CURRICULUM VITAE

PERSONAL INFORMATION

Name Address

Telephone E-Mail

Nationality
Date of birth
Webpage

Interests

EDUCATION

▶ Period

o Acquired qualifications

Institute

Supervisor

▶ Period

Acquired qualifications

o Institute

o Principal subjects

o Thesis subject

▶ Period

Acquired qualifications

Institute

o Principal subjects

o Thesis subject

▶ Period

o Acquired qualifications

o Institute

o Principal subjects

▶ Period

o Graduate school

o Principal subjects

TOLGA BIRDAL, Ph.D. 210 Cowper Street

94301 Palo Alto, CA, USA

+1-650 4415125 tbirdal@stanford.edu tbirdal@gmail.com

Turkish 17.12.1983 http:/tbirdal.me

https://linkedin.com/in/tbirdal

http://campar.in.tum.de/Main/TolgaBirdal https://profiles.stanford.edu/tolga-birdal

3D Computer Vision, Machine Learning, Machine Vision, Pattern

Recognition, High Performance Computing

2019 - Present

Postdoctoral Research Fellow

Stanford University

Prof. Leonidas Guibas / Geometric Computing Group

2014-2018

Dr. Rer. Nat. (Ph.D.)

Technical University of Munich

Informatics

Geometric Methods for 3D Reconstruction from Large Point Clouds

2008-2011

Master of Science

Technical University of Munich

Computational Science and Engineering

3D Deformable Surface Recovery Using RGBD Cameras

2004-2008

Bachelor of Science

Sabanci University

Electronics Engineering

1999-2004

Robert College

Science



PROFESSION

▶ Period

2014-2018

o Employer

Position

o Projects

Siemens Corporate Technology

Otto Hahn Ring 6, 81739, Muenchen, Deutchland

Research Scientist

I have started to contribute in Siemens' machine vision research as a byproduct of my Doctoral studies on large scale 3d reconstruction, where the presence of clutter and occlusion is inevitable. We expect our research to impact Autonomous Systems and Quality Assurance.

▶ Period

2014-2014

Employer

Supervisor

Google Summer of Code

Mountain View, CA, USA

o Position Student

Dr. Vincent Rabaud

Projects
 Implementation of surface matching algorithms into OpenCV

▶ Period

2010-2014

Employer
 Gravi Information Technologies

Istanbul, Turkey

o Position CEO & Co-Fou

Projects

CEO & Co-Founder

Gravi is a research oriented machine vision company in Turkey, developing industry oriented vision libraries. I was responsible in the management and the direction of the research on 3D machine vision.

▶ Period

2008-2011

• Employer BeFunky Inc.

1- -7 -

San Francisco, CA, USA

PositionProjectsChief Engineer & Co-FounderI have co-founded BeFunky, a

I have co-founded BeFunky, an online digital art engine, which utilizes state of the art computer vision algorithms. Besides being the co-founder I have developed the entire system and most of the basis for the algorithms running on BeFunky (www.befunky.com)

▶ Period

2009-2010

 $\circ \ Employer$

Mitsubishi Electric Research Labs

Cambridge, MA, USA

Intern

Prof. Fatih Porikli

SupervisorProjects

Position

At MERL, I worked on simulating human breathing in 4D. This included the implementation of Random Walks for image segmentation, 3D CT processing on CUDA, and real-time Bilateral Filtering.

▶ Period

2007

o Employer

Carnegie Mellon University

Pittsburgh, PA, USA

PositionSupervisor

Intern

Prof. Martial Hebert & Dr. Yan. Ke

Project

Shape Matching Algorithm using Spatial Segmentation Data

▶ Period

Employer

o Position Supervisor

Projects

2005-2007

Vistek Isra Vision

Teknokent, Gebze, Turkey **Application Developer**

Prof. Aytul Ercil

Development of industrial computer vision systems on OCR/OCV, Barcode Reading, Robot Control, Object Classification based on Halcon.

AWARDS

Personal awards

2016, EMVA Young Professional Award. Given to young professionals and novel works with great industrial impact 2014, Ernst von Siemens Scholarship, Siemens AG. Given to talented PhD candidates in industry, showing high academic potential 2004, Merit Scholarship, Sabanci University for success in University **Entrance Exam**

2004. Ranked 81^{st} in Istanbul and $\sim 600^{th}$ in Turkev in University Entrance Exam, among $\sim 1.7M$ applicants

2004, Received Robert College Sait Halman Computer Honor Prize (Given to one who has great achievements in Computer Science)

▶ Publication awards

Best Paper Finalist at Conference on Computer Vision and Pattern Recognition (CVPR) 2019

Best Student Paper Award at International Conference on Computer Vision (ICCV) 2017 Workshop on Multiview Relationships in 3D Data (MVR3D)

Alper Atalay Best Paper Award at SIU 2013 Ranked 3^{rd}

2011, Hottest iPhone App in Photo & Video Category on Apple iTunes Store

2009, Motorola Worldwide Mobile Widget Competition - Winner 2009, GTS Tech Start-up Competition - Finalist, Presenter 2007, TechCrunch40 Tech Start-up Competition - Finalist

Awards in other competitions

2008, Ranked 1^{st} with robot ROBO112 in Projistor Robot Competetion at Dogus University

2008, Ranked 2^{nd} with robot ROBO112 in ITURO Robot Competetion at Istanbul Technical University

2000, Ranked 10^{th} in Izmir Agean Chess Tournament

LANGUAGES

NATIVE LANGUAGE OTHER LANGUAGES Turkish

English (Proficient), German (Intermediate)

PUBLICATIONS

▶ International Conferences

Tolga Birdal, Michael Arbel, Umut Simsekli & Leonidas Guibas: *Synchronizing Probability Measures on Rotations via Optimal Transport*, CVPR 2020

Zan Gojcic, Caifa Zhou, Jan D Wegner, Leonidas J Guibas & **Tolga Birdal**: *Learning multiview 3D point cloud registration*, CVPR 2020

Yongheng Zhao*, **Tolga Birdal***, Jan Eric Lenssen, Emanuele Menegatti, Leonidas Guibas & Federico Tombari: *Quaternion Equivariant Capsule Networks for 3D Point Clouds*, ECCV 2020 **[oral]**

Mai Bui, **Tolga Birdal**, Haowen Deng, Shadi Albarqouni, Leonidas Guibas, Nassir Navab & Slobodan Ilic: *Multimodal 6D Camera Relocalization via Bingham Mixture Models*, ECCV 2020

Mikaela Uy, Jingwei Huang, Minhyuk Sung, **Tolga Birdal** & Leonidas Guibas: *Deformation-Aware 3D Model Embedding and Retrieval*, ECCV 2020

Christiane Sommer, Yumin Sun, Leonidas Guibas, Daniel Cremers & **Tolga Birdal**: From Planes to Corners: Multi-Purpose Primitive Detection in Unorganized 3D Point Clouds, RA-Letters 2020

Fabian Manhardt, Diego Arroyo, Christian Rupprecht, Benjamin Busam, **Tolga Birdal**, Nassir Navab, Federico Tombari: *Explaining the Ambiguity of Object Detection and 6D Pose from Visual Data*, ICCV 2019

Tolga Birdal & Umut Simsekli: *Probabilistic Permutation Synchronization using the Riemannian Structure of the Birkhoff Polytope*, CVPR 2019 **[oral]**

Haowen Deng, **Tolga Birdal** & Slobodan Ilic: *3D Local Features for Direct Pairwise Registration*, CVPR 2019

Yongheng Zhao*, **Tolga Birdal***, Haowen Deng & Federico Tombari: *3D Point-Capsule Networks*, CVPR 2019

Tolga Birdal, Umut Simsekli, Onur Eken & Slobodan Ilic: *Bayesian Pose Graph Optimization via Bingham Distributions and Tempered Geodesic MCMC*, NeurIPS 2018

Tolga Birdal, Benjamin Busam, Nassir Navab, Slobodan Ilic & Peter Sturm: *Generic Primitive Detection in Point Clouds Using Novel Minimal Quadric Fits*, T-PAMI, 2019

Haowen Deng, **Tolga Birdal** & Slobodan Ilic: *PPF-FoldNet: Unsupervised Learning of Rotation Invariant 3D Local Descriptors*, ECCV 2018

Adrian Haarbach, **Tolga Birdal** & Slobodan Ilic: *Survey of Higher Order Rigid Body Motion Interpolation Methods for Keyframe Animation and Continuous-Time Trajectory Estimation*, 3DV 2018 **[spotlight]**

Tolga Birdal, Benjamin Busam, Nassir Navab, Slobodan Ilic & Peter Sturm: *A Minimalist Approach to Type-Agnostic Detection of Quadrics in Point Clouds*, CVPR 2018

Haowen Deng, **Tolga Birdal** & Slobodan Ilic: *PPFNet: Global Context Aware Local Features for Robust 3D Point Matching* CVPR 2018 **[spotlight]**

Tolga Birdal & Slobodan Ilic: *CAD Priors for Accurate and Flexible 3D Reconstruction*, ICCV 2017

Benjamin Busam, **Tolga Birdal** & Nassir Navab: *Camera Pose Filtering with Local Regression Geodesics on the Riemannian Manifold of Dual Quaternions*, ICCVW 2017

Tolga Birdal & Slobodan Ilic: A Point Sampling Algorithm for 3D Matching of Irregular Geometries, IROS 2017

▶ International Conferences

Tolga Birdal, levgeniia Dobryden & Slobodan Ilic: *X-Tag: A Fiducial Tag for Flexible and Accurate Bundle Adjustment*, 3DV 2016

Tolga Birdal, Emrah Bala, Tolga Eren & Slobodan Ilic: *Online Inspection of 3D Parts via a Locally Overlapping Camera Network*, WACV 2016

Tolga Birdal & Slobodan Ilic: *Point Pair Features Based Object Detection and Pose Estimation Revisited*, 3DV 2015 [oral]

Umut Simsekli & **Tolga Birdal**: A Unified Probabilistic Framework For Robust Decoding Of Linear Barcodes, ICASSP 2015

Tolga Birdal, Diana Mateus & Slobodan Ilic: *Towards A Complete Framework For Deformable Surface Recovery Using RGBD Cameras*, IROS 2012

Tolga Birdal & Aytul Ercil: *Real-time Automated Road, Lane and Car Detection for Autonomous Driving*, DSPincars 2007

▶ National Conferences

Tolga Birdal & Slobodan Ilic: *Task Oriented 3D Sampling via Genetic Algorithms*, SIU 2018

Umut Simsekli, **Tolga Birdal**, Emre Koc & Taylan Cemgil: *A Factorization Based Recommender System for Online Services*, SIU 2013

▶ Patents

Tolga Birdal: Computer-aided image processing method, WO2018137935A1.

Tolga Birdal, levgeniia Dobryden & Slobodan Ilic: Marking Device, WO2018077535A1.

Tolga Birdal, Mehmet Ozkanoglu & Abdi Tekin Tatar: *Method and System for Generating Online Cartoon Outputs* US8629883B2.

Tolga Birdal, Emrah Bala, Emre Koc, Mehmet Ozkanoglu & Abdi Tekin Tatar: *Method and System for Providing an Image Effects Interface* US9483237B2.

CONFERENCES

> Academic conferences

CVPR (2017, 2018, 2019), ICML 2019, NeurIPS 2018, ECCV 2018, ICCV (2017, 2019), IROS (2017, 2012), 3DV (2015, 2016), WACV 2016, SIU (2017, 2013, 2008, 2006)

2013, IPAM Computer Vision Graduate Summer School, UCLA (with **NSF Scholarship**)

2012, 2015 & 2016 International Computer Vision Summer School, Sicily - Successful Completion Certificates

▶ Industrial conferences

2016, EMVA Business Conference - Edinburgh

2012 / 2013, World of Industry, Exhibitor - Istanbul

2008, TechCunch 50, Alumni & Exhibitor - San Francisco

2008, NVISION - San Jose

2008, ARCS - Dresden

2007, TechCunch 40, Presenter - San Francisco

2007, Hannover Industrial Fair, Exhibitor - Hannover

2007, ARIF Innovation Festival, Exhibitor - Istanbul

2007, MVTec, Siemens and Intel Training and Workshops - Munich, Nuremberg, Ankara respectively

ABILITIES

PROGRAMMING SKILLS C/C++, Assembler (SSE, SSE2, SSE3, SSSE3, AVX), CUDA,

Matlab, LateX, OpenCV, Halcon, C#, QT, OpenGL, Maple,

Python and overall, the ability to adapt to different languages.

HARDWARE SKILLS Camera Systems (Basler, IDS, Sony, JAI, The Imaging Source

etc), Siemens 3D Imaging Sensors, Lighting Systems (Falcon, RVSI, SmartVision), PIC, FPGA, I/O Control Modules, PLCs,

Smart Cameras, Framegrabbers and other similar hardware.

HOBBIES One Frequent Jazz Drummer

A Cook in the Evenings Occasional Chess Player

A Former Point Guard on Basketball Fields