

Multi-Period Asset Pricing

Part 5

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State processes

State processes in binomial model

The “naive” implementation of the algorithm of the backward induction for AFP is **not practical**.

Example

If we want to price an option with maturity one year and take

one period = one working day,

then we obtain $N = 256$ period model. Already for the boundary conditions we need to write

$$2^N = 2^{256} = \text{practically } \infty$$

equalities.

Idea: adapt the algorithm of backward induction to the *type* of an option.

Standard options in binomial model

We consider a *standard* European option with payoff

$$V_N(\omega) = f_N(S_N(\omega)), \quad \omega \in \Omega,$$

for some (deterministic) function $f_N = f_N(x)$. From the “naive” backward induction we deduce that the AFPs have the form:

$$V_n = f_n(S_n), \quad n = 0, \dots, N,$$

where the functions $f_n = f_n(x)$ are defined recursively:

$$f_n(x) = \frac{1}{1+r} (\tilde{p}f_{n+1}(ux) + \tilde{q}f_{n+1}(dx)), \\ x \in \text{range}(S_n) = \{S_0d^n, S_0d^{n-1}u, \dots, S_0du^{n-1}, S_0u^n\}.$$

Note that at $t = n$ we have to perform $n + 1 \ll 2^n$ computations.

[Problem on “power” option]

[...] = skipped

Problem

Compute AFP V_0 for the “power” option with the payoff

$$V_N(\omega) = (S_N(\omega))^\alpha, \quad \omega \in \Omega,$$

for some exponent $\alpha \in \mathbb{R}$.

Solution

The AFP V_n at $t = n$ has the form: $V_n = f_n(S_n)$, where the functions (f_n) solve the FDE (finite-difference equation):

$$\begin{aligned} f_N(x) &= x^\alpha, \quad x \in \text{range}(S_N), \\ f_n(x) &= \frac{1}{1+r} (\tilde{p}f_{n+1}(ux) + \tilde{q}f_{n+1}(dx)), \\ &\quad x \in \text{range}(S_n), \quad n = 0, \dots, N-1. \end{aligned}$$

[Problem on “power” option]

We look for the solution in the form

$$f_n(x) = a_n x^\alpha,$$

for some constants (a_n) . After the substitution, we deduce that (a_n) solve another FDE:

$$\begin{aligned} a_N &= 1, \\ a_n &= \theta a_{n+1}, \quad n = 0, 1, \dots, N-1, \end{aligned}$$

where

$$\theta = \frac{1}{1+r} (\tilde{p}u^\alpha + \tilde{q}d^\alpha).$$

It follows that $a_n = \theta^{N-n}$ and

$$V_0 = f_0(S_0) = a_0(S_0)^\alpha = \theta^N (S_0)^\alpha.$$

□

[Standard options in binomial model]

We can also deduce an “explicit” formula for any standard option.

If

$$V_N(\omega) = f_N(S_N(\omega)), \quad \omega \in \Omega,$$

then by the “naive” explicit formula,

$$\begin{aligned} V_0 &= \frac{1}{(1+r)^N} \sum_{\omega \in \Omega} V_N(\omega) \tilde{p}^{\#H(\omega)} \tilde{q}^{\#T(\omega)} \\ &= \frac{1}{(1+r)^N} \sum_{n=0}^N f_N(S_0 u^n d^{N-n}) \tilde{p}^n \tilde{q}^{N-n} C_N^n, \end{aligned}$$

where the *binomial coefficient*

$$C_N^n = \frac{N!}{n!(N-n)!} = |\omega : \#H(\omega) = n, \#T(\omega) = N - n|$$

is the number of words with n letters H and $N - n$ letters T .

State processes in binomial model

The stock price $S = (S_n)_{0 \leq n \leq N}$ is an example of a *state process* in binomial model.

Definition

An adapted sequence $Y = (Y_n)_{0 \leq n \leq N}$ is called a **state process** if for any option with expiration time $m \leq N$ and the payoff

$$V_m = f_m(Y_m) \text{ for some function } f_m = f_m(x),$$

its AFP at any time $n \leq m$ has a similar form:

$$V_n = f_n(Y_n) \text{ for some function } f_n = f_n(x).$$

Pricing in practice

General method of AFP: given an option with the payoff

$$V_N = V_N(\omega_1, \dots, \omega_N)$$

find a *state process* Y such that

$$V_N = f_N(Y_N) \text{ for some } f_N = f_N(x).$$

Then (automatically!) for every $0 \leq n \leq N$ the AFP has the form:

$$V_n = f_n(Y_n) \text{ for some } f_n = f_n(x).$$

State processes in binomial model

We observe that

$$\boxed{\# \text{ of computations at } n} = \boxed{\# \text{ of values of } Y_n}$$

“Art” of financial computations: choose state process to minimize the amount of storage.

Remark

State process $(Y_n)_{0 \leq n \leq N}$ can be multi-dimensional:

$$Y_n = (Y_n^1, \dots, Y_n^d).$$

We should look for a state process with the *minimal* dimension.

“Backward” condition

Lemma

The following conditions are equivalent:

1. Y is a state process.
2. For every $t = n$ and every function $f_{n+1} = f_{n+1}(y)$, $y \in \text{range}(Y_{n+1})$, there is a function $f_n = f_n(y)$, $y \in \text{range}(Y_n)$, such that

$$f_n(Y_n(\omega_1, \dots, \omega_n)) = \frac{1}{1+r} (\tilde{p}f_{n+1}(Y_{n+1}(\omega_1, \dots, \omega_n, H)) + \tilde{q}f_{n+1}(Y_{n+1}(\omega_1, \dots, \omega_n, T))),$$

for every outcome $(\omega_1, \dots, \omega_n)$.

Proof.

Follows from the “naive” algorithm of backward induction.

“Forward” condition

The following (“forward”) description is more intuitive.

Lemma (Regression)

Suppose that for every $n = 0, \dots, N - 1$ the value of Y_{n+1} is determined by Y_n and $\omega_{n+1} \in \{H, T\}$, that is,

$$Y_{n+1} = g_{n+1}(Y_n, \omega_{n+1}),$$

for some function

$$g_{n+1} = g_{n+1}(y, \omega_1), \quad y \in \text{range}(Y_n), \omega_1 \in \{T, H\}.$$

Then (Y_n) is a state process.

[Criteria for state processes]

Proof.

Indeed, if $f_{n+1} = f_{n+1}(y)$, $y \in \text{range}(Y_{n+1})$, then

$$f_n(Y_n(\omega_1, \dots, \omega_n)) = \frac{1}{1+r} (\tilde{p}f_{n+1}(Y_{n+1}(\omega_1, \dots, \omega_n, H)) \\ + \tilde{q}f_{n+1}(Y_{n+1}(\omega_1, \dots, \omega_n, T))),$$

for the function $f_n = f_n(y)$, $y \in \text{range}(Y_n)$, given by

$$f_n(y) = \frac{1}{1+r} (\tilde{p}f_{n+1}(g_{n+1}(y, H)) + \tilde{q}f_{n+1}(g_{n+1}(y, T))).$$

Hence, Y is a state process. \square

Problem on up-and-in call

Problem

In N -period binomial model, where $ud = 1$, compute the AFP V_0 of the up-and-in call option with strike K and upper barrier U :

$$V_N = \max(S_N - K, 0)1_{\{M_N \geq U\}},$$

where (M_n) is the historical maximum:

$$M_n = \max_{0 \leq k \leq n} S_k.$$

We present two choices of state processes.

Solution (1)

We observe that $(Y_n = (S_n, M_n))$ is a state process.

Problem on up-and-in call

Indeed, Y_{n+1} is determined by Y_n and ω_{n+1} :

$$\begin{aligned}Y_{n+1}(\omega_{n+1} = H) &= (uS_n, \max(us_n, M_n)), \\Y_{n+1}(\omega_{n+1} = T) &= (dS_n, M_n),\end{aligned}$$

Thus, the AFPs (V_n) have the form: $V_n = f_n(S_n, M_n)$, where the functions (f_n) solve the FDE:

$$\begin{aligned}f_N(s, m) &= \max(s - K, 0)1_{\{m \geq U\}}, \quad (s, m) \in \text{range}(S_N, M_N), \\f_n(s, m) &= \frac{1}{1+r} (\tilde{p}f_{n+1}(us, \max(us, m)) + \tilde{q}f_{n+1}(ds, m)), \\&\quad (s, m) \in \text{range}(S_n, M_n), \quad n = 0, 1, \dots, N-1.\end{aligned}$$

Problem on up-and-in call

At $t = n$ we need to perform as many computations as the size of $\text{range}(S_n, M_n)$, which is $\approx n^2/2$ as $ud = 1$. \square

Solution (2)

Observe that $Y_n = (S_n, Z_n)$, $n = 0, 1, \dots, N$, is a state process, where

$$Z_n = 1_{\{M_n \geq U\}}$$

is the indicator of the barrier event. Indeed,

$$Y_{n+1}(\omega_{n+1} = H) = (uS_n, Z_n + (1 - Z_n)1_{\{uS_n \geq U\}}),$$

$$Y_{n+1}(\omega_{n+1} = T) = (dS_n, Z_n),$$

and therefore, Y_{n+1} is determined by Y_n and ω_{n+1} .

Problem on up-and-in call

The AFPs (V_n) admit the representation:

$$V_n = f_n(Y_n) = f_n(S_n, Z_n),$$

where the functions (f_n) solve the FDE:

$$f_N(s, z) = \max(s - K, 0)z, \quad s \in \text{range}(S_N), \quad z \in \{0, 1\},$$

$$f_n(s, 0) = \frac{1}{1+r} (\tilde{p}f_{n+1}(us, 1_{\{us \geq U\}}) + \tilde{q}f_{n+1}(ds, 0)),$$

$$f_n(s, 1) = \frac{1}{1+r} (\tilde{p}f_{n+1}(us, 1) + \tilde{q}f_{n+1}(ds, 1)),$$

$$s \in \text{range}(S_n), \quad n = 0, 1, \dots, N-1.$$

At $t = n$ we need to perform $2(n+1)$ computations. □

[Problem on Asian option]

Problem

In N -period binomial model, compute the AFP V_0 of Asian option with payoff

$$V_N = \max(A_N - S_N, 0),$$

where A_n is the historical average:

$$A_n = \frac{1}{n+1} \sum_{k=0}^n S_k.$$

We present two choices of state processes.

Solution (1)

Observe that $Y_n = (S_n, A_n)$, $n = 0, 1, \dots, N$, is a state process.

[Problem on Asian option]

Indeed, Y_{n+1} is determined by Y_n and ω_{n+1} :

$$Y_{n+1}(\omega_{n+1} = H) = \left(uS_n, \frac{1}{n+2} ((n+1)A_n + uS_n) \right),$$
$$Y_{n+1}(\omega_{n+1} = T) = \left(dS_n, \frac{1}{n+2} ((n+1)A_n + dS_n) \right).$$

The AFPs (V_n) admit the representation:

$$V_n = f_n(Y_n) = f_n(S_n, A_n),$$

[Problem on Asian option]

where the functions (f_n) solve the FDE:

$$\begin{aligned} f_N(s, a) &= \max(a - s, 0), \quad (s, a) \in \text{range}(S_N, A_N), \\ f_n(s, a) &= \frac{1}{1+r} \left[\tilde{p} f_{n+1} \left(us, \frac{1}{n+2} ((n+1)a + us) \right) \right. \\ &\quad \left. + \tilde{q} f_{n+1} \left(ds, \frac{1}{n+2} ((n+1)a + ds) \right) \right], \\ &\quad (s, a) \in \text{range}(S_n, A_n), \quad n = 0, 1, \dots, N-1. \end{aligned}$$

It is not easy to estimate the size of $\text{range}(S_n, A_n)$. In continuous time, we get a 2-dimensional PDE. □

[Problem on Asian option]

Solution (2)

Observe that $Z_n = A_n/S_n$, $n = 0, 1, \dots, N$, is the state process. Indeed,

$$\begin{aligned} Z_{n+1}(\omega_{n+1} = H) &= \frac{1}{uS_n} \left(\frac{1}{n+2} ((n+1)A_n + uS_n) \right) \\ &= \frac{1}{u(n+2)} ((n+1)Z_n + u), \\ Z_{n+1}(\omega_{n+1} = T) &= \frac{1}{dS_n} \left(\frac{1}{n+2} ((n+1)A_n + dS_n) \right) \\ &= \frac{1}{d(n+2)} ((n+1)Z_n + d), \end{aligned}$$

and therefore, Z_{n+1} is determined by Z_n and ω_{n+1} .

[Problem on Asian option]

Since (S_n) is a state process, we deduce that $Y_n = (S_n, Z_n)$ is a state process as well. It follows that the AFPs (V_n) have the form:

$$V_n = f_n(S_n, Z_n), \quad n = 0, 1, \dots, N,$$

where the functions (f_n) solve the FDE:

$$\begin{aligned} f_N(s, z) &= \max(sz - s, 0) = s \max(z - 1, 0), \\ &\quad (s, z) \in \text{range}(S_N, Z_N), \\ f_n(s, z) &= \frac{1}{1+r} \left[\tilde{p} f_{n+1} \left(us, \frac{1}{u(n+2)}((n+1)z + u) \right) \right. \\ &\quad \left. + \tilde{q} f_{n+1} \left(ds, \frac{1}{d(n+2)}((n+1)z + d) \right) \right], \\ &\quad (s, z) \in \text{range}(S_n, Z_n), \quad n = 0, 1, \dots, N-1. \end{aligned}$$

[Problem on Asian option]

We look for the solution in the form

$$f_n(s, z) = sg_n(z).$$

After the substitution, we deduce that the functions (g_n) solve the FDE:

$$\begin{aligned} g_N(z) &= \max(z - 1, 0), \quad z \in \text{range}(Z_N), \\ g_n(z) &= \frac{1}{1+r} \left[\tilde{p} u g_{n+1} \left(\frac{1}{u(n+2)} ((n+1)z + u) \right) \right. \\ &\quad \left. + \tilde{q} d g_{n+1} \left(\frac{1}{d(n+2)} ((n+1)z + d) \right) \right], \\ &\quad z \in \text{range}(Z_N), \quad n = 0, 1, \dots, N-1. \end{aligned}$$

In continuous time, we get a one-dimensional PDE.



Summary on state processes

Motivation: “naive” algorithm of backward induction is not practical:

$$\boxed{\# \text{ of computations at } n} = \boxed{\# \text{ of trajectories at } n (= 2^n)}$$

Idea: *adapt* the algorithm of backward induction to the *type* of non-traded option.

Method: represent the payoff as a function of a state process Y : $V_N = f_N(Y_N)$. Then (automatically!) $V_n = f_n(Y_n)$ and

$$\boxed{\# \text{ of computations at } n} = \boxed{\# \text{ of values of } Y_n}$$

Goal: *choose* the state process with the *smallest* range (minimal dimension).

Options with random maturity

American options

Options with random maturity

Until now we studied options with *deterministic* maturity. In practice, there are also options whose maturity is *random*.

Example (**Rebate option**)

Rebate option pays \$1 as soon as stock price reaches or falls below barrier L ; otherwise, it expires worthless. The maturity is given by

$$\tau = \min\{1 \leq n \leq N : S_n \leq L\}$$

and is *random*.

Such random maturity is formally defined as a *finite stopping time*.

Finite stopping time

Definition

A random variable $\tau = \tau(\omega)$ is called a **finite stopping time** in the N -period binomial model if

- (a) $\tau \in \{0, 1, \dots, N\}$,
- (b) for every $t = n$ the event $\{\tau \leq n\}$ is determined by the trajectory $(\omega_1, \dots, \omega_n)$ (the event is “known” at $t = n$).

Remark

A random variable τ is a finite stopping time if and only if

- (a') $\sum_{n=0}^N I(\tau = n) = 1$.
- (b') The sequence $(1_{\{\tau=n\}})_{0 \leq n \leq N}$ is *adapted*.

Exit through lower barrier

Example

Let $L > 0$ be a lower barrier for (S_n) and set

$$\tau(\omega) = N \quad \text{if} \quad \min_{0 \leq n \leq N} S_n(\omega) > L$$

and

$$\tau(\omega) = \min\{0 \leq n \leq N : S_n(\omega) \leq L\}, \quad \text{otherwise.}$$

Then τ is a finite stopping time. Indeed, clearly, $\tau \in \{0, 1, \dots, N\}$ and the event

$$\{\omega : \tau(\omega) \leq n\} = \{\omega : \min_{0 \leq k \leq n} S_k \leq L\}$$

depends only on $(\omega_1, \dots, \omega_n)$. □

AFP of options with random maturity

We consider an option paying the amount

$$G_{\tau}(\omega) = G_{\tau}(\omega_1, \dots, \omega_{\tau}) = \sum_{n=0}^N G_n(\omega_1, \dots, \omega_n) 1_{\{\tau=n\}}$$

at a finite stopping time τ , where (G_n) is an adapted sequence.

Replicating strategy:

$$\underbrace{X_0}_{?} \xrightarrow{(\Delta_n)-?} \underbrace{X_{\tau} = G_{\tau}}_{\text{known}}$$

Key idea: move *backward* and think “*conditionally*”!

Naive backward induction

We denote by $X_n = X_n(\omega_1, \dots, \omega_n)$ the capital of replicating strategy at $t = n$ if $\tau \geq n$.

Backward induction:

Time N : on $\{\tau = N\}$ we have that $X_N = G_N$.

\vdots

Time n : on $\{\tau \geq n\}$ we have that

1. if $\tau = n$, then $X_n = G_n$,
2. if $\tau > n$, then

$$X_n = \frac{1}{1+r} (\tilde{p}X_{n+1}(\omega_{n+1} = H) + \tilde{q}X_{n+1}(\omega_{n+1} = T)).$$

Down-and-rebate option

Of course, to get a practical algorithm, we need to use state processes.

Problem (Down-and-rebate)

The option pays $G_\tau = 1$ at the first time τ when $S_\tau \leq L$. Here $L > 0$ is the lower barrier. If $S_n > L$ for all times n , then the option expires worthless. Compute the AFP V_0 .

Solution

We denote by V_n the AFP at $t = n$ if $\tau \geq n$. We look for V_n in the form

$$V_n = f_n(S_n) \quad \text{on} \quad \{\tau \geq n\}$$

for some function $f_n = f_n(x)$.

Down-and rebate option

In other words,

$f_n(x)$: the AFP at $t = n$ if $S_n = x$ and $\tau \geq n$.

We deduce that the functions (f_n) solve the FDE:

$$\begin{aligned}f_N(x) &= 1_{\{x \leq L\}}, \quad x \in \text{range}(S_N), \\f_n(x) &= 1_{\{x \leq L\}} + 1_{\{x > L\}} \frac{1}{1+r} (\tilde{p}f_{n+1}(ux) + \tilde{q}f_{n+1}(dx)), \\x &\in \text{range}(S_n), \quad n = 0, 1, \dots, N-1.\end{aligned}$$

At every time n we have to perform just $n + 1$ computations. □

General case with state processes

In general case, when the option pays $G_\tau = G_\tau(\omega_1, \dots, \omega_\tau)$ at a finite stopping time τ , we look for a state process (Y_n) such that

(a) If $\{\tau \geq n\}$, then

$$\{\tau = n\} = \{Y_n \in A_n\},$$

for some $A_n \subset \mathbb{R}$; with $A_N = \mathbb{R}$ to make τ finite. Equivalently,

$$\tau = \min\{0 \leq n \leq N : Y_n \in A_n\}.$$

(b) On the set $\{\tau = n\}$, option's payoff has the form:

$$G_n = g_n(Y_n),$$

for some function $g_n = g_n(y)$.

General case with state processes

Under (a) + (b), the AFP at $t = n$ can be written as

$$V_n = f_n(Y_n) \quad \text{if } \tau \geq n.$$

Here, $f_n(y)$ is the AFP at $t = n$ if $Y_n = y$ and $\tau \geq n$.

If Y has the evolution:

$$Y_{n+1} = h_{n+1}(Y_n, \omega_{n+1}),$$

for some functions (h_n) , then the functions (f_n) solve the FDE:

$$f_N(y) = g_N(y), \quad y \in \text{range}(Y_N),$$

$$f_n(y) = 1_{\{y \in A_n\}} g_n(y) + \\ 1_{\{y \notin A_n\}} \frac{1}{1+r} (\tilde{p} f_{n+1}(h_{n+1}(y, H)) + \tilde{q} f_{n+1}(h_{n+1}(y, T))), \\ y \in \text{range}(Y_n), \quad n = 0, 1, \dots, N-1.$$

American options in binomial model

Example (American put)

An owner of American put with strike K can exercise it at *any time* until maturity. If the option is exercised at $t = n$, then the owner receives the amount:

$$G_n = \max(K - S_n, 0).$$



A general American option is described by its *intrinsic value* adapted sequence

$$G_n = G_n(\omega_1, \dots, \omega_n), \quad n = 0, \dots, N.$$

Option's holder chooses a finite stopping time τ and gets the payment $G_\tau = G_\tau(\omega_1, \dots, \omega_\tau)$.

American options in binomial model

Questions

1. What is an optimal exercise policy $\hat{\tau}$?
2. What is the arbitrage-free price V_0 ?

Key idea: move *backward* and think “*conditionally*”!

$V_n = V_n(\omega_1, \dots, \omega_n)$: the AFP at $t = n$ if $\hat{\tau} \geq n$.

Boundary condition:

$$V_N = G_N \text{ on } \{\hat{\tau} = N\}.$$

One-step iteration:

$$\underbrace{V_n \text{ on } \{\hat{\tau} \geq n\}}_{?} \longleftarrow \underbrace{V_{n+1} \text{ on } \{\hat{\tau} \geq n+1\}}_{\text{known}}$$

American options in binomial model

Denote by V_n^{stop} and V_n^{cont} the values to *stop* and *continue*. We obtain that

$$V_n^{\text{stop}} = G_n,$$
$$V_n^{\text{cont}} = \frac{1}{1+r}(\tilde{p}V_{n+1}(\omega_{n+1} = H) + \tilde{q}V_{n+1}(\omega_{n+1} = T)).$$

Since the owner wants to maximize the value of his position, we have that

$$V_n = \max(V_n^{\text{stop}}, V_n^{\text{cont}}).$$

The first optimal exercise time:

$$\begin{aligned}\hat{\tau} &= \min\{0 \leq n \leq N : V_n^{\text{stop}} \geq V_n^{\text{cont}}\} \\ &= \min\{0 \leq n \leq N : V_n = G_n\}.\end{aligned}$$

[American options in binomial model]

Remark

The value V_0 we get from the backward induction, is indeed the unique AFP. For example, if $p < V_0$, then we make the profit

$$V_0 - p > 0 \text{ at } t = 0,$$

by using the following strategy:

- (a) buy the option at price p and exercise it at time $\hat{\tau}$;
 - (b) sell short a replicating strategy (X_n) for the payoff $G_{\hat{\tau}}$ at $\hat{\tau}$.
- Notice, that

$$X_n = V_n = V_n^{\text{cont}} \quad \text{if } \hat{\tau} > n$$

and in particular, $X_0 = V_0$.

[American options in binomial model]

If, on the other hand, $p > V_0$, then we make the profit

$$p - V_0 > 0 \text{ at } t = 0,$$

and also possible profits

$$V_n - V_n^{\text{cont}} \geq 0 \text{ at } n < \tau,$$

$$V_\tau - G_\tau \geq 0 \text{ at } n = \tau,$$

if we sell the option at $t = 0$, collect the above profits, and invest until the exercise time τ as

$$V_n^{\text{cont}} \xrightarrow{\Delta_n} V_{n+1}.$$

Notice that V_n^{cont} is exactly the wealth at $t = n$ of a replicating strategy for V_{n+1} . □

American options and state processes

Again, to get a practical algorithm we have to use state processes. Suppose that the intrinsic value has the form:

$$G_n = g_n(Y_n), \quad n = 0, 1, \dots, N,$$

for some functions (g_n) and a state process (Y_n) . Assume that Y has the evolution:

$$Y_{n+1} = h_{n+1}(Y_n, \omega_{n+1}),$$

for some functions $(h_n = h_n(y, \omega_1))$, where $\omega_1 \in \{H, T\}$.

American options and state processes

In this case, the “conditional” AFPs admit the representation:

$$V_n = f_n(Y_n) \text{ on } \{\hat{\tau} \geq n\},$$

where the functions (f_n) have the following meaning:

$f_n(y)$: the AFP at $t = n$ if $Y_n = y$ and $\hat{\tau} \geq n$.

The functions (f_n) solve the FDE:

$$\begin{aligned} f_N(y) &= g_N(y), \quad y \in \text{range}(Y_N), \\ f_n(y) &= \max(g_n(y), f_n^{\text{cont}}(y)), \\ f_n^{\text{cont}}(y) &= \frac{1}{1+r} (\tilde{p}f_{n+1}(h_{n+1}(y, H)) + \tilde{q}f_{n+1}(h_{n+1}(y, T))), \\ &\quad y \in \text{range}(Y_n), \quad n = 0, 1, \dots, N-1. \end{aligned}$$