

# Xiang Li

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## Education

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**Stony Brook University**, Stony Brook, NY, USA  
Ph.D. Candidate in Computer Science

Jan. 2020 - Present  
Advisor: Prof. Michael S. Ryoo,

**Shanghai Jiao Tong University**, Shanghai, China  
M.S. in Control Engineering (Pattern Recognition and Intelligence System)  
Thesis: Continuous visual object tracking with view morphing

Sept. 2015 - Mar. 2018  
Advisor: Prof. Yue Zhou

**Shanghai Jiao Tong University**, Shanghai, China  
B.S. in Automation

Sept. 2011 - June 2015

## Research Interest

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Self-supervised visual representation learning for robotics.

## Selected Publications

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1. **Xiang Li**, Cristina Mata, Jongwoo Park, Kumara Kahatapitiya, Yoo Sung Jang, Jinghuan Shang, Kanchana Ranasinghe, Ryan Burgert, Mu Cai, Yong Jae Lee and Michael S. Ryoo, LLaRA: Supercharging Robot Learning Data for Vision-Language Policy. *The Thirteenth International Conference on Learning Representations (ICLR'25)*.
  - Transform behavior cloning datasets into instruction tuning datasets and finetunes pretrained VLMs into Vision-Language-Action (VLA) models efficiently by aligning robot action to image pixels.
  - Introduce auxiliary datasets generated from the behavior cloning datasets in a self-supervised fashion, to further improve the VLA performance and enable efficient transfer learning, especially when training data is limited.
2. Kanchana Ranasinghe, **Xiang Li**, Kumara Kahatapitiya and Michael S. Ryoo, Understanding Long Videos with Multi-modal Language Models. *The Thirteenth International Conference on Learning Representations (ICLR'25)*.
3. Ryan Burgert, **Xiang Li**, Abe Leite, Kanchana Ranasinghe and Michael S. Ryoo, Diffusion Illusions: Hiding Images in Plain Sight. *Special Interest Group on Computer Graphics and Interactive Techniques (SIGGRAPH'24)*.
4. **Xiang Li**, Belagali, V., Jinghuan Shang and Michael S. Ryoo, Crossway Diffusion: Improving Diffusion-based Visuo-motor Policy via Self-supervised Learning. *IEEE International Conference on Robotics and Automation (ICRA'24)*.
  - Explore multiple self-supervised objectives to improve diffusion policy for behavior cloning.
  - Introduce a straightforward state reconstruction objective that consistently and significantly improves performance.
5. Ryan Burgert, Kanchana Ranasinghe, **Xiang Li** and Michael S. Ryoo, Peekaboo: Text-to-image Diffusion Models are Zero-shot Segmentors. *Workshop on Open-Domain Reasoning Under Multi-Modal Settings @ CVPR (CVPRW'23)*.
6. **Xiang Li**, Jinghuan Shang, Srijan Das and Michael S. Ryoo, Does Self-supervised Learning Really Improve Reinforcement Learning from Pixels? *Advances in Neural Information Processing Systems (NeurIPS'22)*.
  - Unfortunately, NO (when the same amount of data and augmentation is used).
  - Verified by extensively comparing various self-supervised losses under the existing joint learning framework for pixel-based reinforcement learning in multiple simulated and real-world environments.
7. Ryan Burgert, Jinghuan Shang, **Xiang Li** and Michael S. Ryoo, TRITON: Neural Neural Textures Make Sim2Real Consistent. *Conference on Robot Learning (CoRL'22)*.
8. Jinghuan Shang, **Xiang Li**, Kumara Kahatapitiya, Yu-Cheol Lee and Michael S. Ryoo, StARformer: Transformer with State-Action-Reward Representations for Robot Learning. *IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI'22)*.
9. Jinghuan Shang, Kumara Kahatapitiya, **Xiang Li** and Michael S. Ryoo, StARformer: Transformer with State-Action-Reward Representations for Visual Reinforcement Learning. *European Conference on Computer Vision (ECCV'22)*.

## Experience

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**Applied Scientist Co-op, Amazon.com Services LLC**, Westborough, U.S. Nov. 2024 - Mar. 2025  
Scanless Technologies, Amazon Robotics

**Machine Learning Engineer Intern, Bytedance Ltd**, Seattle, U.S. June 2024 - Aug. 2024  
Knowledge Graph, E-commerce  
Improve vision language representations on large-scale noisy datasets via self-supervised learning.

- Prepare structured text data utilizing a large language model
- Optimize the existing multi-modal encoder architecture, boosting average recall on seven diverse datasets by 6.7% at 90% precision while decreasing inference time by 7%.
- Explore multiple self-supervised losses for robust multi-modal representation learning

**Software Engineer Intern, Beijing Falcon Image Tech Co., Ltd**, Beijing, China Sept. 2018 - Sept. 2019  
Autonomous Driving  
Deploy LiDAR-based SLAM and navigation system on multiple types of autonomous driving cars from scratch.

- Develop ROS packages for multiple new LiDAR, IMU and GPS sensors
- Optimize existing LiDAR-based SLAM system for multiple autonomous driving scenarios
- Deploy navigation system for both differential and Ackermann steering geometry

**Software Engineer Intern, Chengshi E-Business Co., Ltd**, Shanghai, China Mar. 2016 - Mar. 2018  
Internet of Things  
Design and develop an intelligent video surveillance system for three warehouses.

- Develop a warehouse simulator in Unity to optimize the placement and coverage of surveillance cameras
- Engineer software solutions for recording and streaming video from multiple camera brands
- Implement a visual motion detection service on Raspberry Pi 3B for real-time monitoring
- Enhanced video stream efficiency and reduced CPU load through hardware-accelerated transcoding

## Patent

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Utility Model: Universal Serial Control Touch-screen Test Device, China 2016  
A CNC-like embedded system that interacts with touchscreens like a human finger. No.2016201772460

## Professional Activities

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- Conference Reviewer: ICML'23-25, NeurIPS'23-25, WACV'24&25, ICRA'24&25, ICLR'24&25 and ECCV'24
- Journal Reviewer: RA-L
- Teaching Assistant:
  - CSE525 Introduction to Robotics (graduate level, 2023 Spring, SBU)
  - CSE527 Introduction to Computer Vision (graduate level, 2021 Fall, SBU)
  - CSE353 Machine Learning (undergrad level, 2020 Spring, SBU)
  - Introduction to Digital Image Processing (undergrad level, 2017, 2018, SJTU)

## Honors and Awards

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- CVPR Outstanding Demos Award [3] 2023
- Outstanding Graduate of Colleges and Universities in Shanghai, China (Top 5%) 2018
- National Scholarship for Graduate Students, China 2017
- Outstanding Graduate of SJTU, China 2015