

Introduction to general relativity: tensors continued

26 April 2021 12:14

Let $p \in M$ be a point in a manifold M . V_p : tangent space at p .
Study behaviour of $v \in V_p$, $v^* \in V_p^*$ etc. under changes of coordinates of M .

(i) Dual of V_p : $V_p^* \equiv$ cotangent space; elements of V_p^* are called covariant vectors. Dual basis

$$e_\mu = \left. \frac{\partial}{\partial x^\mu} \right|_p \quad \text{formally define dual basis}$$

$$e^\mu = dx^\mu \quad (\text{Just a symbol, so far!})$$

via

$$e^\mu(e_\nu) = \delta^\mu_\nu$$

\Rightarrow

$$dx^\mu \left(\left. \frac{\partial}{\partial x^\nu} \right|_p \right) = \delta^\mu_\nu \quad \textcircled{*}$$

dx^μ : linear function of tangent vectors defined by $\textcircled{*}$

Change of coordinate system:

$$v'^{\mu'} = \sum_{\mu=1}^n v^\mu \frac{\partial x'^{\mu'}}{\partial x^\mu} \quad (\text{vector transformation law})$$

Let $\omega \in V_p^*$

$$\omega = \sum_{\mu=1}^n \omega_\mu dx^\mu \stackrel{?!?}{=} \sum_{\mu'=1}^n \omega'_{\mu'} dx'^{\mu'} ?$$

Apply ω to v :

$$\omega(v) = \omega \left(\sum_{\mu} v^\mu \left. \frac{\partial}{\partial x^\mu} \right|_p \right) = \sum_{\mu} v^\mu \omega \left(\left. \frac{\partial}{\partial x^\mu} \right|_p \right)$$

$$= \sum \omega_\mu v^\mu$$

$$\stackrel{!}{=} \omega \left(\sum_{\mu} v'^{\mu'} \left. \frac{\partial}{\partial x'^{\mu'}} \right|_p \right)$$

$$= \omega \left(\sum_{\mu', \mu} v'^{\mu'} \frac{\partial x'^{\mu'}}{\partial x^\mu} \left. \frac{\partial}{\partial x'^{\mu'}} \right|_p \right)$$

$$\sum_{\mu=1}^n \omega_\mu v^\mu = \sum_{\mu, \mu'} \omega'_{\mu'} v^\mu \frac{\partial x'^{\mu'}}{\partial x^\mu}$$

i.e.

$$\omega_\mu = \omega'_{\mu'} \frac{\partial x'^{\mu'}}{\partial x^\mu} \quad \text{or}$$

$$\omega'_{\mu'} = \frac{\partial x^\mu}{\partial x'^{\mu'}} \omega_\mu$$

covariant vector transformation law

In general, for a tensor $T \in T(k, l)$

$$T = \sum_{\mu, \nu} T^{\mu}_{\nu} v^{\mu} \otimes (v^{\nu})^*$$

$\mu = (\mu_1, \dots, \mu_k) \quad \nu = (\nu_1, \dots, \nu_k)$

$$v^{\mu} = \frac{\partial}{\partial x^{\mu_1}} \Big|_p \otimes \frac{\partial}{\partial x^{\mu_2}} \Big|_p \otimes \dots \otimes \frac{\partial}{\partial x^{\mu_k}} \Big|_p$$

$$(v^{\nu})^* = dx^{\nu_1} \otimes dx^{\nu_2} \otimes \dots \otimes dx^{\nu_k}$$

Components of T in new coord. system: $\frac{\partial}{\partial x^{\mu'}} \Big|_p$

$$T^{\mu' \dots \mu'_k}_{\nu' \dots \nu'_k} = \sum_{\mu_1 \dots \mu_k} T^{\mu_1 \dots \mu_k}_{\nu_1 \dots \nu_k} \frac{\partial x^{\mu'_1}}{\partial x^{\mu_1}} \dots \frac{\partial x^{\mu'_k}}{\partial x^{\mu_k}} \frac{\partial x^{\nu_1}}{\partial x^{\nu'_1}} \dots \frac{\partial x^{\nu_k}}{\partial x^{\nu'_k}}$$

\Rightarrow Tensor transformation law $\textcircled{*}$

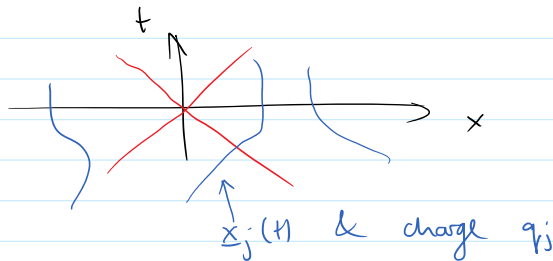
A collection of numbers $T^{\mu}_{\nu}(p)$ w. μ transforming like $\textcircled{*}$ is classically called a tensor (field).

A smooth tensor field T of type (k, k) is one for which

$T(\omega^1, \dots, \omega^k; v_1, \dots, v_k)$ is smooth for all

smooth $\omega^1, \dots, \omega^k, v_1, \dots, v_k$ ($\omega \in V_p^*$ is smooth if $\omega \circ \gamma$ is smooth, γ smooth $\gamma, \omega(\gamma)$ is C^∞)

Examples: (i) Currents and densities in SR.
Let $M = \mathbb{R}^{1,3}$.



N particles: $j=1, \dots, N$

Density (of charge) $\rho(x, t) = \sum_{j=1}^N q_j \delta^{(3)}(x - x_j(t))$
(Dirac Delta function)

Current $\underline{J}(x, t) = \sum_{j=1}^N q_j \delta^{(3)}(x - x_j(t)) \frac{dx_j(t)}{dt}$

Define a four vector J^{μ} by setting

$$J = \begin{pmatrix} \rho \\ \underline{J} \end{pmatrix}$$

Ex. argue that J^{μ} is a vector (in V_p) field under changes of coordinates via Lorentz transformations

$$x'^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu}$$

of coordinates via Lorentz transformations

$$x'^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu}$$

(ii) Energy-momentum tensor in SR. Let $M = \mathbb{R}^{1,3}$. Consider a collection N particles with energy-momentum four vectors p_j^{μ} ; $j=1, \dots, N$

The density of μ th component $p^{\mu}(t)$ is defined to be

$$T^{\mu 0}(x, t) \equiv \sum_{j=1}^N p_j^{\mu}(t) \delta^{(3)}(x - x_j(t))$$

Corresponding current

$$J^{\mu k} \text{ can } T^{\mu k}(x, t) = \sum_{j=1}^N p_j^{\mu}(t) \frac{dx_j^k}{dt}(t) \delta^{(3)}(x - x_j(t))$$

Combine to a single formula ($x \equiv (x, t)$)

$$T^{\mu \nu}(x) = \sum_{j=1}^N p_j^{\mu} \frac{dx_j^{\nu}}{dt} \delta^{(3)}(x - x_j(t))$$

(Here $x^0(t) = t$). Since

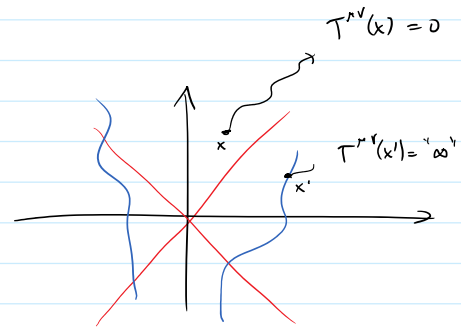
$$p_j^{\nu} = E_j \frac{dx_j^{\nu}}{dt}$$

we have

$$T^{\mu \nu}(x) = \sum_j \frac{p_j^{\mu} p_j^{\nu}}{E_j} \delta^{(3)}(x - x_j(t))$$

\Rightarrow

T is symmetric; i.e. $T^{\mu \nu} = T^{\nu \mu}$



Writing

$$T^{\mu \nu}(x) = \sum_j \int d\tau p_j^{\mu} \frac{dx_j^{\nu}}{d\tau} \delta^{(4)}(x - x_j(\tau))$$

argue (ex). under Lorentz transformations $x'^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu}$

$$T'^{\mu' \nu'} = \Lambda^{\mu'}_{\mu} \Lambda^{\nu'}_{\nu} T^{\mu \nu}$$

$$\left(\Lambda^{\mu'}_{\nu'} = \frac{\partial x'^{\mu'}}{\partial x^{\nu'}} \right)$$

T is a tensor of type $(2,0)$

(iii) The metric tensor

A metric tensor g is a tensor field of type $(0,2)$, which is symmetric and nondegenerate, i.e., $\forall v_1, v_2 \in V_p$

$$g(v_1, v_2) = g(v_2, v_1)$$

and

$$\Rightarrow \begin{aligned} g(v, v_i) &= 0 & \forall v \in V_p \\ v_i &= 0 \end{aligned}$$

A metric is the extra data we need to supply us with a notion of infinitesimal length:

infinitesimal displacement \approx tangent vector

"infinitesimal squared distance" \approx quadratic function of tangent vector

Choose coordinate basis $\frac{\partial}{\partial x^\mu}|_p$: expand g :

$$g = \sum_{\mu, \nu} g_{\mu\nu} dx^\mu \otimes dx^\nu \quad (\equiv ds^2)$$

We often omit " \otimes " sign:

$$ds^2 = g = \sum_{\mu, \nu} g_{\mu\nu} dx^\mu dx^\nu$$

A metric actually supplies us with extra data of a inner product on V_p , $\forall p \in M$:

$$\begin{aligned} (v, w)_p &\equiv \sum_{\mu, \nu} g_{\mu\nu} (dx^\mu \otimes dx^\nu)(v, w) \\ &= \sum_{\mu, \nu} g_{\mu\nu} (dx^\mu(v) dx^\nu(w)) \\ &= \sum_{\mu, \nu} g_{\mu\nu} v^\mu w^\nu \end{aligned}$$

$$\boxed{v = \sum v^\mu \frac{\partial}{\partial x^\mu}|_p}$$

Gram-Schmidt procedure: orthonormal basis v_i for V_p s.t.

$$(v_\mu, v_\nu) = g(v_\mu, v_\nu) = s_\mu \delta_{\mu\nu}$$

where $s_\mu \in \{\pm 1\}$

ex: prove this

The number of ± 1 is independent of oth. basis
 \Rightarrow signature of g

A metric g with $s_\mu = +1$, $\forall \mu$, is Riemannian (g is positive definite). The metric of spacetime has signature $(-1, +1, +1, +1)$

A metric g is simultaneously interpreted as a $(0,2)$ tensor and also as a multilinear map from

$g: V_p \times V_p \rightarrow \mathbb{R}$
 also as a linear map from V_p to V_p^* induced via

$$v \mapsto g(\cdot, v) \equiv \cdot(v)$$

also as a linear map from V_p to V_p^* induced via

$$v \mapsto g(\cdot, v) \equiv \omega$$

what is this map?

$$g(\cdot, v) : V_p \rightarrow \mathbb{R}$$

$$g(\cdot, v) \in V_p^*$$

This map is 1 to 1 & onto and gives us a canonical basis-independent correspondence between vectors & dual vectors

Abstract index notation

Suppose $T \in T(k, l)$

Think T as a multilinear map from $(V_p^*)^{\otimes k} \otimes (V_p)^{\otimes l} \rightarrow \mathbb{R}$

Can specify T via its components in a basis $T^{a_1 \dots a_k}_{b_1 \dots b_l}$

Often it is enough just to know which arguments of T take vectors / or dual vectors. Capture this by labelling each argument with a lower case latin letter

Superscript indices label contravariant entries &
Subscript indices \rightarrow covariant entries eg.

$$T^{ab}_{cd}$$

denotes a $(2, 2)$ tensor. Here lower-case latin letters label arguments and tensor type (not components with respect to a basis)