, Y \in \mathcal{X}(M)$ $Z \in \mathcal{J}(k,l)$:

$$\nabla_{(X+Y)} Z \equiv \nabla_X Z + \nabla_Y Z$$

(0') $\forall f \in \mathcal{F}(M)$, $X \in \mathcal{X}(M)$, $Y \in \mathcal{J}(k,l)$

$$\nabla_{fX} Y = f \nabla_X Y$$

(1) Linearity: $A, B \in \mathcal{J}(k,l)$

$$\nabla_X (A+B) = \nabla_X A + \nabla_X B$$

(In AIN: note $\nabla_X \equiv X^a \nabla_a$)

$$\nabla_c (A^{a_1 \dots a_k}_{b_1 \dots b_l} + B^{a_1 \dots a_k}_{b_1 \dots b_l}) = \nabla_c A^{a_1 \dots a_k}_{b_1 \dots b_l} + \nabla_c B^{a_1 \dots a_k}_{b_1 \dots b_l}$$

2. Leibniz rule: For all $A \in \mathcal{J}(k,l)$, $B \in \mathcal{J}(k',l')$

$$\nabla_X (A \otimes B) = (\nabla_X A) \otimes B + A \otimes (\nabla_X B)$$

In AIN:

$$\nabla_e (A^{a_1 \dots a_k}_{b_1 \dots b_l} B^{c_1 \dots c_{k'}}_{d_1 \dots d_{l'}}) = (\nabla_e A^{a_1 \dots a_k}_{b_1 \dots b_l}) B^{c_1 \dots c_{k'}}_{d_1 \dots d_{l'}} + A^{a_1 \dots a_k}_{b_1 \dots b_l} (\nabla_e B^{c_1 \dots c_{k'}}_{d_1 \dots d_{l'}})$$

In AIN:

$$\nabla_e \left(A_{b_1 \dots b_n}^{a_1 \dots a_n} B_{d_1 \dots d_r}^{c_1 \dots c_r} \right) = \left(\nabla_e A_{b_1 \dots b_n}^{a_1 \dots a_n} \right) B_{d_1 \dots d_r}^{c_1 \dots c_r} + A_{b_1 \dots b_n}^{a_1 \dots a_n} \left(\nabla_e B_{d_1 \dots d_r}^{c_1 \dots c_r} \right)$$

(3) Commutativity with contraction: For all $A \in \mathcal{T}(M)$

$$\nabla_X (\mathcal{L}_{j^i} A) = \mathcal{L}_{j^i, j^n} (\nabla_X A)$$

In AIN:

$$\nabla_d \left(A_{b_1 \dots b_n}^{a_1 \dots a_n} \right) = \left(\nabla_d A \right)_{b_1 \dots b_n}^{a_1 \dots a_n}$$

(4) Reduction to vector fields on scalar functions

Let $f \in \mathcal{F}(M)$ then

$$\nabla_X (f) = X(f)$$

AIN:

$$X(f) = X^a \nabla_a f$$

(5) Torsion free:

$$\nabla_X Y - \nabla_Y X - [X, Y] = 0$$

\Rightarrow

In AIN (ex): $\forall f \in \mathcal{F}(M)$

$$\nabla_a \nabla_b f = \nabla_b \nabla_a f$$

Simple consequences: $\forall X \in \mathcal{X}(M), Y \in \mathcal{X}(M), f \in \mathcal{F}(M)$

$$(k) \quad \nabla_X (fY) = X(f)Y + f \nabla_X Y$$

$$\begin{aligned} (k+1) \quad [v, w](f) &= v(w(f)) - w(v(f)) \\ &= \underline{v^a \nabla_a} (\underline{w^b \nabla_b} f) - \underline{w^a \nabla_a} (v^b \nabla_b f) \\ &= v^a (\nabla_a w^b) \nabla_b f - w^a (\nabla_a v^b) \nabla_b f \\ &\quad + v^a w^b \nabla_a \nabla_b f - v^a w^b \nabla_b \nabla_a f \end{aligned}$$

So vector field $[v, w]$ is given by

$$[v, w]^b = v^a \nabla_a w^b - w^a \nabla_a v^b$$

There are many derivative operators obeying (1), ..., (5)

The simplest example is the ordinary derivative operator

∂_a defined as follows. Let ψ be a chart & $T \in T(p)$ with components $T_{x_1 \dots x_k}^{y_1 \dots y_k}$ in coord. basis

∂_a acts via

$$\partial_a T_{x_1 \dots x_k}^{y_1 \dots y_k} \xrightarrow[\substack{\text{in} \\ \text{coord. basis} \\ \psi}]{\text{in}} \frac{\partial}{\partial x^a} (T_{x_1 \dots x_k}^{y_1 \dots y_k})$$

→ obviously defined only in chart ψ . (ex check ∂_a obeys (5) → (5))

Suppose ∇_a & $\tilde{\nabla}_a$ are two derivative operators obeying (5) → (5). As a map on $f \in \mathcal{F}(M)$

$$(\tilde{\nabla}_a - \nabla_a)(f) = \tilde{\nabla}_a f - \nabla_a f = 0$$

Now consider

$$(\tilde{\nabla}_a - \nabla_a) \text{ on } T(0,1):$$

$$(\tilde{\nabla}_a - \nabla_a) : T(0,1) \rightarrow T(0,2)$$

Let $f \in \mathcal{F}(M)$ & $\omega \in T(0,1)$. Then $f\omega_a \in T(0,1)$

We find

$$\underbrace{(\tilde{\nabla}_a - \nabla_a)}_{\text{Leibniz}}(f\omega_b) \stackrel{\text{ex}}{=} f \underbrace{(\tilde{\nabla}_a - \nabla_a)}_{\text{Leibniz}}(\omega_b) \quad \textcircled{A}$$

(via Leibniz & (4))

Claim: (4) implies that $\tilde{\nabla}_a \omega_b - \nabla_a \omega_b$ only depends on ω_b at p . Strategy: Let $\omega'_b \in T(0,1)$ have property

$$\omega'_b|_p = \omega_b|_p$$

We will argue:

$$\tilde{\nabla}_a \omega_b - \nabla_a \omega_b = \tilde{\nabla}_a \omega'_b - \nabla_a \omega'_b$$

One can find (ex) smooth functions f_α which vanish at p and smooth $\mu_b(\alpha) \in T(0,1)$ such that

$$\omega'_b - \omega_b = \sum_{\alpha=1}^n \underbrace{(f_\alpha)}_{\text{vanish at } p} \mu_b(\alpha) \quad f_\alpha|_p = 0$$

Apply $(\tilde{\nabla}_a - \nabla_a)$:

$$(\tilde{\nabla}_a - \nabla_a)(\omega'_b - \omega_b) = \sum_{\alpha=1}^n f_\alpha (\tilde{\nabla}_a - \nabla_a) \mu_b(\alpha)$$

= 0 at p because $f|_p = 0$

Hence $\underbrace{(\tilde{\nabla}_a - \nabla_a) \omega_b}_{\text{doesn't depend on } \omega_b \text{ away from } p} = \underbrace{(\tilde{\nabla}_a - \nabla_a) \omega_b}_{\text{at } p}$

$(\tilde{\nabla}_a - \nabla_a)$: as a map of tensors of type $(0,1)$ at p to $\mathcal{T}(0,2)$

$C: V_p^* \rightarrow V_p^* \otimes V_p^*$
By duality $V_p^* \cong V_p$, C can be interpreted as a map
from $V_p^* \otimes V_p \otimes V_p \rightarrow \mathbb{R}$ or as an
element of $V_p \otimes V_p \otimes V_p^*$. We write C_{ab}^c for the
ATN of C . WARNING! BUT C_{ab}^c does not transform as a tensor field of type $\mathcal{T}(1,2)$ if we choose $\tilde{\nabla}_a = \partial_a$

$$\nabla_a \omega_b = \tilde{\nabla}_a \omega_b - C_{ab}^c \omega_c$$

Consider $\omega_b = \nabla_b f \stackrel{(5)}{=} \tilde{\nabla}_b f$ $f \in \mathcal{F}(M)$

$$\underbrace{\nabla_a \nabla_b f}_{\text{Symmetric (5)}} = \underbrace{\tilde{\nabla}_a \tilde{\nabla}_b f}_{\text{Symmetric (5)}} - C_{ab}^c \nabla_c f$$

$$C_{ab}^c = C_{ba}^c$$

The Leibniz property & (4) now determines $(\tilde{\nabla}_a - \nabla_a)$ on all tensor fields: let $\omega \in \mathcal{T}(0,1)$ and $t \in \mathcal{T}(1,0) \cong \mathcal{X}(M)$.

$$\omega_a t^a \in \mathcal{F}(M)$$

(4):

$$(\tilde{\nabla}_a - \nabla_a)(\omega_b t^b) = 0$$

Leibniz & (3):

$$t^b (\tilde{\nabla}_a - \nabla_a) \omega_b + \omega_b (\tilde{\nabla}_a - \nabla_a) t^b = 0$$

$$\Rightarrow t^b C_{ab}^c \omega_c + \omega_b (\tilde{\nabla}_a - \nabla_a) t^b = 0$$

$$\Rightarrow \omega_b ((\tilde{\nabla}_a - \nabla_a) t^b + t^c C_{ac}^b) = 0$$

or

$$\nabla_a t^b = \tilde{\nabla}_a t^b + C_{ac}^b t^c$$

$$\nabla_a t^b = \tilde{\nabla}_a t^b + C_{ac}^b t^c$$

ex: for $T \in \mathcal{T}(M)$

$$\nabla_a T_{c_1 \dots c_k}^{b_1 \dots b_k} = \tilde{\nabla}_a T_{c_1 \dots c_k}^{b_1 \dots b_k} + \sum_j C_{ad}^{b_j} T_{c_1 \dots c_k}^{b_1 \dots d \dots b_k} - \sum_j C_{ac_j}^d T_{c_1 \dots d \dots c_k}^{b_1 \dots b_k} \quad (\text{if } k)$$

In other words action $\tilde{\nabla}_a - \nabla_a$ on arbitrary $\mathcal{T}(M)$ is determined by $C_{ab}^c \leftarrow \left[V_p \otimes V_r^* \otimes V_p^* \right]$

Converse: $C_{ab}^c \in V_p \otimes V_r^* \otimes V_p^*$ and a derivative operator $\tilde{\nabla}_a$ then ∇_a defined by (†) is also a derivative operator

C_{ab}^c doesn't always transform as a tensor field of type $\mathcal{T}(1,2)$ under change of coords (eg. when $\tilde{\nabla}_a \equiv \partial_a$)

Most important example: let $\tilde{\nabla}_a = \partial_a$. In this case $C_{ab}^c \mapsto \Gamma_{ab}^c$, called Christoffel symbols:

$$\nabla_a t^b = \partial_a t^b + \Gamma_{ac}^b t^c$$

in coords.

$$\nabla_\mu t^\nu = \partial_\mu t^\nu + \Gamma_{\mu\lambda}^\nu t^\lambda$$