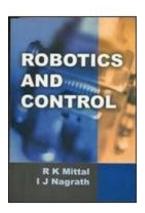
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Tata McGraw-Hill Education Pvt. Ltd., 2003. Softcover. Book Condition: New. First edition. # The book provides a compressive overview of the fundamental skills underlying the mechanism and control of manipulators. # Detailed chapter on Velocity Transformations, jacobian and Singularities. # Trajectory Planning is developed using both joint space and Cartesian space methods. # Dynamic Modeling is treated by Lagrange-Euler and Euler-Newton formulations; complex derivations are put in the appendix to ensure a smooth flow for the reader. # A comprehensive...

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- Authored by I.J. Nagrath, R.K. Mittal
- Released at 2003



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