# Completeness Thresholds for Memory Safety: Unbounded Guarantees via Bounded Proofs

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October 18, 2023

### What This Work Is About

- Connection between bounded & unbounded proofs
- Ideas to increase trust in bounded model checking

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- Connection between bounded & unbounded proofs
- Ideas to increase trust in bounded model checking
- When is a bounded "proof" a proof?

# Model Checking: Easy Off-by-1 Error

- WHILE language with pointer arithmetic
- Targeted property: Memory safety
- Memory assumption array(a, s):  $a[0] \dots a[s-1]$  allocated

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for i in [0 : s-1] do !a[i+1]
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for i in [0 : s-1] do !a[i+1]
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Which bounds should we choose for s?

- s = 0: No error
- s = 1: Error

# Model Checking: "Harder" Off-by-N Error

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Memory assumption: for i in [0:s-2] do array(a, s) !a[i+2]
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Memory assumption: for i in [0:s-2] do array(a, s) !a[i+2]
```

Which bounds should we choose for s?

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- s = 1: No error
- s = 2: Error

### Model Checking: No Off-by-N Error

```
Memory assumption: for i in [0:s-1] do array(a, s) !a[i]
```

Which s can convince us?

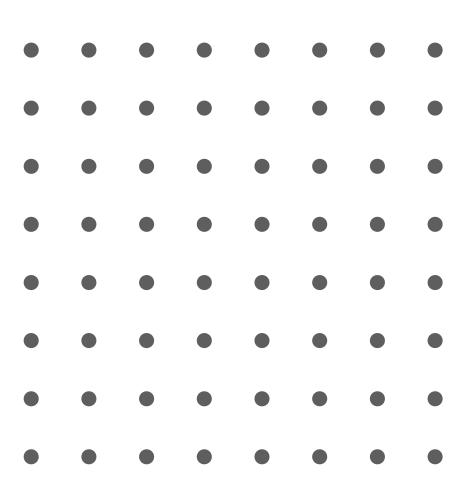
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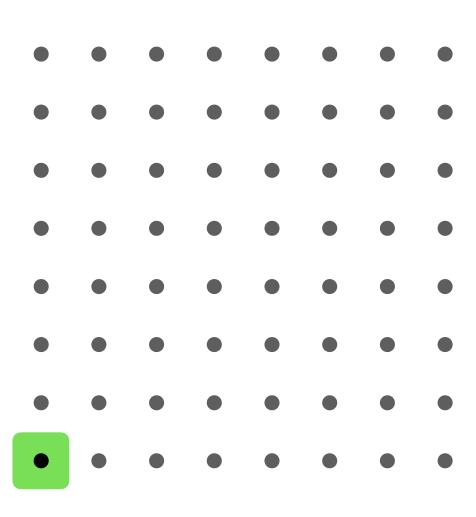
Which s can convince us?

- s = 0: No error
- s = 1: No error
- s = 2: No error  $\Rightarrow$  Which size bound is large enough?
- s = 3: No error

- Finite state transition system T
- Prove property Gp  $G \approx globally \approx p$  holds in every state
- Approach: Prove Gp for all paths up to length k  $T \models_k Gp$

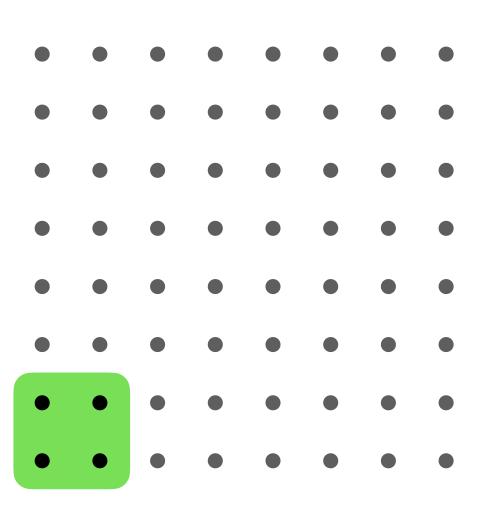


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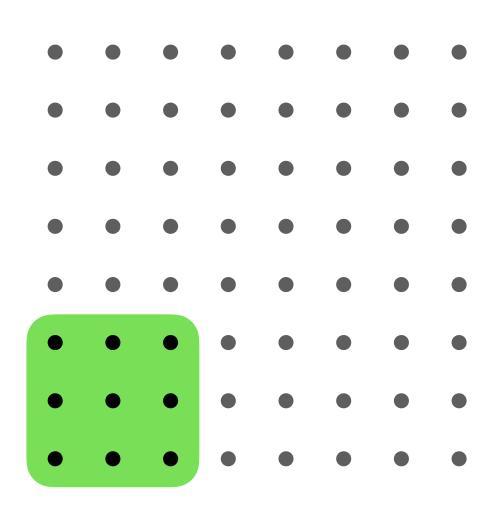
$$T \models_0 \mathsf{G} p$$

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$$T \models_1 \mathsf{G} p$$

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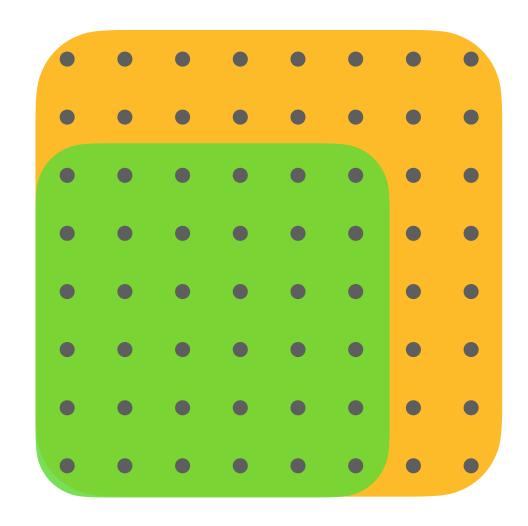
 $T \models_2 \mathbf{G}p$ 

When should we stop?

• k is completeness thresholds (CT) iff

$$T \models_k \phi \Rightarrow T \models \phi$$

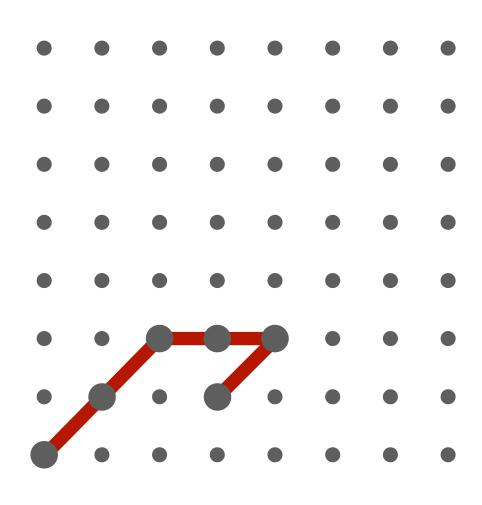
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- For specific  $\phi$ : Can over-approximate CT via of key props of T
- For  $\phi = Gp$  we know CT(T, Gp) = diameter(T) (longest distance between any states)

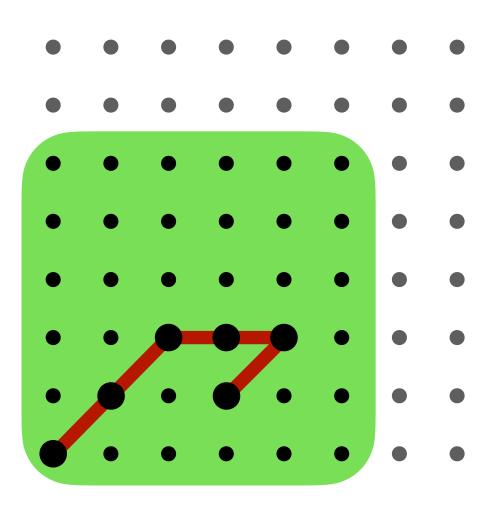


diameter(T) = 5

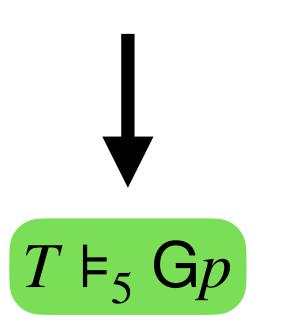
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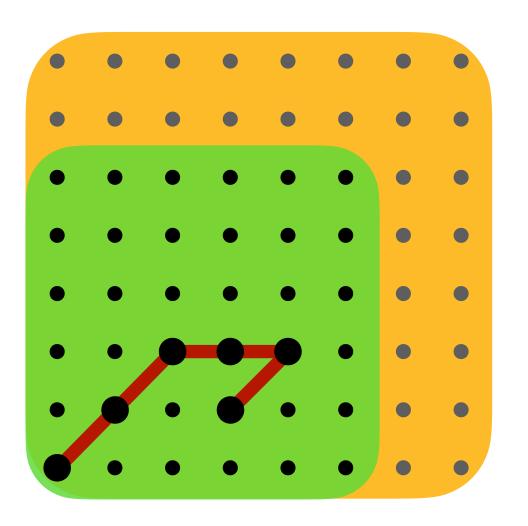


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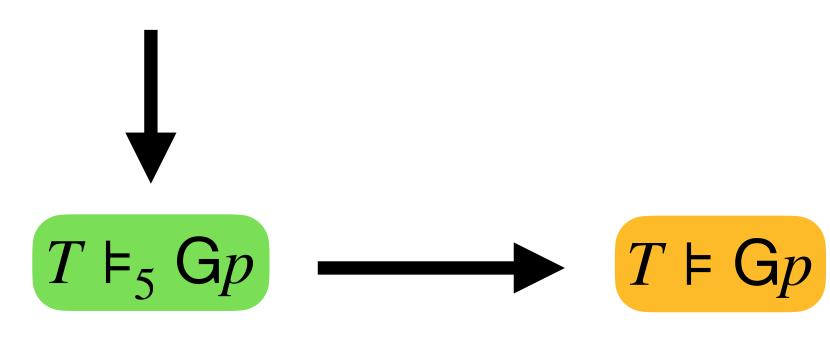


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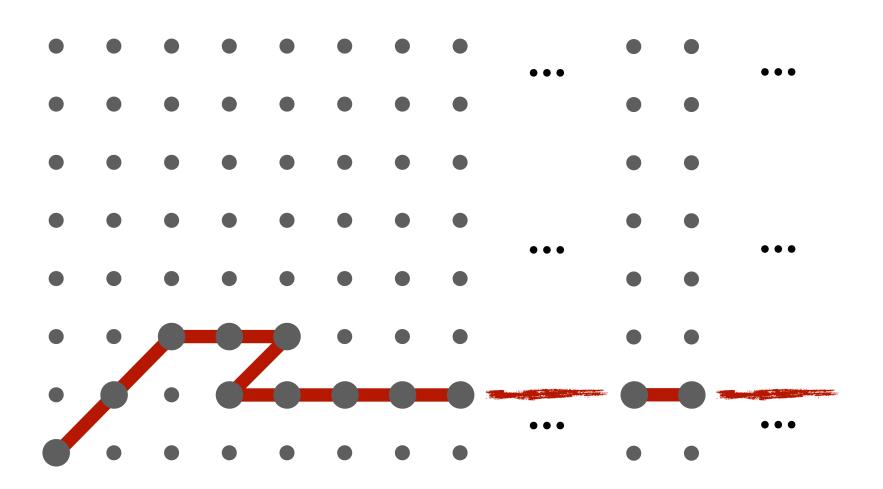
diameter(T) = 5



# CTs for Infinite Systems?

#### **Problem**

Key properties used to describe CTs may be ∞



$$diameter(T) = \infty$$

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#### **Problem**

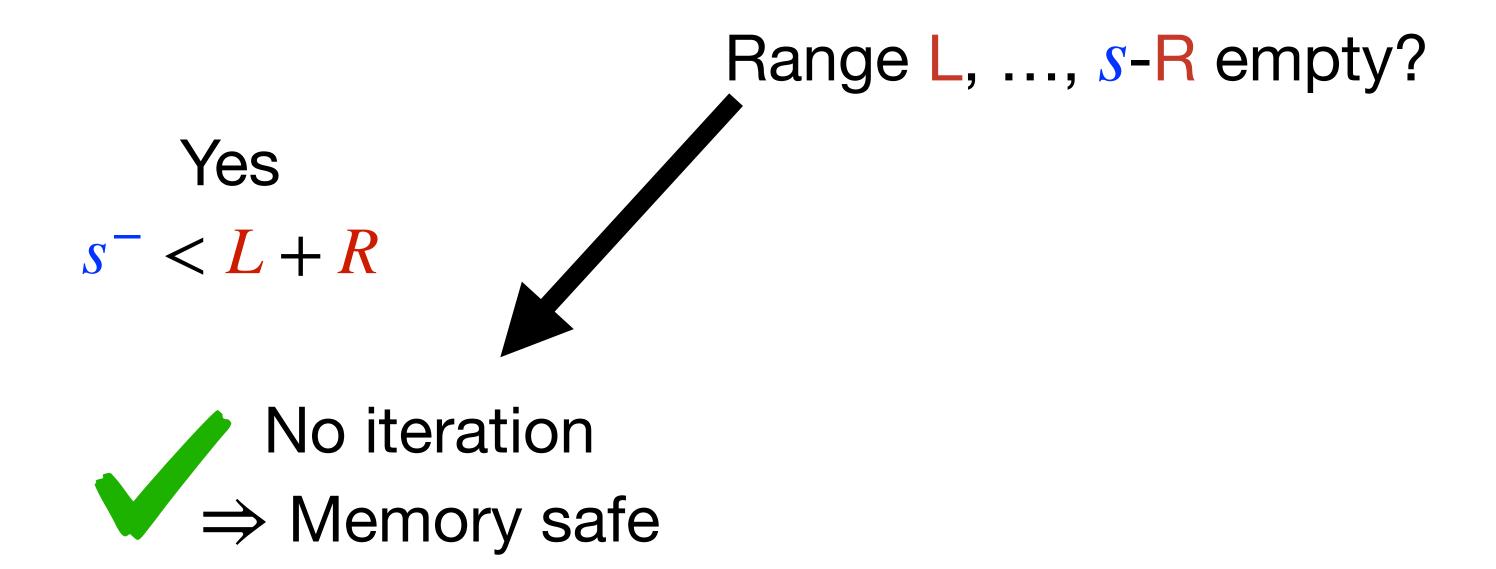
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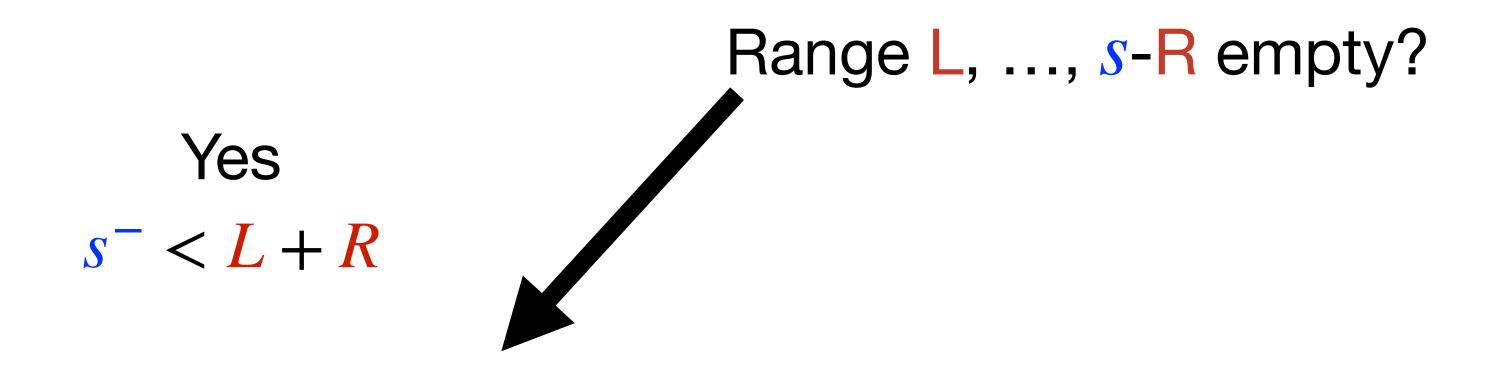
#### **Our Approach**

Analyse program's *verification conditions* instead of transition system

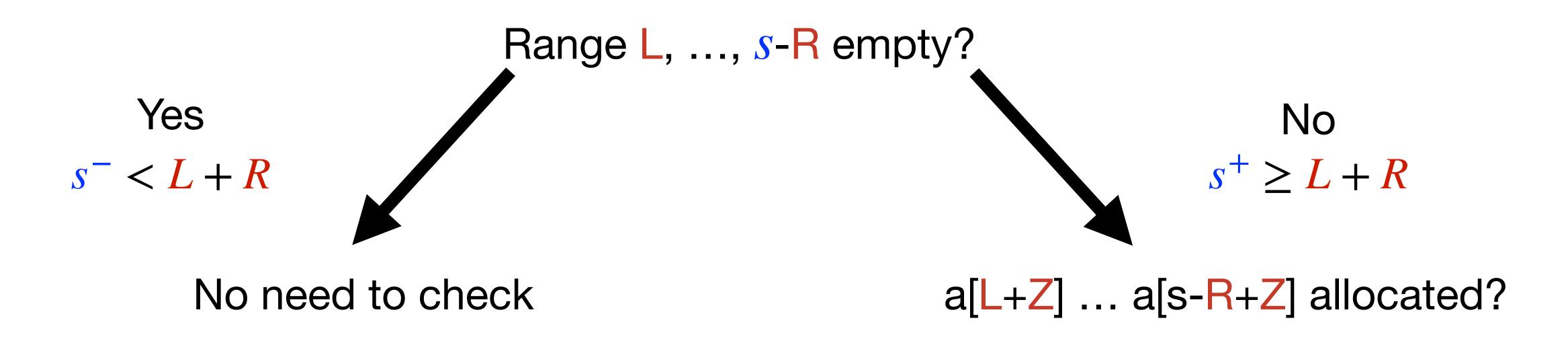
Only source for memory errors

Memory assumption: for i in [L : s-R] do array(a, s) !a[i+Z]

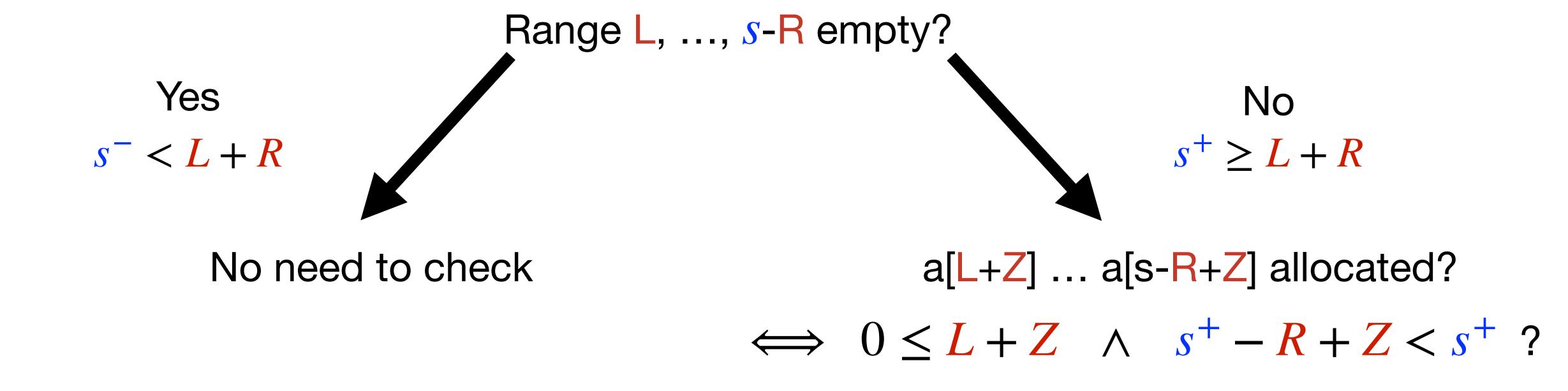




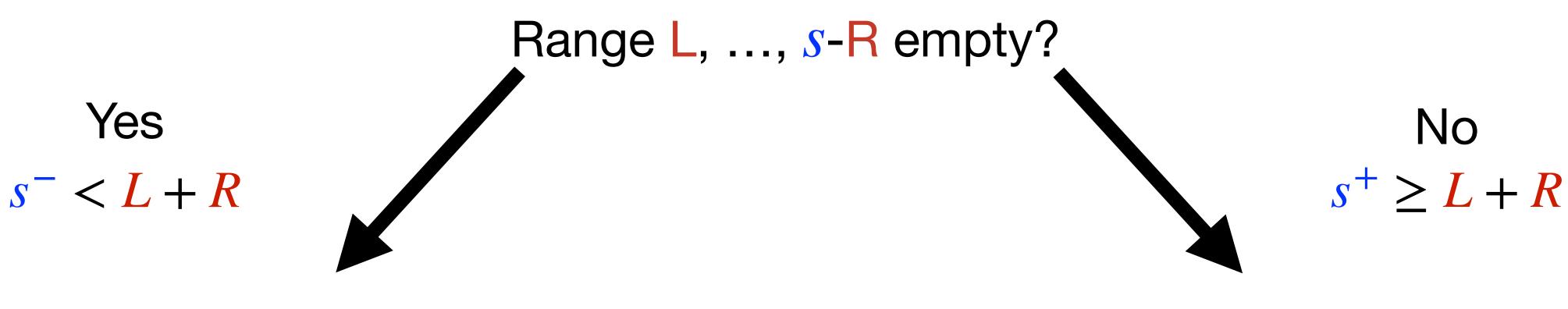
No need to check



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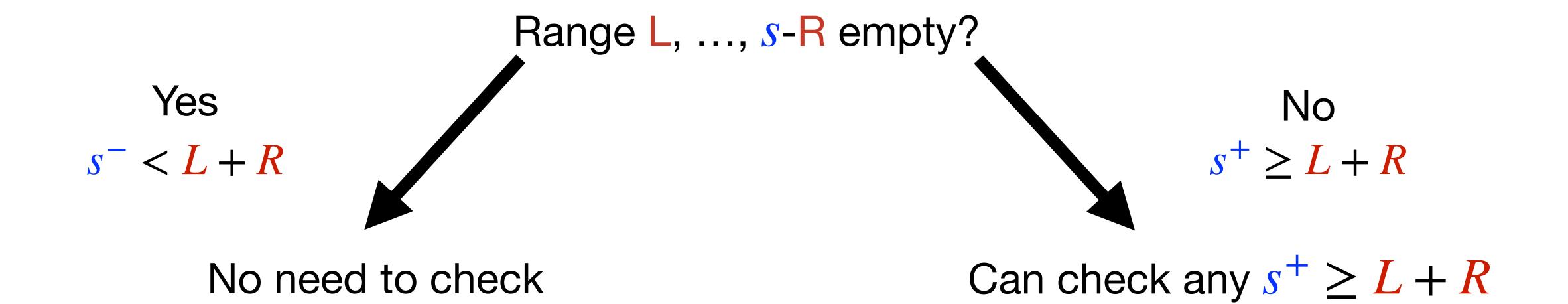


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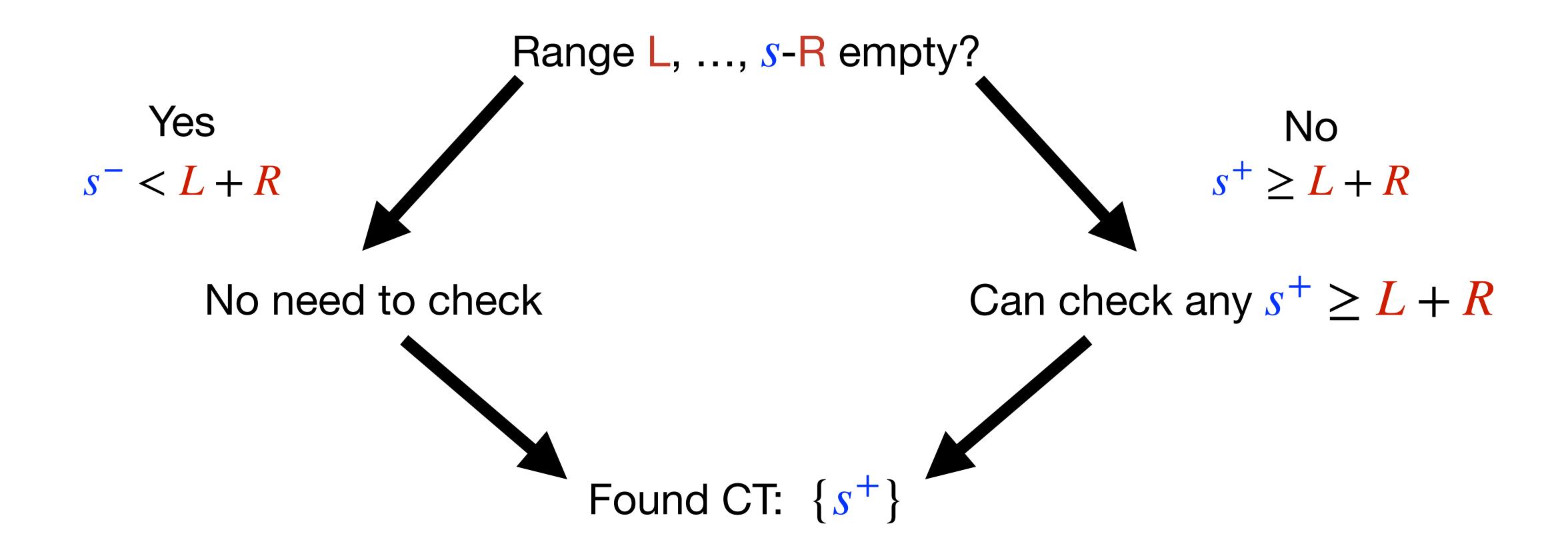
$$a[L+Z] \dots a[s-R+Z]$$
 allocated?  
 $\iff 0 \le L+Z \land R+Z < ?$ 

$$\iff 0 \le L + Z \land -R + Z < 0 ?$$

No 
$$s^+ \Rightarrow$$
 Can check any  $s^+ \ge L + R$ 



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### Completeness Thresholds

- Program variable x with domain X
- Specification  $\forall x \in X.Spec(c)$

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- Specification  $\forall x \in X.Spec(c)$
- Subdomain  $Q \subseteq X$  is a CT for x in  $\forall x \in X$ . Spec(c) iff  $\forall x \in Q$ .  $Spec(c) \Rightarrow \forall x \in X$ . Spec(c)
- For us: CT are subdomains, not depths

### Verification Conditions

• Logical formula vc is VC for any spec Spec(c) iff

$$\models vc \Rightarrow \models Spec(c)$$

- Can verify VC instead of program
- In general: VCs are over-approximations, i.e., possible that  $\not\models vc$  but  $\models Spec(c)$

### How to Prove CTs

• Generate VC:  $Spec(c) \implies \forall x \in X. \ vc(x)$ 

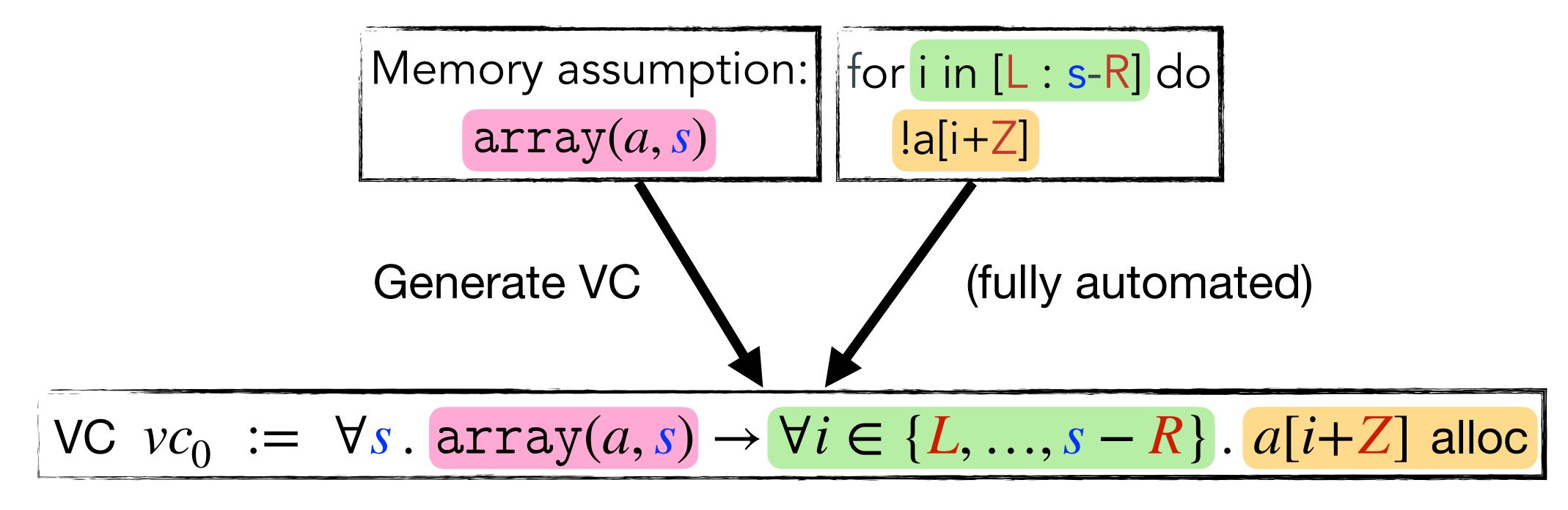
### How to Prove CTs

• Generate VC:  $Spec(c) \implies \forall x \in X. \ vc(x)$ 

• Identify subdomain  $Y \subseteq X$  where choice  $x \in Y$  does not influence validity of vc(x)

$$\left( \models vc(x) \iff \models vc' \text{ with } x \notin \text{free}(vc') \right)$$

 $\implies$  Found CT:  $(X \setminus Y) \cup \{y\}$  (for any choice of  $y \in Y$ )



```
\forall c_0 := \forall s. \ \operatorname{array}(a, s) \to \forall i \in \{L, ..., s - R\} \ . \ a[i + Z] \ \text{alloc}
```

Range L, ..., s-R empty?

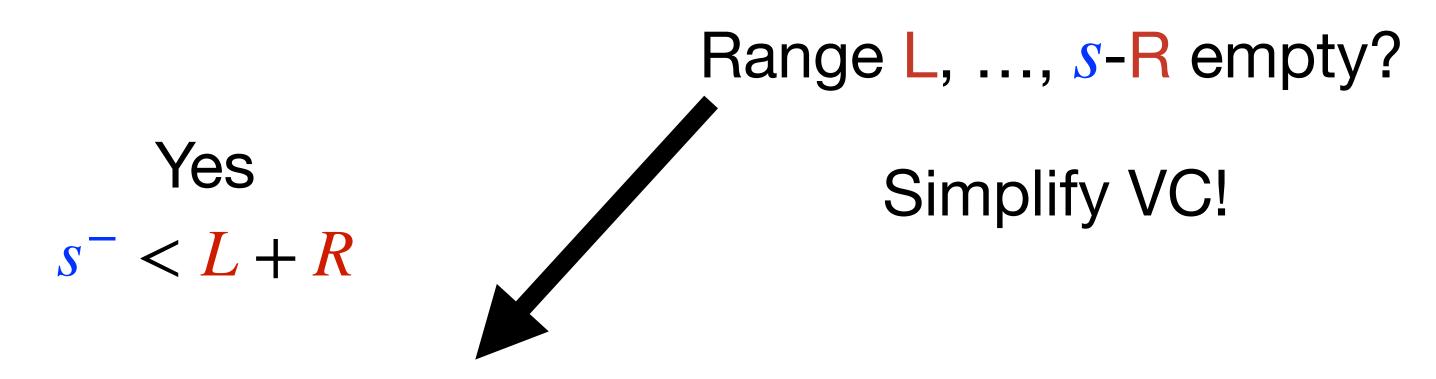
 $vc_0 \equiv \forall s^- \dots \rightarrow \forall i \in \emptyset \dots$ 

**■** True

$$\text{VC } vc_0 := \forall \textbf{\textit{s}}. \ \text{array}(a,\textbf{\textit{s}}) \rightarrow \forall i \in \{\textbf{\textit{L}},...,\textbf{\textit{s}}-\textbf{\textit{R}}\} \ . \ a[i+\textbf{\textit{Z}}] \ \text{alloc}$$

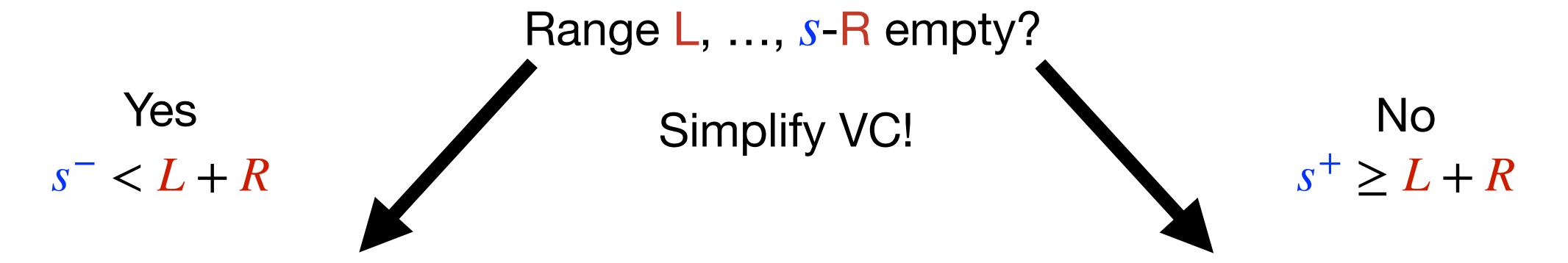
Yes Simplify VC! 
$$s^- < L + R$$

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$$vc_0 \equiv \forall i. (L \leq i < s^+ - R) \rightarrow (0 \leq i + Z < s^+)$$

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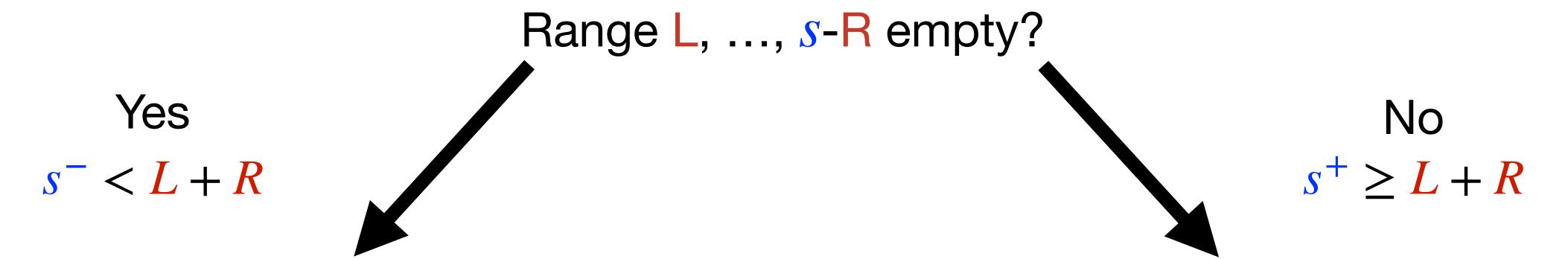
Yes  $s^- < L + R$ 

No need to check

Range L, ..., s-R empty? Simplify VC! No  $s^+ \ge L + R$   $vc_0 \equiv \forall i . (L \le i < -R) \rightarrow (0 \le i + Z < R)$   $\equiv \forall i . (L \le i \rightarrow 0 \le i + Z)$   $\land (i \le -R) \rightarrow i + Z < 0)$ 

⇒ Validity does not depend on size

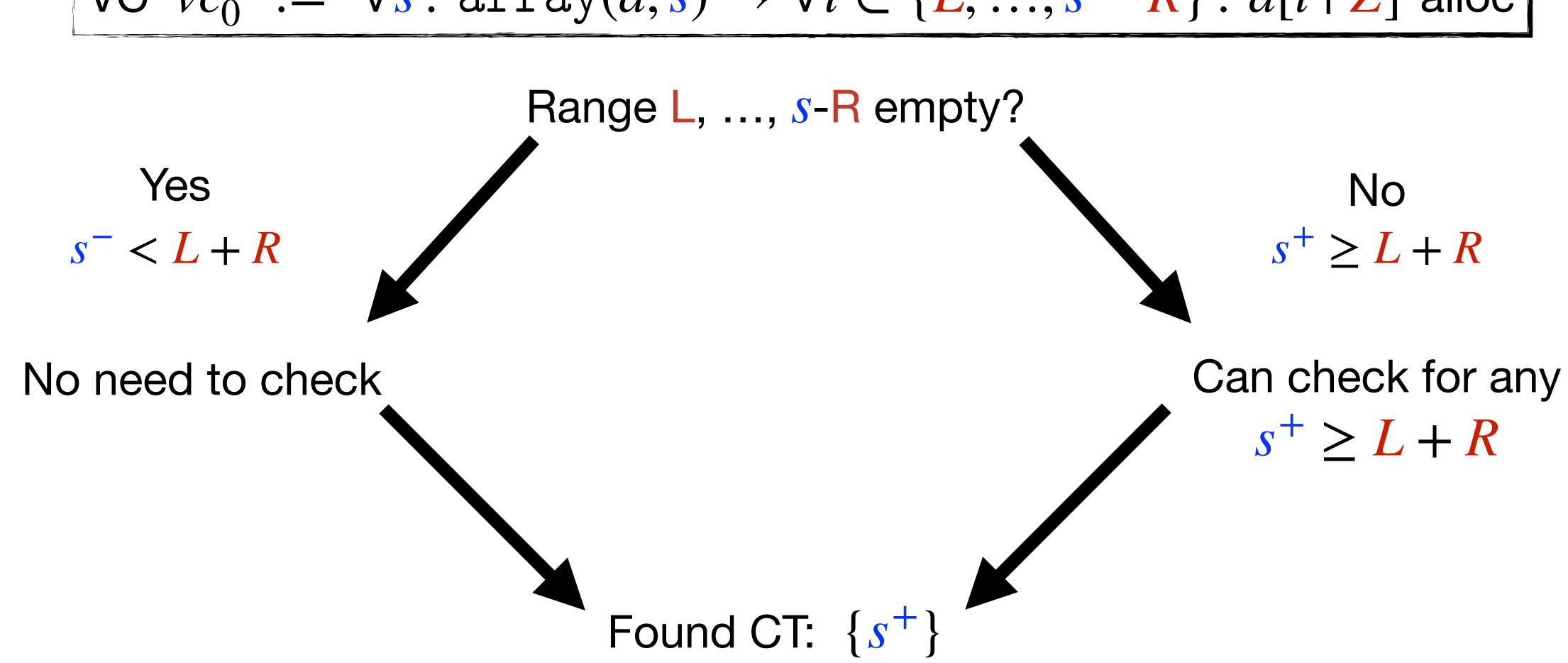
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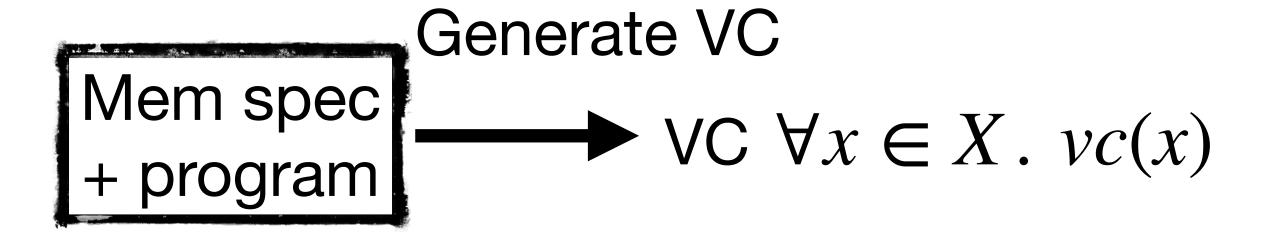
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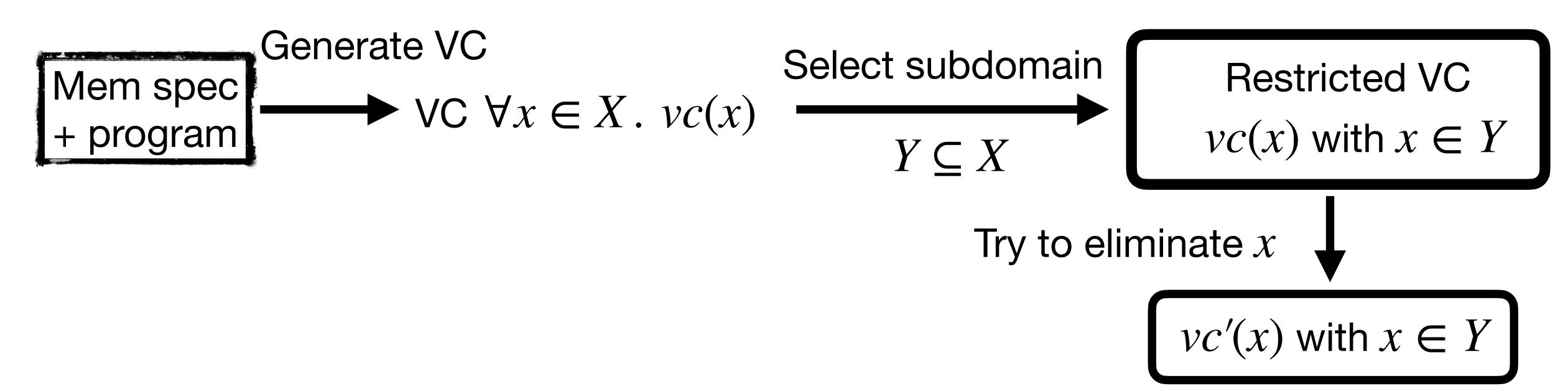
Can check for any 
$$s^+ > L + R$$

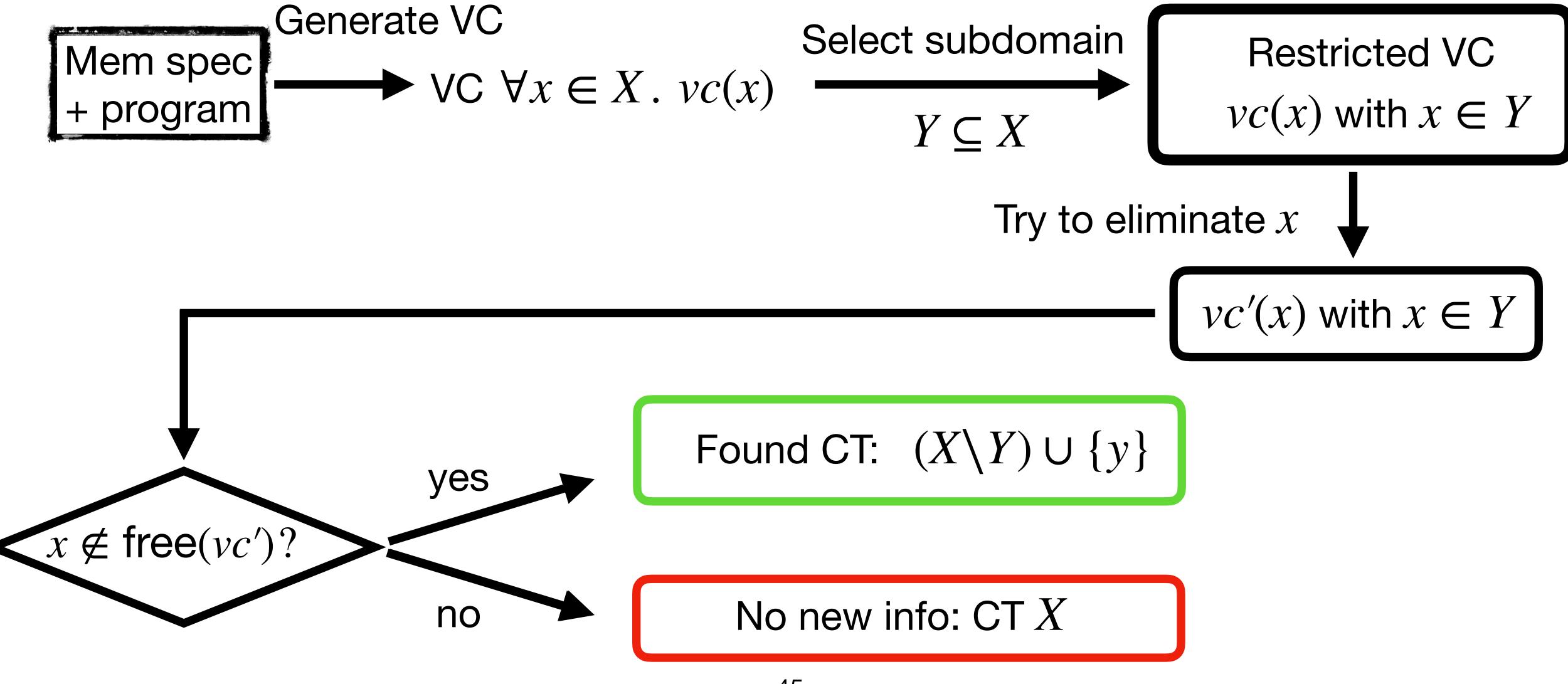
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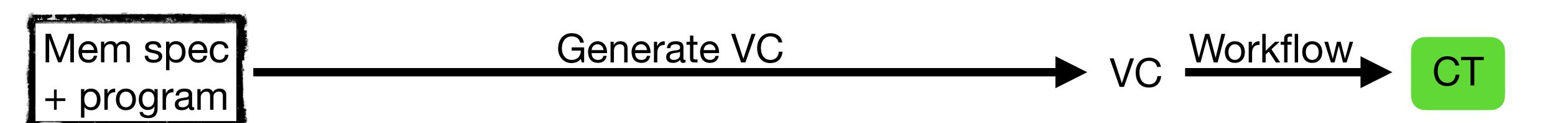


Mem spec + program

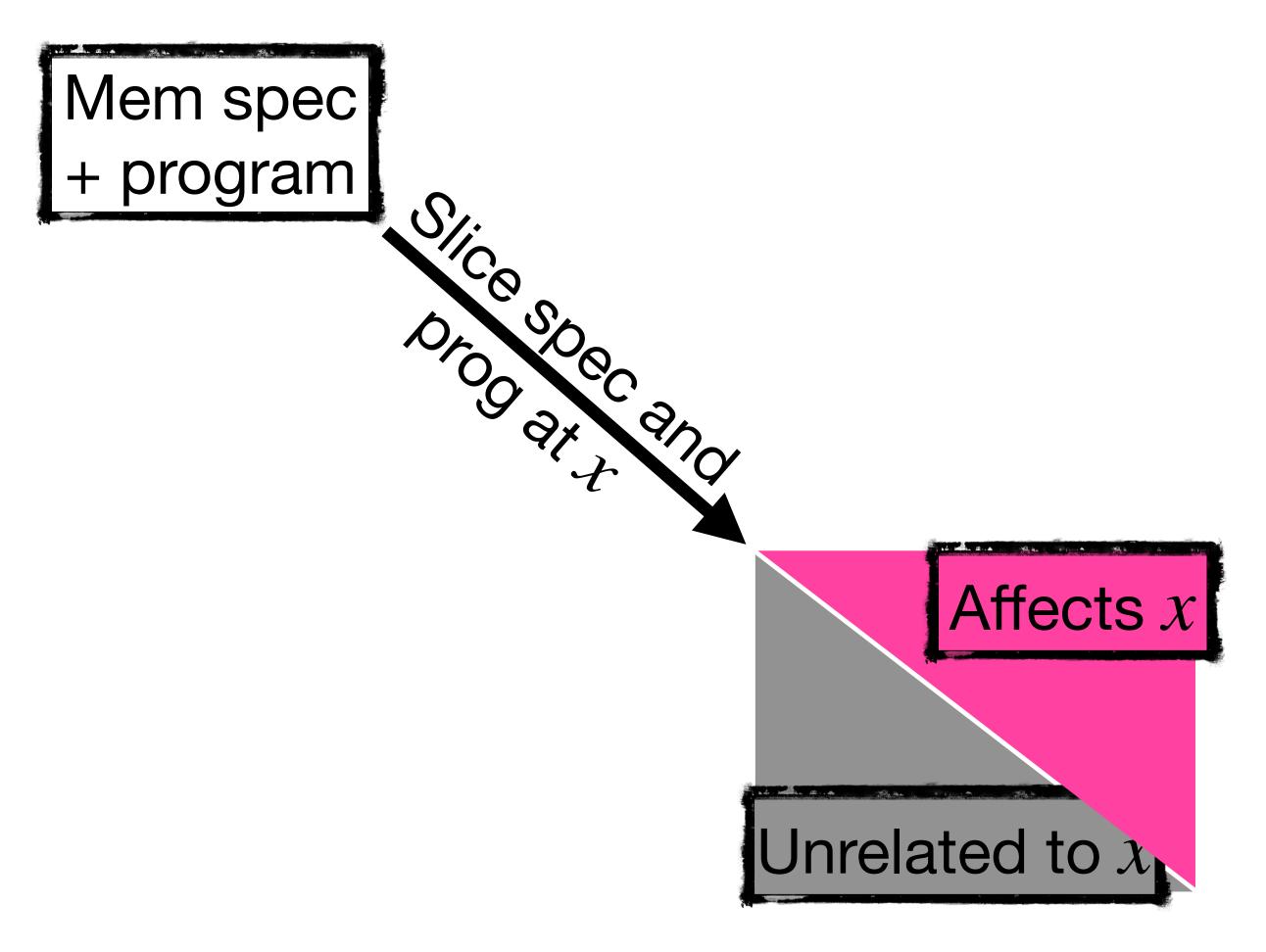




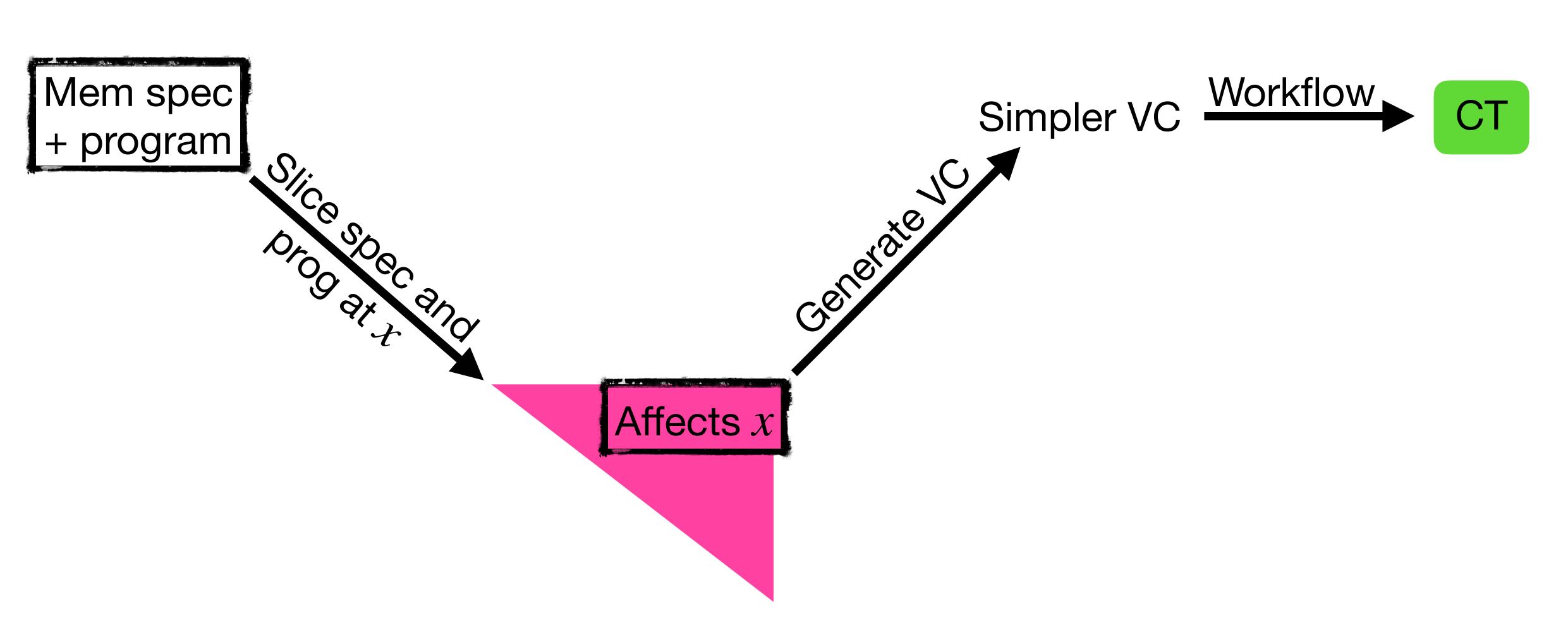


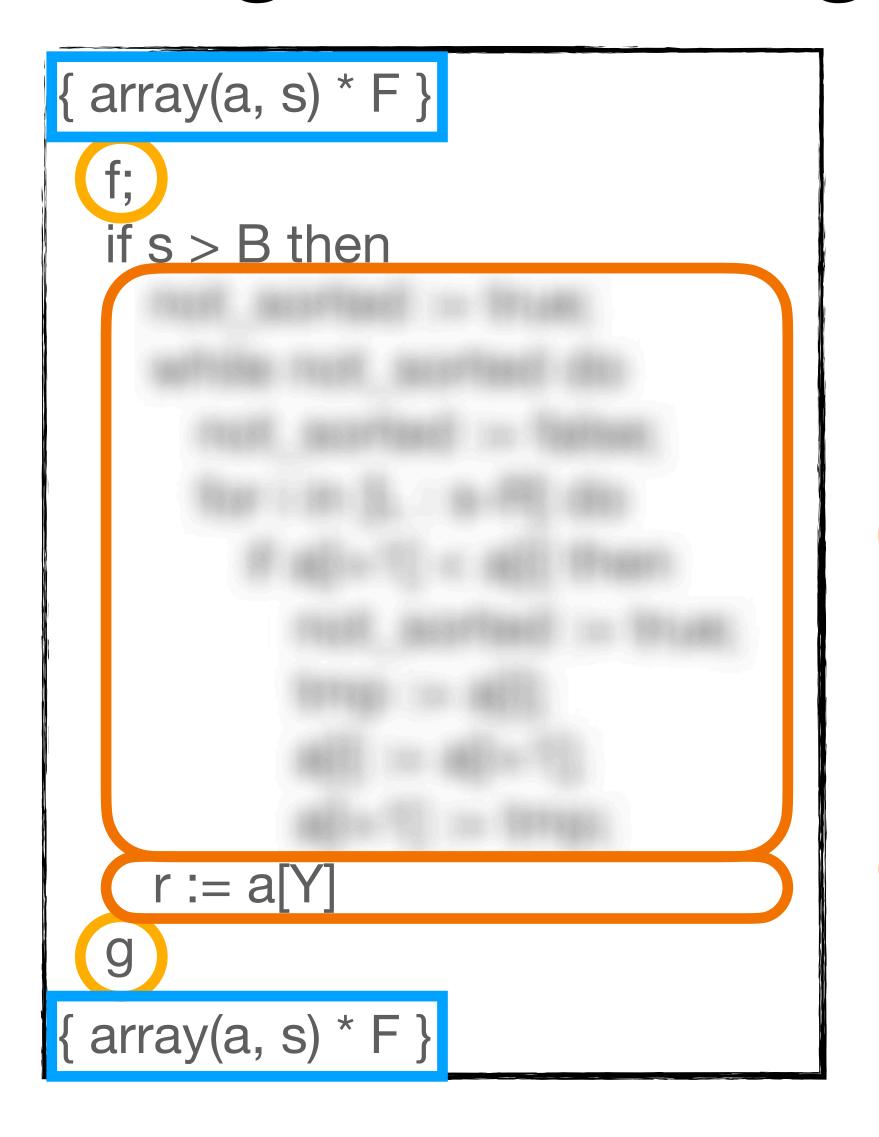












#### **Precondition**

Complex code not mentioning a, s

bubble\_sort(a)

Select element

Complex code not mentioning a, s

**Postcondition** 

```
{ array(a, s) * F }
  if s > B then
    not_sorted := true;
    while not_sorted do
      not_sorted := false;
      for i in [L:s-R] do
        if a[i+1] < a[i] then
           not_sorted := true;
          tmp := a[i];
          a[i] := a[i+1];
          a[i+1] := tmp;
    r := a|Y|
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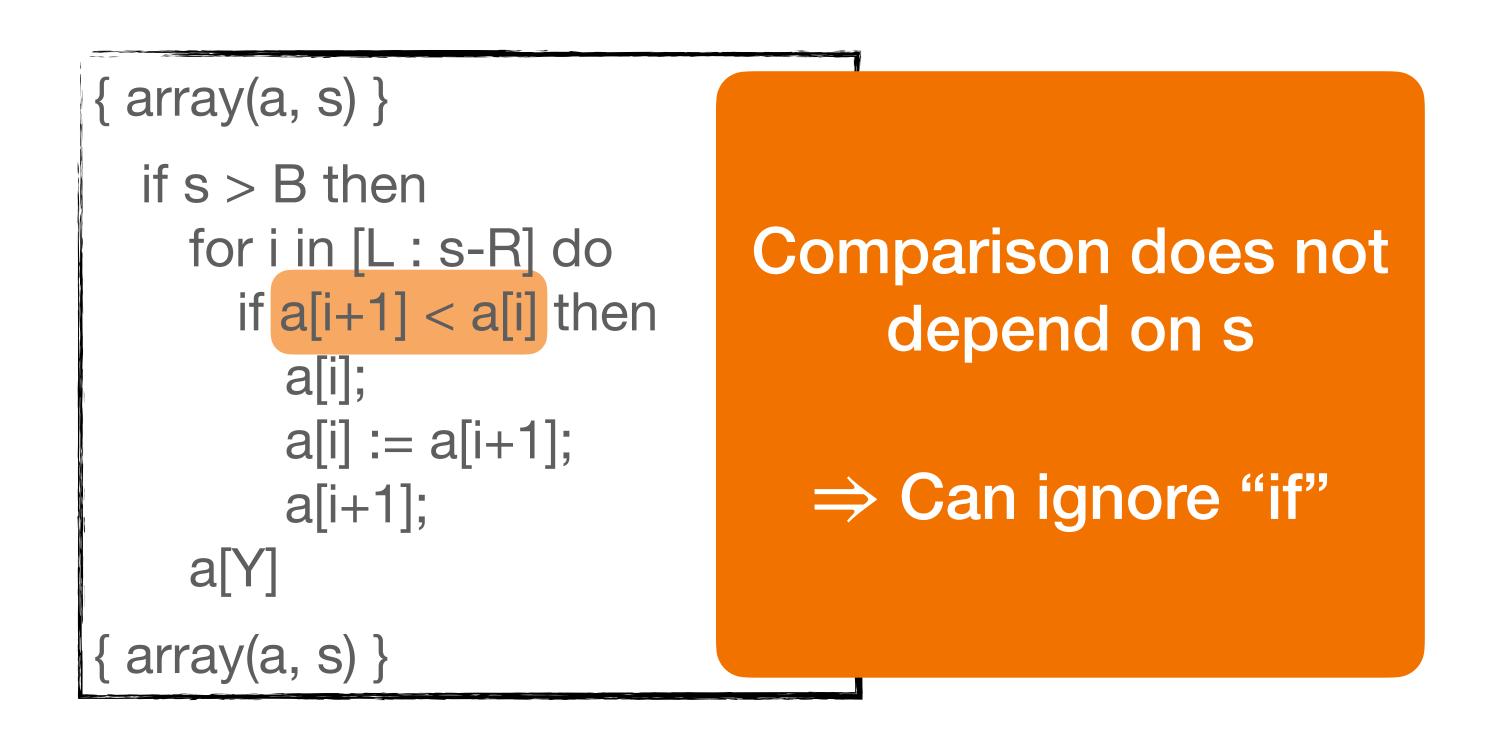
a[i];

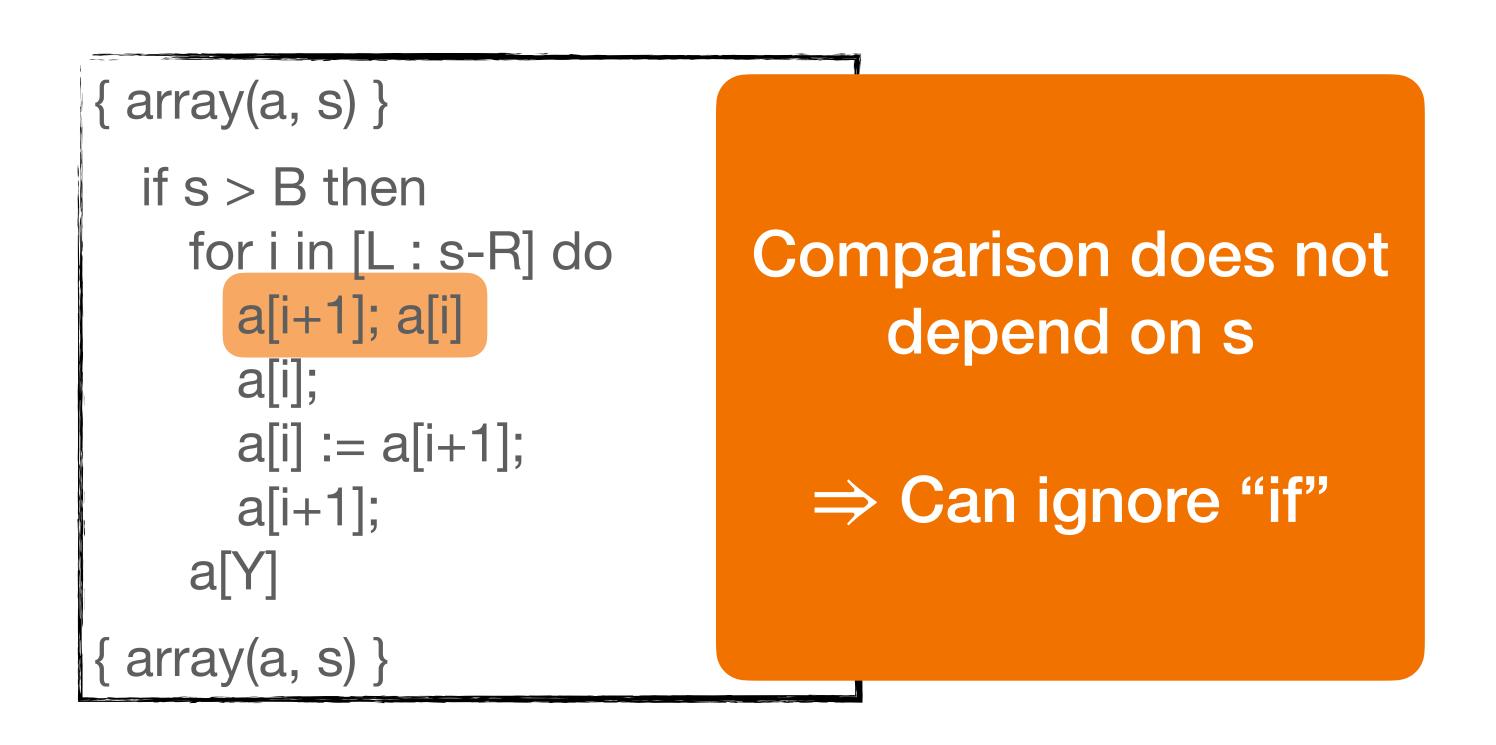
a[i] := a[i+1];

a[i+1];

a[Y]

{ array(a, s) }
```





```
{ array(a, s) }

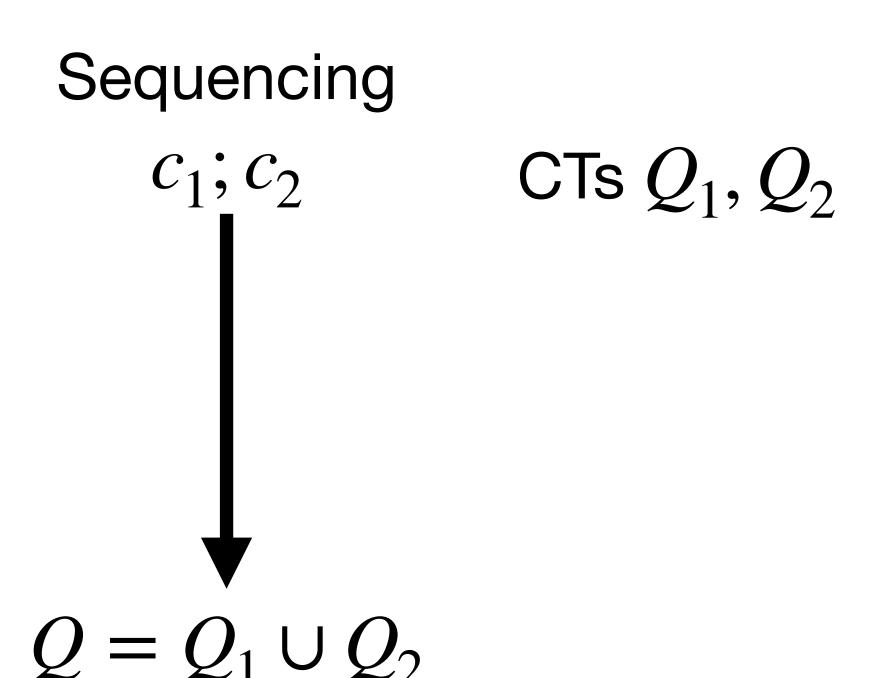
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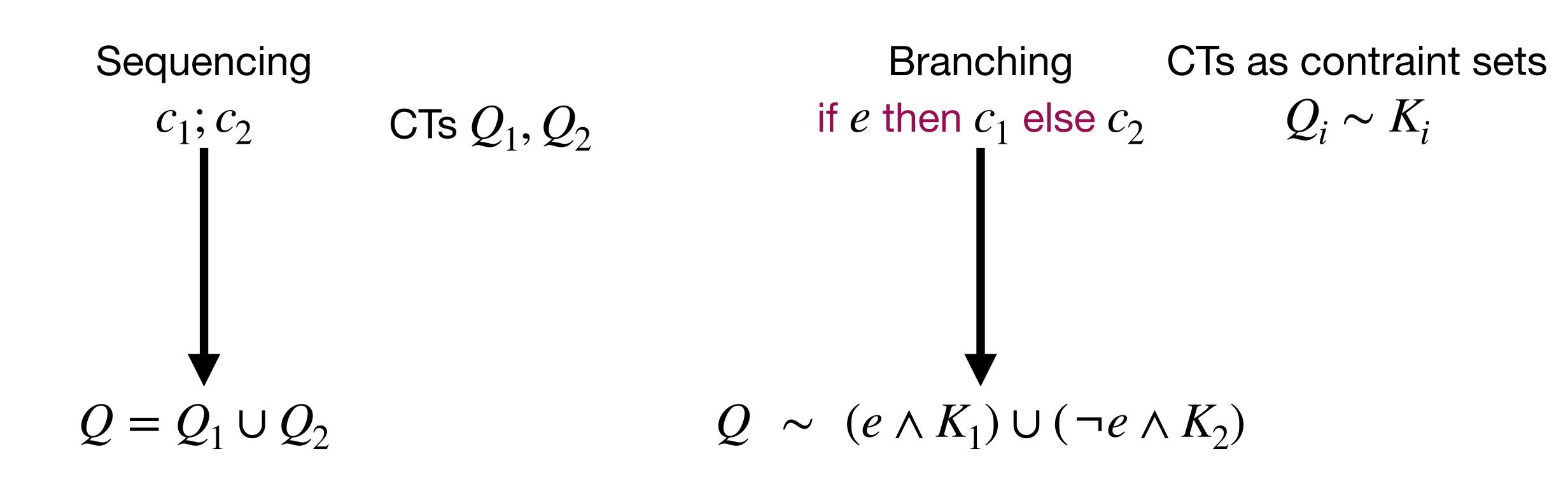
a[i+Z]
a[Y]

{ array(a, s) }
```

# Scalability CT Combinators

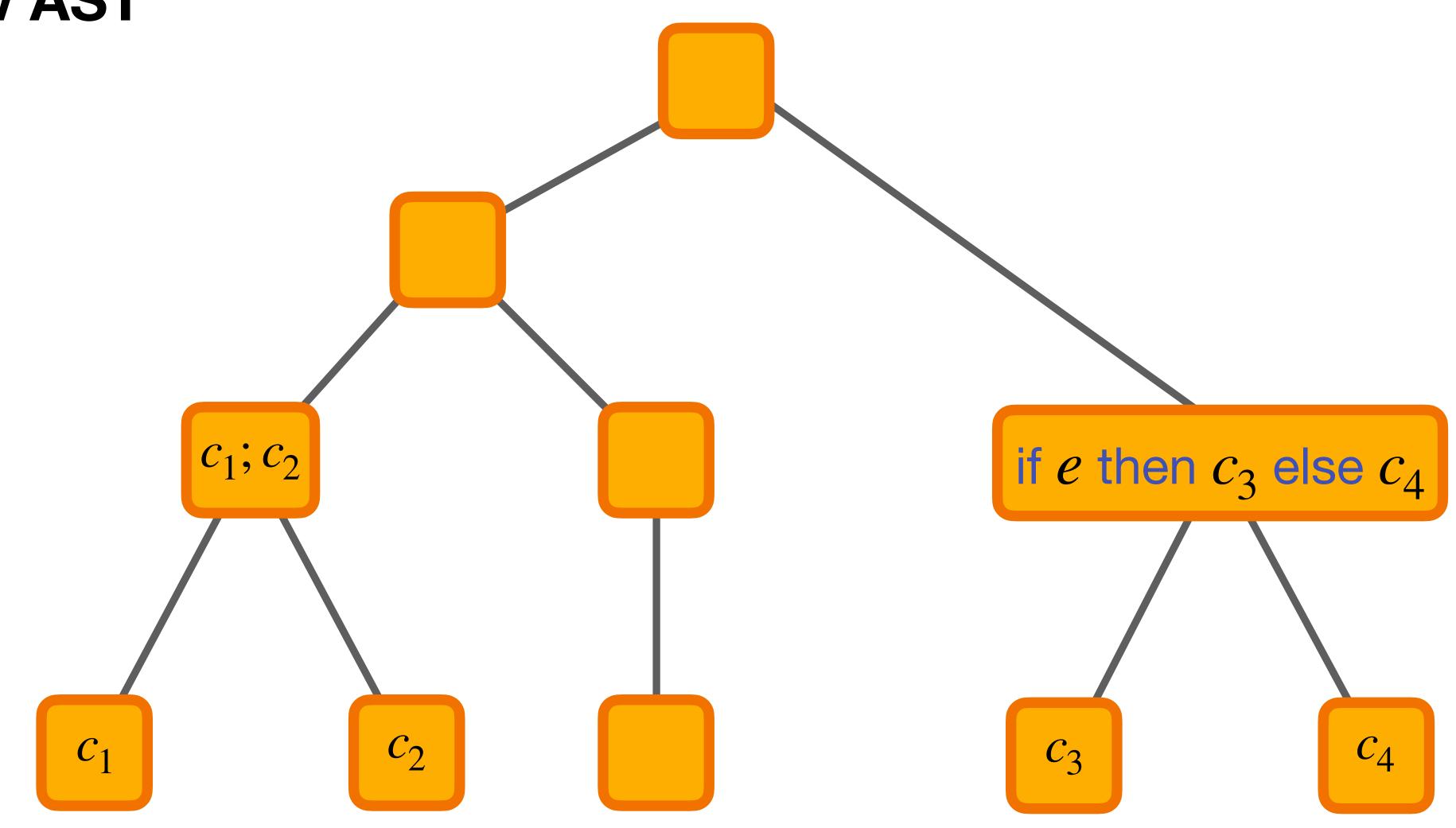


# Scalability CT Combinators



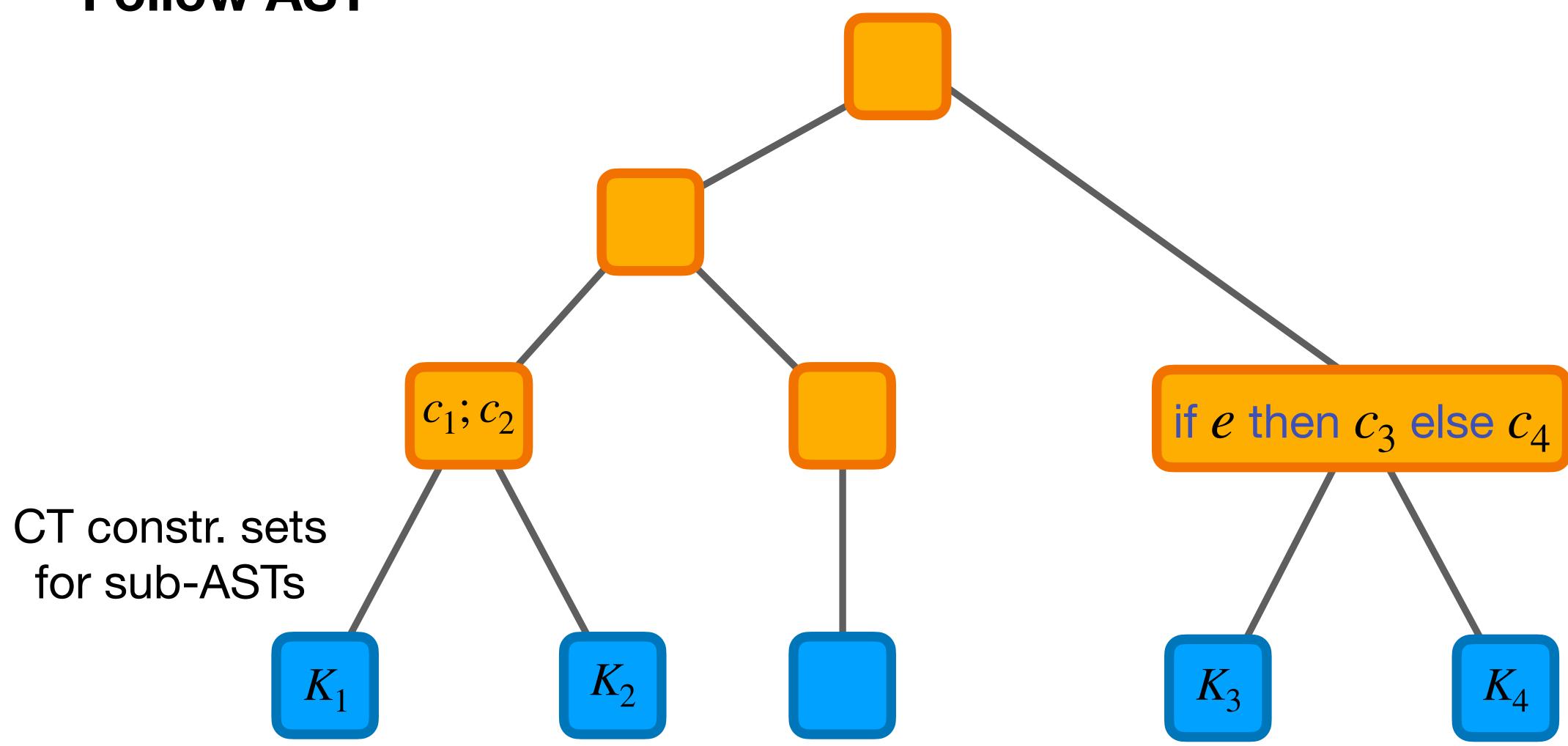
# Scalability

**Follow AST** 



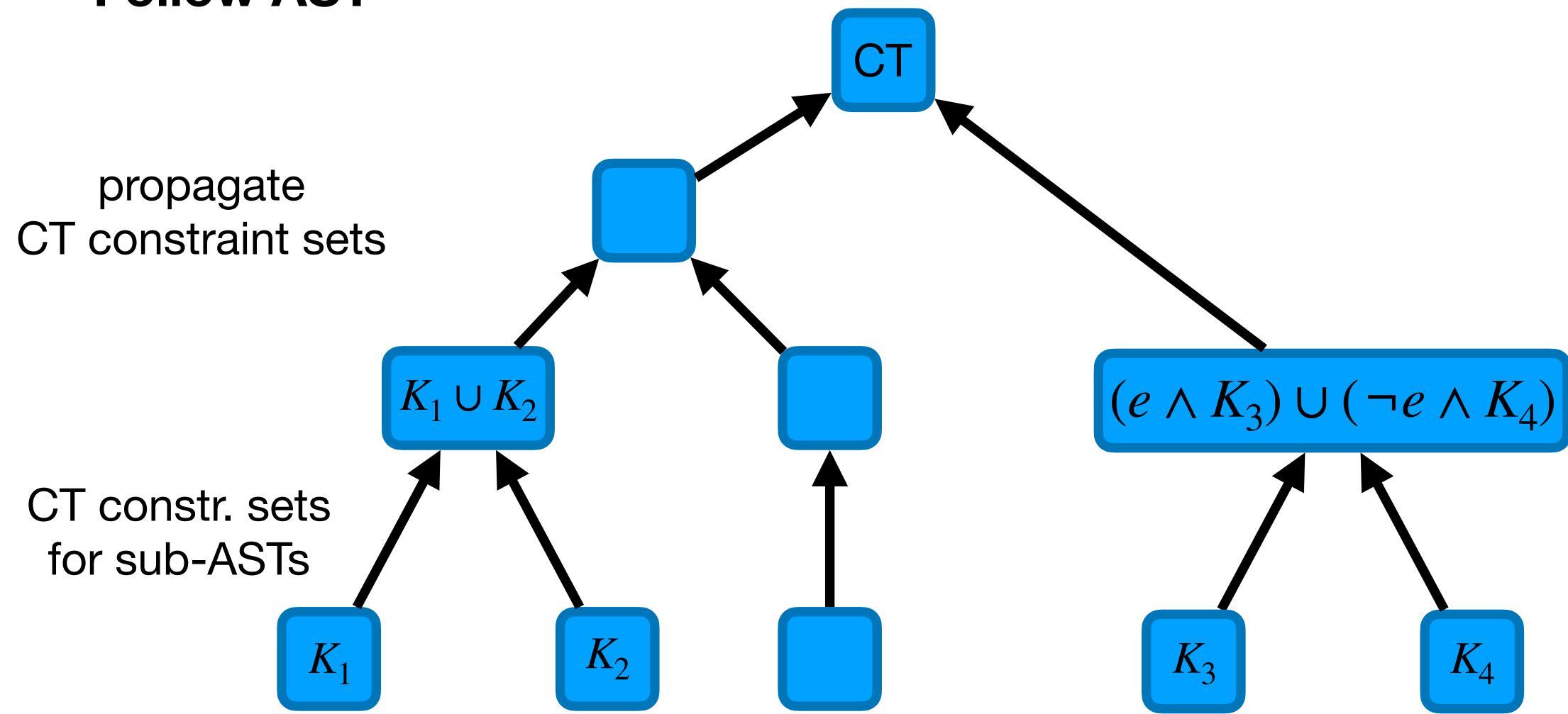
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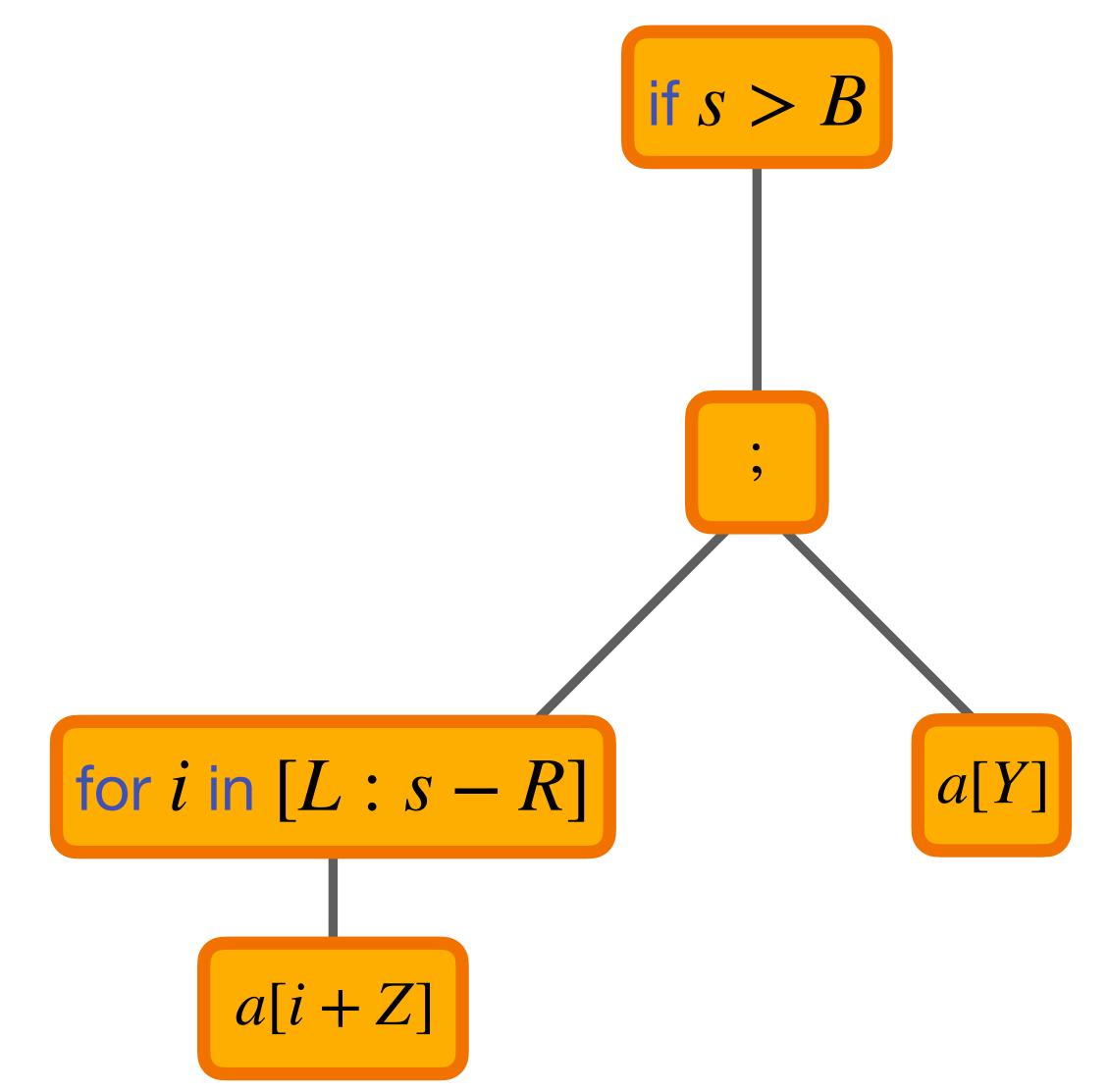
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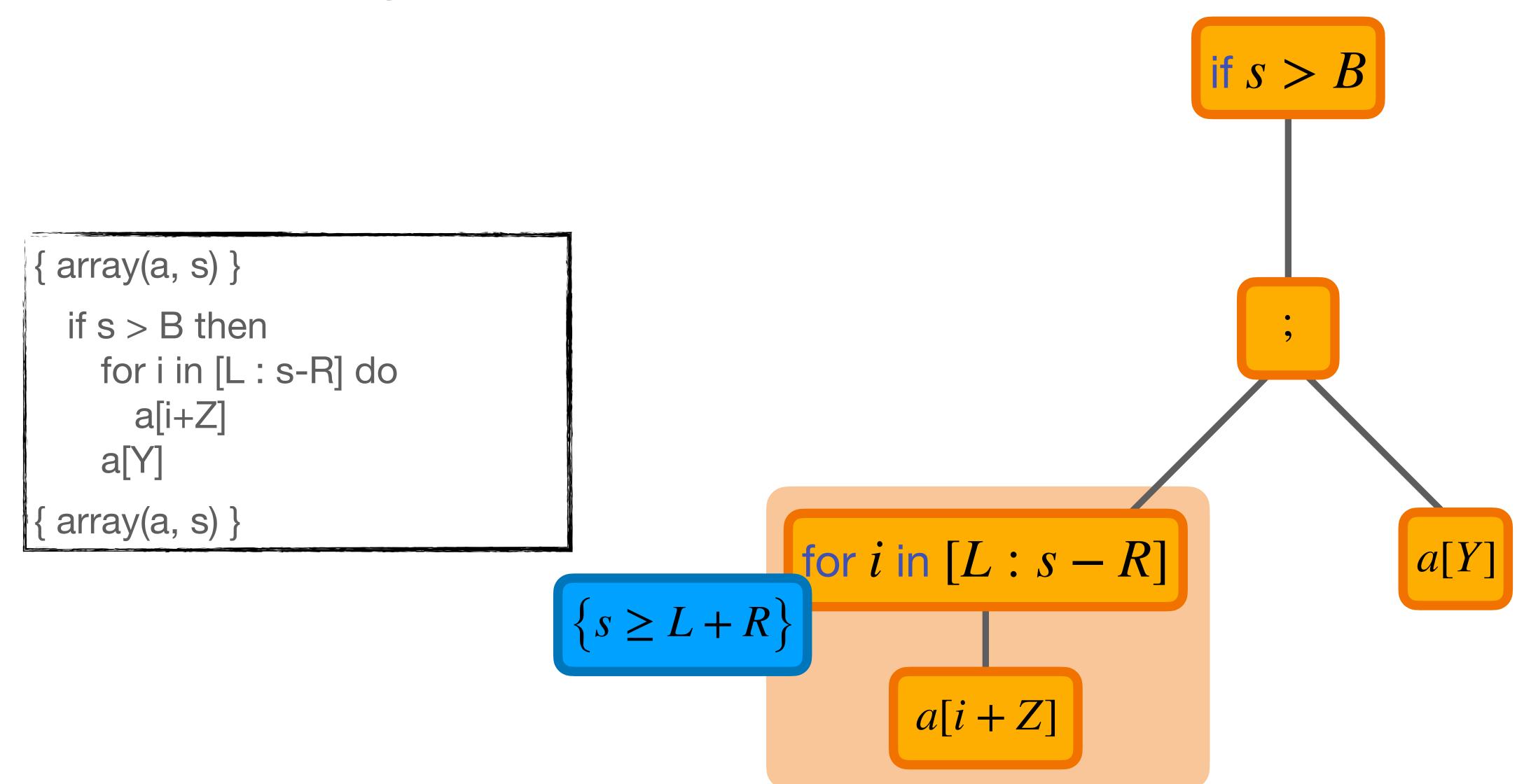
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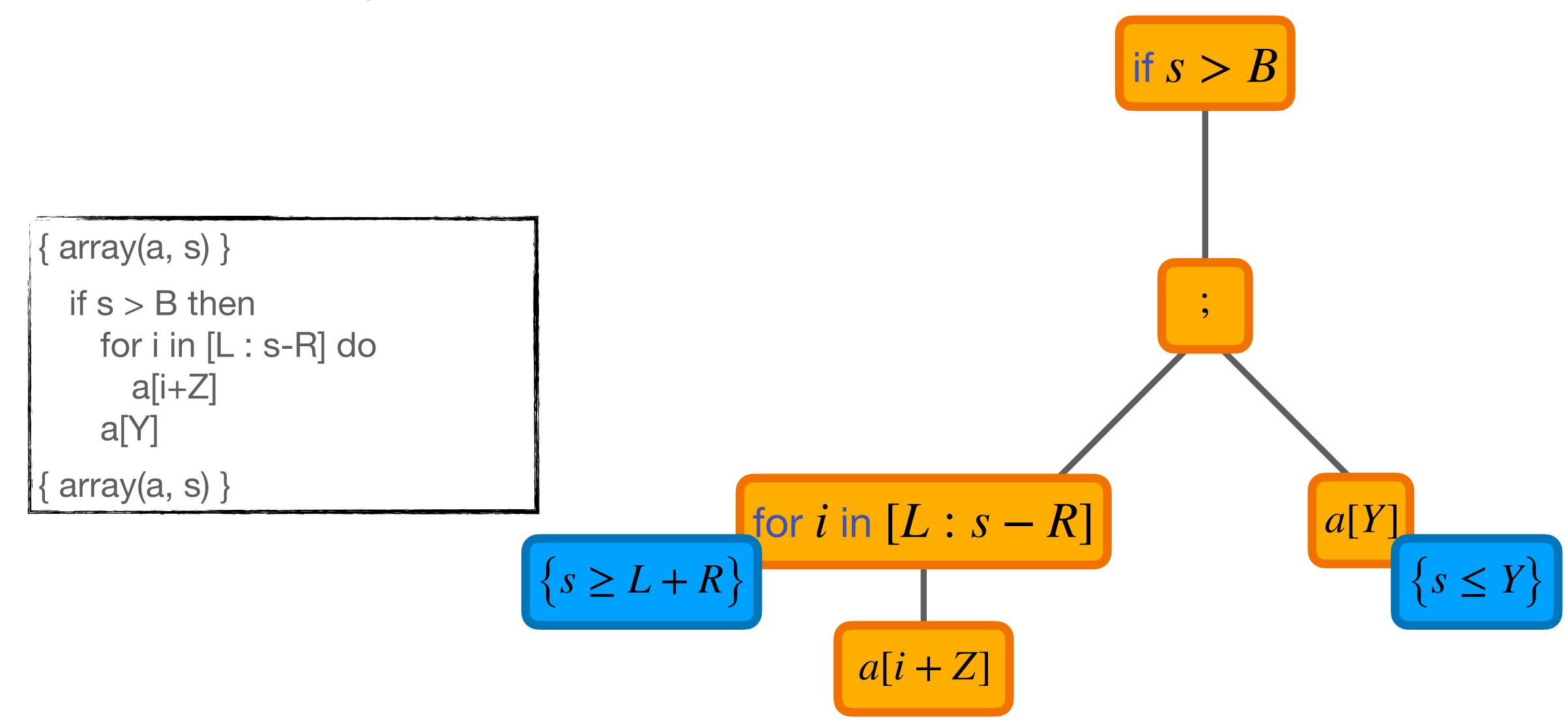
a[i+Z]

a[Y]

{ array(a, s) }
```







```
if s > B
{ array(a, s) }
  if s > B then
                                                         \left\{ s \ge L + R; \ s \le Y \right\}
    for i in [L:s-R] do
      a[i+Z]
    a[Y]
 array(a, s) }
                                                   for i in [L:s-R]
                                                           a[i+Z]
```

```
\begin{cases} s > B & \land s \ge L + R; \\ s > B & \land s \le Y \end{cases}
{ array(a, s) }
  if s > B then
                                                                          \left\{ s \ge L + R; \ s \le Y \right\}
     for i in [L:s-R] do
        a[i+Z]
     a[Y]
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                                                                   for i in [L:s-R]
                                                                             a[i+Z]
```

#### Outlook: Plans & Challenges

#### **Plans**

- Demo scalability: Complex programs & data (e.g. lists, trees)
- Evaluate CT's impact on runtime:
  - ⇒ Case study: FreeRTOS' TCP stack
- Generalise CTs to arbitrary correctness properties

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#### Challenge: Automation

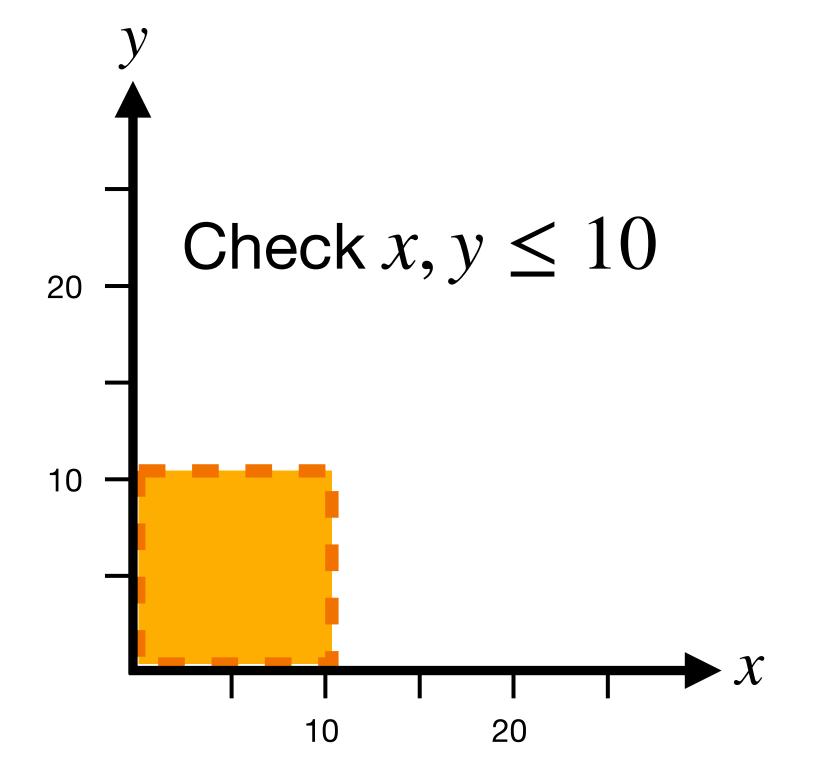
- Pattern recognition
- automatic VC rewriting

#### Outlook: Increase Trust in BMC

Turn bounded into unbounded proof

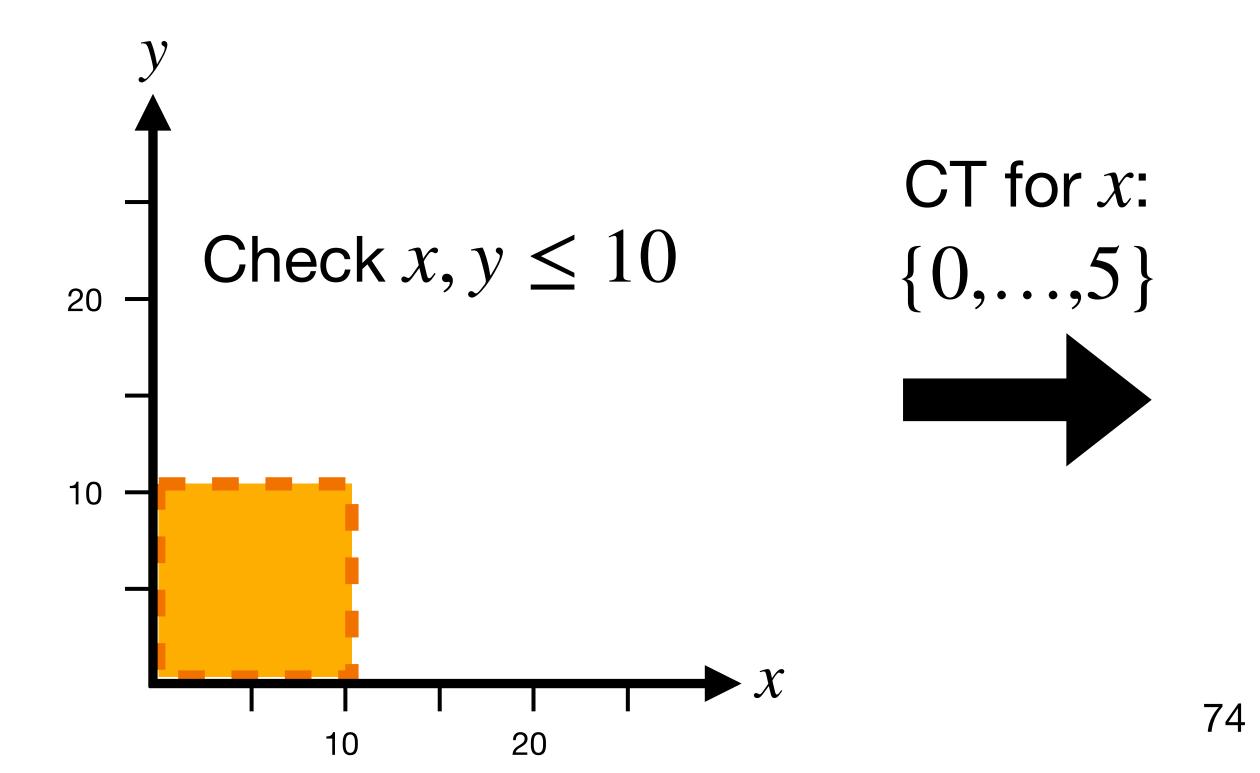
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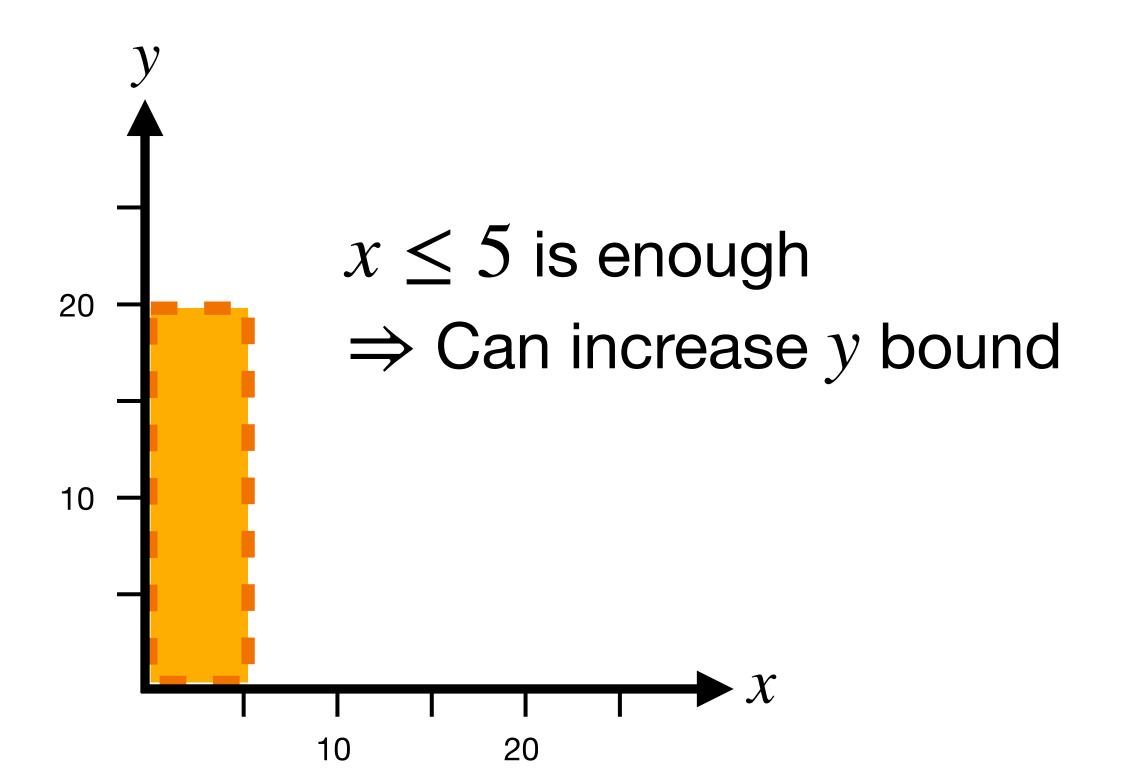
- Turn bounded into unbounded proof
- Shift resources to critical bounds



#### Outlook: Increase Trust in BMC

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#### Conclusion

- First generalisation of CTs to infinite state systems
- Connection between bounded & unbounded proofs in program verification
- Foundational research but potential for integration into BMC

# Backup Slides

#### Precise VCs

• VC vc is precise for x in Spec iff

$$\forall v. \left( \models Spec[x \mapsto v] \Rightarrow \models vc[x \mapsto v] \right)$$

Intuition: vc does not over-approximate wrt. x

• Q is CT  $vc \land vc$  is precise  $\Rightarrow Q$  is CT Spec

#### Precise VCs

Unbounded proof  $\forall x. Spec$  $\models \forall x . Spec$  $\forall x. vc$ Q is CT for vcvc precise for xBounded proof Q is CT for Spec  $\models \forall x \in Q . Spec$