

Algorithmic Verification of Linear Dynamical Systems

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PhD Defence

Linear dynamical systems

A *linear dynamical system* is given by (M, s) where

- $M \in \mathbb{Q}^{d \times d}$ is the *update matrix*
- $s \in \mathbb{Q}^d$ is the *initial configuration*

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Verification of LDS

Find algorithms that

1. take (M, s) and a property φ , and
2. decide whether $\langle s, Ms, M^2s, M^3s, \dots \rangle$ satisfies φ .

Example of LDS: linear loops

initialise x_1, x_2

while $\neg P(x_1, x_2)$:

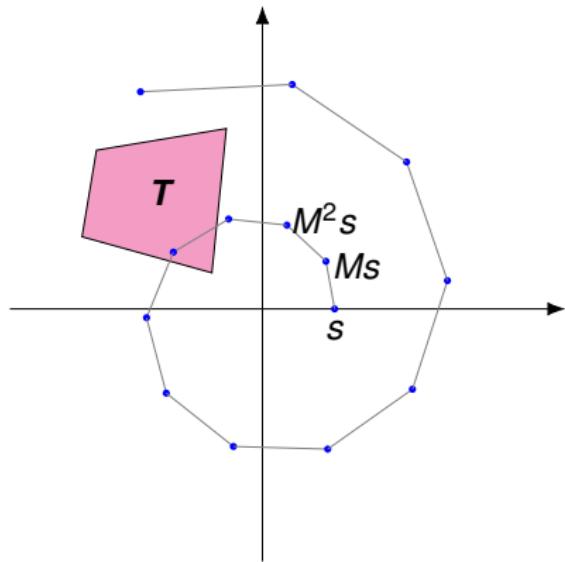
$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = M \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

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s initial value of (x_1, x_2) , $T = \{(x_1, x_2) : P(x_1, x_2)\}$

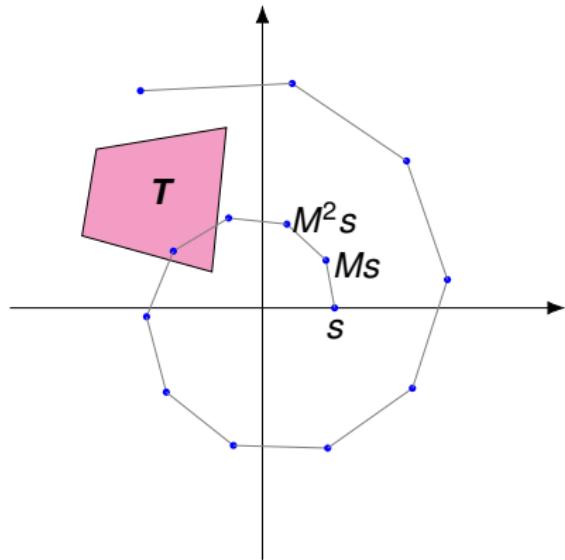
$(x_1, x_2) = M^n s$ after n iterations

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Loop terminates $\Leftrightarrow \langle s, Ms, M^2s, \dots \rangle$ reaches T

The Reachability Problem

A subset of \mathbb{R}^d is *semialgebraic* if it can be defined using inequalities of the form $p(x_1, \dots, x_d) > 0$ and $p(x_1, \dots, x_d) = 0$ for $p \in \mathbb{Q}[x_1, \dots, x_d]$

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Reachability Problem in dimension d

Given $M \in \mathbb{Q}^{d \times d}$, $s \in \mathbb{Q}^d$ and a semialgebraic target T , decide whether $\langle s, Ms, M^2s, \dots, \rangle$ reaches T

Generalising reachability

Suppose we have (M, s) and semialgebraic T_1, \dots, T_m

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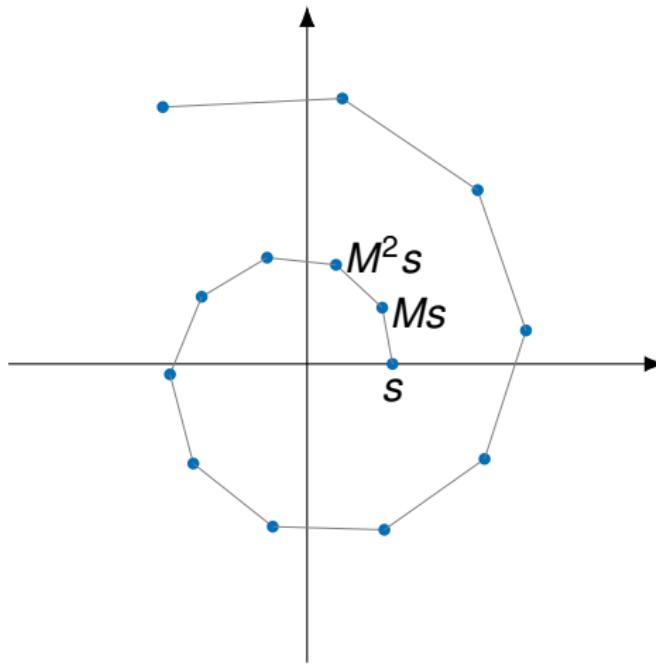
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Model-Checking Problem in dimension d

Given $M \in \mathbb{Q}^{d \times d}$, $s \in \mathbb{Q}^d$, semialgebraic T_1, \dots, T_m and a property φ over T_1, \dots, T_m , decide whether $\langle s, Ms, M^2s, \dots \rangle$ satisfies φ

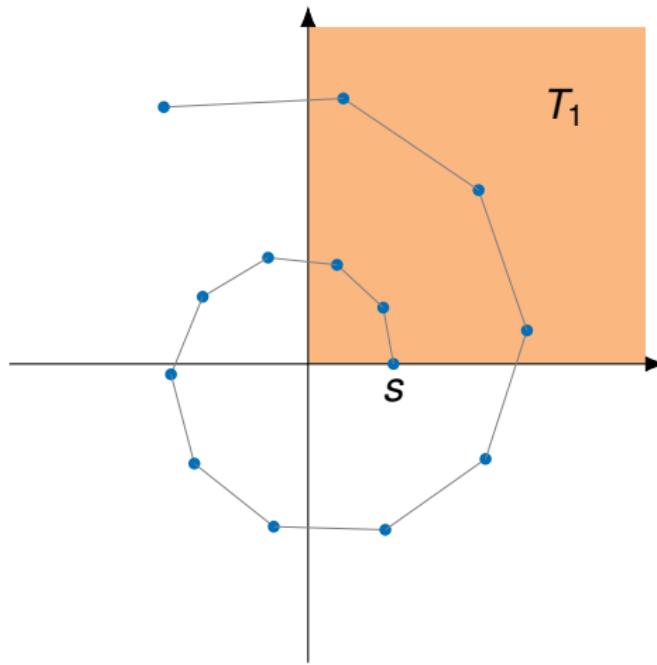
Generalising reachability, cont'd

Consider (M, s) and T_1, T_2, T_3



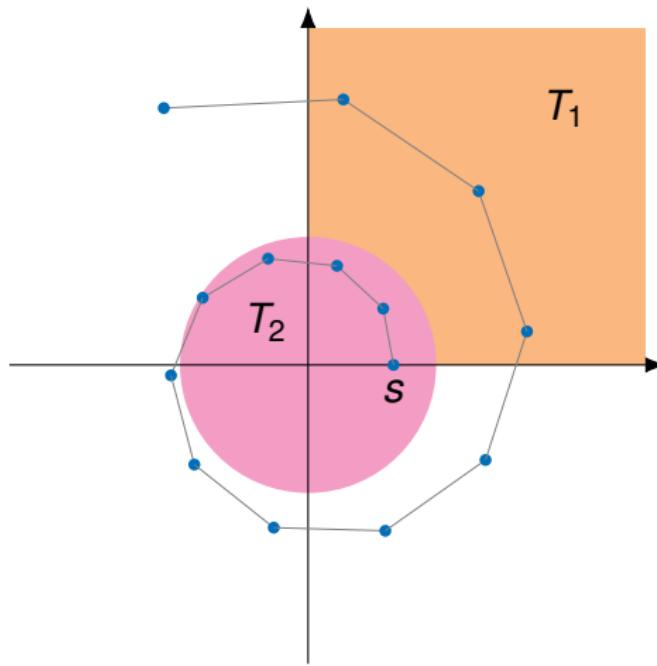
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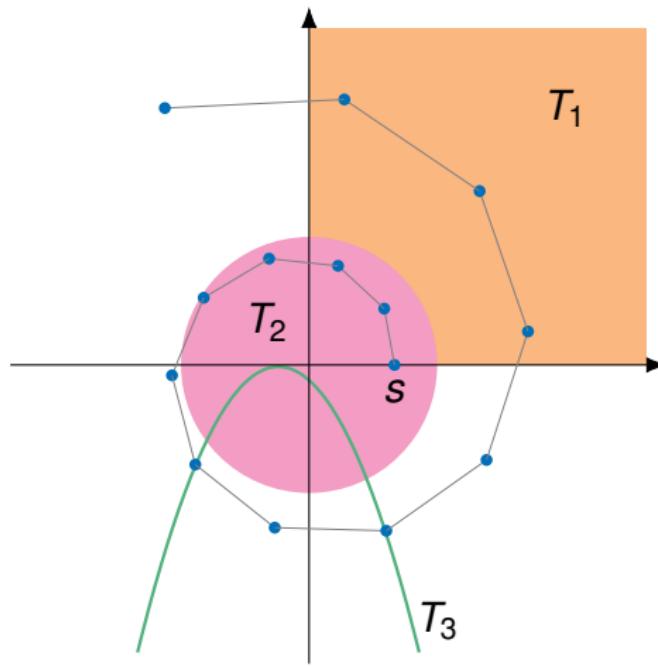
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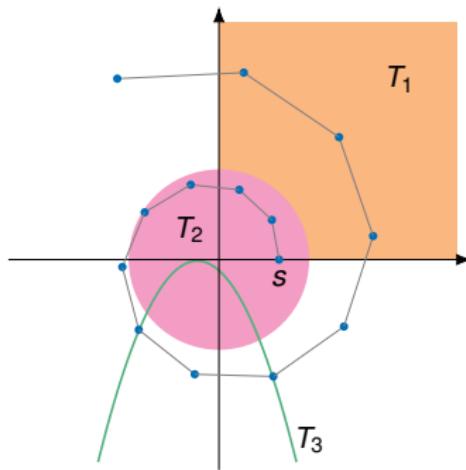
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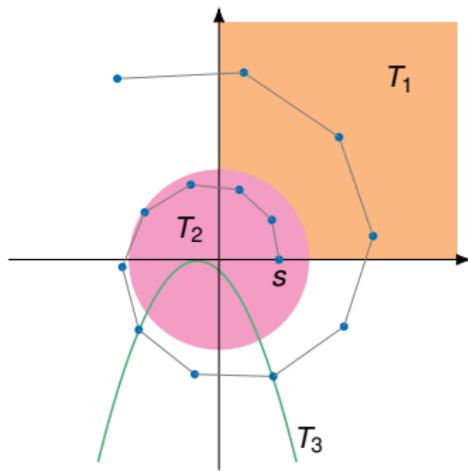
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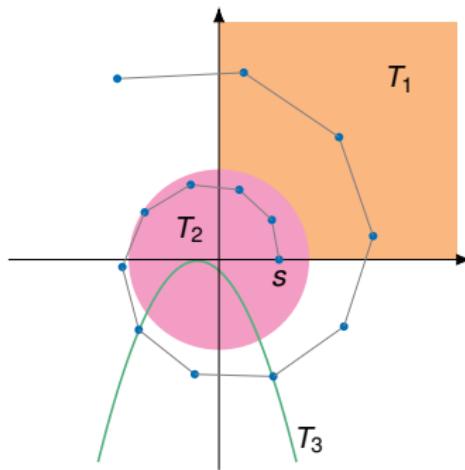


$$\alpha = \{T_1, T_2\} \{T_1, T_2\} \{T_1, T_2\} \{T_2\} \{T_2\} \emptyset \{T_3\} \emptyset \{T_3\} \cdots$$

$\alpha(n) \subseteq \{T_1, T_2, T_3\}$ records T_i such that $M^n s \in T_i$

Generalising reachability, cont'd

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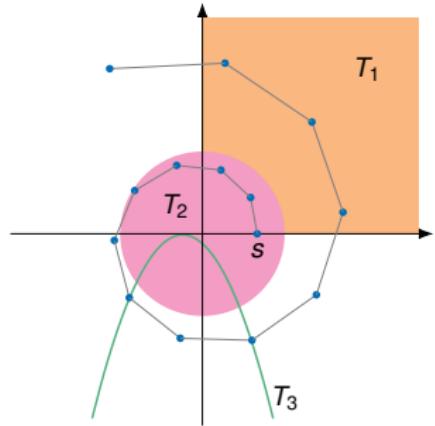


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Verifying (M, s) wrt $T_1, T_2, T_3 \Leftrightarrow$ verifying α

Generalising reachability, final

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Model-Checking Problem in dimension d

Given $M \in \mathbb{Q}^{d \times d}$, $s \in \mathbb{Q}^d$, semialgebraic T_1, \dots, T_m and an automaton \mathcal{A} , decide whether \mathcal{A} accepts the characteristic word α

This thesis

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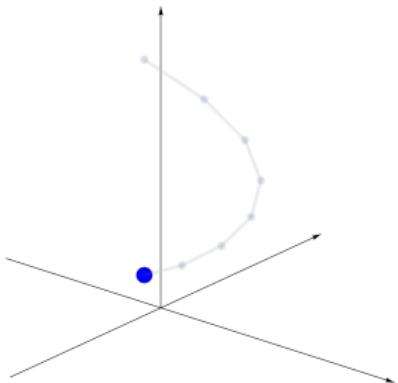
Previously, decidability was only known for reachability-type properties and restricted M

Contributions:

- ▶ A new framework in which decidability of various fragments of the MCP can be shown
- ▶ Extending our decidability results in any significant way requires number-theoretic breakthroughs

Skolem Problem

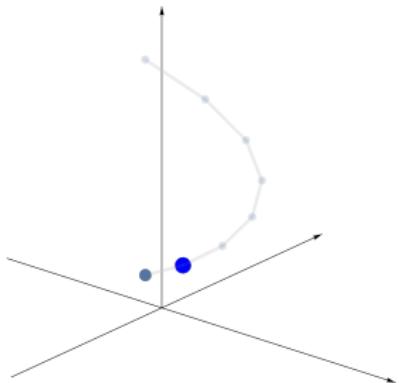
Given (M, s) and a hyperplane H ,
decide whether $M^n s \in H$ for some n



$$\langle s, Ms, M^2s, M^3s, \dots \rangle$$

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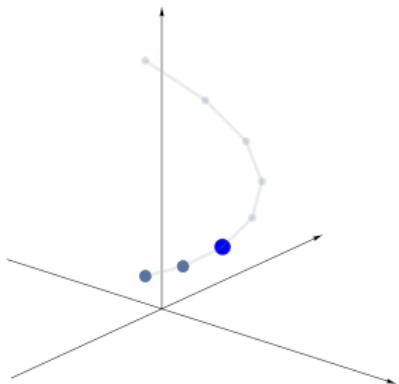
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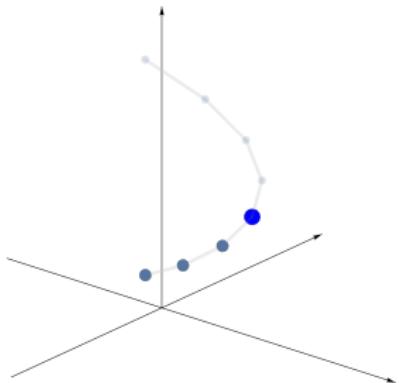
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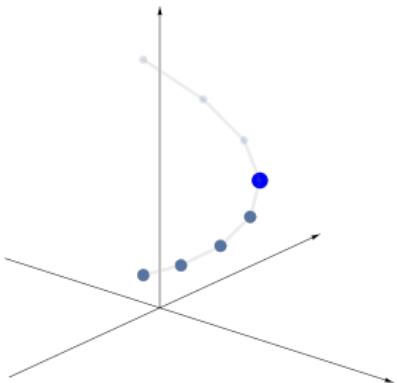
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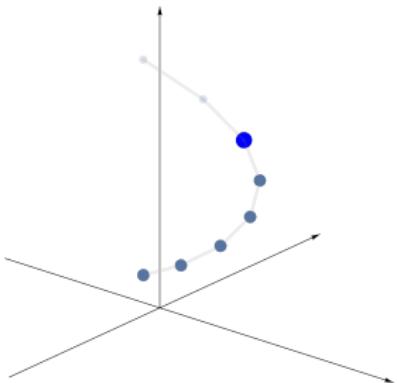
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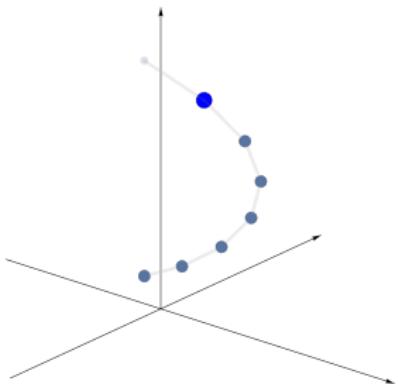
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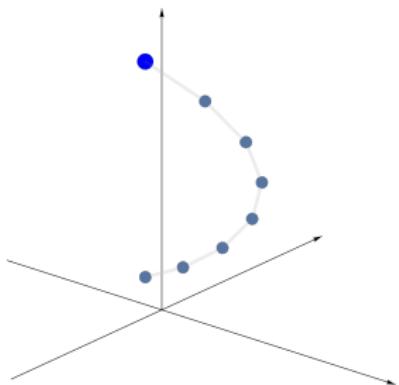
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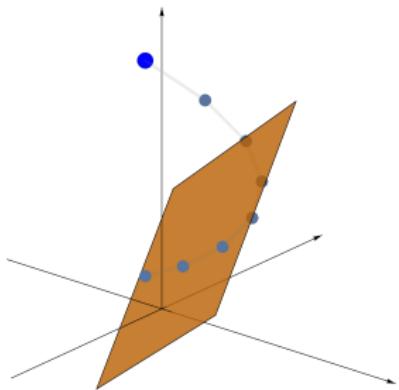
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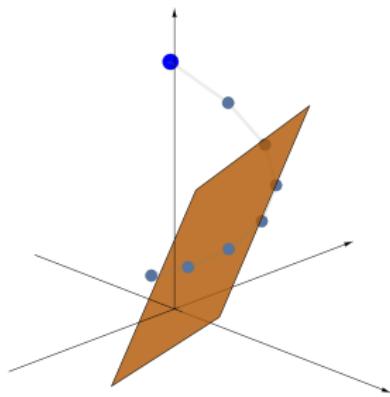
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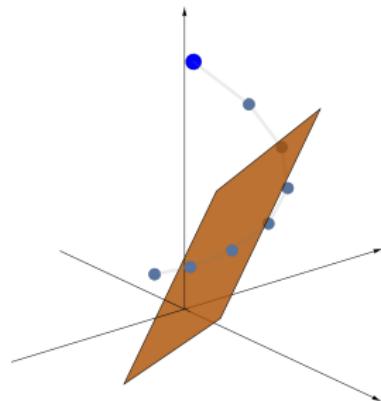
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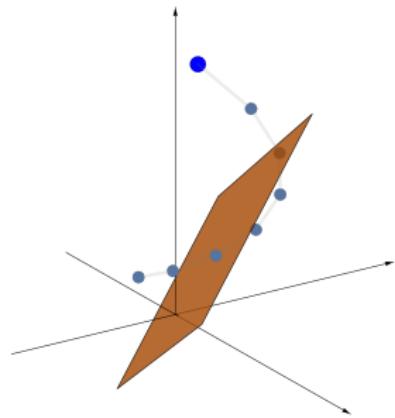
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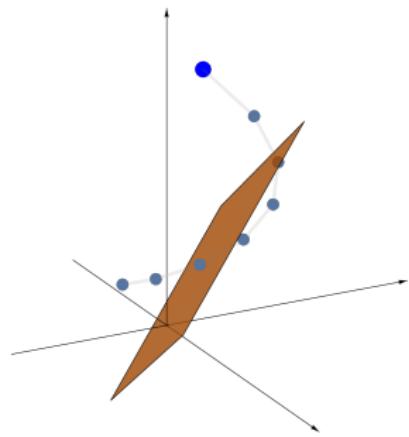
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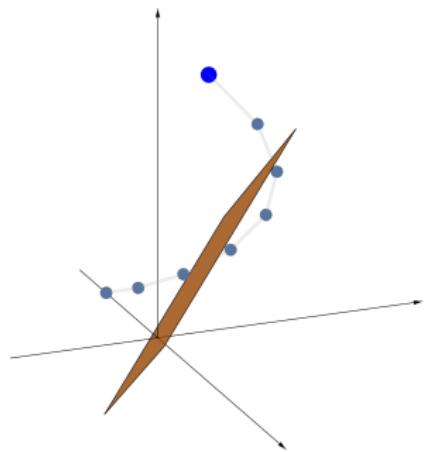
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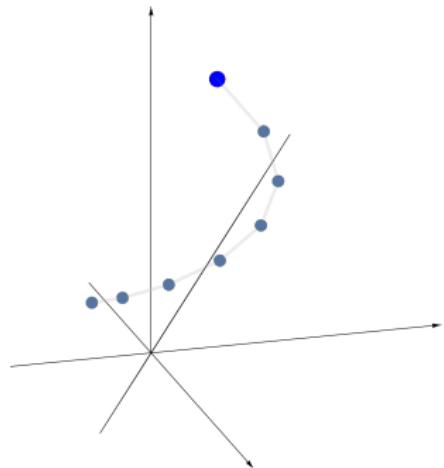
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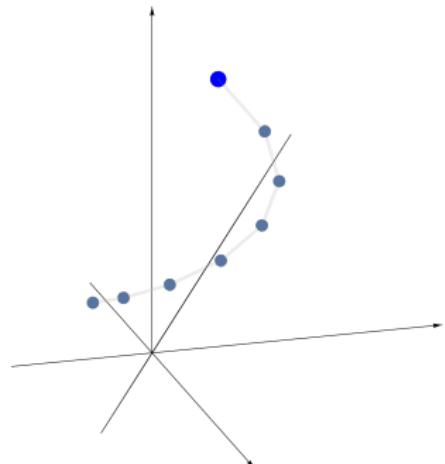


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Skolem Problem

Given (M, s) and a hyperplane H ,
decide whether $M^n s \in H$ for some n

Decidable in dimension $d \leq 4$,
famously open in dimension $d = 5$



$$\langle s, Ms, M^2s, M^3s, \dots \rangle$$

Skolem Problem, cont'd

A sequence $(u_n)_{n \in \mathbb{N}}$ is a *linear recurrence sequence* if there exist $d > 0$ and constants a_1, \dots, a_d such that

$$u_{n+d} = a_1 u_{n+d-1} + \dots + a_d u_n$$

for all n

E.g. $u_{n+3} = 3u_{n+2} + u_{n+1} - 2u_n$

Skolem Problem, LRS version

Given an LRS $(u_n)_{n \in \mathbb{N}}$, decide whether $u_n = 0$ for some n

Skolem Problem, final

Skolem Problem in dimension d

Given $M \in \mathbb{Q}^{d \times d}$, $s \in \mathbb{Q}^d$, and a hyperplane H , decide whether there exists n such that $M^n s \in H$

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Consequently, the Reachability and Model-Checking problems are Skolem-hard in dimension $d = 5$

Positivity Problem

Positivity Problem in dimension d

Given $M \in \mathbb{Q}^{d \times d}$, $s \in \mathbb{Q}^d$, and an open halfspace H , decide whether there exists n such that $M^n s \in H$

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Decidable for $d \leq 5$

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The Reachability and Model-Checking problems are Positivity-hard in dimension $d = 6$

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Using tricks we can reduce the Skolem Problem in dimension 5
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Main result #1

The Model-Checking Problem is decidable in dimension $d \leq 3$.
In dimension $d = 4$, already the Reachability Problem is both
Skolem-hard and Positivity-hard

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I will focus on:

MCP is decidable if $d \leq 3$

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Model-Checking Problem with $d \leq 3$

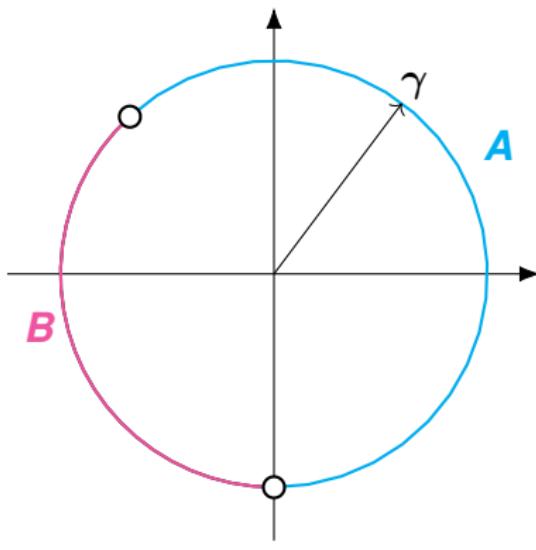
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Main idea: α has a suffix that is a *toric word*

Toric words

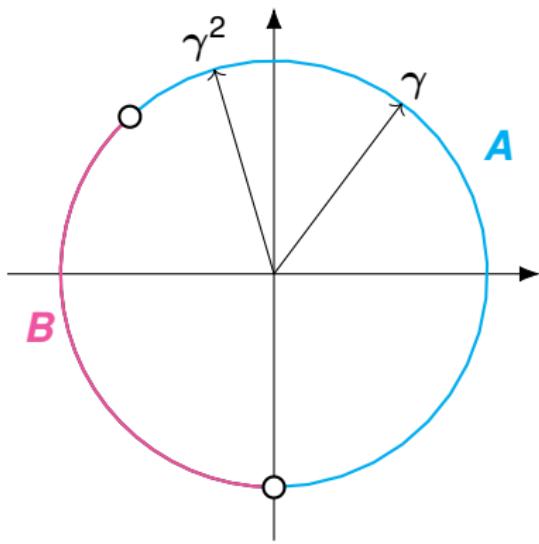
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A

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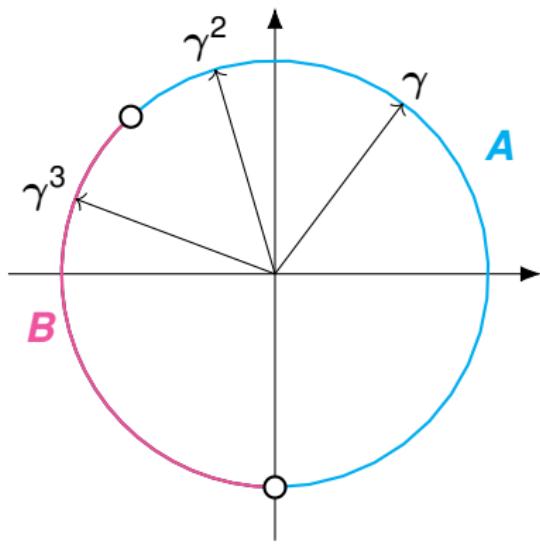
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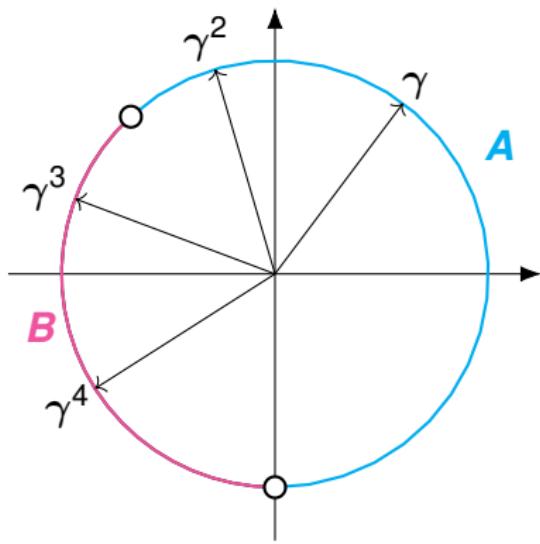
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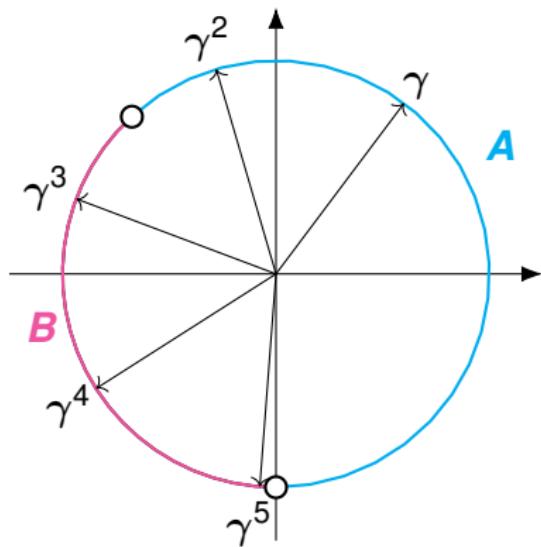
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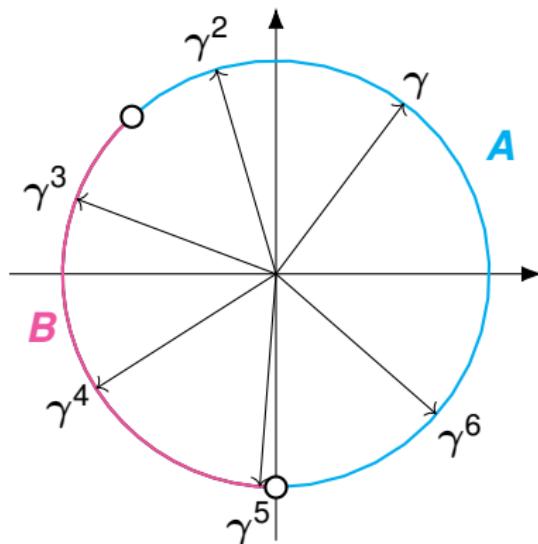
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Toric words, formally

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We are coding the trajectory $(\gamma_1^n, \dots, \gamma_k^n)_{n \in \mathbb{N}}$ with respect to $\{S_a: a \in \Sigma\}$

What is so good about toric words?

Well-studied in symbolic dynamics and combinatorics on words

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Always *almost-periodic* and in cases arising from the MCP,
effectively almost-periodic

Almost-periodic words

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- u does not occur in $\alpha[D, \infty)$, or
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The diagram illustrates a word α composed of overlapping blocks of length D . The first block is underlined with a bracket labeled " $\leq D$ ". The second block is underlined with a bracket labeled " $\leq D$ " below it. The third block is underlined with a bracket labeled " $\leq D$ " above it. The fourth block is underlined with a bracket labeled " $\leq D$ " below it. The word continues with ellipses at the end.

Almost-periodic words

$\leq D$

$\overbrace{abbb}^{\leq D}baabababababbab\overbrace{bbb}^{\leq D}bababbabababab\overbrace{abbb}^{\leq D}babababbab\overbrace{bbb}^{\leq D}babababababababbb\dots$

Semёnov's theorem

Given effectively almost-periodic α and an automaton \mathcal{A} , it is decidable whether \mathcal{A} accepts α

Decidability of the MCP in dimension $d \leq 3$

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Proof. There exists effectively computable N such that $\beta := \alpha[N, \infty)$ is toric: there exists $\gamma \in \mathbb{T}$ and S_a for every $a \subseteq \{T_1, \dots, T_m\}$ such that

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$$\begin{aligned} M^n s \in T &\Leftrightarrow P^{-1}C^n\Gamma^n Ps \in T \\ &\Leftrightarrow \Gamma^n(Ps) \in C^{-n}P(T) \\ &\Leftrightarrow (\gamma_1^n, \dots, \gamma_d^n) \in T_n \end{aligned}$$

where $T_n = f(C^{-n})$ for a “reasonable” function f .

Toricity in LDS, cont'd

$M^n s \in T \Leftrightarrow (\underbrace{\gamma_1^n, \dots, \gamma_d^n}_{\Gamma^n}) \in T_n$ where $|\gamma_i| = 1$ and $T_n = f(C^{-n})$

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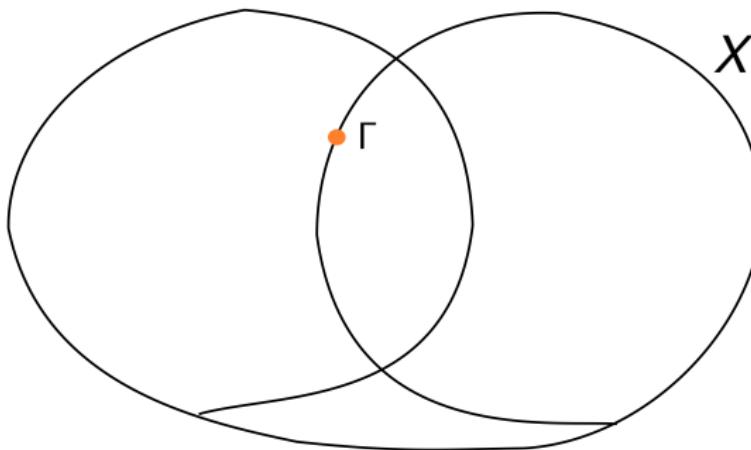
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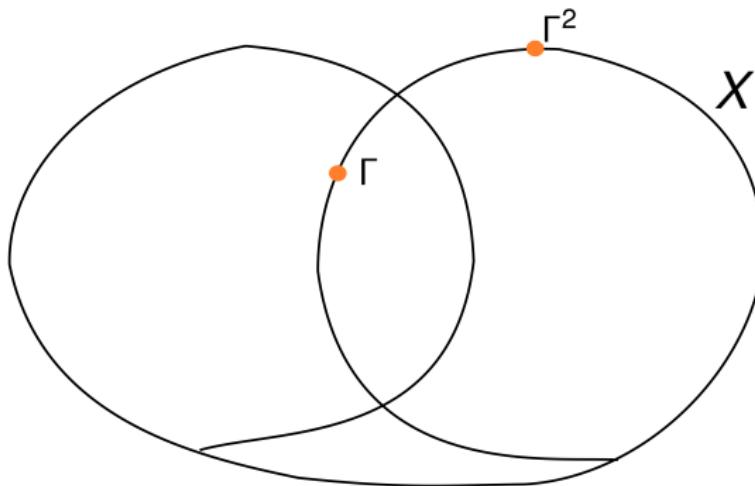
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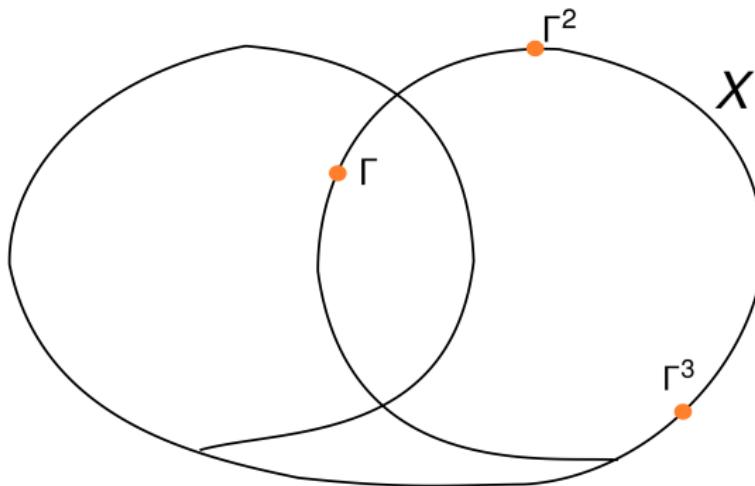
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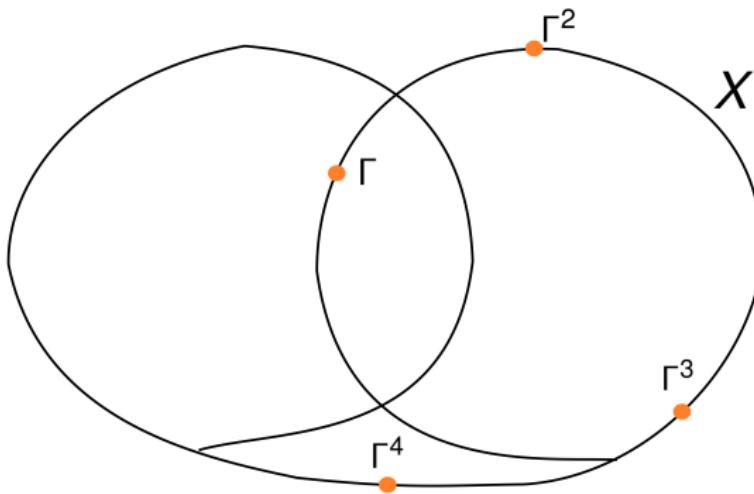
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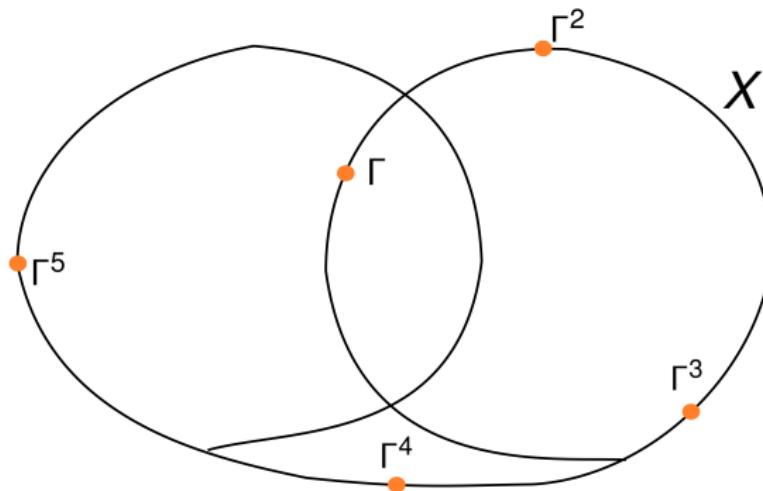
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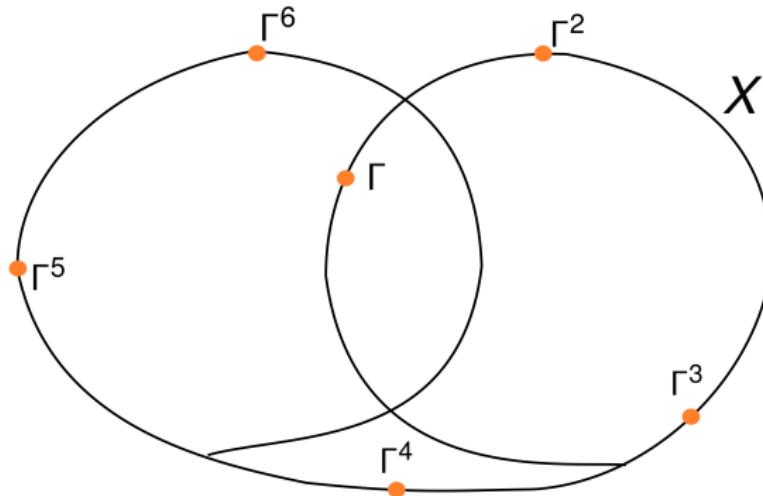
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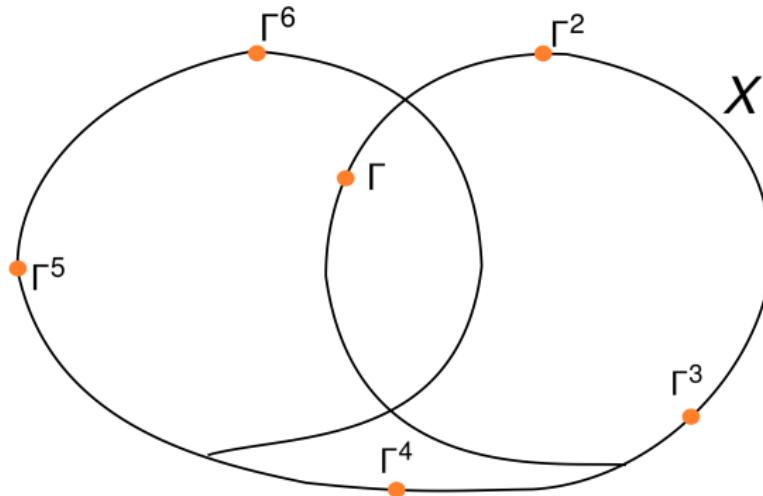
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What about $(T_n)_{n \in \mathbb{N}}$?

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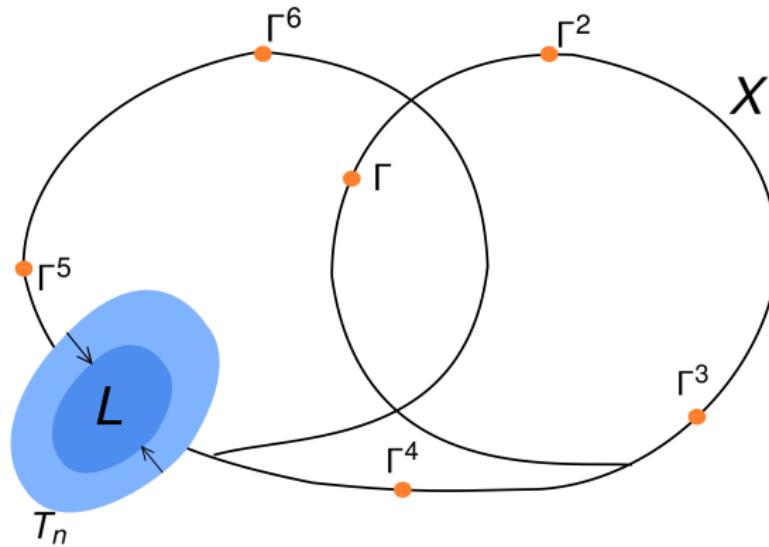
$(T_n)_{n \in \mathbb{N}} = (f(C^{-n}))_{n \in \mathbb{N}}$ converges to a limit shape L

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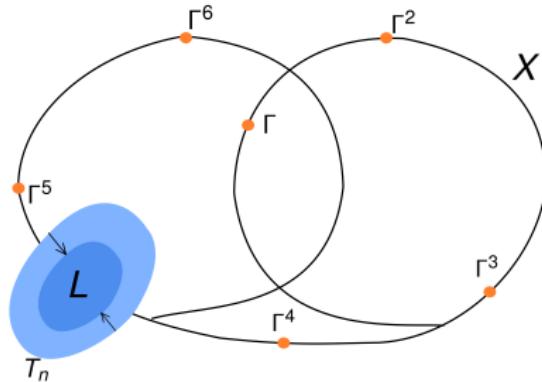
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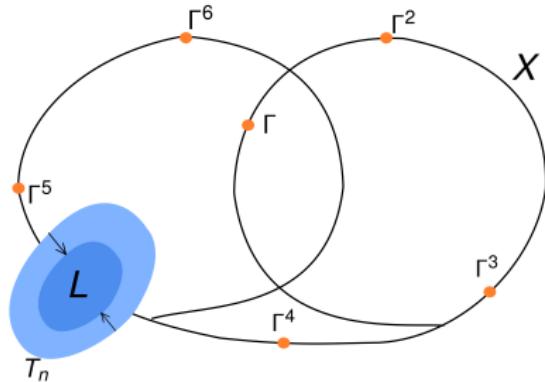
Recall: $M^n s \in T \Leftrightarrow \Gamma^n \in T_n$



If $T_n \Delta L$ disappears fast, then $\Gamma^n \in T_n \Leftrightarrow \Gamma^n \in L$ for large n

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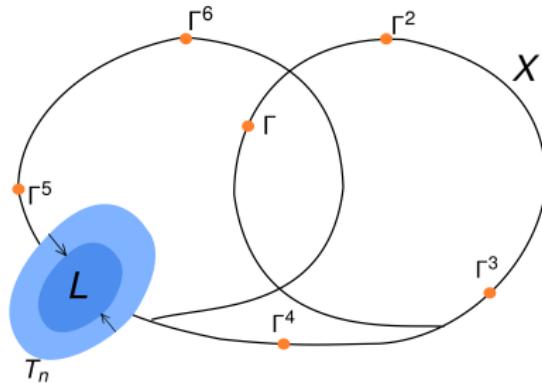
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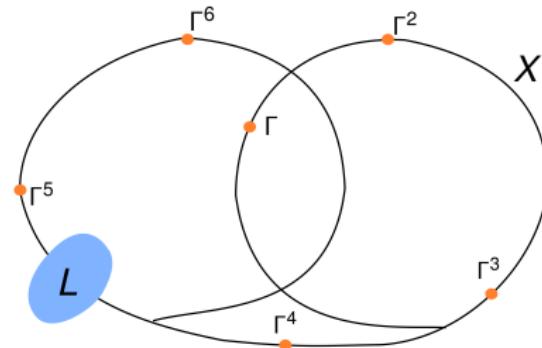
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MCP is decidable if $d \leq 3$

Given $d \leq 3$, $M \in \mathbb{Q}^{d \times d}$, $s \in \mathbb{Q}^d$, semialgebraic T_1, \dots, T_m , and an automaton \mathcal{A} , it is decidable whether \mathcal{A} accepts the characteristic word α of (M, s) wrt T_1, \dots, T_m

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A set is tame if it can be obtained, through set operations, from semialgebraic sets that (i) are contained in a 3D subspace, or (ii) have intrinsic dimension 1

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\mathcal{A} prefix-independent \Leftrightarrow whether α is accepted does not change through finitely many modifications

Hardness

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Hardness, cont'd

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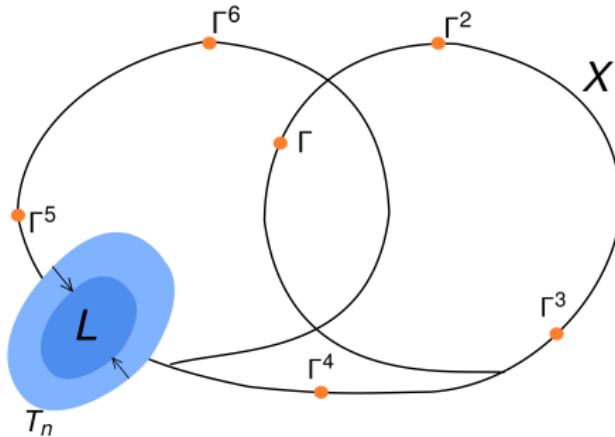
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- Lifting prefix-independence \Rightarrow Skolem-hardness

Reachability Problem revisited

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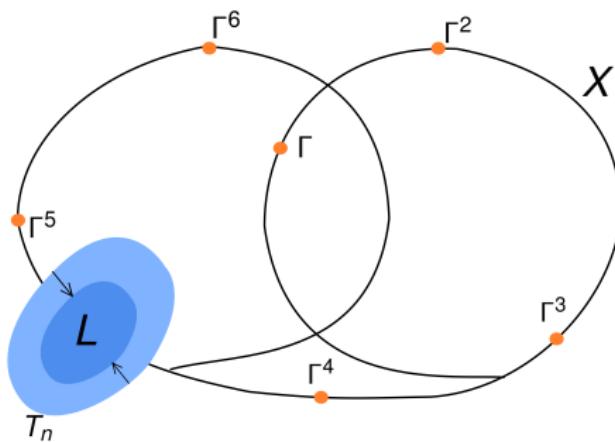


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$(T_n)_{n \in \mathbb{N}}$ converges to a limit shape L



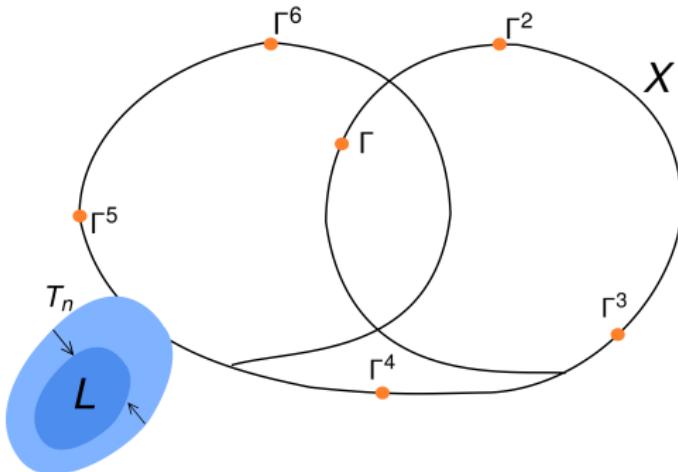
Reached infinitely often: L has ample intersection with X

Reachability Problem revisited

$$M^n s \in T \Leftrightarrow \Gamma^n \in T_n$$

$(\Gamma^n)_{n \in \mathbb{N}}$ is dense in compact $X \subseteq \mathbb{T}^d \subset \mathbb{C}^d$

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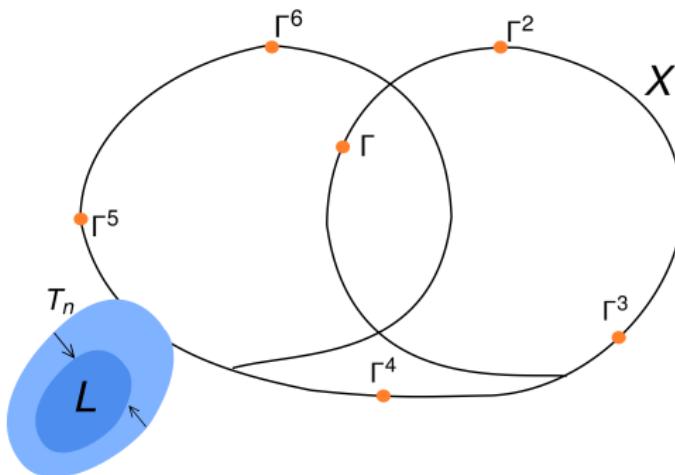


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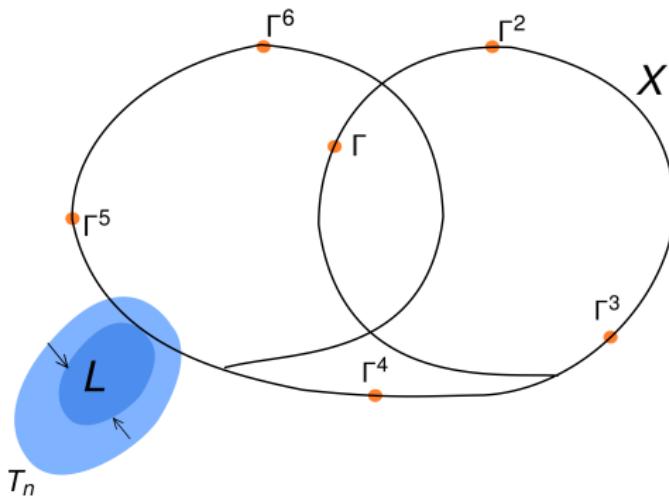
Not reachable: T_n is separated from X for large n

Reachability Problem revisited

$$M^n s \in T \Leftrightarrow \Gamma^n \in T_n$$

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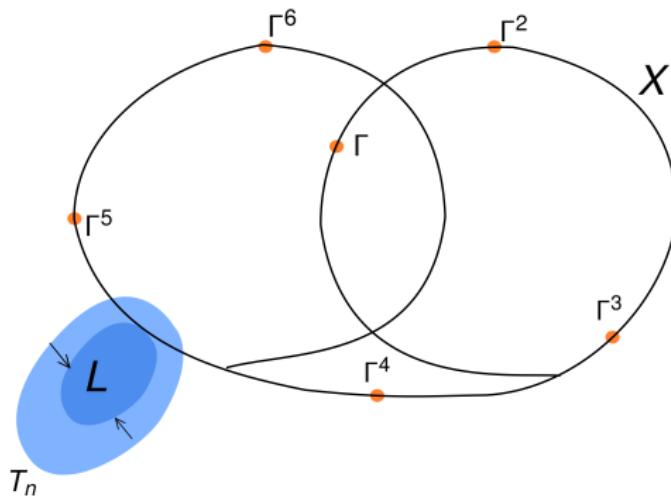


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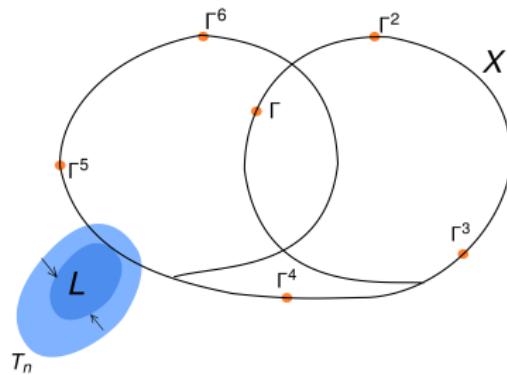
$(T_n)_{n \in \mathbb{N}}$ converges to a limit shape L



Difficult: $T_n \cap X$ disappears but T_n not separated from X

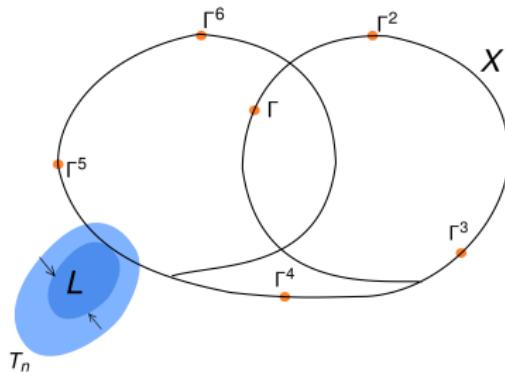
Topological reachability

Difficult case of the Reachability Problem:



Topological reachability

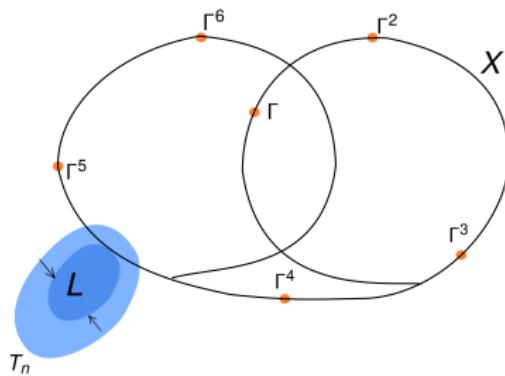
Difficult case of the Reachability Problem:



Topological Reachability Problem. Given (M, s) and target T , decide whether in every $B(s, \varepsilon)$ for $\varepsilon > 0$ there exists \hat{s} such that the orbit of (M, \hat{s}) reaches T

Topological reachability

Difficult case of the Reachability Problem:



Topological Reachability Problem. Given (M, s) and target T , decide whether in every $B(s, \varepsilon)$ for $\varepsilon > 0$ there exists \hat{s} such that the orbit of (M, \hat{s}) reaches T

Decidable by just looking at $L \cap X$!

Summary of decidability

MCP is decidable for tame targets

Given arbitrary $d > 0$, $M \in \mathbb{Q}^{d \times d}$, $s \in \mathbb{Q}^d$, **tame semialgebraic** T_1, \dots, T_m , and an automaton \mathcal{A} , it is decidable whether \mathcal{A} accepts α

Prefix-independent MCP is decidable

Given arbitrary $d > 0$, **diagonalisable** $M \in \mathbb{Q}^{d \times d}$, $s \in \mathbb{Q}^d$, semialgebraic T_1, \dots, T_m , and a **prefix-independent** automaton \mathcal{A} , it is decidable whether \mathcal{A} accepts α

Tame \Leftrightarrow can be obtained from semialgebraic sets that (i) are contained in a 3D subspace, or (ii) have intrinsic dimension 1

Prefix-independent \Leftrightarrow whether α is accepted does not change after finite modifications