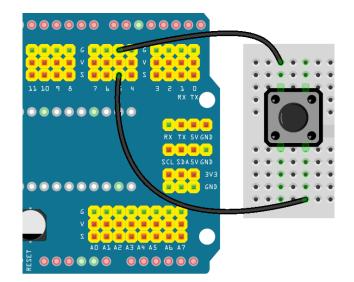
**Task 1.** Connect the circuit as shown in the picture:







## Code example:

```
#define BAUDRATE 115200
#define BUTTON1_PIN 5
int buttonstate;

void setup() {
  pinMode(BUTTON1_PIN,INPUT_PULLUP);
  Serial.begin(BAUDRATE); }

void loop() {
  buttonstate = digitalRead(BUTTON1_PIN);
  if(buttonstate == LOW)
      Serial.println("Button is down");
  else
      Serial.println("Button is up");
  delay(250); }
```

## What's new:

digitalRead function, if statement, int type variable

**Task 2.** Using the circuit from Task 1, write a program that controls the built-in LED. The LED should be turned on if the button connected to DIO 5 is pressed.

```
#define BAUDRATE 115200
#define BUTTON1 PIN 5
int buttonstate;
void setup() {
pinMode(LED BUILTIN,OUTPUT);
pinMode(BUTTON1 PIN, INPUT PULLUP);
 Serial.begin(BAUDRATE); }
void loop() {
buttonstate = digitalRead(BUTTON1 PIN);
if(buttonstate == LOW) {
     digitalWrite(LED BUILTIN, HIGH);
     Serial.println("Button is down"); }
 else {
     digitalWrite(LED BUILTIN, LOW);
     Serial.println("Button is up"); }
 delay(250);
}
```

**Task 3.** Write a program that will blink (turn on and then turn off) the built-in LED 5 times, every time the DIO5 button is pressed.

```
#define BAUDRATE 115200
#define BUTTON1_PIN 5
int buttonstate;
void setup() {
```

```
pinMode(LED_BUILTIN,OUTPUT);
pinMode(BUTTON1_PIN,INPUT_PULLUP);
Serial.begin(BAUDRATE); }

void loop() {
  buttonstate = digitalRead(BUTTON1_PIN);
  if(buttonstate == LOW)
   for(int i=0;i<5;i++) {
    Serial.println(i);
   digitalWrite(LED_BUILTIN,HIGH);
   delay(500);
  digitalWrite(LED_BUILTIN,LOW);
  delay(500); }
  delay(250);
}</pre>
```

**for** expression, increment operator

**Task 4.** Using the code from the previous task, create a function that allows the user to define a number and period of blinks.

```
#define BAUDRATE 115200
#define BUTTON1_PIN 5
int buttonstate;

void setup() {
  pinMode(LED_BUILTIN,OUTPUT);
  pinMode(BUTTON1_PIN,INPUT_PULLUP);
  Serial.begin(BAUDRATE);
}
```

```
void loop() {
  buttonstate = digitalRead(BUTTON1_PIN);
  if(buttonstate == LOW)
  led_blink(5,1000);
  delay(250);
}

void led_blink(int times,int duration) {
  for(int i=0;i<times;i++) {
     Serial.println(i);
     digitalWrite(LED_BUILTIN,HIGH);
     delay(duration/2);
     digitalWrite(LED_BUILTIN,LOW);
     delay(duration/2); }
}</pre>
```

#### void function

**Task 5.** Write a program that works in the following way - if the DIO5 button is pressed, the built-in LED should be turned off, if the button is not pressed, the LED should be turned on.

```
#define BUTTON1_PIN 5

void setup() {
  pinMode(LED_BUILTIN,OUTPUT);
  pinMode(BUTTON1_PIN,INPUT_PULLUP); }

void loop() {
  digitalWrite(LED_BUILTIN,digitalRead(BUTTON1_PIN)); }
```

**Task 6.** Write a program that switches off the built-in LED, after 4 seconds from when the user releases the button.

### Solution #1:

```
#define BUTTON1 PIN 5
int buttonstate;
void setup() {
pinMode(LED BUILTIN,OUTPUT);
pinMode(BUTTON1 PIN,INPUT PULLUP);
digitalWrite(LED BUILTIN, HIGH);
void loop() {
buttonstate = digitalRead(BUTTON1 PIN);
 if(buttonstate == LOW) {
 delay(100);
while(buttonstate == LOW) {
 buttonstate = digitalRead(BUTTON1 PIN);
 delay(100); }
 delay(4000);
 digitalWrite(LED BUILTIN,LOW);
while(1);
 }
}
```

## Solution #2:

```
#define BUTTON1_PIN 5

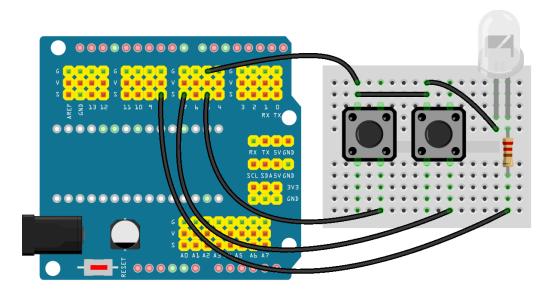
void setup() {
  pinMode(LED_BUILTIN,OUTPUT);
  pinMode(BUTTON1_PIN,INPUT_PULLUP);
```

```
digitalWrite(LED_BUILTIN, HIGH); }

void loop() {
  if(digitalRead(BUTTON1_PIN) == LOW) {
    delay(100);
    while(digitalRead(BUTTON1_PIN) == LOW)
    delay(100);
    delay(4000);
    digitalWrite(LED_BUILTIN, LOW);
    while(1); }
```

# while expression

**Task 7.** Connect the circuit as shown in the picture. Write a program that works as follows - one button should turn on the LED, and the other should turn it off.



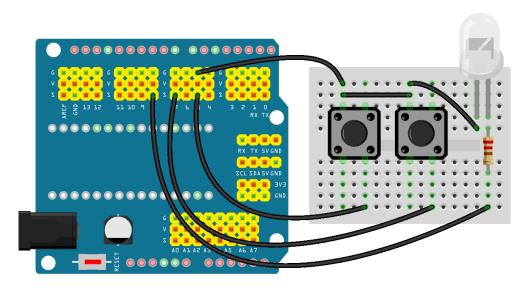
```
#define BUTTON1_PIN 5
#define BUTTON2_PIN 7
#define LED PIN 8
```

```
void setup() {
  pinMode(LED_PIN,OUTPUT);
  pinMode(BUTTON1_PIN,INPUT_PULLUP);
  pinMode(BUTTON2_PIN,INPUT_PULLUP);
  digitalWrite(LED_PIN,LOW); }

void loop() {
  if(digitalRead(BUTTON1_PIN) == LOW) {
    digitalWrite(LED_PIN,HIGH);
    delay(100);
    while(digitalRead(BUTTON1_PIN) == LOW);
    while(digitalRead(BUTTON2_PIN) == HIGH);
    digitalWrite(LED_PIN,LOW);
}

delay(100);
}
```

**Task 8.** Built a prototype of a device that controls the state of an LED with one button.



```
#define BUTTON PIN 5
#define LED PIN 8
bool led state=LOW;
void setup() {
 pinMode(LED PIN,OUTPUT);
 pinMode(BUTTON PIN, INPUT PULLUP);
 digitalWrite(LED PIN,led state); }
void loop() {
 if(button pressed(BUTTON PIN)) {
  led state = !led_state;
  digitalWrite(LED PIN, led state);
 }
 delay(100);
}
bool button pressed(int button pin) {
 if(digitalRead(button pin) == LOW) {
  delay(100);
  while(digitalRead(button pin) == LOW);
  return true;
 else
 return false;
}
```

**Task 9.** Built a prototype of a device that measures the user's reaction time.

#### Hint:

```
#define BAUDRATE 115200
unsigned long timer;
```

```
void setup() {
  Serial.begin(BAUDRATE);
  Serial.println(timer); }

void loop() {
  timer = millis();
  Serial.println(timer);
  delay(500); }
```

millis() function, unsigned long data type.

Function *millis()* returns the number of milliseconds passed since the Arduino board began running the program. This number will overflow (go back to zero), after approximately 50 days.

#### Reference:

www.arduino.cc/reference/en/language/functions/time/millis/

**Task 10.** Built a prototype of a device that blinks 3 LEDs. The first LED should blink once per second, the second LED twice, and the third LED three times per second. Using *millis()* function is mandatory.

**Task 11.** Built a human reaction time meter.

# Exercise no 2: Digital inputs

## For those interested:

1. Basics of Tactile Switches:

components.omron.com/us-en/ds related pdf/A293-E1.pdf

2. The debounce debacle:

www.edn.com/the-debounce-debacle/

3. Pull-up Resistors:

<u>learn.sparkfun.com/tutorials/pull-up-resistors</u>

4. Video - What is Switch Bounce and How to Debounce

www.youtube.com/watch?v=IvU8m\_30iK0&t=111s

### Solution for task 11

```
#define BAUDRATE 9600
#define BUTTON1 PIN 7
int buttonstate;
int start time;
int result;
void setup() {
pinMode(LED BUILTIN,OUTPUT);
pinMode(BUTTON1 PIN,INPUT PULLUP);
Serial.begin(BAUDRATE);
digitalWrite(LED BUILTIN, HIGH);}
void loop() {
 digitalWrite(LED BUILTIN, HIGH);
 Serial.println("Reaction time meter");
 Serial.println("Press the button after the LED is off.");
 delay(4000);
buttonstate = digitalRead(BUTTON1 PIN);
 while(buttonstate != HIGH) {
   Serial.println("Please remove your finger from the button");
  buttonstate = digitalRead(BUTTON1 PIN);
   delay(1000);}
 digitalWrite(LED BUILTIN, LOW);
 start time = millis();
buttonstate = digitalRead(BUTTON1 PIN);
while(buttonstate == HIGH)
  buttonstate = digitalRead(BUTTON1 PIN);
 result = millis() - start time;
 Serial.print("Result: ");
 Serial.println(result);
while(1); }
```