

1. Before first connect AR10 hand's usb and then arduino's usb to the computer with Ubuntu .
2. Command to run on the Centos 7
 - 1.1. Turn on the computer -> choose advanced centos 7 -> choose second one from the top
 - 1.2. Open the terminal and run following commands in given order
 - 1.2.1. export ROS_MASTER_URI=http://10.1.71.79:11311
 - 1.2.2. export ROS_IP=10.1.70.233
 - 1.2.3. rosrn nidaq Togzhan6221
2. On the laptop open C:\Users\tactile_pc1\Downloads\Togzhanfiles\send_command and run the script
3. On the computer with Ubuntu -> open the terminal type the following commands in the given order
 - 3.1. In 1st terminal : roscore
 - 3.2. In 2nd terminal: rosrn roserial_python serial_node.py /dev/ttyACM2
 - 3.3. In 3rd terminal: cd ros_s/arhand
 - 3.4. In 3rd terminal: source devel/setup.bash
 - 3.5. In 3rd terminal: cd AR10/ar10/scripts
 - 3.6. In 3rd terminal: rosrn ar10 hand_move.py
4. Go back to the laptop and enter value 1: to open hand 0: to close hand and -1 to exit
5. By typing rostopic echo /handChatter you can observe data from the pressure sensor and accelerometer