

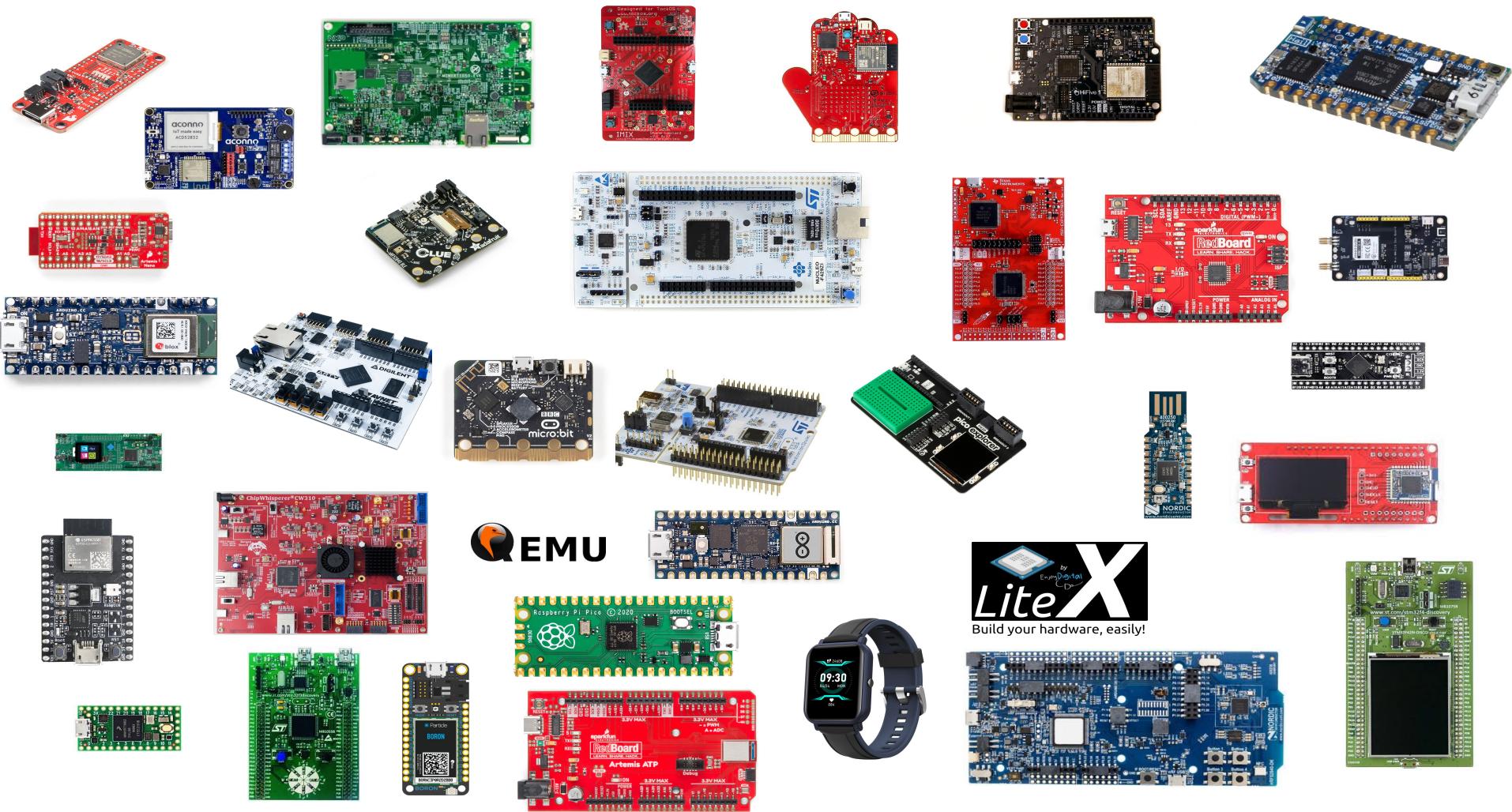
The Treadmill Distributed Hardware Testbed

TockWorld 7 – June 26, 2024
Leon Schuermann

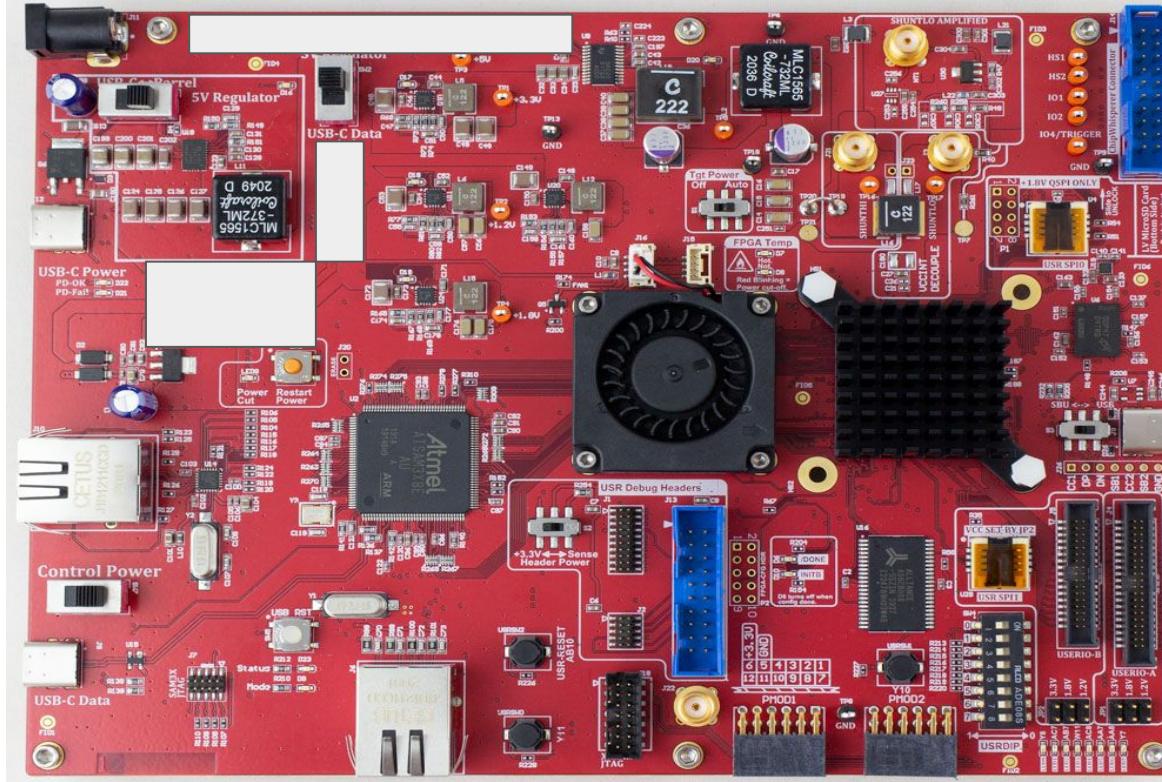
Tock lacks automated HW testing

- Today: low assurance that a change will not break boards / subsystems
 - HW tests require time + effort
 - No standardized test workflow:
userspace examples, kernel unit tests, kernel integration tests
 - Interactions between hardware peripherals break isolated software components in subtle ways
- High testing effort for releases
 - Long delay between releases
 - Lots to test, hard to run them, knowledge around tests is lost

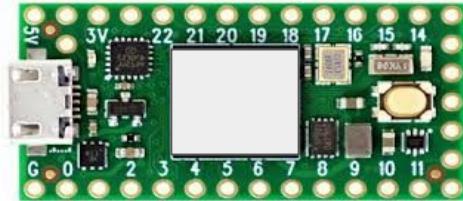
Tock supports *lots* of boards!



Name That Board!



Name That Board!



Name That “Board”!



Tock supports *lots* of boards

... some niche boards, used by only a few contributors

... some very expensive boards, infeasible to acquire (multiple of)

... some proprietary HW, which we'll not get our hands on

... some with heavy-weight / hard-to-use toolchains

- Difficulties getting these targets tested, e.g., for releases
- Maintenance- and refactoring-changes get merged without even basic testing

The Treadmill Distributed Hardware Testbed

← treadmill-ci

➊ Reload udev rules #11

Summary

Triggered via push 2 hours ago

lschuermann pushed -> 2b59567 dev/tockworld7-treadmill-...

Status Success

Jobs

eval-strategy (ubuntu-latest) Success

nrf52840-hw-ci Success

Run details

Usage

Workflow file

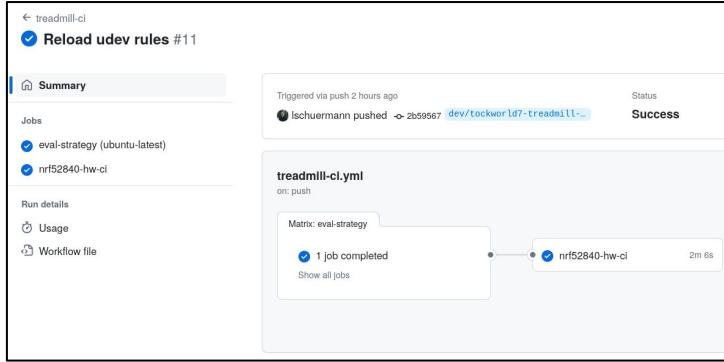
treadmill-ci.yml

on: push

Matrix: eval-strategy

➊ 1 job completed

Show all jobs



```
..... SYSTEMCALL ARGUMENT DECODING .....
```

```
/// Enumeration of the system call classes based on the identifiers
/// specified in the Tock ABI.
///
/// These are encoded as 8 bit values as on some architectures the value can
/// be encoded in the instruction itself.
#[repr(u8)]
#[derive(Copy, Clone, Debug)]
pub enum SyscallClass {
    Yield = 0,
    Subscribe = 1,
    Command = 2,
    ReadOnlyAllow = 3,
    ReadWriteAllow = 4,
    Memop = 5,
    Exit = 6,
    UserSpaceReadableAllow = 7,
}

/// Enumeration of the yield system calls based on the Yield identifier
/// values specified in the Tock ABI.
#[derive(Copy, Clone, Debug)]
pub enum YieldCall {
    Null = 0,
    Wait = 1,
    WaitFor = 2,
}

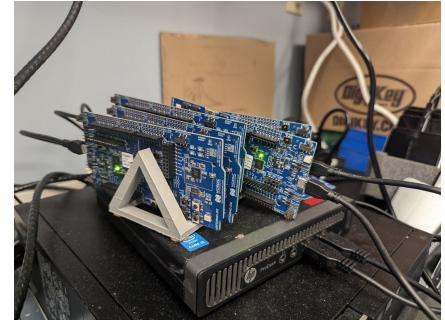
impl TryFrom for YieldCall {
    type Error = usize;

    fn try_from(yield_variant: usize) -> Result<YieldCall, usize> {
        match yield_variant {
            0 => Ok(YieldCall::Null),
            1 => Ok(YieldCall::Wait),
            2 => Ok(YieldCall::WaitFor),
            _ => Err(yield_variant),
        }
    }
}
```

```
..... SYSTEMCALL ARGUMENT DECODING .....
```

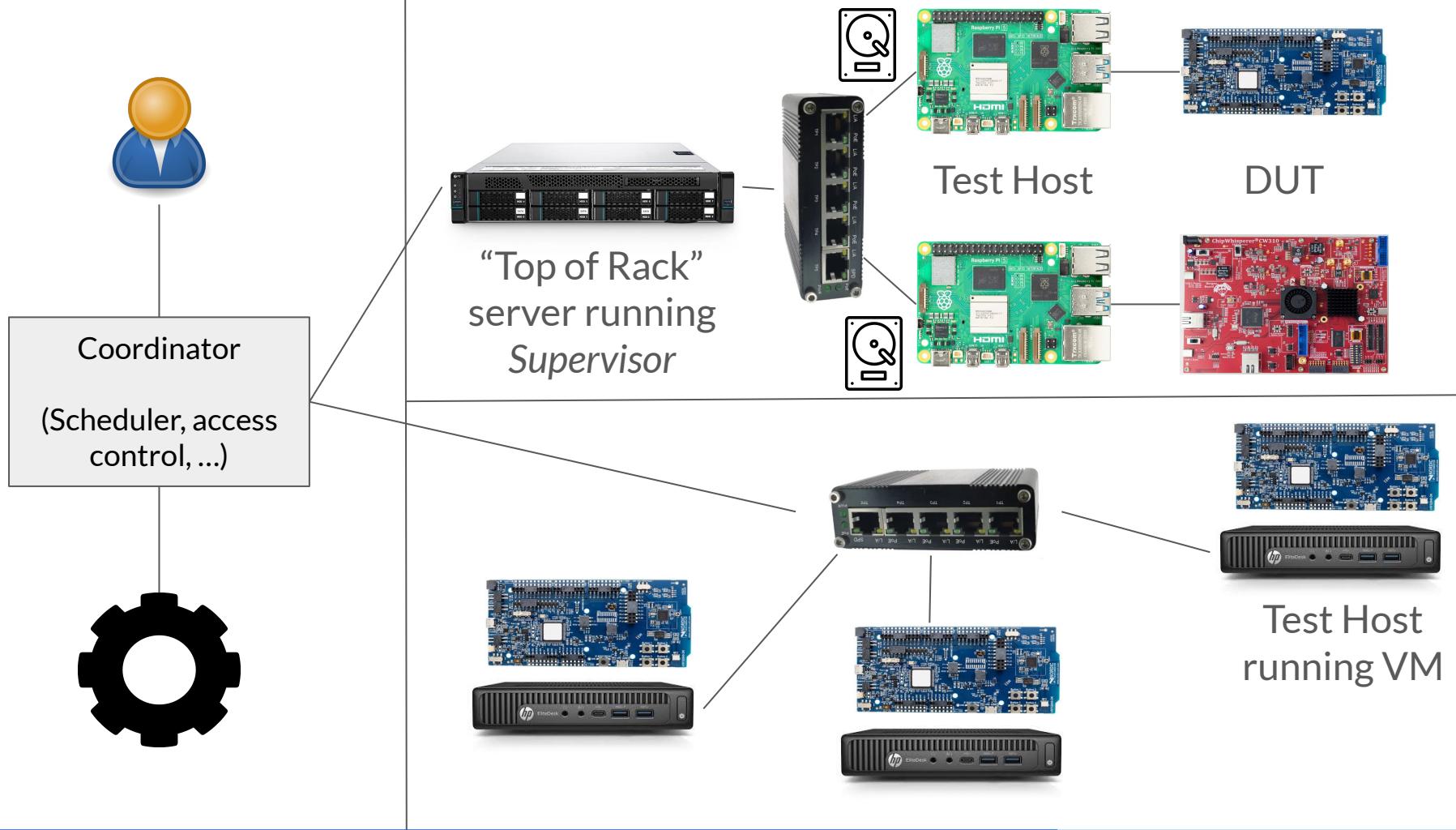
```
Compiling rustc-std-workspace-core v1.39.0 (/home/pi/rustup/toolchains/nightly-2024-05-26-aarch64-unknown-linux-gnu/librustlib/src/rust/library/rustc-std-workspace-core)
Compiling tock-cells v0.1.0 (/home/pi/tock/libraries/tock-cells)
Compiling tock-registers v0.9.0 (/home/pi/tock/libraries/tock-register-interface)
Compiling tock-tbf v0.1.0 (/home/pi/tock/libraries/tock-tbf)
Compiling enum-primitive v0.1.0 (/home/pi/tock/libraries/enum_primitive)
Compiling tickv v1.0.0 (/home/pi/tock/libraries/tickv)
Compiling kernel_v0.1.0 (/home/pi/tock/kernel)
Compiling cortexm_v0.1.0 (/home/pi/tock/arch/cortex-m)
Compiling cortexv7m_v0.1.0 (/home/pi/tock/arch/cortex-v7m)
Compiling nrfsx_v0.1.0 (/home/pi/tock/chips/nrfsx)
Compiling capsules-system_v0.1.0 (/home/pi/tock/libraries/capsules/system)
Compiling cortexv4_v0.1.0 (/home/pi/tock/arch/cortex-m4)
Compiling nrfs2_v0.1.0 (/home/pi/tock/chips/nrfs2)
Compiling capsules-extra_v0.1.0 (/home/pi/tock/libraries/capsules/extra)
Compiling nrf52840_v0.1.0 (/home/pi/tock/chips/nrf52840)
Compiling component_v0.1.0 (/home/pi/tock/boards/components)
Compiling nrf52_components v0.1.0 (/home/pi/tock/boards/nordic/nrf52_componen
ts)
    Finished release profile [optimized + debuginfo] target(s) in 1m 02s
    test      36 3348 2136 3426 /home/pi/tock/target/thumbv7em-none-eabi
/RELEASE/nrf5240dk
3f37fcff1f07ff4e4d032c1e684e4eb45ab5dd687a2f067db840da
/target/thumbv7em-none-eabi/release/nrf5240dk
pi@raspberrypi:/tock/boards/nordic/nrf52840dk $ tockloader flash --board nrf52d
k --openocd -a 0xb ../../target/thumbv7em-none-eabi/release/nrf5240dk.bin
[INFO ] Using settings from ./NRF52_BOARDS["nrf52dk"]
[INFO ] Finished in 14.244 seconds
pi@raspberrypi:/tock/boards/nordic/nrf52840dk $
pi@raspberrypi:/tock/boards/nordic/nrf52840dk $
```

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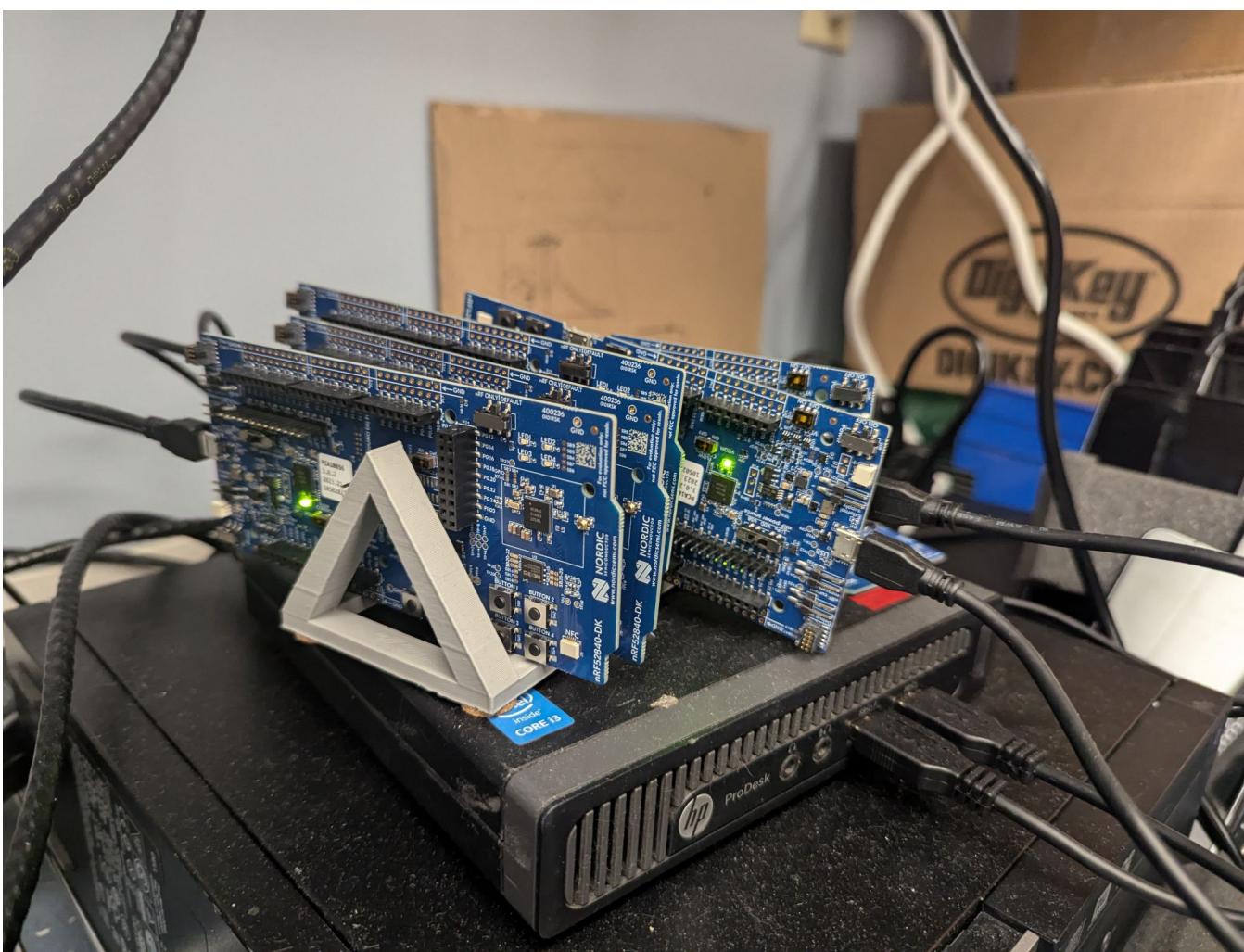
Goal: A Distributed, Reliable Testbed for Development + CI

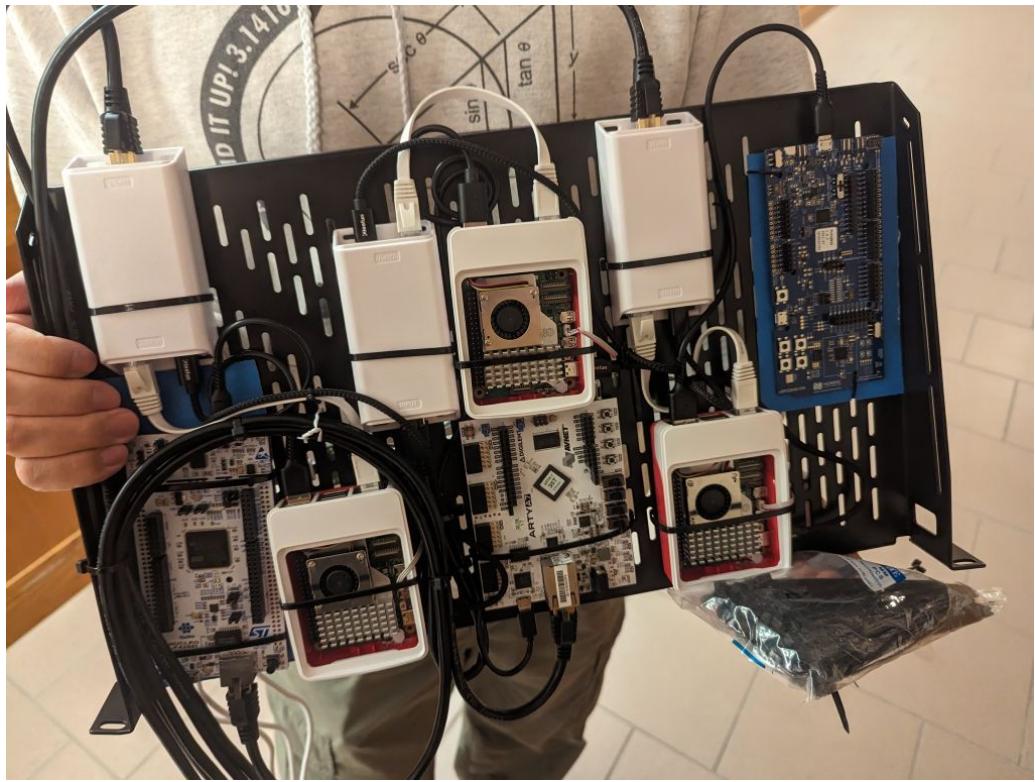
- Physically distributed across multiple different sites
 - Research institutions: UVA, UCSD, Princeton, ...
 - At companies & downstream users; adding downstream targets into the upstream CI
- Reliable
 - Schedule among set of available boards
 - Retry on different HW in case of hardware failure, network outage, etc.
- Accommodate diverse testing workloads
 - Layer of abstraction: Linux environment with HW access
 - (Optional) access to hardware peripherals / GPIO
- Secure
 - Isolate different test jobs
 - Access control for individual boards (restrict type of workload & user access)



Current State

- Initial proof of concept working since ~January
 - Targeted Linux containers exclusively
 - Basic architecture seems decent
 - Coordinator written in Elixir + Phoenix → rewrite it in Rust!
- Rewrite started ~2-3 weeks ago
 - For now, focusing on low-level components & engineering
 - Taking in lessons learned from the first attempt
- Increasing momentum: 2-4 people working on this starting now!
- Interest from other communities as well – Rust Embedded, Embassy
- Hardware deployments “ready” at UCSD, Princeton, UVA(?)







Demo