Applications of Stochastic Calculus in Finance Chapter 9: Intensity-based approach

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1 A simple reduced-form model with constant intensity

Intensity-based (or reduced-form) approach is silent about why a firm defaults, and instead default is exogenously given through a default rate, i.e. the default intensity of a single jump process.

A simple example would be assuming that the default time τ as an exponential random variable independent of the Brownian filtration $\{\mathscr{F}_t\}_{t\geq 0}$, and having constant intensity λ . Then

$$\mathbf{Q}(\tau > t | \mathscr{F}_t) = \mathbf{Q}(\tau > t) = e^{-\lambda t}.$$

Remark 1. (Calibration of default intensity λ). In an ideal situation where the CDS premium is payed continuously until the default time τ , the discounted payoff of the CDS buyer at time 0 is

$$\Pi_b(0) = \mathbf{1}_{\{\tau \leq T_n\}} P(0,\tau) LGD - \int_0^{\tau \wedge T_n} P(0,s) \kappa ds$$

Given the constant default intensity λ , the CDS spread at time t = 0 is the fixed rate κ such that $\mathbf{E}^{\mathbf{Q}}[\Pi_b(0)] = 0$, which is

$$R_{CDS}(0) = \frac{\mathbf{E}^{\mathbf{Q}}[\mathbf{1}_{\{\tau \leq T_n\}}P(0,\tau)]LGD}{\mathbf{E}^{\mathbf{Q}}[\int_0^{\tau \wedge T_n}P(0,s)ds]}.$$

Note that τ has the intensity $\lambda e^{-\lambda s}$ for $s \ge 0$. Hence,

$$\mathbf{E}^{\mathbf{Q}}[\mathbf{1}_{\{\tau \leq T_n\}}P(0,\tau)] = \int_0^{T_n} \lambda e^{-\lambda s} P(0,s) ds$$

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and

$$\mathbf{E}^{\mathbf{Q}}\left[\int_{0}^{\tau \wedge T_{n}} P(0, s) ds\right] = \int_{0}^{\infty} \lambda e^{-\lambda s} \int_{0}^{s \wedge T_{n}} P(0, u) du ds$$

$$= -\int_{0}^{\infty} \left(\int_{0}^{s \wedge T_{n}} P(0, u) du\right) de^{-\lambda s}$$

$$= \int_{0}^{T_{n}} e^{-\lambda s} P(0, s) ds,$$

which yields that

$$R_{CDS}(0) = \lambda LGD$$
.

In practice, this is often used to calibrate the default intensity and therefore the default probability in terms of CDS spread.

However, the constant intensity λ is insufficient for most credit risk problems. It would be desirable that the default intensity λ is stochastic. Two types of stochastic intensities will be considered in this Chapter. The first one models the *systematic factor (common noise)* while the second one models the *systemic factor (correlated noise)*.

Moreover, we also need to calculate conditional default probability and conditional price at any time t, which is a delicate issue in the reduced-form framework. Note that in the structural models, conditional values can be simply obtained from the corresponding initial values by replacing V_0 with V_t .

2 \mathscr{F}_t -doubly stochastic stopping times

Fix a filtered probability space $(\Omega, \mathcal{G}, \{\mathcal{G}_t\}_{t\geq 0}, \mathbf{P})$, where the filtration $\{\mathcal{G}_t\}_{t\geq 0}$ represents the flow of the complete market information. Let τ be a default time which is a \mathcal{G}_t -stopping time. Throughout, we will assume that there exists a sub-filtration $\{\mathcal{F}_t\}_{t\geq 0}$, usually a Brownian filtration, such that $\mathcal{F}_t \subset \mathcal{G}_t$ and $\mathcal{G}_t = \mathcal{F}_t \vee \mathcal{H}_t$, where $\mathcal{H}_t = \sigma(\{\tau \leq u\} : u \leq t)$. When $\mathcal{F}_t = \{\emptyset, \Omega\}$, then $\mathcal{G}_t = \mathcal{H}_t$.

The following lemma shows that events in \mathcal{G}_t is actually \mathcal{F}_t -observable conditional on $\{\tau > t\}$.

Lemma 1. For every $A \in \mathcal{G}_t$, there exists $B \in \mathcal{F}_t$ such that

$$A \cap \{\tau > t\} = B \cap \{\tau > t\}. \tag{1}$$

Proof. Define σ -algebra:

$$\mathscr{G}_t^* = \{A \in \mathscr{G}_t : \text{ there exists } B \in \mathscr{F}_t \text{ such that } (1) \text{ holds} \}$$

It is obvious that $\mathscr{G}_t^* \subset \mathscr{G}_t$. We prove the other inclusion by showing \mathscr{F}_t , $\mathscr{H}_t \subset \mathscr{G}_t^*$. Firstly $\mathscr{F}_t \subset \mathscr{G}_t^*$ by simply taking B = A for any $A \in \mathscr{F}_t$. To show that $\mathscr{H}_t \subset \mathscr{G}_t^*$, note that any $A \in \mathscr{H}_t$, $A \cap \{\tau > t\}$ is either \emptyset or $\{\tau > t\}$, so we can take for B either \emptyset or Ω . \square

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Assumption 1 There exists a nonnegative \mathcal{F}_t -progressively measurable process λ such that

$$\mathbf{P}(\tau > t | \mathscr{F}_t) = e^{-\int_0^t \lambda_s ds}.$$

From the above assumption, a market participant with access to the partial market information \mathcal{F}_t cannot observe whether default has occurred by time t. In other words, τ is NOT an \mathcal{F}_t -stopping time.

The following lemma generalizes Lemma 1 to random variables in the sense that for any r.v. $Y \in \mathcal{G}_t$, there exists $\tilde{Y}_t \in \mathcal{F}_t$ such that $\tilde{Y}_t = Y_t$ conditional on $\{\tau > t\}$. It is called filtration switching formula. When $\mathcal{F}_t = \{\emptyset, \Omega\}$, it is formula (10) in Chapter 8.

Lemma 2. (Filtration switching formula) Suppose that Assumption 1 holds. For any $r.v. Y \in \mathscr{G}_{\infty}$,

$$\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{G}_t] = \mathbf{1}_{\{\tau>t\}} \frac{\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{F}_t]}{\mathbf{P}(\tau>t|\mathscr{F}_t)} = \mathbf{1}_{\{\tau>t\}} e^{\int_0^t \lambda_s ds} \mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{F}_t].$$
(2)

Proof. We need to show that

$$\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y\mathbf{P}(\tau>t|\mathscr{F}_t)|\mathscr{G}_t] = \mathbf{1}_{\{\tau>t\}}\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{F}_t].$$

That is, RHS of the above equality is the conditional expectation of $\mathbf{1}_{\{\tau>t\}}Y\mathbf{P}(\tau>t|\mathscr{F}_t)$ on \mathscr{G}_t : For any $A \in \mathscr{G}_t$,

$$\mathbf{E}[\mathbf{1}_{A}\mathbf{1}_{\{\tau>t\}}Y\mathbf{P}(\tau>t|\mathscr{F}_{t})] = \mathbf{E}[\mathbf{1}_{A}\mathbf{1}_{\{\tau>t\}}\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{F}_{t}]].$$

From Lemma 1, there exists $B \in \mathscr{F}_t$ such that $\mathbf{1}_A \mathbf{1}_{\{\tau > t\}} = \mathbf{1}_B \mathbf{1}_{\{\tau > t\}}$. Therefore, it is equivalent to show that

$$\mathbf{E}[\mathbf{1}_{B}\mathbf{1}_{\{\tau>t\}}Y\mathbf{P}(\tau>t|\mathscr{F}_{t})] = \mathbf{E}[\mathbf{1}_{B}\mathbf{1}_{\{\tau>t\}}\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{F}_{t}]].$$

But this follows by taking the conditional expectations of both sides on \mathcal{F}_t :

$$RHS = \mathbf{E}[\mathbf{E}[\mathbf{1}_{B}\mathbf{1}_{\{\tau>t\}}\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{F}_{t}]|\mathscr{F}_{t}]]$$
$$= \mathbf{E}[\mathbf{1}_{B}\mathbf{E}[\mathbf{1}_{\{\tau>t\}}|\mathscr{F}_{t}]\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{F}_{t}]],$$

and

$$LHS = \mathbf{E}[\mathbf{E}[\mathbf{1}_{B}\mathbf{1}_{\{\tau>t\}}Y\mathbf{E}[\mathbf{1}_{\{\tau>t\}}|\mathscr{F}_{t}]|\mathscr{F}_{t}]]$$
$$= \mathbf{E}[\mathbf{1}_{B}\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{F}_{t}]\mathbf{E}[\mathbf{1}_{\{\tau>t\}}|\mathscr{F}_{t}]]. \quad \Box$$

We have now the following expressions for conditional default probabilities.

Proposition 1. Suppose that Assumption 1 holds. Then

$$\mathbf{P}(\tau > T | \mathscr{G}_t) = \mathbf{1}_{\{\tau > t\}} \mathbf{E}[e^{-\int_t^T \lambda_s ds} | \mathscr{F}_t]$$
(3)

$$\mathbf{P}(t < \tau \le T | \mathcal{G}_t) = \mathbf{1}_{\{\tau > t\}} \mathbf{E}[1 - e^{-\int_t^T \lambda_s ds} | \mathcal{F}_t]$$
(4)

$$\mathbf{P}(t < \tau \le t + \Delta | \mathcal{G}_t) = \mathbf{1}_{\{\tau > t\}} \lambda_t \Delta \quad \text{for } \Delta = o(1).$$
 (5)

Proof. We only establish the first one. The other two then follow from (3). Note that $\mathbf{1}_{\{\tau>T\}} = \mathbf{1}_{\{\tau>T\}} \mathbf{1}_{\{\tau>T\}}$. Then from Lemma 2,

$$\begin{split} \mathbf{P}(\tau > T | \mathcal{G}_t) &= \mathbf{E}[\mathbf{1}_{\{\tau > t\}} \mathbf{1}_{\{\tau > T\}} | \mathcal{G}_t] \\ &= \mathbf{1}_{\{\tau > t\}} e^{\int_0^t \lambda_s ds} \mathbf{E}[\mathbf{1}_{\{\tau > T\}} | \mathcal{F}_t] \\ &= \mathbf{1}_{\{\tau > t\}} e^{\int_0^t \lambda_s ds} \mathbf{E}[\mathbf{E}[\mathbf{1}_{\{\tau > T\}} | \mathcal{F}_T] | \mathcal{F}_t] \\ &= \mathbf{1}_{\{\tau > t\}} e^{\int_0^t \lambda_s ds} \mathbf{E}[e^{-\int_0^T \lambda_s ds} | \mathcal{F}_t]. \quad \Box \end{split}$$

Remark 2. Note that in the simple example where τ is an exponential r.v. independent of \mathscr{F}_t , then (3) and (4) reduce to formulaes (11) and (12) in Chapter 8, respectively.

Based on Proposition 1, we have the following <u>Doob-Meyer decomposition</u> for the single jump process $\mathbf{1}_{\{\tau < t\}}$ for $t \ge 0$.

Proposition 2. Suppose that Assumption 1 holds. Then the process

$$N_t = \mathbf{1}_{\{\tau \le t\}} - \int_0^t \lambda_s \mathbf{1}_{\{\tau > s\}} ds \text{ for } t \ge 0$$

is a \mathcal{G}_t -martingale.

Proof. From Proposition 1 and Lemma 2, we obtain that

$$\begin{aligned} \mathbf{E}[N_T|\mathscr{G}_t] &= 1 - \mathbf{E}[\mathbf{1}_{\{\tau > T\}}|\mathscr{G}_t] - \int_0^t \lambda_s \mathbf{1}_{\{\tau > s\}} ds - \int_t^T \mathbf{E}[\lambda_s \mathbf{1}_{\{\tau > s\}}|\mathscr{G}_t] ds \\ &= 1 - \mathbf{1}_{\{\tau > t\}} \mathbf{E}[e^{-\int_t^T \lambda_s ds}|\mathscr{F}_t] - \int_0^t \lambda_s \mathbf{1}_{\{\tau > s\}} ds \\ &- \int_t^T \mathbf{1}_{\{\tau > t\}} e^{\int_0^t \lambda_u du} \mathbf{E}[\lambda_s \mathbf{1}_{\{\tau > s\}}|\mathscr{F}_t] ds. \end{aligned}$$

But note that the last term can be further simplified as

$$\int_{t}^{T} \mathbf{1}_{\{\tau>t\}} e^{\int_{0}^{t} \lambda_{u} du} \mathbf{E}[\lambda_{s} \mathbf{1}_{\{\tau>s\}} | \mathscr{F}_{t}] ds = \int_{t}^{T} \mathbf{1}_{\{\tau>t\}} e^{\int_{0}^{t} \lambda_{u} du} \mathbf{E}[\lambda_{s} \mathbf{E}[\mathbf{1}_{\{\tau>s\}} | \mathscr{F}_{s}] | \mathscr{F}_{t}] ds$$

$$= \mathbf{1}_{\{\tau>t\}} \mathbf{E}[\int_{t}^{T} \lambda_{s} e^{-\int_{t}^{s} \lambda_{u} du} ds | \mathscr{F}_{t}]$$

$$= \mathbf{1}_{\{\tau>t\}} \mathbf{E}[1 - e^{-\int_{t}^{T} \lambda_{s} ds} | \mathscr{F}_{t}].$$

Hence, $\mathbf{E}[N_T|\mathcal{G}_t] = N_t$. \square

We further impose the following assumption, so called <u>Hypothesis H</u> in the literature. This assumption will be used for the construction of the default time τ later on.

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Assumption 2 (Hypothesis H) Every \mathcal{F}_t -martingale is also a \mathcal{G}_t -martingale, or equivalently¹,

$$\mathbf{P}(\tau > t | \mathscr{F}_{\infty}) = \mathbf{P}(\tau > t | \mathscr{F}_{t}) \text{ for } t \geq 0.$$

The equivalent conditions of Hypothesis H can be established as follows.

Suppose that every \mathscr{F}_t -martingale is a \mathscr{G}_t -martingale. Then, for $X \in \mathscr{F}_{\infty}$, $M_t := \mathbf{E}[X|\mathscr{F}_t]$ is an \mathscr{F}_t -martingale. It follows that

$$\mathbf{E}[X|\mathcal{G}_t] = \mathbf{E}[M_{\infty}|\mathcal{G}_t] = M_t = \mathbf{E}[X|\mathcal{F}_t]. \tag{6}$$

Since $\mathbf{1}_{\tau>t} \in \mathscr{G}_t$, by the definition of conditional expectation,

$$\mathbf{E}[\mathbf{1}_{\tau>t}X] = \mathbf{E}[\mathbf{1}_{\tau>t}\mathbf{E}[X|\mathscr{F}_t]].$$

However, conditioning on the RHS w.r.t \mathcal{F}_t yields

$$\mathbf{E}[\mathbf{1}_{\tau>t}\mathbf{E}[X|\mathscr{F}_t]] = \mathbf{E}[\mathbf{E}[\mathbf{1}_{\tau>t}|\mathscr{F}_t]\mathbf{E}[X|\mathscr{F}_t]]$$
$$= \mathbf{E}[\mathbf{E}[\mathbf{1}_{\tau>t}|\mathscr{F}_t|X].$$

By taking $X = \mathbf{1}_C$ for $C \in \mathscr{F}_{\infty}$, we have

$$\mathbf{E}[\mathbf{1}_{\tau>t}\mathbf{1}_C] = \mathbf{E}[\mathbf{E}[\mathbf{1}_{\tau>t}|\mathscr{F}_t]\mathbf{1}_C],$$

that is

$$\mathbf{P}(\tau > t | \mathscr{F}_{\infty}) = \mathbf{P}(\tau > t | \mathscr{F}_{t}).$$

On the other hand, suppose the above equality holds. We first prove (6). Note that for $A \in \mathcal{G}_t$, there exists $B \in \mathcal{F}_t$ such that $\mathbf{1}_A \mathbf{1}_{\tau > t} = \mathbf{1}_B \mathbf{1}_{\tau > t}$. Hence, it is sufficient to show that

$$\mathbf{E}[X\mathbf{1}_{B}\mathbf{1}_{\tau>t}] = \mathbf{E}[\mathbf{E}[X|\mathscr{F}_{t}]\mathbf{1}_{B}\mathbf{1}_{\tau>t}].$$

However, by conditioning w.r.t. \mathscr{F}_{∞} and \mathscr{F}_{t} respectively, the LHS is equal to

$$\mathbf{E}[X\mathbf{1}_{B}\mathbf{1}_{\tau>t}] = \mathbf{E}[X\mathbf{1}_{B}\mathbf{E}[\mathbf{1}_{\tau>t}|\mathscr{F}_{\infty}]],$$

and the RHS is equal to

$$\mathbf{E}[\mathbf{E}[X|\mathscr{F}_t|\mathbf{1}_B\mathbf{1}_{\tau>t}] = \mathbf{E}[X\mathbf{1}_B\mathbf{E}[\mathbf{1}_{\tau>t}|\mathscr{F}_t]],$$

which are equal by the assumption. Next, we prove that every \mathscr{F}_t -martingale is a \mathscr{G}_t -martingale from (6). Let M be an \mathscr{F}_t -martingale. Then, for any T > t, since $M_T \in \mathscr{F}_{\infty}$, $\mathbf{E}[M_T|\mathscr{G}_t] = \mathbf{E}[M_T|\mathscr{F}_t] = M_t$, which means M is also a \mathscr{G}_t -martingale.

Definition 1. A \mathcal{G}_t -stopping time τ that satisfies Assumptions 1 and 2 is called an \mathcal{F}_t -doubly stochastic stopping time.

¹ One can make a comparison with Markov property with \mathscr{F}_{∞} represents 'future', \mathscr{F}_t represents 'present', \mathscr{H}_t represents 'present' and $\mathscr{G}_t = \mathscr{F}_t \vee \mathscr{H}_t$ represents 'present and past'. Then, the Hypothesis H also implies the following (1) $\mathbf{E}[X|\mathscr{G}_t] = \mathbf{E}[X|\mathscr{F}_t]$; (2) $\mathbf{E}[XY|\mathscr{F}_t] = \mathbf{E}[X|\mathscr{F}_t]\mathbf{E}[Y|\mathscr{F}_t]$ for $X \in \mathscr{F}_{\infty}$ and $Y \in \mathscr{H}_t$.

Proposition 3. Suppose that Assumptions 1 and 2 hold. Then the process

$$N_t = \mathbf{1}_{\{\tau \leq t\}} - \int_0^t \lambda_s \mathbf{1}_{\{\tau > s\}} ds \text{ for } t \geq 0$$

is an $(\mathcal{F}_{\infty} \vee \mathcal{H}_t)$ -martingale.

Proof. First, analogous to the proof of Lemma 2, it can be proved that the following generalized filtration switching formula holds

$$\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{F}_{\infty}\vee\mathscr{H}_{t}]=\mathbf{1}_{\{\tau>t\}}\frac{\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{F}_{\infty}]}{\mathbf{P}(\tau>t|\mathscr{F}_{\infty})}=\mathbf{1}_{\{\tau>t\}}e^{\int_{0}^{t}\lambda_{s}ds}\mathbf{E}[\mathbf{1}_{\{\tau>t\}}Y|\mathscr{F}_{\infty}].$$

Then similar to the proof of Proposition 2, we obtain that

$$\begin{split} &\mathbf{E}[N_{T}|\mathscr{F}_{\infty}\vee\mathscr{H}_{t}]\\ =&1-\mathbf{E}[\mathbf{1}_{\{\tau>T\}}|\mathscr{F}_{\infty}\vee\mathscr{H}_{t}]-\int_{0}^{t}\lambda_{s}\mathbf{1}_{\{\tau>s\}}ds-\int_{t}^{T}\mathbf{E}[\lambda_{s}\mathbf{1}_{\{\tau>s\}}|\mathscr{F}_{\infty}\vee\mathscr{H}_{t}]ds\\ =&1-\mathbf{1}_{\{\tau>t\}}e^{-\int_{t}^{T}\lambda_{s}ds}-\int_{0}^{t}\lambda_{s}\mathbf{1}_{\{\tau>s\}}ds-\int_{t}^{T}\mathbf{1}_{\{\tau>t\}}e^{\int_{0}^{t}\lambda_{u}du}\mathbf{E}[\lambda_{s}\mathbf{1}_{\{\tau>s\}}|\mathscr{F}_{\infty}]ds\\ =&1-\mathbf{1}_{\{\tau>t\}}e^{-\int_{t}^{T}\lambda_{s}ds}-\int_{0}^{t}\lambda_{s}\mathbf{1}_{\{\tau>s\}}ds-\mathbf{1}_{\{\tau>t\}}\int_{t}^{T}e^{\int_{0}^{t}\lambda_{u}du}\lambda_{s}e^{-\int_{0}^{s}\lambda_{u}du}ds\\ =&1-\mathbf{1}_{\{\tau>t\}}e^{-\int_{t}^{T}\lambda_{s}ds}-\int_{0}^{t}\lambda_{s}\mathbf{1}_{\{\tau>s\}}ds-\mathbf{1}_{\{\tau>t\}}(1-e^{-\int_{t}^{T}\lambda_{s}ds})\\ =&\mathbf{1}_{\{\tau\leq t\}}-\int_{0}^{t}\lambda_{s}\mathbf{1}_{\{\tau>s\}}ds.\quad \Box \end{split}$$

3 Intensity-based Approach

Construction of intensity-based models: We want to construct a default time τ which satisfies Assumptions 1 and 2, so it is a \mathcal{F}_t -doubly stochastic stopping time.

- (1) Given a probability space $(\Omega, \mathcal{G}, \mathbf{Q})$, start with a filtration $\{\mathcal{F}_t\}_{t\geq 0}$ (usually Brownian filtration) satisfying the usual conditions, and $\mathcal{F}_{\infty} \subset \mathcal{G}$.
- (2) Let λ_t for $t \ge 0$ be a nonnegative \mathscr{F}_t -progressively measurable process such that $\int_0^t \lambda_s ds < \infty$, a.s. for $t \ge 0$.
 - (3) Fix an exponential r.v. E with intensity 1 and independent of \mathscr{F}_{∞} , and define

$$\tau=\inf\{t\geq 0: \int_0^t \lambda_s ds\geq E\}.$$

(4) Finally define $\mathcal{G}_t = \mathcal{F}_t \vee \mathcal{H}_t$ where $\mathcal{H}_t = \sigma(\{\tau \leq u\} : u \leq t)$.

Proposition 4. Under the above <u>canonical construction</u>, the random time τ is a \mathscr{F}_t -doubly stochastic stopping time.

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Proof.

$$\mathbf{Q}(\tau > t | \mathscr{F}_{\infty}) = \mathbf{Q}(E > \int_0^t \lambda_s ds | \mathscr{F}_{\infty}) = \mathbf{Q}(E > x)|_{x = \int_0^t \lambda_s ds} = e^{-\int_0^t \lambda_s ds}.$$

Conditioning both sides on \mathcal{F}_t then yields

$$\mathbf{Q}(\tau > t | \mathscr{F}_t) = e^{-\int_0^t \lambda_s ds}.$$

Hence, both Assumptions 1 and 2 hold. \Box

Assumption 3 Suppose that under the spot measure \mathbf{Q} , the short rate r is \mathcal{F}_t -progressively measurable, and there exists a nonnegative \mathcal{F}_t -progressively measurable intensity λ such that

$$\int_0^t (|r_s| + \lambda_s) ds, \ a.s. \ for \ t \ge 0.$$

and Assumptions 1 and 2 hold.

<u>Conditional default probability</u> can be easily computed under intensity-based models.

$$\mathbf{Q}(\tau \le T | \mathcal{G}_t) = 1 - \mathbf{Q}(\tau > T | \mathcal{G}_t)$$
$$= 1 - \mathbf{1}_{\{\tau > t\}} \mathbf{E}[e^{-\int_t^T \lambda_s ds} | \mathcal{F}_t].$$

Consider a corporate bond which is supposed to pay 1 at maturity T. When defaults occurs for such a corporate bond, the recovery could be delivered either at maturity T (correspond to Merton's model), or at the default time τ (correspond to first-passage-time model).

If the recovery is delivered at maturity T, the discounted payoff at time t is then $\frac{B_t}{B_T}(\mathbf{1}_{\{\tau>T\}}+\delta\mathbf{1}_{\{t<\tau\leq T\}})$ for some recovery rate $\delta\in[0,1]$

Proposition 5. *Under the intensity-based model, if the recovery is delivered at maturity T, the conditional value of the corporate bond at time t is*

$$P_t = \delta \mathbf{1}_{\{\tau > t\}} \mathbf{E}^{\mathbf{Q}} [e^{-\int_t^T r_s ds} | \mathscr{F}_t] + (1 - \delta) \mathbf{1}_{\{\tau > t\}} \mathbf{E}^{\mathbf{Q}} [e^{-\int_t^T (r_s + \lambda_s) ds} | \mathscr{F}_t].$$

where P(t,T) is the time t value of T-bond.

Proof. The arbitrage price the corporate bond at any time $t \leq T$ is

$$\begin{split} P_t &= \mathbf{E}^{\mathbf{Q}} [\frac{B_t}{B_T} (\mathbf{1}_{\{\tau > T\}} + \delta \mathbf{1}_{\{t < \tau \le T\}}) | \mathscr{G}_t] \\ &= \mathbf{E}^{\mathbf{Q}} [\frac{B_t}{B_T} (\delta \mathbf{1}_{\{\tau > t\}} + (1 - \delta) \mathbf{1}_{\{\tau > T\}}) | \mathscr{G}_t] \end{split}$$

For the first term, by the Hypothesis H, we have

$$\begin{split} \mathbf{E}^{\mathbf{Q}} [\frac{B_t}{B_T} \delta \mathbf{1}_{\{\tau > t\}} | \mathscr{G}_t] &= \delta \mathbf{1}_{\{\tau > t\}} \mathbf{E}^{\mathbf{Q}} [\frac{B_t}{B_T} | \mathscr{G}_t] \\ &= \delta \mathbf{1}_{\{\tau > t\}} \mathbf{E}^{\mathbf{Q}} [e^{-\int_t^T r_s ds} | \mathscr{F}_t]. \end{split}$$

Hence, we only need to compute

$$\begin{split} \mathbf{E}^{\mathbf{Q}}[e^{-\int_{t}^{T}r_{s}ds}\mathbf{1}_{\{\tau>T\}}|\mathscr{G}_{t}] &= \mathbf{1}_{\{\tau>t\}}e^{\int_{0}^{t}\lambda_{s}ds}\mathbf{E}^{\mathbf{Q}}[e^{-\int_{t}^{T}r_{s}ds}\mathbf{1}_{\{\tau>T\}}|\mathscr{F}_{t}] \\ &= \mathbf{1}_{\{\tau>t\}}e^{\int_{0}^{t}\lambda_{s}ds}\mathbf{E}^{\mathbf{Q}}[e^{-\int_{t}^{T}r_{s}ds}\mathbf{E}^{\mathbf{Q}}[\mathbf{1}_{\{\tau>T\}}|\mathscr{F}_{T}]|\mathscr{F}_{t}] \\ &= \mathbf{1}_{\{\tau>t\}}\mathbf{E}^{\mathbf{Q}}[e^{-\int_{t}^{T}(r_{s}+\lambda_{s})ds}|\mathscr{F}_{t}], \end{split}$$

where the first equality follows from the filtration switching formula in Lemma 2. $\hfill\Box$

If the recovery is delivered at default time τ , the discounted payoff at time t is then $\frac{B_t}{B_T}\mathbf{1}_{\{\tau>T\}}+\frac{B_t}{B_\tau}\delta\mathbf{1}_{\{t<\tau\leq T\}}.$

Proposition 6. Under the intensity-based model, if the recovery is delivered at the default time τ , the conditional value of the corporate bond at time t is

$$P_{t} = \mathbf{1}_{\{\tau > t\}} \mathbf{E}^{\mathbf{Q}} [e^{-\int_{t}^{T} (r_{s} + \lambda_{s}) ds} | \mathscr{F}_{t}]$$

$$+ \delta \mathbf{1}_{\{\tau > t\}} \int_{t}^{T} \mathbf{E}^{\mathbf{Q}} [\lambda_{u} e^{-\int_{t}^{u} (r_{s} + \lambda_{s}) ds} | \mathscr{F}_{t}] du.$$

Proof. The arbitrage price the corporate bond at any time $t \leq T$ is

$$\begin{split} P_t &= \mathbf{E}^{\mathbf{Q}} [\frac{B_t}{B_T} \mathbf{1}_{\{\tau > T\}} + \frac{B_t}{B_\tau} \delta \mathbf{1}_{\{t < \tau \le T\}} | \mathcal{G}_t] \\ &= \mathbf{E}^{\mathbf{Q}} [e^{-\int_t^T r_s ds} \mathbf{1}_{\{\tau > T\}} | \mathcal{G}_t] + \delta \mathbf{E}^{\mathbf{Q}} [e^{-\int_t^\tau r_s ds} \mathbf{1}_{\{t < \tau \le T\}} | \mathcal{G}_t] \end{split}$$

The first conditional expectation has been computed in the last proposition. Hence, we only need to compute the second one:

$$\mathbf{E}^{\mathbf{Q}}[e^{-\int_t^\tau r_s ds}\mathbf{1}_{\{t<\tau\leq T\}}|\mathscr{G}_t] = \mathbf{E}^{\mathbf{Q}}[\mathbf{E}^{\mathbf{Q}}[e^{-\int_t^\tau r_s ds}\mathbf{1}_{\{t<\tau\leq T\}}|\mathscr{F}_\infty\vee\mathscr{H}_t]|\mathscr{G}_t]$$

Similar to (4) in Proposition 1, it can be shown that for $t \le u$,

$$\mathbf{Q}(t < \tau \le u | \mathscr{F}_{\infty} \vee \mathscr{H}_t) = \mathbf{1}_{\{\tau > t\}} (1 - e^{-\int_t^u \lambda_s ds})$$

so the conditional density of τ on $\mathscr{F}_{\infty} \vee \mathscr{H}_t$ is

$$1_{\{\tau>t\}}\lambda_u e^{-\int_t^u \lambda_s ds}$$

for $u \ge t$. Therefore,

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$$\mathbf{E}^{\mathbf{Q}}[e^{-\int_{t}^{\tau} r_{s} ds} \mathbf{1}_{\{t < \tau \leq T\}} | \mathcal{G}_{t}] = \mathbf{E}^{\mathbf{Q}}[\int_{t}^{T} \mathbf{1}_{\{\tau > t\}} \lambda_{u} e^{-\int_{t}^{u} \lambda_{s} ds} e^{-\int_{t}^{u} r_{s} ds} du | \mathcal{G}_{t}]$$

$$= \mathbf{1}_{\{\tau > t\}} \int_{t}^{T} \mathbf{E}^{\mathbf{Q}}[\lambda_{u} e^{-\int_{t}^{u} (r_{s} + \lambda_{s}) ds} | \mathcal{G}_{t}] du$$

We are left to show that

$$\mathbf{1}_{\{\tau>t\}}\mathbf{E}^{\mathbf{Q}}[\lambda_{u}e^{-\int_{t}^{u}(r_{s}+\lambda_{s})ds}|\mathscr{G}_{t}]=\mathbf{1}_{\{\tau>t\}}\mathbf{E}^{\mathbf{Q}}[\lambda_{u}e^{-\int_{t}^{u}(r_{s}+\lambda_{s})ds}|\mathscr{F}_{t}]$$

which follows from Assumption 2. Indeed, it is sufficient to show that for any $A \in \mathcal{G}_t$,

$$\mathbf{E}^{\mathbf{Q}}[\mathbf{1}_{A}\mathbf{1}_{\{\tau>t\}}\mathbf{E}^{\mathbf{Q}}[\lambda_{u}e^{-\int_{t}^{u}(r_{s}+\lambda_{s})ds}|\mathscr{F}_{t}]] = \mathbf{E}^{\mathbf{Q}}[\mathbf{1}_{A}\mathbf{1}_{\{\tau>t\}}\lambda_{u}e^{-\int_{t}^{u}(r_{s}+\lambda_{s})ds}]$$

From Lemma 1, there exits $B \in \mathscr{F}_t$ such that $\mathbf{1}_A \mathbf{1}_{\{\tau > t\}} = \mathbf{1}_B \mathbf{1}_{\{\tau > t\}}$. Therefore, it is equivalent to show that

$$\mathbf{E}^{\mathbf{Q}}[\mathbf{1}_{B}\mathbf{1}_{\{\tau>t\}}\mathbf{E}^{\mathbf{Q}}[\lambda_{u}e^{-\int_{t}^{u}(r_{s}+\lambda_{s})ds}|\mathscr{F}_{t}]] = \mathbf{E}^{\mathbf{Q}}[\mathbf{1}_{B}\mathbf{1}_{\{\tau>t\}}\lambda_{u}e^{-\int_{t}^{u}(r_{s}+\lambda_{s})ds}]$$

Take conditional expectations of RHS first on \mathscr{F}_{∞} and then on \mathscr{F}_t , and of LHS on \mathscr{F}_t :

$$RHS = \mathbf{E}^{\mathbf{Q}} [\mathbf{E}^{\mathbf{Q}} [\mathbf{1}_{B} \mathbf{1}_{\{\tau > t\}} \lambda_{u} e^{-\int_{t}^{u} (r_{s} + \lambda_{s}) ds} | \mathscr{F}_{\infty}]]$$

$$= \mathbf{E}^{\mathbf{Q}} [\mathbf{1}_{B} \mathbf{Q} (\tau > t | \mathscr{F}_{\infty}) \lambda_{u} e^{-\int_{t}^{u} (r_{s} + \lambda_{s}) ds}]$$

$$= \mathbf{E}^{\mathbf{Q}} [\mathbf{1}_{B} \mathbf{Q} (\tau > t | \mathscr{F}_{t}) \lambda_{u} e^{-\int_{t}^{u} (r_{s} + \lambda_{s}) ds}]$$

$$= \mathbf{E}^{\mathbf{Q}} [\mathbf{E}^{\mathbf{Q}} [\mathbf{1}_{B} \mathbf{Q} (\tau > t | \mathscr{F}_{t}) \lambda_{u} e^{-\int_{t}^{u} (r_{s} + \lambda_{s}) ds} | \mathscr{F}_{t}]]$$

$$= \mathbf{E}^{\mathbf{Q}} [\mathbf{1}_{B} \mathbf{Q} (\tau > t | \mathscr{F}_{t}) \mathbf{E}^{\mathbf{Q}} [\lambda_{u} e^{-\int_{t}^{u} (r_{s} + \lambda_{s}) ds} | \mathscr{F}_{t}]],$$

and

$$LHS = \mathbf{E}^{\mathbf{Q}} [\mathbf{E}^{\mathbf{Q}} [\mathbf{1}_{B} \mathbf{1}_{\{\tau > t\}} \mathbf{E}^{\mathbf{Q}} [\lambda_{u} e^{-\int_{t}^{u} (r_{s} + \lambda_{s}) ds} | \mathscr{F}_{t}] | \mathscr{F}_{t}]]$$

$$= \mathbf{E}^{\mathbf{Q}} [\mathbf{1}_{B} \mathbf{O}(\tau > t | \mathscr{F}_{t}) \mathbf{E}^{\mathbf{Q}} [\lambda_{u} e^{-\int_{t}^{u} (r_{s} + \lambda_{s}) ds} | \mathscr{F}_{t}]]. \quad \Box$$

Remark 3. Note that in the above calculation, using filtration switching formula directly on $\mathbf{E}^{\mathbf{Q}}[e^{-\int_t^{\tau} r_s ds} \mathbf{1}_{\{t < \tau \leq T\}} | \mathcal{G}_t]$ does not help:

$$\mathbf{E}^{\mathbf{Q}}[e^{-\int_t^{\tau} r_s ds} \mathbf{1}_{\{t < \tau \le T\}} | \mathscr{G}_t] = \mathbf{1}_{\{\tau > t\}} e^{\int_0^t \lambda_s ds} \mathbf{E}^{\mathbf{Q}}[e^{-\int_t^{\tau} r_s ds} \mathbf{1}_{\{t < \tau \le T\}} | \mathscr{F}_t],$$

as this needs the conditional density of τ on \mathcal{F}_t , which is difficult to obtain.

4 Reduced-form models with correlated intensities

We model a pair of interactive default times τ and $\bar{\tau}$, where τ represents the default time of the reference entity, and $\bar{\tau}$ represents the default time of the CDS seller. Another interpretation is $(\tau, \bar{\tau})$ are a pair of default times for a basket CDS with two reference names.

Assumption 4 Let $(\tau, \bar{\tau})$ be a pair of non-negative random variables defined on a complete probability space $(\Omega, \mathcal{G}, \mathbf{Q})$, and $\{\mathcal{G}_t\}_{t\geq 0}$ be the natural filtration of $(H_t, \bar{H}_t) = (\mathbf{1}_{\{\tau \leq t\}}, \mathbf{1}_{\{\bar{\tau} \leq t\}})$, $t \geq 0$. i.e. $\mathcal{G}_t = \sigma(H_s, \bar{H}_s, s \leq t)$, such that

$$M_t := H_t - \int_0^t \mathbf{1}_{\{\tau > s\}} \lambda_s ds, \ t \ge 0,$$

and

$$ar{M}_t := ar{H}_t - \int_0^t \mathbf{1}_{\{ar{ au}>s\}} ar{\lambda}_s ds, \ t \geq 0,$$

are both $(\mathcal{G}_t, \mathbf{Q})$ -martingales. Moreover, λ and $\bar{\lambda}$ are given by

$$\lambda_s = a_1 + a_2 \mathbf{1}_{\{\bar{\tau} < s\}},\tag{7}$$

$$\bar{\lambda}_s = \bar{a}_1 + \bar{a}_2 \mathbf{1}_{\{\tau < s\}},\tag{8}$$

for constants $a_1, \bar{a}_1 > 0$ and $a_2, \bar{a}_2 \geq 0$. Finally, we assume that $\mathbf{Q}(\tau > 0) = \mathbf{Q}(\bar{\tau} > 0) = 1$.

We aim to calculate the joint distribution of $(\tau, \bar{\tau})$ using the Girsanov's theorem introduced in Chapter 8. The difficulty herein is the looping feature of the two intensity processes. If τ happens (the reference entity defaults), the intensity of $\bar{\tau}$ will increase from \bar{a}_1 to $\bar{a}_1 + \bar{a}_2$. Similarly, if $\bar{\tau}$ happens (the CDS seller defaults), the intensity of τ will increase from a_1 to $a_1 + a_2$. By changing the probability measure \mathbf{Q} to another probability measure, we open this loop, which will in turn facilitate the calculation of the joint distribution of $(\tau, \bar{\tau})$.

Theorem 1. Suppose that Assumption 4 holds. Then, for $T, U \ge 0$,

$$\mathbf{Q}(\tau > T) = \frac{a_2 e^{-(a_1 + \bar{a}_1)T} - \bar{a}_1 e^{-(a_1 + a_2)T}}{a_2 - \bar{a}_1}; \tag{9}$$

$$\mathbf{Q}(\bar{\tau} > U) = \frac{\bar{a}_2 e^{-(\bar{a}_1 + a_1)U} - a_1 e^{-(\bar{a}_1 + \bar{a}_2)U}}{\bar{a}_2 - a_1}.$$
 (10)

Proof. We first prove (9). For $t \in [0, T]$, let

$$Z_t = \mathbf{1}_{\{\tau > t\}} e^{\int_0^t \mathbf{1}_{\{\tau > s\}} \lambda_s ds}$$

Then, Theorem 8 in Chapter 8 (with $\mu = 1$) implies that Z is an $(\mathcal{G}_t, \mathbf{Q})$ -martingale. Define a new probability measure \mathbf{Q}^1 on \mathcal{G}_T by

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$$\frac{d\mathbf{Q}^1}{d\mathbf{O}} = Z_T.$$

Then, Theorem 9 in Chapter 8 (with $\mu = 1$) implies that $H_t = \mathbf{1}_{\{\tau \le t\}}$, $t \in [0, T]$, is an $(\mathcal{G}_t, \mathbf{Q}^1)$ -positive martingale, which is 0, \mathbf{Q}^1 -a.e.

By Bayes' formula, we have

$$\mathbf{Q}(\tau > T) = \mathbf{E}^{\mathbf{Q}} [Z_T e^{-\int_0^T \mathbf{1}_{\{\tau > s\}\lambda_s ds}}]$$

$$= \mathbf{E}^{\mathbf{Q}} [Z_T e^{-\int_0^T \lambda_s ds}]$$

$$= \mathbf{E}^{\mathbf{Q}^1} [e^{-\int_0^T \lambda_s ds}]$$

$$= \mathbf{E}^{\mathbf{Q}^1} [e^{-\int_0^T a_1 + a_2 \mathbf{1}_{\{\bar{\tau} \le s\}} ds}]$$

Note that under \mathbf{Q}^1 , for $s \in [0,T]$, $\bar{\lambda}_s = \bar{a}_1 + \bar{a}_2 \mathbf{1}_{\{\tau \leq s\}} = \bar{a}_1$, \mathbf{Q}^1 -a.e., so we further have

$$\begin{split} \mathbf{Q}(\tau > T) &= e^{-a_1 T} \left(\mathbf{E}^{\mathbf{Q}^1} [\mathbf{1}_{\{\bar{\tau} > T\}}] + \mathbf{E}^{\mathbf{Q}^1} [\mathbf{1}_{\{\bar{\tau} \le T\}} e^{-a_2 (T - \bar{\tau})}] \right) \\ &= e^{-a_1 T} \left(e^{-\bar{a}_1 T} + \int_0^T e^{-a_2 (T - s)} \bar{a}_1 e^{-\bar{a}_1 s} ds \right) \\ &= e^{-a_1 T} \frac{(a_2 - \bar{a}_1) e^{-\bar{a}_1 T} + \bar{a}_1 e^{-\bar{a}_1 T} - \bar{a}_1 e^{-a_2 T}}{a_2 - \bar{a}_1}, \end{split}$$

which proves (9).

To prove (10), with

$$ar{Z}_t = \mathbf{1}_{\{ar{ au}>t\}} e^{\int_0^t \mathbf{1}_{\{ar{ au}>s\}}ar{\lambda}_s ds}$$

for $t \in [0, U]$, we define a new probability measure $\bar{\mathbf{Q}}^1$ on \mathcal{G}_T by

$$\frac{d\bar{\mathbf{Q}}^1}{d\mathbf{O}} = \bar{Z}_U.$$

Then, $\bar{H}_t = \mathbf{1}_{\{\bar{\tau} \leq t\}}, t \in [0, U]$, is an $(\mathscr{G}_t, \bar{\mathbf{Q}}^1)$ -positive martingale, which is $0, \bar{\mathbf{Q}}^1$ -a.e. The rest of the proof follows along the same argument as the first case. \Box

An interesting observation is that the reference entity's survival probability $\mathbf{Q}\{\tau > T\}$ is independent of \bar{a}_2 . This is because for $s \in [0,T]$, $\{\tau \leq s\}$ is an zero event on the set $\{\tau > T\}$, so $\bar{\lambda}_s$ will keep as the constant \bar{a}_1 and is independent of \bar{a}_2 . Similarly, the CDS seller's survival probability $\mathbf{Q}\{\bar{\tau} > U\}$ is independent of a_2 .

When $a_2=0$, i.e. the CDS seller's default will not affect the reference entity, then (9) reduces to $\mathbf{Q}(\tau>T)=e^{-aT}$. When $a_2=\bar{a}_1$, then the L'Hopital's rule implies that

$$\mathbf{Q}(\tau > T) = (1 + \bar{a}_1 T) e^{-(a_1 + \bar{a}_1)T}.$$

Theorem 2. Suppose that Assumption 4 holds. Then, for $U > T \ge 0$,

$$\mathbf{Q}(\tau > T, \bar{\tau} > U) = e^{-(a_1 + \bar{a}_1)T} \frac{\bar{a}_2 e^{-(a_1 + \bar{a}_1)(U - T)} - a_1 e^{-(\bar{a}_1 + \bar{a}_2)(U - T)}}{\bar{a}_2 - a_1}.$$
 (11)

Proof. We take conditional expectation on \mathcal{G}_T and get

$$\mathbf{Q}(\tau > T, \bar{\tau} > U) = \mathbf{E}^{\mathbf{Q}} \left[\mathbf{1}_{\{\tau > T\}} \mathbf{Q}(\bar{\tau} > U | \mathcal{G}_T) \right].$$

Note that

$$\mathbf{Q}(\bar{\tau} > U | \mathcal{G}_T) = \mathbf{1}_{\{\bar{\tau} > T\}} \left(\mathbf{1}_{\{\tau > T\}} \mathbf{Q}(\bar{\tau} > U - T) + \mathbf{1}_{\{\tau \le T\}} e^{-(\bar{a}_1 + \bar{a}_2)(U - T)} \right).$$

Hence,

$$\begin{split} \mathbf{Q}(\tau > T, \bar{\tau} > U) &= \mathbf{E}^{\mathbf{Q}}[\mathbf{1}_{\{\bar{\tau} > T\}} \mathbf{1}_{\{\bar{\tau} > T\}}] \times \mathbf{Q}(\bar{\tau} > U - T) \\ &= \mathbf{E}^{\mathbf{Q}}[\mathbf{1}_{\{\bar{\tau} > T\}} \mathbf{1}_{\{\bar{\tau} > T\}} e^{\int_{0}^{T} \mathbf{1}_{\{\bar{\tau} > s\}} \bar{\lambda}_{s} ds} e^{-\int_{0}^{T} \mathbf{1}_{\{\bar{\tau} > s\}} \bar{\lambda}_{s} ds}] \times \mathbf{Q}(\bar{\tau} > U - T) \\ &= \mathbf{E}^{\mathbf{Q}}[\mathbf{1}_{\{\tau > T\}} \bar{Z}_{T} e^{-\int_{0}^{T} \bar{\lambda}_{s} ds}] \times \mathbf{Q}(\bar{\tau} > U - T) \\ &= \mathbf{E}^{\bar{\mathbf{Q}}^{\mathbf{I}}}[\mathbf{1}_{\{\tau > T\}} e^{-\int_{0}^{T} \bar{a}_{1} + \bar{a}_{2} \mathbf{1}_{\{\tau \le s\}} ds}] \times \mathbf{Q}(\bar{\tau} > U - T). \end{split}$$

Note that under $\bar{\mathbf{Q}}^1$, for $s \in [0,T]$, $\lambda_s = a_1 + a_2 \mathbf{1}_{\{\bar{\tau} \leq s\}} = a_1$, $\bar{\mathbf{Q}}^1$ -a.e., so we further have

$$\mathbf{Q}(\tau > T, \bar{\tau} > U) = \bar{\mathbf{Q}}^{1}(\tau > T)e^{-\bar{a}_{1}T} \times \mathbf{Q}(\bar{\tau} > U - T) = e^{-(a_{1} + \bar{a}_{1})T} \times \mathbf{Q}(\bar{\tau} > U - T),$$

which completes the proof. \Box

Note that the above joint probability is independent of a_2 . This is because on the set $\{\bar{\tau} > U\}$, we also have $\bar{\tau} > T$, so $\{\bar{\tau} \le s\}$ for $s \in [0, U]$ is a zero event on $\{\bar{\tau} > U\}$. Thus, λ will keep as the constant a_1 , and is independent of a_2 .

Exercise 1. For $T > U \ge 0$, show the joint probability

$$\mathbf{Q}(\tau > T, \bar{\tau} > U) = e^{-(a_1 + \bar{a}_1)U} \mathbf{Q}(\tau > T - U).$$

Thus, $(\tau, \bar{\tau})$ admit the joint density

$$f_{(\tau,\bar{\tau})}(T,U) = \begin{cases} (\bar{a}_1 + \bar{a}_2)e^{-(\bar{a}_1 + \bar{a}_2)U}a_1e^{(\bar{a}_2 - a_1)T}, & \text{if } U > T; \\ (a_1 + a_2)e^{-(a_1 + a_2)T}\bar{a}_1e^{(a_2 - \bar{a}_1)U}, & \text{if } U < T. \end{cases}$$
(12)

Exercise 2. (Total hazard construction of correlated default times [1])

In general, when there are M default times $(\tau^i)_{1 \le i \le M}$ as in the basket CDS, we may simulate those default times via the so called *total hazard construction*. It is based on the following simple observation: For a single jump process $H_t = \mathbf{1}_{\{\tau \le t\}}$, $t \ge 0$, with a constant intensity a > 0, we can simulate its associated jump time τ as

$$\hat{\tau} = \inf\{t \ge 0 : \Lambda_t \ge E\}$$

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where E is a standard exponential r.v. and $\Lambda_t := \int_0^t a ds$, the so called hazard of τ . Then, $\hat{\tau} = \tau$ in distribution. Indeed, for any T > 0,

$$\mathbf{Q}(\hat{\tau} > T) = \mathbf{Q}(\Lambda_T < E) = \mathbf{Q}(aT < E) = e^{-aT}.$$

Assumption 5 Let $(\tau^i)_{1 \leq i \leq M}$ be a sequence of non-negative random variables defined on a complete probability space $(\Omega, \mathcal{G}, \mathbf{Q})$, and $\{\mathcal{G}_t\}_{t>0}$ be the natural filtration of $H_t^i = \mathbf{1}_{\{\tau^i \le t\}}$, $t \ge 0, 1 \le i \le M$, i.e. $\mathscr{G}_t = \sigma(H_s^i, s \le t, 1 \le i \le M)$, such that

$$M_t^i := H_t^i - \int_0^t \mathbf{1}_{\{\tau^i > s\}} \lambda_s^i ds, \ t \ge 0, \ 1 \le i \le M,$$

are $(\mathcal{G}_t, \mathbf{Q})$ -martingales. Moreover, λ^i , $1 \le i \le M$, are given by

$$\lambda_s^i = a_{ii} + \sum_{j \neq i} a_{ij} \mathbf{1}_{\{\tau^j \le s\}},\tag{13}$$

with a constant matrix $A = (a_{ij})_{1 \le i,j \le M}$ satisfying $a_{ij} > 0$ and $a_{ij} \ge 0$ for $i \ne j$. Finally, we assume that $\mathbf{Q}(\tau^i > 0) = 1$ for $1 \le i \le M$.

Note that there are M! orders of $(\tau^i)_{1 \le i \le M}$. Let us consider one of the orders: $\{\tau^1 < \tau^2 < \dots < \tau^M\}$. In such a case, we construct the M default times as follows.

Step 0: Let $(E^i)_{1 \le i \le M}$ be a sequence of mutually independent standard exponential random variables.

Step 1: Since there is no default prior to τ^1 , its intensity is a_{11} and, therefore,

$$\hat{\tau}^1 = \inf \left\{ t \ge 0 : \int_0^t a_{11} ds \ge E^1 \right\} = \frac{E^1}{a_{11}}.$$

Step 2: Prior to τ^2 , τ^1 has already occurred, so the intensity of τ^2 is a_{22} + $a_{21}\overline{\mathbf{1}_{\{\tau^1 \le s\}}}$ and it can be constructed by

$$\hat{\tau}^2 = \inf \left\{ t \ge 0 : \int_0^{\hat{\tau}^1} a_{22} ds + \int_{\hat{\tau}^1}^t (a_{22} + a_{21}) ds \ge E^2 \right\}$$
$$= \frac{E^1}{a_{11}} + \frac{a_{22}}{a_{22} + a_{21}} \left(\frac{E^2}{a_{22}} - \frac{E^1}{a_{11}} \right).$$

Step k: In general, we construct τ^k for $1 \le k \le M$ recursively by

$$\hat{\tau}^k = \inf \left\{ t \geq 0 : \sum_{i=1}^{k-1} \int_{\hat{\tau}^{i-1}}^{\hat{\tau}^i} (a_{kk} + \sum_{j=1}^{i-1} a_{kj}) ds + \int_{\hat{\tau}^{k-1}}^t (a_{kk} + \sum_{j=1}^{k-1} a_{kj}) ds \geq E^k \right\},$$

where $\hat{\tau}^0 := 0$ and $\sum_{i=1}^0 := 1$. Then, on the set $\{\tau^1 < \tau^2 < \dots < \tau^M\}$, we have $(\tau_i)_{1 \le i \le M} = (\hat{\tau}_i)_{1 \le i \le M}$ in distribution. The same result holds for the other (M!-1) situations via permutation.

Consider the intensity model in section 4. Thus, M=2, $a_{11}=a_1$, $a_{12}=a_2$, $a_{22}=\bar{a}_1$ and $a_{21}=\bar{a}_2$. Show that $(\tau,\bar{\tau})$ have the expressions (equal in distribution)

$$\tau = \begin{cases} \frac{E^1}{a_{11}}, & \text{if } \frac{E^1}{a_{11}} < \frac{E^2}{a_{22}}; \\ \frac{E^2}{a_{22}} + \frac{a_{11}}{a_{11} + a_{12}} (\frac{E^1}{a_{11}} - \frac{E^2}{a_{22}}), & \text{if } \frac{E^1}{a_{11}} > \frac{E^2}{a_{22}}, \end{cases}$$

and

$$\bar{\tau} = \begin{cases} \frac{E^1}{a_{11}} + \frac{a_{22}}{a_{22} + a_{21}} (\frac{E^2}{a_{22}} - \frac{E^1}{a_{11}}), & \text{if } \frac{E^1}{a_{11}} < \frac{E^2}{a_{22}}; \\ \frac{E^2}{a_{22}}, & \text{if } \frac{E^1}{a_{11}} > \frac{E^2}{a_{22}}. \end{cases}$$

Equivalently, on $\{\tau < \bar{\tau}\}\$,

$$\begin{cases} E^1 = a_{11}\tau; \\ E^2 = a_{22}\tau + (\bar{\tau} - \tau)(a_{22} + a_{21}), \end{cases}$$

and on the set $\{\tau > \bar{\tau}\}$,

$$\begin{cases} E^2 = a_{22}\bar{\tau}; \\ E^1 = a_{11}\bar{\tau} + (\tau - \bar{\tau})(a_{11} + a_{12}). \end{cases}$$

The above total hazard construction procedure also yields the joint density of default times. To see this, since (E^1,E^2) have the joint density $f_{(E^1,E^2)}(t,u)=e^{-(t+u)}$, and the Jacobi determinant of (E^1,E^2) with respect to $(\tau,\bar{\tau})$ is

$$\left| \frac{\partial(E^1, E^2)}{\partial(\tau, \bar{\tau})} \right| = \begin{cases} a_{11}(a_{22} + a_{21}), & \text{if } \tau < \bar{\tau}; \\ a_{22}(a_{11} + a_{12}), & \text{if } \tau > \bar{\tau}. \end{cases}$$

Hence, we can obtain the joint density of $(\tau, \bar{\tau})$ by

$$f_{(\tau,\bar{\tau})}(T,U) = f_{(E^1,E^2)}(t,u) \left| \frac{\partial (E^1,E^2)}{\partial (\tau,\bar{\tau})} \right|,$$

which yields exactly the same joint density formula (12).

References

 Yu, Fan. Correlated defaults in intensity-based models. Mathematical Finance 17(2) (2007): 155-173.