

UNIVERSIDADE DE AVEIRO

DESEMPENHO E DIMENSIONAMENTO DE REDES

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Relatório do Trabalho no.4

Autores:

Pedro Coelho 59517

Nuno Silva 72708

Professores:

Amaro Fernandes de Sousa

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1 Trabalho

1.1 a.)

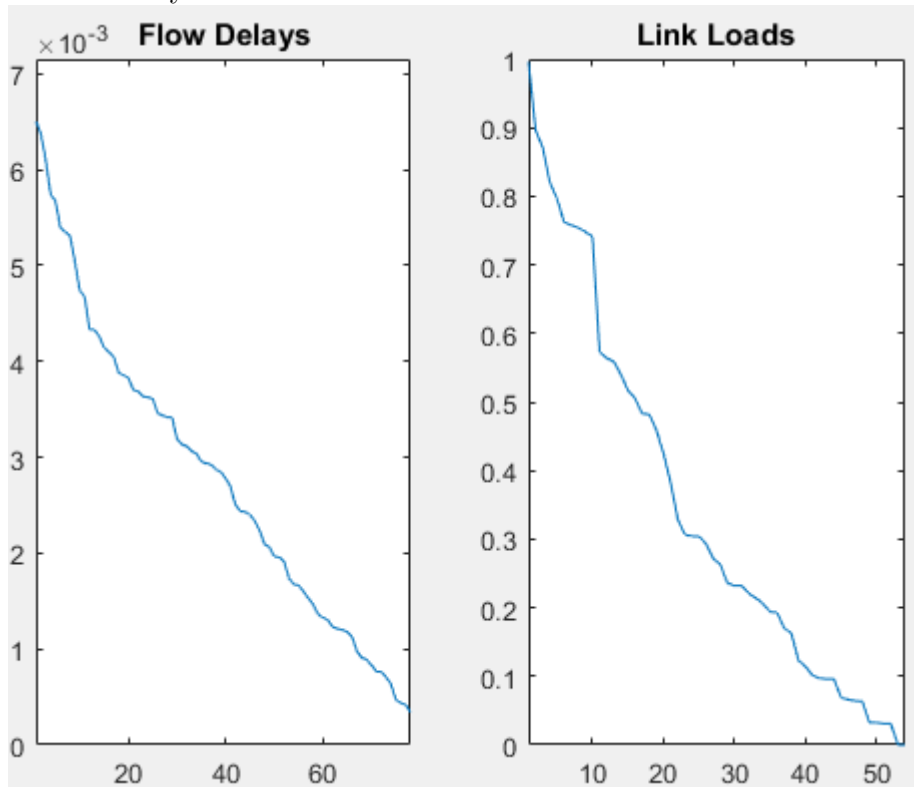
Ao executarmos o scrip fornecido obtemos os seguintes resultados:

MaximumLoad = 0.9960

AverageLoad = 0.3478

AverageDelay = 0.0032

MaxAvDelay = 0.0065



1.2 b.)

O problema b impõe como custo a soma da carga nas ligações pelo que foi necessário editar o código fornecido para ter isto em conta. Desta alteração resultou o código que se segue.

```
Matrizes;
miu= R*1e9/(8*1000);
NumberLinks= sum(sum(R>0));
lambda_s= T*1e6/(8*1000);
gama= sum(sum(lambda_s));
d= L*1e3/2e8;

pairs= [];
for origin=1:16
    for destination=(origin+1):17
        if T(origin,destination)+T(destination,origin)>0
            pairs= [pairs; origin destination];
```

```

        end
    end
end
npairs= size(pairs,1);
lambda= zeros(17);
routes= zeros(npairs,17);
for i=1:npairs
    origin= pairs(i,1);
    destination= pairs(i,2);
    Load= lambda./miu;
    r= ShortestPathSym(Load,origin,destination);
    routes(i,:)= r;
    j= 1;
    while r(j)~= destination
        lambda(r(j),r(j+1))= lambda(r(j),r(j+1)) +...
            lambda_s(origin,destination);
        lambda(r(j+1),r(j))= lambda(r(j+1),r(j)) +...
            lambda_s(destination,origin);
        j= j+1;
    end
end
Load= lambda./miu;
Load(isnan(Load))= 0;
MaximumLoad= max(max(Load))
AverageLoad= sum(sum(Load))/NumberLinks

AverageDelay= (lambda./(miu-lambda)+lambda.*d);
AverageDelay(isnan(AverageDelay))= 0;
AverageDelay= 2*sum(sum(AverageDelay))/gama
Delay_s= zeros(npairs,1);
for i=1:npairs
    origin= pairs(i,1);
    destination= pairs(i,2);
    r= routes(i,:);
    j= 1;
    while r(j)~= destination
        Delay_s(i)= Delay_s(i)+ 1/(miu(r(j),r(j+1))-...
            lambda(r(j),r(j+1))) + d(r(j),r(j+1));
        Delay_s(i)= Delay_s(i)+ 1/(miu(r(j+1),r(j))-...
            lambda(r(j+1),r(j))) + d(r(j+1),r(j));
        j= j+1;
    end
end
MaxAvDelay= max(Delay_s)

```

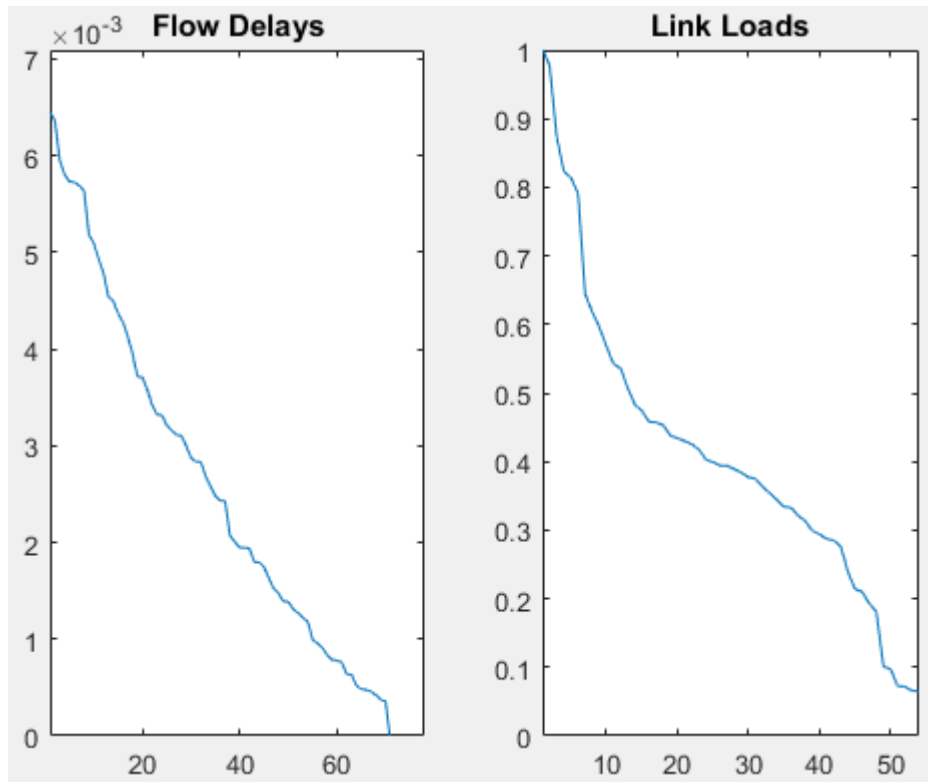
A execução deste scrip providenciou os seguintes resultados:

MaximumLoad = 1.0020

AverageLoad = 0.4109

AverageDelay = 0.0024

MaxAvDelay = 0.0064



A obtenção de um Maximum load superior a 1 torna claro que neste caso não faz sentido a aproximação de Kleinrock.

1.3 b'.)

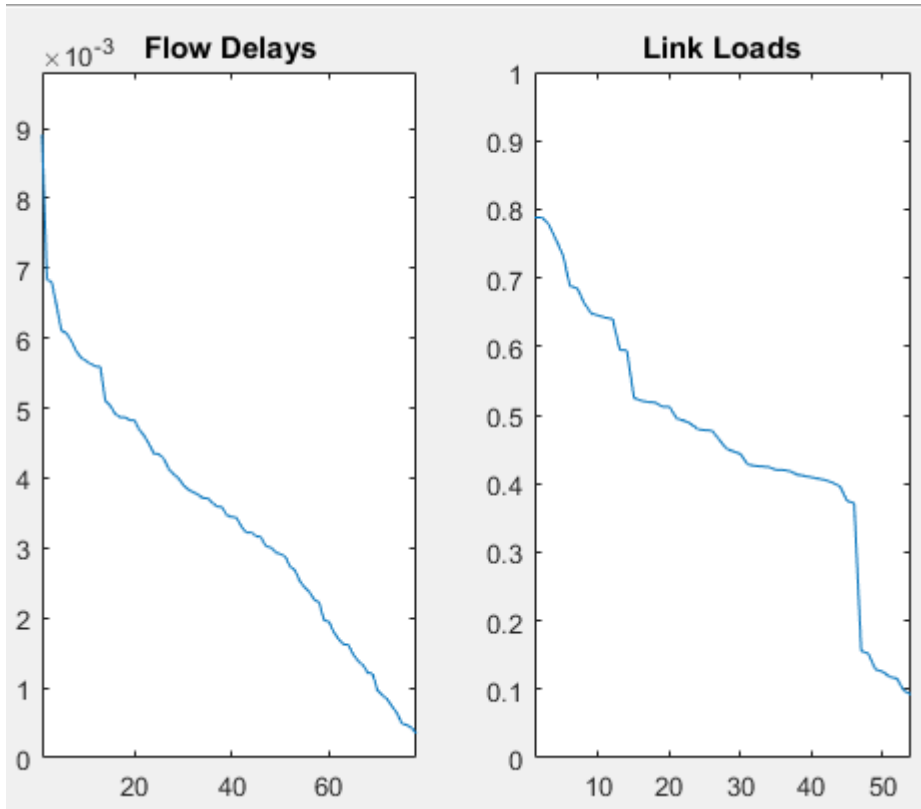
Devido à alínea anterior não fazer sentido foi criada uma versão alternativa à mesma onde os custos seriam o quadrado, pequena alteração surtiu resultados com valores que podem ser considerados.

MaximumLoad = 0.7880

AverageLoad = 0.4629

AverageDelay = 0.0037

MaxAvDelay = 0.0089



1.4 c.)

Um outro cenário onde o custo a considerar é o tempo de viagem do pacote criou uma outra versão do simulador.

```

Matrizes;
miu= R*1e9/(8*1000);
NumberLinks= sum(sum(R>0));
lambda_s= T*1e6/(8*1000);
gama= sum(sum(lambda_s));
d= L*1e3/2e8;

pairs= [];
for origin=1:16
    for destination=(origin+1):17
        if T(origin,destination)+T(destination,origin)>0
            pairs= [pairs; origin destination];
        end
    end
end
npairs= size(pairs,1);
lambda= zeros(17);
routes= zeros(npairs,17);
for i=1:npairs
    origin= pairs(i,1);
    destination= pairs(i,2);
    aux=1./(miu-lambda) + d;
    r= ShortestPathSym(aux,origin,destination);
    routes(i,:)= r;
end

```

```

j= 1;
while r(j)~= destination
    lambda(r(j),r(j+1))= lambda(r(j),r(j+1)) + ...
        lambda_s(origin , destination );
    lambda(r(j+1),r(j))= lambda(r(j+1),r(j)) + ...
        lambda_s(destination , origin );
    j= j+1;
end
end
Load= lambda./miu;
Load(isnan(Load))= 0;
MaximumLoad= max(max(Load))
AverageLoad= sum(sum(Load))/NumberLinks

AverageDelay= (lambda./(miu-lambda)+lambda.*d);
AverageDelay(isnan(AverageDelay))= 0;
AverageDelay= 2*sum(sum(AverageDelay))/gama
Delay_s= zeros(npairs,1);
for i=1:npairs
    origin= pairs(i,1);
    destination= pairs(i,2);
    r= routes(i,:);
    j= 1;
    while r(j)~= destination
        Delay_s(i)= Delay_s(i)+ 1/(miu(r(j),r(j+1))-...
            lambda(r(j),r(j+1))) + d(r(j),r(j+1));
        Delay_s(i)= Delay_s(i)+ 1/(miu(r(j+1),r(j))-...
            lambda(r(j+1),r(j))) + d(r(j+1),r(j));
        j= j+1;
    end
end
end
MaxAvDelay= max(Delay_s)

subplot(1,2,1)
printDelay_s= sortrows(Delay_s,-1);
plot(printDelay_s)
axis([1 npairs 0 1.1*MaxAvDelay])
title('Flow_Delays')
subplot(1,2,2)
printLoad= sortrows(Load(:),-1);
printLoad= printLoad(1:NumberLinks);
plot(printLoad)
axis([1 NumberLinks 0 1])
title('Link_Loads')

```

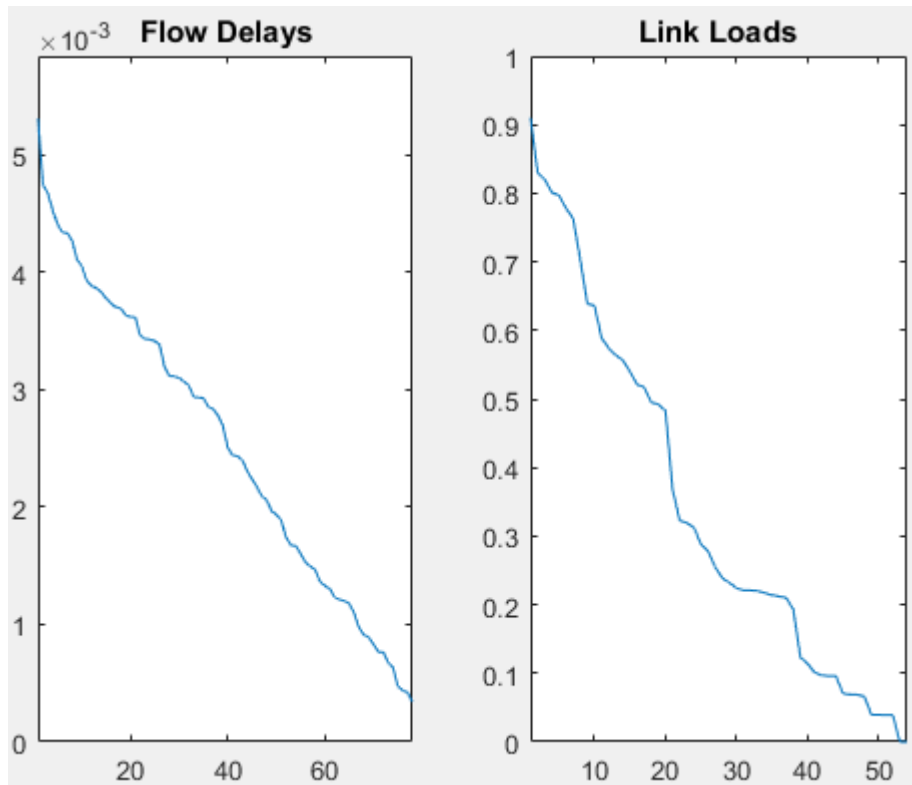
Os resultados obtivos foram os seguintes:

MaximumLoad = 0.9100

AverageLoad = 0.3447

AverageDelay = 0.0026

MaxAvDelay = 0.0053



1.5 d.)

Ao compararmos os resultados é possível extrapolar que a solução B' tornou possível um equilíbrio entre a carga aplicada reduzindo consideravelmente o load máximo, em contrapartido o delay teve o comportamento inverso. A solução C, que apenas difere da A na soma do termo $1/\mu + \lambda$ em cada iteração, permitiu uma redução do delay e uma ligeira redução do load máximo, pelo que esta solução parece ser a mais favorável.

1.6 e.)

O script de simulação para esta alínea é baseado naquele presente nos slides teóricos da disciplina. Este simulador foi ainda desenvolvido por forma a testar a simulação as n vezes necessárias apenas numa execução.

Todas as funções auxiliares desenvolvidas têm em conta o atraso médio como valor de referência para o cálculo do custo.

```
% Lowest Delay
clear all; clc; format long;

n = [3, 10, 30, 300, 3000];

fprintf('\nLowest Delay\n');
fprintf('      n\tGlobalBest\n');

for k = 1:length(n)
    %Global search
    GlobalBest = Inf;
    for j = 1:n(k)
        CurrentSolution = GreedyRandomized_E();
```



```

CurrentObjective = Evaluate_E(CurrentSolution);
repeat = true;

%Local search
while repeat
    NeighbourBest = Inf;

    %Calculating best neighbor
    for i=1:size(CurrentSolution,1)
        NeighbourSolution =...
        BuildNeighbour_E(CurrentSolution,i);
        NeighbourObjective = Evaluate_E(NeighbourSolution);
        if NeighbourObjective < NeighbourBest
            NeighbourBest = NeighbourObjective;
            NeighbourBestSolution = NeighbourSolution;
        end
    end

    %Is current better than best set it as new best
    if NeighbourBest < CurrentObjective
        CurrentObjective = NeighbourBest;
        CurrentSolution = NeighbourBestSolution;
    %If cant find a better solution dont repeat
    else
        repeat = false;
    end
end

%If current better than best set it as the new best
if CurrentObjective < GlobalBest
    GlobalBestSolution = CurrentSolution;
    GlobalBest = CurrentObjective;
end
end

fprintf(' %5d\t%0.6f\n', n(k), GlobalBest);
end

pairs = GlobalBestSolution.pairs;
routes = GlobalBestSolution.routes;
lambda = GlobalBestSolution.lambda;

Matrizes;
miu= R*1e9/(8*1000);
NumberLinks= sum(sum(R>0));
lambda_s= T*1e6/(8*1000);
gama= sum(sum(lambda_s));
d= L*1e3/2e8;

npairs= size(pairs,1);

```

```

Load= lambda./miu;
Load(isnan(Load))= 0;
MaximumLoad= max(max(Load))
AverageLoad= sum(sum(Load))/NumberLinks

AverageDelay= (lambda./(miu-lambda)+lambda.*d);
AverageDelay(isnan(AverageDelay))= 0;
AverageDelay= 2*sum(sum(AverageDelay))/gama
Delay_s= zeros(npairs,1);
for i=1:npairs
    origin= pairs(i,1);
    destination= pairs(i,2);
    r= routes(i,:);
    j= 1;
    while r(j)~= destination
        Delay_s(i)= Delay_s(i)+ 1/(miu(r(j),r(j+1))-...
            lambda(r(j),r(j+1))) + d(r(j),r(j+1));
        Delay_s(i)= Delay_s(i)+ 1/(miu(r(j+1),r(j))-...
            lambda(r(j+1),r(j))) + d(r(j+1),r(j));
        j= j+1;
    end
end
MaxAvDelay= max(Delay_s)

subplot(1,2,1)
printDelay_s= sortrows(Delay_s,-1);
plot(printDelay_s)
axis([1 npairs 0 1.1*MaxAvDelay])
title('Flow_Delays')
subplot(1,2,2)
printLoad= sortrows(Load(:),-1);
printLoad= printLoad(1:NumberLinks);
plot(printLoad)
axis([1 NumberLinks 0 1])
title('Link_Loads')

```

Greedy Randomized:

```

function solution = GreedyRandomized_E()
% Randomizes pair order

Matrices;
miu = R*1e9/(8*1000);
NumberLinks = sum(sum(R>0));
lambda_s = T*1e6/(8*1000);
gama = sum(sum(lambda_s));
d = L*1e3/2e8;

pairs = [];
for origin = 1:16

```

```

    for destination = (origin + 1):17
        if T(origin , destination) + T(destination , origin)>0
            pairs = [pairs; origin destination];
        end
    end
end

% npairs = column length
npairs = size(pairs,1);
% random permutation of the nodes from 1 to npairs.
b = randperm(npairs);
for i = 1:npairs
    % reorder by the random permutation
    aux(i,:) = pairs(b(i),:);
end
pairs = aux;

lambda = zeros(17);
routes = zeros(npairs,17);

% same as solution C
for i = 1:npairs
    origin = pairs(i,1);
    destination = pairs(i,2);

    AverageDelay = (1./(miu-lambda)+d);
    AverageDelay(isnan(AverageDelay))= 0;
    r = ShortestPathSym(AverageDelay,origin,destination);

    routes(i,:)= r;
    j= 1;

    while r(j) ~= destination
        lambda(r(j),r(j+1)) = lambda(r(j),r(j+1)) +...
        lambda_s(origin,destination);
        lambda(r(j+1),r(j)) = lambda(r(j+1),r(j)) +...
        lambda_s(destination,origin);
        j= j+1;
    end
end

solution.pairs = pairs;
solution.routes = routes;
solution.lambda = lambda;
end

```

Evaluate:

```

function Solution = Evaluate_E(CurrentSolution)
lambda = CurrentSolution.lambda;
Matrizes;

```

```

miu= R*1e9/(8*1000);
d= L*1e3/2e8;
lambda_s= T*1e6/(8*1000);
gama= sum(sum(lambda_s));

AverageDelay= (lambda./(miu-lambda)+lambda.*d);
AverageDelay(isnan(AverageDelay))= 0;
AverageDelay = 2*sum(sum(AverageDelay))/gama;

Solution = AverageDelay;
end

```

Build Neighbour:

```

function NeighbourSolution = BuildNeighbour_E(solution , i)
Matrizes;
lambda_s = T * 1e6 / (8*1000);
miu = R * 1e9 / (8*1000);
d = L * 1e3 / 2e8;

% get current origin and destination
origin = solution.pairs(i,1);
destination = solution.pairs(i,2);

% reset lambda
r = solution.routes(i,:);
j = 1;
while r(j) ~= destination
    solution.lambda(r(j),r(j+1)) = solution.lambda(r(j),r(j+1)) -...
    lambda_s(origin ,destination);
    solution.lambda(r(j+1),r(j))= solution.lambda(r(j+1),r(j)) -...
    lambda_s(destination ,origin);
    j= j+1;
end

% route choice - by delay
AverageDelay = (1./(miu-solution.lambda)+d);
r = ShortestPathSym(AverageDelay ,origin ,destination);

% recalculate solution lambda
solution.routes(i,:) = r;
j = 1;
while r(j) ~= destination
    solution.lambda(r(j),r(j+1)) = solution.lambda(r(j),r(j+1)) +...
    lambda_s(origin ,destination);
    solution.lambda(r(j+1),r(j))= solution.lambda(r(j+1),r(j)) +...
    lambda_s(destination ,origin);
    j= j+1;
end

```

```

NeighbourSolution.pairs = solution.pairs;
NeighbourSolution.routes = solution.routes;
NeighbourSolution.lambda = solution.lambda;
end

```

Os valores obtidos para as várias iterações, e para o globalbest foram os seguintes:

Lowest Delay

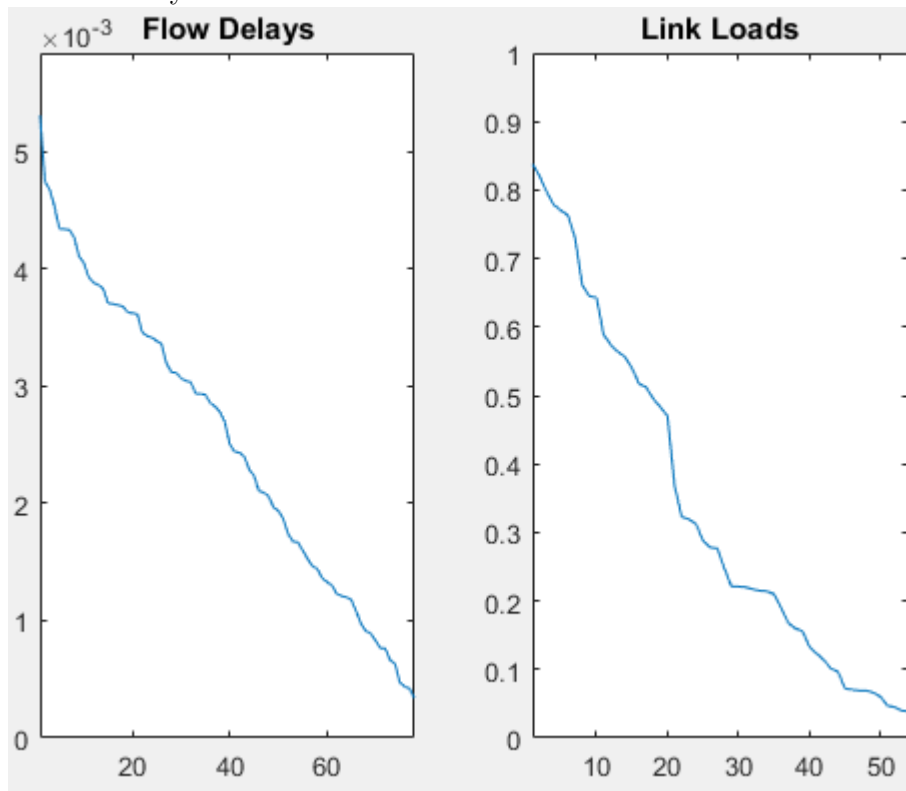
n	GlobalBest
3	0.002640
10	0.002639
30	0.002640
300	0.002636
3000	0.002625

MaximumLoad = 0.8380000000000000

AverageLoad = 0.342498148148148

AverageDelay = 0.002624882299909

MaxAvDelay = 0.005310230444438



1.7 f.)

O simulador f foi construído da mesma forma que o anterior, a única diferença está no custo que as funções auxiliares utilizam, tratando-se agora do custo da carga da ligação.

```

% Lowest Delay
clear all; clc; format long;

n = [3, 10, 30, 300, 3000];

```

```

fprintf( '\nLowest_Delay\n' );
fprintf( '_____n\tGlobalBest\n' );

for k = 1:length(n)
    %Global search
    GlobalBest = Inf;
    for j = 1:n(k)
        CurrentSolution = GreedyRandomized_F();
        CurrentObjective = Evaluate_F(CurrentSolution);
        repeat = true;

        %Local search
        while repeat
            NeighbourBest = Inf;

            %Calculating best neighbor
            for i=1:size(CurrentSolution,1)
                NeighbourSolution = ...
                BuildNeighbour_F(CurrentSolution,i);
                NeighbourObjective = Evaluate_F(NeighbourSolution);
                if NeighbourObjective < NeighbourBest
                    NeighbourBest = NeighbourObjective;
                    NeighbourBestSolution = NeighbourSolution;
                end
            end

            %Is current better than best set it as new best
            if NeighbourBest < CurrentObjective
                CurrentObjective = NeighbourBest;
                CurrentSolution = NeighbourBestSolution;
                %If cant find a better solution dont repeat
            else
                repeat = false;
            end
        end

        %If current better than best set it as the new best
        if CurrentObjective < GlobalBest
            GlobalBestSolution = CurrentSolution;
            GlobalBest = CurrentObjective;
        end
    end

    fprintf( '%5d\t%0.6f\n', n(k), GlobalBest );
end

pairs = GlobalBestSolution.pairs;
routes = GlobalBestSolution.routes;

```

```

lambda = GlobalBestSolution.lambda;

Matrizes;
miu= R*1e9/(8*1000);
NumberLinks= sum(sum(R>0));
lambda_s= T*1e6/(8*1000);
gama= sum(sum(lambda_s));
d= L*1e3/2e8;

npairs= size(pairs,1);

Load= lambda./miu;
Load(isnan(Load))= 0;
MaximumLoad= max(max(Load))
AverageLoad= sum(sum(Load))/NumberLinks

AverageDelay= (lambda./(miu-lambda)+lambda.*d);
AverageDelay(isnan(AverageDelay))= 0;
AverageDelay= 2*sum(sum(AverageDelay))/gama
Delay_s= zeros(npairs,1);
for i=1:npairs
    origin= pairs(i,1);
    destination= pairs(i,2);
    r= routes(i,:);
    j= 1;
    while r(j)~= destination
        Delay_s(i)= Delay_s(i)+ 1/(miu(r(j),r(j+1))-...
            lambda(r(j),r(j+1))) + d(r(j),r(j+1));
        Delay_s(i)= Delay_s(i)+ 1/(miu(r(j+1),r(j))-...
            lambda(r(j+1),r(j))) + d(r(j+1),r(j));
        j= j+1;
    end
end
MaxAvDelay= max(Delay_s)

subplot(1,2,1)
printDelay_s= sortrows(Delay_s,-1);
plot(printDelay_s)
axis([1 npairs 0 1.1*MaxAvDelay])
title('Flow_Delays')
subplot(1,2,2)
printLoad= sortrows(Load(:),-1);
printLoad= printLoad(1:NumberLinks);
plot(printLoad)
axis([1 NumberLinks 0 1])
title('Link_Loads')

```

Greedy Randomized:

```

function solution = GreedyRandomized_F()
% Randomizes pair order

```

```

Matrizes;
miu = R*1e9/(8*1000);
NumberLinks = sum(sum(R>0));
lambda_s = T*1e6/(8*1000);
gama = sum(sum(lambda_s));
d = L*1e3/2e8;

pairs = [];
for origin = 1:16
    for destination = (origin + 1):17
        if T(origin , destination) + T(destination , origin)>0
            pairs = [pairs; origin destination];
        end
    end
end

% npairs = column length
npairs = size(pairs,1);
% random permutation of the nodes from 1 to npairs.
b = randperm(npairs);
for i = 1:npairs
    % reorder by the random permutation
    aux(i,:) = pairs(b(i),:);
end
pairs = aux;

lambda = zeros(17);
routes = zeros(npairs,17);

% same as solution C
for i = 1:npairs
    origin = pairs(i,1);
    destination = pairs(i,2);
    Load= lambda./miu;
    r = ShortestPathSym(Load.^2,origin , destination );

    routes(i,:)= r;
    j= 1;

    while r(j) ~= destination
        lambda(r(j),r(j+1)) = lambda(r(j),r(j+1)) +...
        lambda_s(origin , destination );
        lambda(r(j+1),r(j)) = lambda(r(j+1),r(j)) +...
        lambda_s(destination , origin );
        j= j+1;
    end
end

solution.pairs = pairs;

```



```

solution.routes = routes;
solution.lambda = lambda;
end

```

Evaluate:

```

function Solution = Evaluate_F(CurrentSolution)
lambda = CurrentSolution.lambda;

Matrizes;
miu= R*1e9/(8*1000);

Load= lambda./miu;
Load(isnan(Load))= 0;
MaximumLoad = max(max(Load));

Solution = MaximumLoad;
end

```

Build Neighbour:

```

function NeighbourSolution = BuildNeighbour_F(solution , i)
Matrizes;
lambda=solution.lambda;
lambda_s = T * 1e6 / (8*1000);
miu = R * 1e9 / (8*1000);
d = L * 1e3 / 2e8;

% get current origin and destination
origin = solution.pairs(i,1);
destination = solution.pairs(i,2);

% reset lambda
r = solution.routes(i,:);
j = 1;
while r(j) ~= destination
    solution.lambda(r(j),r(j+1)) = solution.lambda(r(j),r(j+1)) -...
    lambda_s(origin,destination);
    solution.lambda(r(j+1),r(j))= solution.lambda(r(j+1),r(j)) -...
    lambda_s(destination,origin);
    j= j+1;
end

% route choice - by delay
Load= lambda./miu;
r = ShortestPathSym(Load.^2,origin,destination);

% recalculate solution lambda
solution.routes(i,:) = r;
j = 1;
while r(j) ~= destination
    solution.lambda(r(j),r(j+1)) = solution.lambda(r(j),r(j+1)) +...

```

```

    lambda_s(origin , destination );
    solution .lambda(r(j+1),r(j))= solution .lambda(r(j+1),r(j)) +...
    lambda_s(destination , origin );
    j= j+1;
end

NeighbourSolution.pairs = solution.pairs;
NeighbourSolution.routes = solution.routes;
NeighbourSolution.lambda = solution.lambda;
end

```

Foram obtidos os seguintes resultados:

Lowest Delay

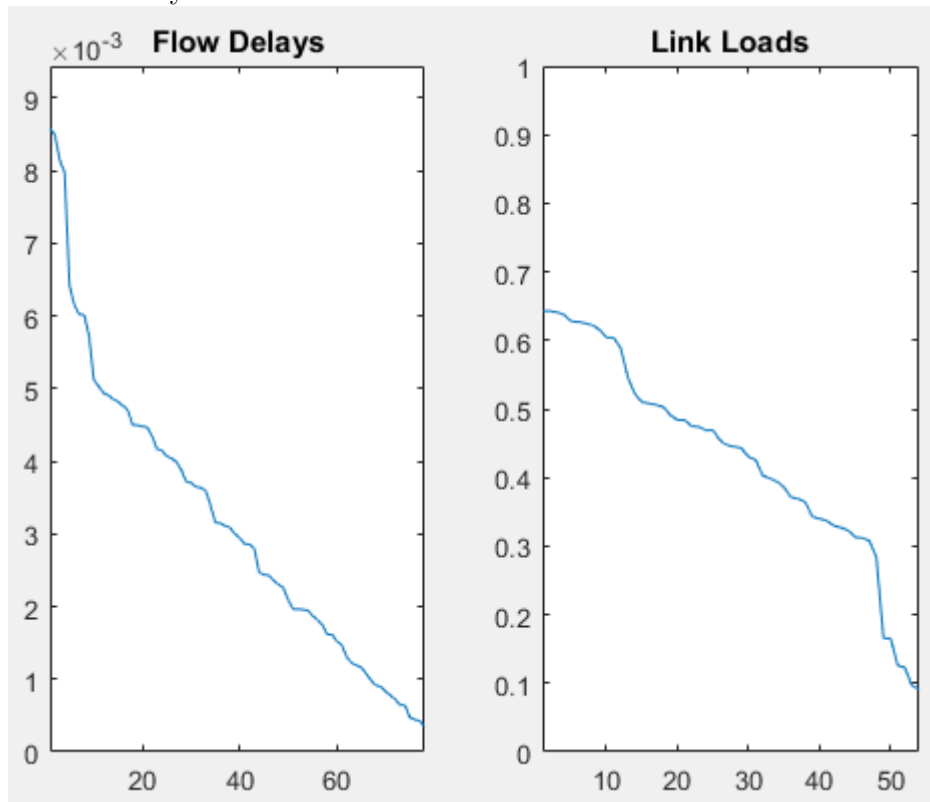
n	GlobalBest
3	0.749000
10	0.677000
30	0.667000
300	0.647000
3000	0.643000

MaximumLoad = 0.6430000000000000

AverageLoad = 0.430318518518518

AverageDelay = 0.003727578517302

MaxAvDelay = 0.008580633418399



1.8 g.)

Comparando os resultados obtidos para os exercícios E e F é possível verificar que foram obtidos melhores resultados para os valores no ex E sendo possível verificar delay medio e load medio

mais baixos, tendo, no entanto, o load máximo sido consideravelmente mais elevado. É possível verificar ainda que a solução no exercício E converge mais rapidamente, sendo que para 3, 10 e 30 iterações se obteve resultados semelhantes.

Observando os resultados obtidos há uma clara convergência mais rápida em E, uma vez que em 3, 10 e 30 houve resultados bastante semelhantes. Conclui-se também que a solução E é a mais favorável pois tem delay e load médios mais baixos, peca apenas por um load máximo mais elevado.