

Introduction to Dynamical Systems

Differential equs

ODEs

$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx = 0$$

$$m \ddot{x} + kx = 0$$

PDEs

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$$

$$u(x, t)$$

$$\frac{dx}{dt}$$

$$\dot{x}$$

$$\ddot{x}$$

Difference equs
(iterated maps)

$$x_{n+1} = f(x_n)$$

$$\dot{x}_1 = f_1(x_1, \dots, x_n)$$

\vdots

$$\dot{x}_n = f_n(x_1, \dots, x_n)$$

n-dimensional system

$$\dot{x} = f(x)$$

$$f_i(x_1, x_2, \dots, x_n)$$

autonomous systems

$$f_i(x_1, x_2, \dots, x_n, t)$$

nonautonomous systems

$$x_{n+1} = t$$

$$\dot{x}_{n+1} = 1$$

n-order ODE \Rightarrow

\Rightarrow can write as n-dim system

$$m \ddot{x} + b \dot{x} + kx = 0$$

$$x_1 = x - \text{position}$$

$$x_2 = \dot{x} - \text{velocity}$$

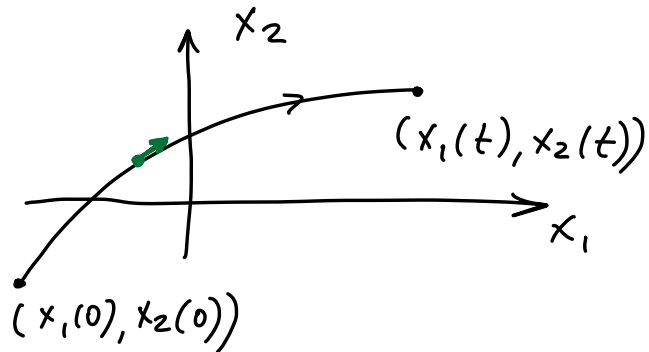
$$\Downarrow$$

$$\dot{x}_1 = x_2$$

$$\dot{x}_2 = \frac{1}{m} [-b x_2 - k x_1]$$

$$\dot{x}_1 = f_1(x_1, x_2)$$

$$\dot{x}_2 = f_2(x_1, x_2)$$



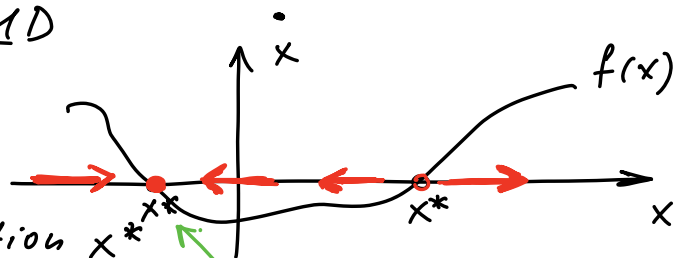
Systems in 1D

$$\dot{x} = f(x)$$

$f(x) = 0 \Rightarrow$ solution x^*

x^* - fixed points

(equilibriums, steady-states)



locally stable
(not globally)

$$\dot{x} = \frac{dx}{dt} \approx \frac{x_i - x_{i-1}}{\Delta t}$$

$$\dot{x} > 0 \quad x_i > x_{i-1} \rightarrow$$

$$\dot{x} < 0 \quad x_i < x_{i-1} \leftarrow$$

Linear stability analysis

$$\dot{x} = f(x)$$

x^* - f.p.

$$\eta(t) = x(t) - x^*$$

small perturbation

$\eta(t)$ - grow or decay?

$$\dot{\eta} = \frac{d}{dt} (x(t) - x^*) = \dot{x}$$

$$\begin{aligned} \dot{\eta} &= f(\eta(t) + x^*) = \\ &= \underbrace{f(x^*)}_{=0} + f'(x^*)\eta + O(\eta^2) \end{aligned}$$

Taylor's series expansion
 $\eta \ll 1$

$$\boxed{\dot{\eta} = f'(x^*)\eta} \quad \text{linear drift. equ.}$$

$$\eta(t) = e^{f'(x^*)t}$$

$f'(x^*) > 0 \Rightarrow \eta(t)$ grows exponentially
 $\Rightarrow x^*$ - unstable

$f'(x^*) < 0 \Rightarrow \eta(t)$ decays \Rightarrow
 x^* - stable

characteristic time $\frac{1}{|f'(x^*)|}$

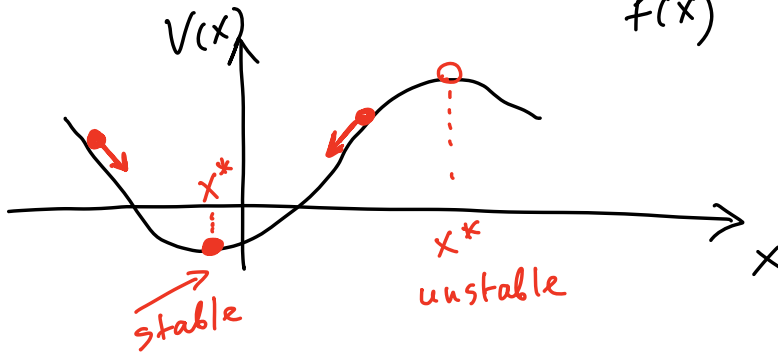
$$\dot{x} = f(x)$$

$V(x)$:

Potential

$$f(x) = - \frac{dV}{dx}$$

$$\frac{dV(x(t))}{dt} = \frac{dV}{dx} \cdot \underbrace{\frac{dx}{dt}}_{f(x)} = - \left(\frac{dV}{dx} \right)^2 \leq 0$$



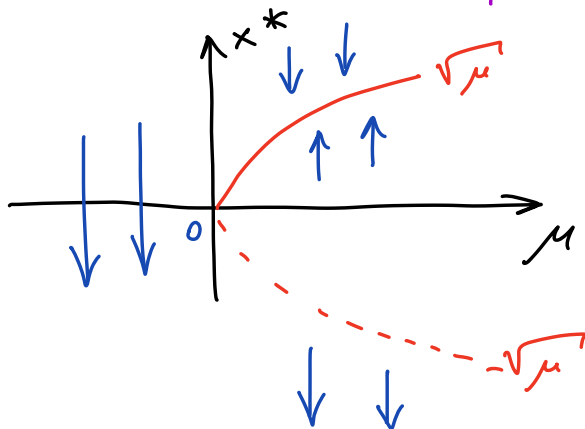
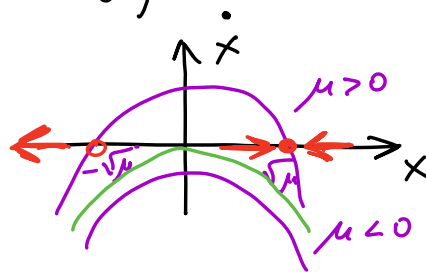
$$\frac{dV}{dx} = 0 \Leftrightarrow f(x) = 0$$

$$\text{local min/max} \Leftrightarrow x^* \text{ - f.p.}$$

Bifurcations

1D (1) Saddle-node bif.

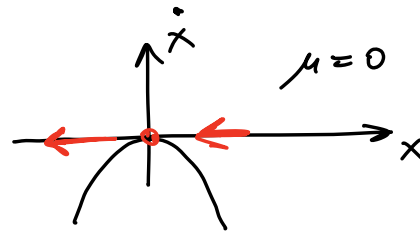
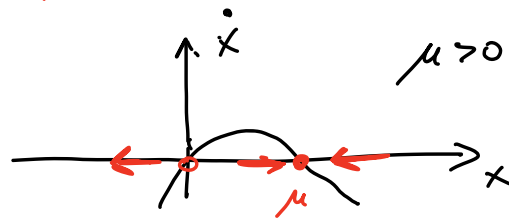
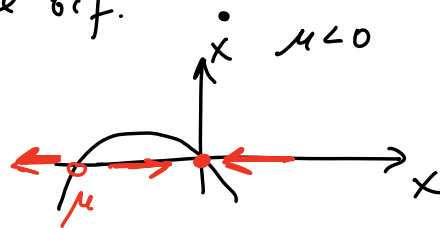
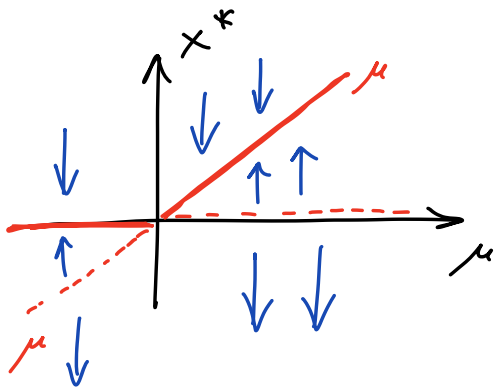
$$\boxed{\dot{x} = \mu - x^2}$$



$\mu = 0$ - bif. point

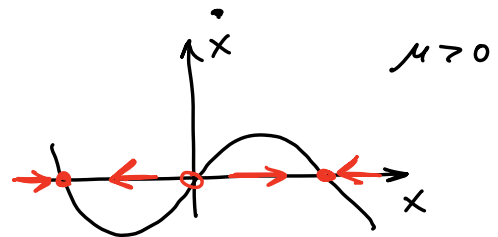
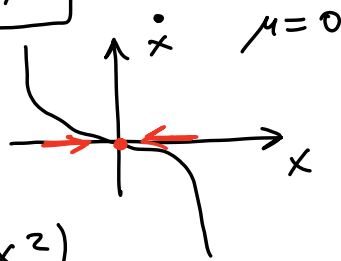
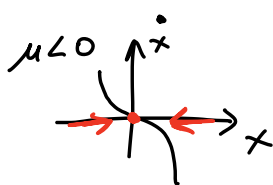
② Transcritical bif.

$$\dot{x} = \mu x - x^2$$



③ Pitchfork bif. (supercritical bif.)

$$\dot{x} = \mu x - x^3$$



$$f(x) = x(\mu - x^2)$$

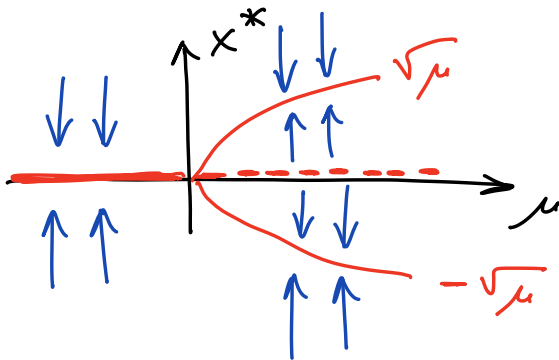
$$f(x) = 0 \iff x^* = 0 \quad x^* = \pm\sqrt{\mu} \quad \mu > 0$$

$$f'(x^*) \quad f'(x) = \mu - 3x^2$$

$$f'(0) = \mu \Rightarrow \begin{aligned} \mu > 0 &- x^* = 0 \text{ unstable} \\ \mu < 0 &- x^* = 0 \text{ stable} \end{aligned}$$

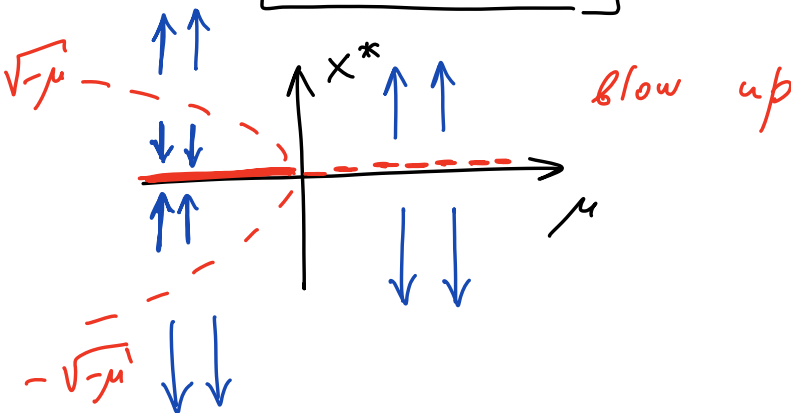
$$f'(\pm\sqrt{\mu}) = \mu - 3\mu = -2\mu < 0$$

$x^* = \pm\sqrt{\mu}$ stable
($\mu > 0$)



(3) Pitchfork bif. (subcritical)

$$\dot{x} = \mu x + x^3$$



Consider $\dot{x} = \mu x + x^3 - x^5$ HW

Consider $\dot{x} = h + \mu x - x^3$ HW

$h = 0$ - pitchfork bif.

$h \neq 0$ - breaks the symmetry

hint: split $f(x)$ into 2 functions

$$y = -h \quad y = \mu x - x^3$$

$$f(x) = 0$$

