## Clean Data – Missings Map

arm

冟

arm\_y

accel accel

\_arm\_z

\_arm\_x

accel

agnet\_arm\_x

agnet

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gyros\_arm\_x \_accel\_arm yaw\_arm pitch\_arm

gyros\_arm\_y

gyros\_arm\_z

belt x

lagnet\_

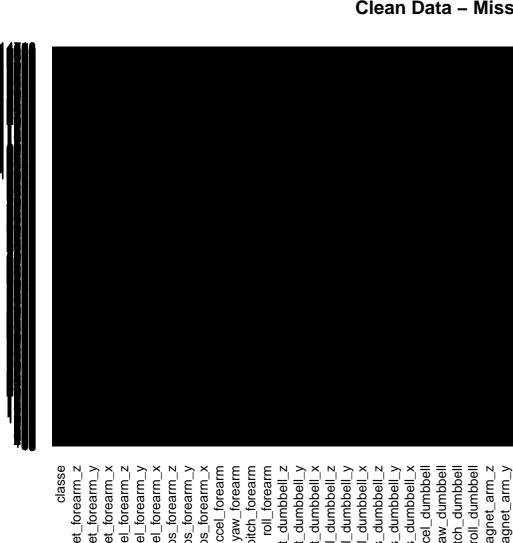
accel\_belt\_z accel\_belt\_y accel\_belt\_x gyros\_belt\_z

agnet\_belt\_y

agnet\_belt\_z

accel\_belt

gyros\_belt\_y gyros\_belt\_x yaw\_belt pitch\_belt roll belt



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