

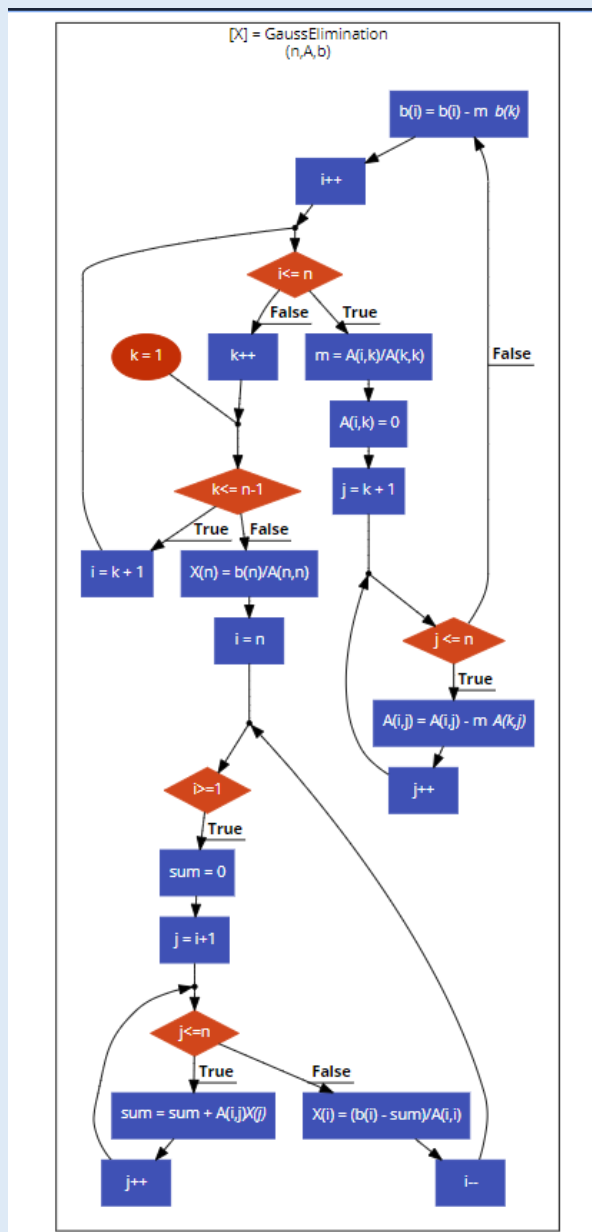
NUMERICAL ANALYSIS ASSIGNMENT 1 - PART 2

14 May 2019

FLOWCHART

1. Gaussian-elimination

i Describe how gauss elimination method works:



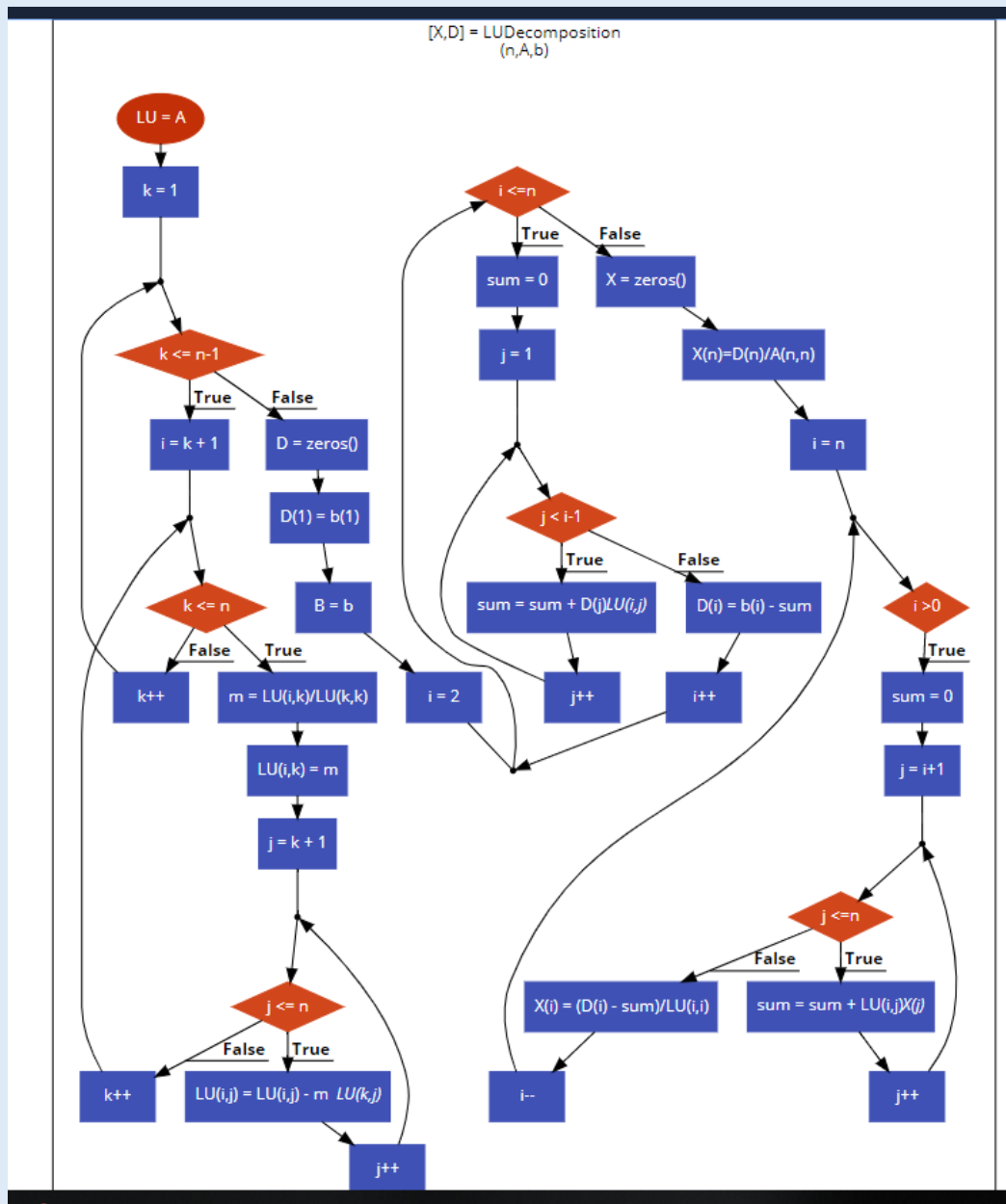
Analysis and conclusion for the behavior of Gauss Elimination:

Gauss Elimination finds the roots of linear equation by eliminating the lower elements in the coefficient matrix then applying backward substitution to get the roots.

Gauss Elimination always converges to the roots of the equation in $O(n^3)$.

2. LU decomposition

i Describe how LU decomposition method works:



Analysis and conclusion for the behavior of LU Decomposition:

LU Decomposition finds the roots by splitting the coefficient matrix into lower and upper matrices multiplied together, applying forward substitution on the lower matrix then applying backward substitution on the upper matrix.

LU Decomposition always converges to the roots of the equation in $O(n^3)$.

3. Gaussian-Jordan

i Describe how Gaussian Jordan method works:

```
function [timeElapsed,system_matrix,steps,lastMatrix,solution] = gauss_jordan(coeff_matrix,
constants_matrix, num_of_unknowns)
    %create_system_matrix
    for index=1 to length(constants_matrix)
        coeff_matrix(index, length(constants_matrix)+1) <-- constants_matrix(index)
    end
    system_matrix <-- coeff_matrix
    result <-- system_matrix

    %forward_elimination
    steps(1) <-- result
    for pivot_index=1 to num_of_unknowns
        %normalize
        pivot <-- result(pivot_index, pivot_index)
        for col=1 to num_of_unknowns+1
            result(pivot_index, col) <-- result(pivot_index, col)/pivot
        end
        steps(pivot_index) <-- result
        %apply_elimination
        for row=1 to num_of_unknowns
            if row equals pivot_index
                continue
            end
            row_pivot <-- result(row,pivot_index)
            for col=pivot_index to num_of_unknowns+1
                result(row,col) <-- result(row,col)-row_pivot*result(pivot_index,col)
            end
        end
    end
    lastMatrix <-- result

    %back_substitution
    solution <-- [0,0]
    for i=1 to num_of_unknowns
        solution(i) <-- lastMatrix(i, num_of_unknowns+1)
    end
end
```

Analysis and conclusion for the behavior of Gauss Jordan:

Its two main purposes are to solve system of linear equations and calculate the inverse of a matrix.

Similar to the Gauss elimination except

- 1. Elimination is applied to all equations (excluding the pivot equation) instead of just the subsequent equations.**
- 2. All rows are normalized by dividing them by their pivot elements.**
- 3. No back substitution is required.**

4. Gauss-Seidel

i Describe how Gauss Seidel method works:

```
function [numOfIterations,final,errorArray,answers] =  
GaussSeidel(numberOfFunctions,coeff_matrix,constants_matrix,initialGuess,maxIterations,epsil  
on)  
answers = double.empty  
previous = double.empty  
for i = 1 to numberOfFunctions  
    answers <-- [answers;initialGuess(i)]  
end  
iteration = 1 , error = 100  
errorArray = double.empty  
final = double.empty  
while (iteration less than or equal maxIterations & error greater than epsilon)  
    for i = 1 to length(answers)  
        j = 1  
        previous(i) <-- answers(i)  
        answers(i) <-- constants_matrix(i)  
        for k = 1 to length(answers) - 1  
            if (j equal i)  
                j <-- j + 1  
            end  
            answers(i) <-- answers(i) - coeff_matrix(i,j)*answers(j)  
            j = j + 1  
        end  
        answers(i) <-- answers(i) / coeff_matrix(i,i)  
        error <-- abs(((answers(i) - previous(i)) / answers(i)) * 100)  
        errorArray(i , iteration) <-- error  
        final(i,iteration) <-- answers(i)  
    end  
    iteration <-- iteration + 1  
end  
numOfIterations <-- iteration - 1
```

Analysis and conclusion for the behavior of Gauss Seidal:

It is an iterative method used to solve a linear system of equations of n linear equations with unknown x : $A x = B$

Though it can be applied to any matrix with non-zero elements on the diagonals, convergence is only guaranteed if the matrix is either **diagonally dominant**, or **symmetric and positive definite**.

PROBLAMATIC FUNCTIONS

In Gauss Seidel method :

One class of system of equations always converges: One with a diagonally dominant coefficient matrix, with non-zero elements on the diagonals.

If a system of linear equations is not diagonally dominant, check to see if rearranging the equations can form a diagonally dominant matrix.

Not every system of equations can be rearranged to have a diagonally dominant coefficient matrix.

SAMPLE RUNS AND SNAPSHOTS

The image displays two sequential screenshots of a software application titled "EnterEquations2".

Top Screenshot:

- The label "Number of Equation :" is in red. The input box contains the value "3".
- The label "Equation_1 :" is in red. The input box contains the equation $25*x1 + 5*x2 + x3 = 106.8$.
- An "Add" button is visible to the right of the equation input.
- A "NEXT" button is located at the bottom right.

Bottom Screenshot:

- The label "Number of Equation :" is in red. The input box contains the value "3".
- The label "Equation_2" is in red. The input box contains the equation $64*x1 + 8*x2 + x3 = 177.2$.
- An "Add" button is visible to the right of the equation input.
- A "NEXT" button is located at the bottom right.

EnterEquations2

Number of Equation :

Equation_3

Add

NEXT

Gaussian-elimination

Elimination

[X]

Execution Time

step number :

Next Step

[A] : [B]

25	5	1	106.8
64	8	1	177.2
144	12	1	279.2

Elimination

[X]

0.290476
19.6905
1.08571

Execution Time

2.5267

step number :

4

Next Step

[A] :

144	12	1
0	2.916667	0.8263889
0	2.666667	0.5555556

[B]

279.2
58.32778
53.11111

Elimination

[X]

0.290476
19.6905
1.08571

Execution Time

2.5267

step number :

5

Next Step

[A] :

144	12	1
0	2.916667	0.8263889
0	0	-0.2

[B]

279.2
58.32778
-0.2171429

LU Decomposition

LU_Decomposition

Execution Time : 1.2906

Step : 1 **is** Decompose A into L and U step:1 /3

Where $[A] = [L][U]$

NEXT

[A]

25	5	1
64	8	1
144	12	1

[L]

1	0	0
0	1	0
0	0	1

[U]

25	5	1
0	0	0
0	0	0

LU_Decomposition

Execution Time : 1.2906

Step : 1 **is** Decompose A into L and U step:2 /3

Where $[A] = [L][U]$

NEXT

[A]

144	12	1
64	8	1
25	5	1

[L]

1	0	0
0.444444	1	0
0	0	1

[U]

144	12	1
0	2.666667	0.555556
0	0	0

LU-Decomposition

Execution Time : 1.2906

Step : 1 **is** Decompose A into L and U step:3 /3

Where $[A] = [L][U]$

NEXT

[A]

144	12	1
64	8	1
25	5	1

[L]

1	0	0
0.44444	1	0
0.17361	1.0938	

[U]

144	12	1
0	2.666667	0.5555
0	0	0.21875

Gauss Jordan

EnterEquations2

Number of Equation : 3

Equation_1 : $x1 + x2 + 2 \cdot x3 = 8$

Add

NEXT

EnterEquations2

Number of Equation :

Equation_2

EnterEquations2

Number of Equation :

Equation_3

Elimination

[X]

8.4444
-2.8889
1.2222

Execution Time

1.1114

step number :

1

Next Step

[A] :

1	1	2
-1	-2	3
3	7	4

[B]

8
1
10

Elimination

[X]

8.4444
-2.8889
1.2222

Execution Time

1.1114

step number :

2

Next Step

[A] :

1	1	2
0	1	-5
0	4	-2

[B]

8
-9
-14

[X]

8.4444
-2.8889
1.2222

Execution Time

1.1114

step number :

3

Next Step

[A]

:

[B]

1 0 0
0 1 0
0 0 1

8.4444
-2.8889
1.2222

Gauss Seidel Method

Which converges :

EnterEquations2

Number of Equation :

Equation_1 :

Add

NEXT

EnterEquations2

Number of Equation :

Equation_2 :

Add

NEXT

EnterEquations2

Number of Equation :

3

Equation_3

$3*x1 + 7*x2 + 13*x3 = 76$

Add

NEXT

Data


Initial Points :

101

Max Iterations :

Epsilon :

NEXT

 Data

Initial Points :

101


Max Iterations :

50

Epsilon :

.0001

NEXT

 Seidel

Number Of Iterations :

10

Execution Time :

1.2109

Iteration number :

1

NEXT

[X]

0.5

4.9

3.09231

matrix of error

100

100

67.6617

Number Of Iterations :

10

Execution Time :

1.2109

Iteration number :

2

NEXT**[X]**

0.146795
3.71526
3.81176

matrix of error

240.611
31.8886
18.8744

Number Of Iterations :

10

Execution Time :

1.2109

Iteration number :

3

NEXT**[X]**

0.742751
3.1644
3.97084

matrix of error

80.2363
17.4081
4.00642

Number Of Iterations :

10

Execution Time :

1.2109

Iteration number :

4

NEXT**[X]**

0.946753
3.02814
3.99713

matrix of error

21.5475
4.49957
0.657719

Number Of Iterations :

10

Execution Time :

1.2109

Iteration number :

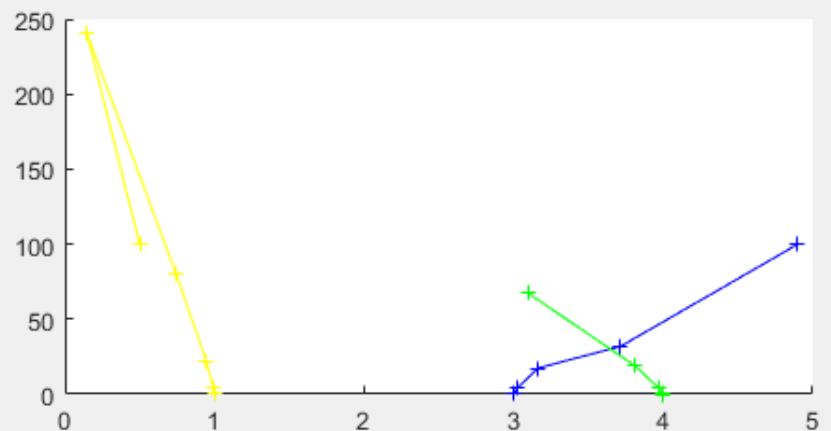
10

NEXT**[X]**

1
3
4

matrix of error

0.000854004
0.00018898
2.70494e-05



Gauss Seidel Method

Which diverges :

EnterEquations2

Number of Equation :

3

Equation_1 :

$3*x1 + 7*x2 + 13*x3 = 76$

Add

NEXT

EnterEquations2

Number of Equation :

3

Equation_2

$x1 + 5*x2 + 3*x3 = 28$

Add

NEXT

EnterEquations2

Number of Equation :

3

Equation_3

$12*x1 + 3*x2 + -5*x3 = 1$

Add

NEXT

Data

Initial Points :

1 0 1

Max Iterations :

50

Epsilon :

.0001

NEXT

Number Of Iterations :

50

Execution Time :

5.6354

Iteration number :

1

NEXT**[X]**

21
0.8
50.68

matrix of error

95.2381
100
98.0268

Number Of Iterations :

50

Execution Time :

5.6354

Iteration number :

2

NEXT**[X]**

-196.147
14.4213
-462.299

matrix of error

110.706
94.4527
110.963

Error of each Iteration :

[illegible]

TEAM

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ندی سلامہ محمد علی	۵۵
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