

Adaptive smoothing lengths in SPH

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ABSTRACT

Context. There is a need to improve the fidelity of SPH simulations of self-gravitating gas dynamics.

Aims. We remind users of SPH that, if smoothing lengths are adjusted so as to keep the number of neighbours, N , in the range $N_{\text{NEIB}} \pm \Delta N_{\text{NEIB}}$, the tolerance, ΔN_{NEIB} , should be set to zero, as first noted by Nelson & Papaloizou. We point out that this is a very straightforward and computationally inexpensive constraint to implement.

Methods. We demonstrate this by simulating acoustic oscillations of a self-gravitating isentropic monatomic gas-sphere (cf. Lucy), using $N_{\text{TOT}} \sim 6,000$ particles and $N_{\text{NEIB}} = 50$.

Results. We show that there is a marked reduction in the rates of numerical dissipation and diffusion as ΔN_{NEIB} is reduced from 10 to zero. Moreover this reduction incurs a very small computational overhead.

Conclusions. We propose that this should become a standard test for codes used in simulating star formation. It is a highly relevant test, because pressure waves generated by the switch from approximate isothermality to approximate adiabaticity play a critical role in the fragmentation of collapsing prestellar cores. Since many SPH simulations in the literature use $N_{\text{NEIB}} = 50$ and $\Delta N_{\text{NEIB}} \geq 10$, their results must be viewed with caution.

Key words. Hydrodynamics - Methods: numerical - Stars: oscillations

1. Introduction

Numerical simulations play an increasingly important role in the study of star formation, and of other non-linear phenomena involving self-gravitating gas dynamics, for example the development of cosmological structure, galaxy formation and stellar collisions. Since these problems involve complex three-dimensional configurations and/or large ranges of density, Smoothed Particle Hydrodynamics (SPH; e.g. Monaghan 1992) is well suited to such simulations. The principal alternative is to use an Adaptive Mesh Refinement (AMR) Finite Difference code (e.g. Truelove et al. 1998), although this is in general more expensive computationally. However, ultimately neither method is useful, unless it can be shown that the results are converged, and are not compromised by numerical artefact. This requires test problems with known analytic, or semi-analytic, solutions, which involve the same basic physical phenomena as occur during star formation.

We propose such a test here, namely acoustic oscillations of a self-gravitating, isentropic, monatomic gas-sphere in the fundamental radial mode. This test was originally performed by Lucy (1977) in his seminal paper introducing SPH, and therefore we shall refer to it as the Lucy test. It has been performed subsequently (e.g. Steinmetz & Müller 1993; Nelson & Papaloizou 1994), but infrequently. It is an appropriate test because it measures (i) the level of dissipation associated with artificial viscosity, in the absence of shocks; (ii) the extent to which transients, due to the discrete nature of particles (or cells), remove energy from genuine modes and transfer it to other spurious modes (i.e. numerical diffusion); (iii) the ability of the code to model acous-

tic oscillations, and in particular adiabatic bounces; and (iv) the ability of the code to deal with free (or nearly free) boundaries.

Point (iii) is particularly important because it seems that collapsing prestellar cores are most prone to fragment at the stage when the gas switches from being approximately isothermal to being approximately adiabatic (e.g. Boss et al. 2000). Fragmentation at this juncture is presumably due to interactions between the complex system of pressure waves which is generated by adiabatic bounces in a converging but disordered inflow, and it is therefore essential that spurious waves are not being generated. In this context it is worth noting that the isentropic assumption is not strictly the same as adiabaticity, and is made here for analytic convenience rather than realism. In simulations where shocks develop, artificial viscosity must be incorporated, in which case, *either* the resulting energy dissipation must be included in the energy equation, *or* – if the thermal timescale is sufficiently short, and the main concern is not with the detailed structure of the shock front – a barotropic equation of state may be invoked. There are no shocks in the present simulation, and therefore the rate of energy dissipation due to artificial viscosity is low, but not negligible. The isentropic assumption then simply implies that the small amount of energy dissipated by artificial viscosity is spirited away by some unspecified process.

It is also appropriate to point out that, although the gas in prestellar cores is largely molecular, it behaves as a monatomic gas (i.e. effective adiabatic exponent $\gamma = 5/3$) until the temperature rises above ~ 100 K. At lower temperatures the rotational degrees of freedom are not significantly excited, since para-H₂ has its first excited level ($J = 2$) at $k_B(512$ K), and ortho-H₂ has its first excited level ($J = 3$) at $k_B(854$ K) (e.g. Black &

Bodenheimer 1975). Neglect of this fact can lead to artificially enhanced fragmentation of collapsing prestellar cores, since with $\gamma = 5/3$ the Jeans mass increases quite rapidly with increasing density in the adiabatic regime ($M_{\text{JEANS}} \propto \rho^{1/2}$), whereas with $\gamma = 7/5$ it increases much more slowly ($M_{\text{JEANS}} \propto \rho^{1/10}$).

In Section 2, we describe the numerical code used and how the test is initiated. In Section 3 we present and discuss the results. In Section 4 we summarise our conclusions.

2. Numerical details

The code we have used – DRAGON (Goodwin et al. 2004) – is a standard SPH code, using a second-order Runge-Kutta integration scheme, multiple particle timesteps, adaptive smoothing lengths, time-dependent artificial viscosity (Morris & Monaghan 1997), and an octal spatial-decomposition tree (Barnes & Hut 1986) for calculating gravitational accelerations and constructing neighbour lists. In calculating gravitational accelerations, tree-cells are opened if they present an angle greater than $\theta_{\text{CRIT}} = 0.5$, and quadrupole moments are included. The smoothing length of a particle is adjusted so that its neighbour list contains $N = N_{\text{NEIB}} \pm \Delta N_{\text{NEIB}}$ other particles¹.

As an illustration of the Lucy test, we demonstrate how much the performance of this code improves as ΔN_{NEIB} is reduced, and how marginal the extra computational cost is. The equilibrium isentropic sphere is set up by placing equal-mass particles on an hexagonal close-packed array within a sphere of radius unity; then stretching this uniform-density sphere radially to reproduce the density profile of a polytrope with exponent 5/3 (or equivalently index 3/2); and finally relaxing the system by evolving the particle positions using the SPH code, until the net kinetic energy falls to a very small value (relative to the magnitude of the gravitational potential energy). In the results presented here the sphere is represented by $N_{\text{TOT}} = 5,895$ particles, and we set $N_{\text{NEIB}} = 50$. The parameters in the time-dependent artificial viscosity (Morris & Monaghan 1997) are $\alpha_* = 0.1$, $C_1 = 0.2$, $\beta = 2\alpha$. To excite the fundamental mode, each particle is displaced radially from its equilibrium radius r to a new radius $r' = r[1 + A\xi(r/R)]$, and then released from rest. Here $\xi(s)$ ($0 \leq s \leq 1$) is the eigenfunction of the fundamental radial mode². A is the initial amplitude of the oscillation, which we set to $A = 0.1$.

3. Results and Discussion

Figures 1 and 2 show oscillations simulated with $\Delta N_{\text{NEIB}} = 0, 2, 5$, and 10. In Fig. 1, the quantity plotted is the mean x -

¹ Some SPH codes (e.g. Price & Monaghan 2004) do not specify the number of neighbours, but instead, for each particle, iterate around a loop,

$$h_i = h_0 \left[\frac{m_i}{\rho_i} \right]^{1/3},$$

$$\rho_i = \sum_j \left\{ \frac{m_j}{h_i^3} W\left(\frac{|\mathbf{r}_j - \mathbf{r}_i|}{h_i} \right) \right\},$$

until fractional changes in ρ_i drop below a user-defined tolerance, ϵ . Here h_0 is a constant of order unity, and the summation is over all neighbours j for which $|\mathbf{r}_j - \mathbf{r}_i| < 2h_i$ (i.e. all particles within the smoothing kernel of particle i). Provided ϵ is sufficiently small, this is statistically equivalent to setting $N_{\text{NEIB}} = 32\pi h_0^3/3$ and $\Delta N_{\text{NEIB}} = 0$.

² The eigenfunction, $\xi(s)$, for the fundamental radial mode of a self-gravitating isentropic monatomic gas-sphere was very kindly supplied, in the form of a dense look-up table, by Alfred Gautschy.

Table 1. Decay of the fundamental mode. The first column gives ΔN_{NEIB} . The second column gives the e-folding time for the amplitude of the fundamental mode, T_A , as a multiple of its period, P_0 . The third column gives the net oscillation energy left after 10 periods, \mathcal{E}_{10} , as a fraction of the initial oscillation energy, \mathcal{E}_0 . The fourth column gives the simulation time to evolve the oscillating gas-sphere for 10 periods on eight 2.2Ghz Opteron CPUs each with 8GB memory, t_{10} .

ΔN_{NEIB}	T_A/P_0	$\mathcal{E}_{10}/\mathcal{E}_0$	t_{10}/s
0	13.6	0.955	9545
2	7.6	0.939	9403
5	3.8	0.927	8996
10	3.1	0.925	8164

displacement

$$\bar{x} = \frac{1}{N_{\text{TOT}}} \sum_i \{|x_i|\} \quad (1)$$

(the mean being taken over all the particles, with equal weighting), as a function of time (normalised to the central freefall time, t_{FF} , in the unperturbed equilibrium state). In Fig. 2, the quantity plotted is the total kinetic energy, normalised to the magnitude of the gravitational potential energy in the equilibrium state (i.e. $\mathcal{K}/|\Omega_0|$, where \mathcal{K} is the total kinetic energy, Ω is the total gravitational potential energy, and subscript 0 refers to values in the unperturbed equilibrium state), again as a function of time (normalised to t_{FF}). Some decay parameters are recorded in Table 1.

In addition to the fundamental mode, some additional modes are unintentionally excited from the outset. This is because, following relaxation, the equilibrium state of an isentropic monatomic sphere is not modelled exactly, due to the smoothing inherent in SPH. In particular, the density is underestimated near the centre and near the boundary. (This can be improved by increasing N_{NEIB} and $N_{\text{TOT}}/N_{\text{NEIB}}$, but that requires extra computational resource.) Furthermore, the fundamental mode is excited with finite amplitude, but the eigenfunction is derived on the assumption of infinitesimal amplitude. (This can be moderated by adopting a lower value for A , but the test is not then relevant to real simulations of star formation, where ultimately we are concerned with non-linear perturbations.)

Setting aside the effect of other modes present in the initial conditions, the subsequent decay of the fundamental mode is in general due to two effects. First, the oscillation energy may be dissipated by artificial viscosity. The dissipation of energy due to artificial viscosity occurs wherever two neighbouring SPH particles approach one another. Second, the oscillation energy may be transferred to other modes. This occurs wherever local density or velocity fluctuations are created by the discrete nature of the SPH particles, or by the ‘peculiar velocities’ of individual SPH particles. Both effects occur more rapidly for larger values of ΔN_{NEIB} . (They also occur more rapidly for smaller values of N_{TOT} and smaller values of N_{NEIB} , but these parameters are not varied here.)

When $\Delta N_{\text{NEIB}} = 0$, the neighbour list of an SPH particle changes very seldom, and – when it does – very little. Therefore the acceleration experienced by the particle varies very slowly, and the velocity field is very smooth. The upshot is that neighbouring particles only approach one another very

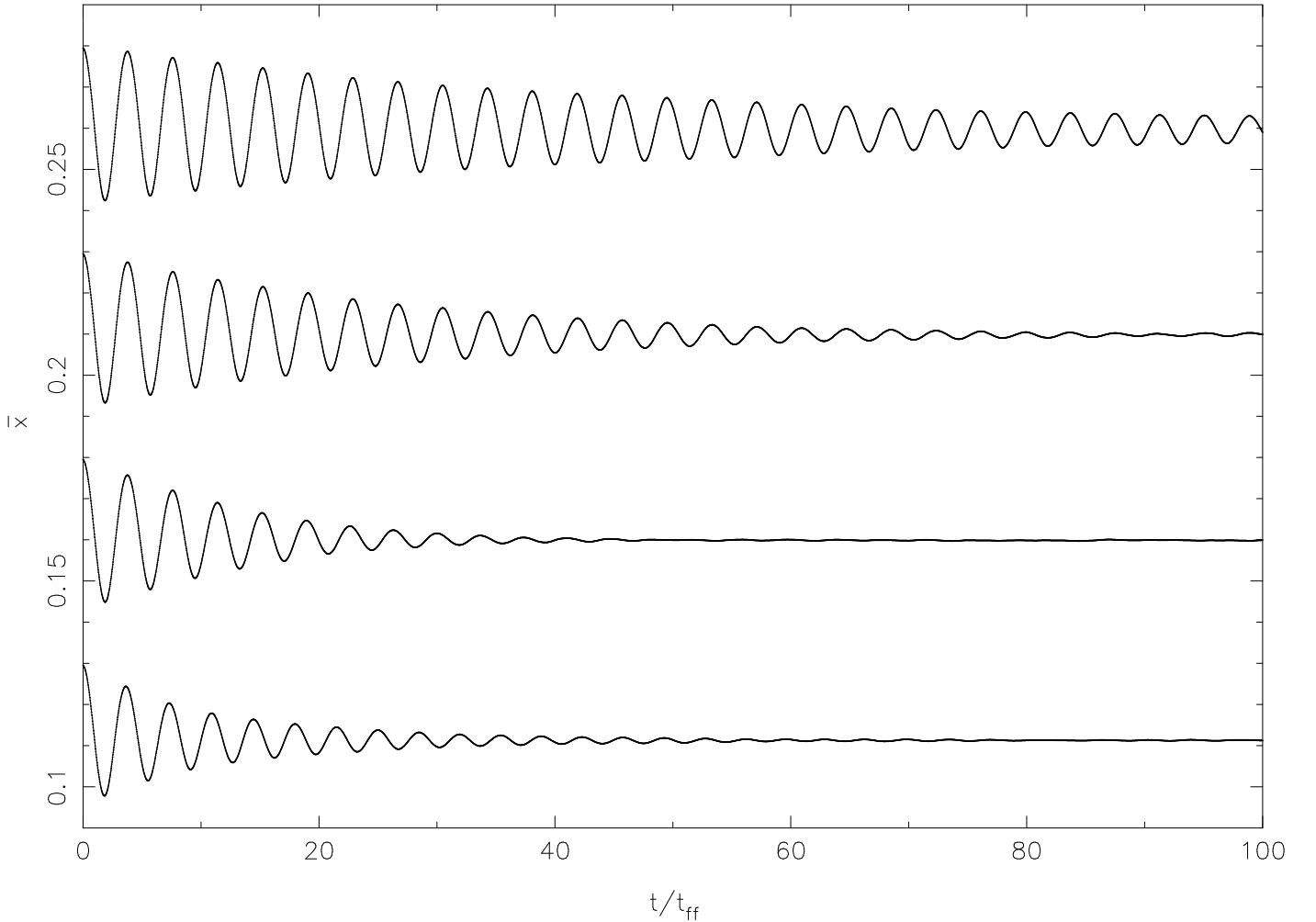


Fig. 1. The mean x -displacement, \bar{x} (where the mean is over all particles, with equal weighting), against time, t (in units of the freefall time in the equilibrium state, t_{ff}). The results are displaced vertically by Δx to fit them all on one plot. Reading from the top, (a) $\Delta N_{NEIB} = 0$, $\Delta x = 0$; (b) $\Delta N_{NEIB} = 2$, $\Delta x = -0.05$; (c) $\Delta N_{NEIB} = 5$, $\Delta x = -0.10$; (d) $\Delta N_{NEIB} = 10$, $\Delta x = -0.15$.

slowly, and the rate of dissipation due to artificial viscosity is low. Notwithstanding the slow rate of dissipation, there are small fluctuations in density and velocity, and these feed energy into other modes, so that the fundamental mode decays (see Figs. 1 & 2).

As ΔN_{NEIB} is increased, the neighbour list of an SPH particle changes more frequently, and more abruptly. Therefore the acceleration experienced by the particle varies in a more idiosyncratic manner, and the velocity and density fields are more noisy. The upshot is that neighbouring particles often approach one another more rapidly, and the rate of dissipation due to artificial viscosity is therefore higher. In addition, the noisy velocity and density fields are very effective at feeding energy into other modes, so that the fundamental mode decays more rapidly (see Figs. 1 & 2).

In principle, the number of neighbours can change by $2\Delta N_{NEIB}$ at each timestep, from $N_{NEIB} - \Delta N_{NEIB}$ to $N_{NEIB} + \Delta N_{NEIB}$ or vice versa. Thus with $N_{NEIB} = 50$ and $\Delta N_{NEIB} = 10$, the number of neighbours can change from 40 to 60 or vice versa. In practice such large changes are unlikely, but it is still the case that increasing ΔN_{NEIB} results in increased fluctuations in the neighbour lists. In particular, particles in condensing regions tend to have N fluctuating between $\sim N_{NEIB}$ and $\sim (N_{NEIB} + \Delta N_{NEIB})$.

whilst particles in expanding regions tend to have N fluctuating between $\sim N_{NEIB}$ and $\sim (N_{NEIB} - \Delta N_{NEIB})$.

In Table 1, we record, for each value of ΔN_{NEIB} (column 1), the e-folding time of the amplitude of the fundamental mode, T_A , in terms of its period, $P_0 = 3.7t_{ff}$ (column 2); the oscillation energy left after ten periods, \mathcal{E}_{10} , as a fraction of its initial value, \mathcal{E}_0 (column 3); and the simulation time to evolve the oscillating gas-sphere for 10 periods on eight 2.2Ghz Opteron CPUs each with 8GB memory (column 4). The oscillation energy is given by

$$\mathcal{E} = \mathcal{K} + (\mathcal{T} - \mathcal{T}_0) + (\Omega - \Omega_0), \quad (2)$$

where \mathcal{T} is the thermal energy, and again the subscript 0 indicates the unperturbed equilibrium state.

We note that the oscillation energy decays rather slowly due to dissipation, even with $\Delta N_{NEIB} = 10$. This is because the oscillations have low amplitude, and therefore the relative velocities between neighbouring particles are always very subsonic. Not only are the initial amplitudes low, but in the cases with high ΔN_{NEIB} the amplitudes decay rapidly due to numerical diffusion. In other words, when ΔN_{NEIB} is high, the rate of dissipation is reduced because diffusion rapidly spreads the oscillation energy amongst many different modes and thereby reduces even further the relative velocities between neighbouring particles. This is re-

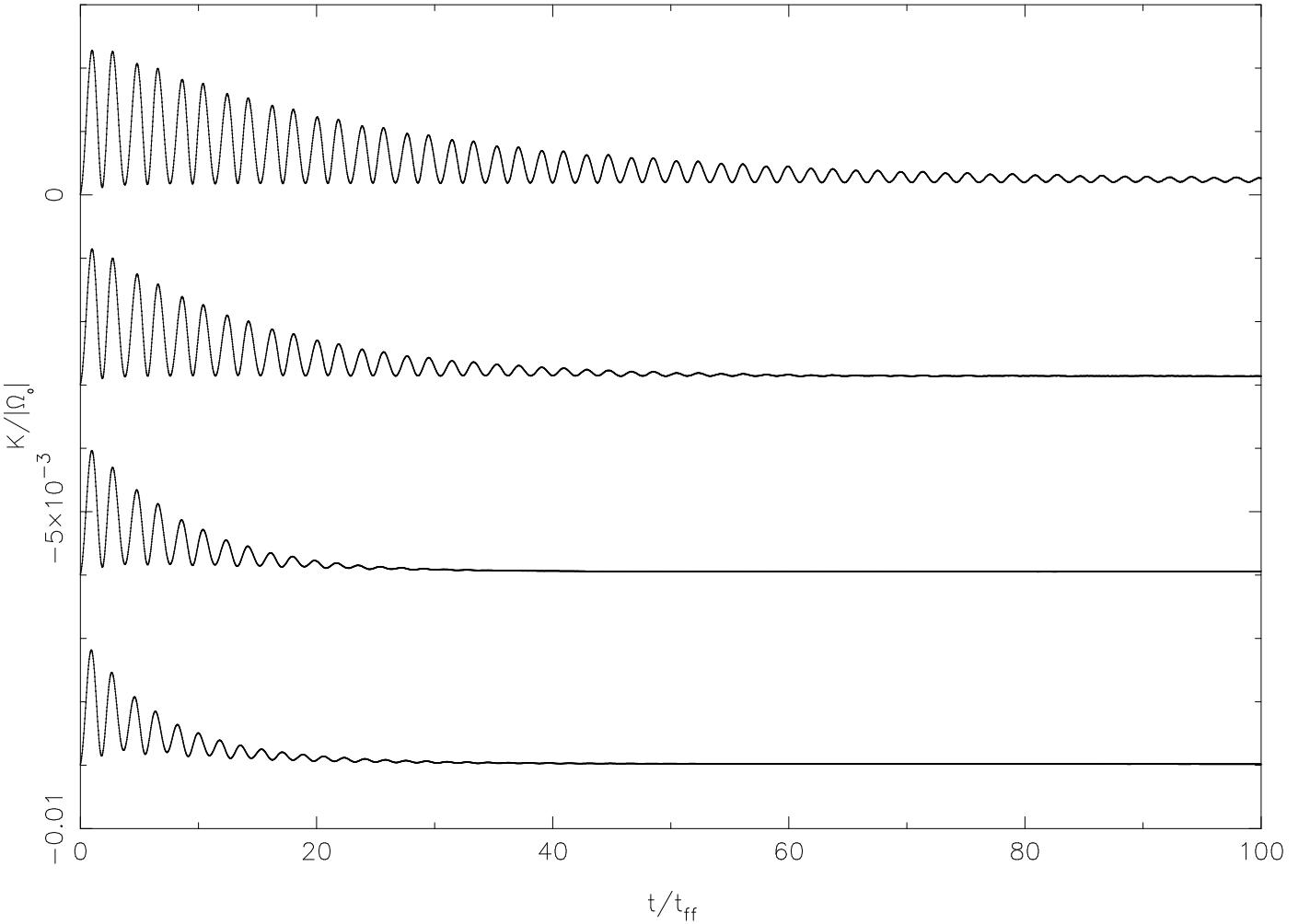


Fig. 2. The total kinetic energy, \mathcal{K} (normalised to the magnitude of the self-gravitational potential energy in the equilibrium state, $|\Omega_0|$), against time, t (in units of the freefall time in the equilibrium state, t_{ff}). The results are displaced vertically by $\Delta\mathcal{K}$ to fit them all on one plot. Reading from the top, (a) $\Delta N_{\text{NEIB}} = 0$, $\Delta\mathcal{K} = 0$; (b) $\Delta N_{\text{NEIB}} = 2$, $\Delta\mathcal{K} = -0.003$; (c) $\Delta N_{\text{NEIB}} = 5$, $\Delta\mathcal{K} = -0.006$; (d) $\Delta N_{\text{NEIB}} = 10$, $\Delta\mathcal{K} = -0.009$.

lected in the results presented in Fig. 2 and the third column of Table 1. Because the decay of the fundamental mode is largely due to numerical diffusion, the oscillation energy only falls by a few percent after ten periods (see the third column of Table 1), whereas the amplitude of the variation in kinetic energy falls much more rapidly. The variation in kinetic energy eventually disappears, not because the kinetic energy itself disappears, but because numerical diffusion transfers oscillation energy to other modes with different periods and different phases. Consequently the oscillation energy becomes thermalised, and \mathcal{K} is finite but approximately constant.

The simulations presented here have been continued for 100 periods. In this limit, there are so many modes excited, with so many different phases, that the gas-spheres become virialised with

$$2\mathcal{K} + 2\mathcal{T} + \Omega \approx 0; \quad (3)$$

\mathcal{K} is still finite.

4. Conclusions

From the plots in Figs. 1 and 2, and the above discussion, we infer that the results obtained with $\Delta N_{\text{NEIB}} = 0$ are far more re-

liable than those obtained with $\Delta N_{\text{NEIB}} = 10$, and significantly more reliable even than those obtained with $\Delta N_{\text{NEIB}} = 2$, both in terms of having less dissipation and – more importantly – in terms of having less numerical diffusion.

Setting $\Delta N_{\text{NEIB}} = 0$ also requires little extra computation. For example, to follow 10 oscillation periods with $\Delta N_{\text{NEIB}} = 0$ takes only 17% longer than with $\Delta N_{\text{NEIB}} = 10$. Moreover, 7% of this increase is due to the fact that with $\Delta N_{\text{NEIB}} = 0$ the sphere continues to oscillate with a significant amplitude after 10 periods, and therefore the timestep remains short. When allowance is made for this, the real cost of reducing ΔN_{NEIB} from 10 to 0 is only a 10% increase in computation.

Therefore our principal conclusions are (i) that $\Delta N_{\text{NEIB}} = 0$ should be the default option for SPH codes which adapt smoothing lengths in this way; and (ii) that the Lucy test provides a very useful way of evaluating the fidelity of codes used in simulations of star formation.

We emphasise that we have not set out to reproduce as accurately or economically as possible acoustic oscillations of a self-gravitating isentropic sphere in the fundamental mode. We have simply demonstrated how the results produced using a standard SPH code, with a modest number of particles ($N_{\text{tot}} = 5,895$) depend on ΔN_{NEIB} . There are adjustments to SPH which will im-

prove (extend) the timescales for dissipation and numerical diffusion in the present simulation. For example, using standard artificial viscosity with $\alpha = 0$ and $\beta = 0.1$ increases the e-folding time for the fundamental mode to ~ 60 oscillation periods, but at the same time compromises the shock-capturing ability of the code so that it can not then be used for simulations in which shocks are likely. Similarly, the e-folding time for the fundamental mode can be extended by increasing N_{NEIB} or $N_{\text{TOT}}/N_{\text{NEIB}}$, but this must inevitably be at the expense of resources which are needed elsewhere, *viz.* to maximise the extent and/or duration of a simulation.

The useful duration of the present simulation can be identified with the e-folding time of the fundamental mode, which with $\Delta N_{\text{NEIB}} = 0$ is 13.6 oscillation periods, but with $\Delta N_{\text{NEIB}} = 10$ is only 3.1 oscillation periods³.

Adaptive Mesh Refinement codes used for simulating star formation should also aim to reproduce or improve upon the results produced here, using comparable computational resources. *In addition*, they should do so for a gas-sphere which moves at constant velocity relative to the underlying Cartesian grid, in order to match the Lagrangian advantages of SPH.

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³ In fact, even 3.1 oscillation periods is an overestimate of the e-folding time in the simulation with $\Delta N_{\text{NEIB}} = 10$, since this case is so noisy that numerical diffusion actually re-invigorates the fundamental mode, but with a phase-shift relative to the initial oscillation!