Package 'Rglpk'

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Version 0.6-1	
Title R/GNU Linear Programming Kit Interface	
Description R interface to the GNU Linear Programming Kit. GLPK is open source software for solving large-scale linear programming (LP), mixed integer linear programming (MILP) and other related problems.	
Depends slam (>= 0.1-9)	
SystemRequirements GLPK library package (e.g., libglpk-dev on Debian/Ubuntu)	
License GPL-2 GPL-3	
<pre>URL http://R-Forge.R-project.org/projects/rglp/,</pre>	
http://www.gnu.org/software/glpk/	
NeedsCompilation yes	
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2 Rglpk_read_file

Description

High level R interface to the CPLEX_LP, MATHPROG and MPS reader of the GNU Linear Programming Kit (GLPK). Example data from the GLPK release is included in the './examples/' sub-directory.

Usage

```
## File reader for various formats
Rglpk_read_file(file, type = c("MPS_fixed", "MPS_free", "CPLEX_LP", "MathProg"),
ignore_first_row = FALSE, verbose = FALSE)
## print method
## S3 method for class 'MP_data_from_file'
print(x, ...)
```

Arguments

x an object of class "MP_data_from_file".

... further arguments passed on to the print method.

Details

Rglpk_read_file() takes the path to a file as an argument and calls GLPK's file reader. The description of the linear or mixed integer linear program is returned as an object of class "MP_data_from_file".

Value

Rglpk_read_file() returns the specification of a (mixed integer) linear program defined in file as an object of class "MP_data_from_file". The returned object is a list containing the following components.

objective a "simple_triplet_matrix" representing the coefficients to x in the objective function.

constraints a list with three elements: a "simple_triplet_matrix" of coefficients, a char-

acter vector of constraint directions, and a numeric vector representing the right

hand side.

bounds a list containing two elements: lower and upper. Each of which contain a list

specifying indices (ind) and corresponding bounds (val).

types a character vector specifying whether the corresponding objective variable is of

type binary ("B"), continuous ("C"), or integer ("I").

maximum a logical indicating whether a minimum or a maximum is sought.

Further meta data is provided as attributes to the object.

Author(s)

Stefan Theussl

Examples

```
## read a CPLEX LP file
x <- Rglpk_read_file( system.file(file.path("examples", "plan.lp"), package</pre>
= "Rglpk"), type = "CPLEX_LP")
## optimal solution: 296.2166
Rglpk_solve_LP(x$objective, x$constraints[[1]], x$constraints[[2]],
                x$constraints[[3]], x$bounds, x$types, x$maximum)
## read a MATHPROG file
x <- Rglpk_read_file( system.file(file.path("examples", "assign.mod"), package</pre>
= "Rglpk"), type = "MathProg")
## optimal solution: 76
Rglpk_solve_LP(x$objective, x$constraints[[1]], x$constraints[[2]],
                x$constraints[[3]], x$bounds, x$types, x$maximum)
## read a MATHPROG file
x <- Rglpk_read_file( system.file(file.path("examples", "plan.mps"), package</pre>
= "Rglpk"), type = "MPS_fixed")
## optimal solution: 296.2166
Rglpk_solve_LP(x$objective, x$constraints[[1]], x$constraints[[2]],
                x$constraints[[3]], x$bounds, x$types, x$maximum)
```

Rglpk_solve_LP

Linear and Mixed Integer Programming Solver Using GLPK

Description

High level R interface to the GNU Linear Programming Kit (GLPK) for solving linear as well as mixed integer linear programming (MILP) problems.

Usage

Arguments

a numeric vector representing the objective coefficients. obj mat a numeric vector or a matrix of constraint coefficients. dir a character vector with the directions of the constraints. Each element must be one of "<", "<=", ">", ">=", or "==". rhs the right hand side of the constraints. bounds NULL (default) or a list with elements upper and lower containing the indices and corresponding bounds of the objective variables. The default for each variable is a bound between 0 and Inf. a character vector indicating the types of the objective variables. types can be types either "B" for binary, "C" for continuous or "I" for integer. By default NULL, taken as all-continuous. Recycled as needed. a logical giving the direction of the optimization. TRUE means that the objective max is to maximize the objective function, FALSE (default) means to minimize it. control a list of parameters to the solver. Currently the only options are: verbose, a logical for turning on/off additional solver output; canonicalize_status, a

a list of control parameters (overruling those specified in control).

Details

GLPK is open source. The current version can be found at http://www.gnu.org/software/glpk/glpk.html. Package **Rglpk** provides a high level solver function using the low level C interface of the GLPK solver. R interface packages which port all low level C routines of the GLPK API to R are also available. Consult the 'See Also' Section for references.

Value

A list containing the optimal solution, with the following components.

solution the vector of optimal coefficients

FALSE; TRUE.

objval the value of the objective function at the optimum

status an integer with status information about the solution returned. If the control

parameter canonicalize_status is set (the default) then it will return 0 for the optimal solution being found, and non-zero otherwise. If the control parameter

logical indicating whether to canonicalize GLPK status codes or not. Defaults:

is set to FALSE it will return the GLPK status codes.

Author(s)

Stefan Theussl and Kurt Hornik

References

```
GNU Linear Programming Kit (http://www.gnu.org/software/glpk/glpk.html). GLPK Interface to R (http://cran.R-project.org/package=Rglpk).
```

See Also

glpk and **glpkAPI** for C API bindings; 1p in package **lpSolve**; ROI_solve in package **ROI**; Rsymphony_solve_LP in package **Rsymphony**.

Examples

```
## Simple linear program.
## maximize: 2 x_1 + 4 x_2 + 3 x_3
## subject to: 3 \times 1 + 4 \times 2 + 2 \times 3 \le 60
              2 x_1 + x_2 + 2 x_3 <= 40
                x_1 + 3 x_2 + 2 x_3 \le 80
##
##
                 x_1, x_2, x_3 are non-negative real numbers
obj <- c(2, 4, 3)
mat \leftarrow matrix(c(3, 2, 1, 4, 1, 3, 2, 2, 2), nrow = 3)
dir <- c("<=", "<=", "<=")
rhs <- c(60, 40, 80)
max <- TRUE
Rglpk_solve_LP(obj, mat, dir, rhs, max = max)
## Simple mixed integer linear program.
## maximize: 3 x_1 + 1 x_2 + 3 x_3
## subject to: -1 x_1 + 2 x_2 + x_3 <= 4
                        4 x_2 - 3 x_3 <= 2
##
                  x_1 - 3 x_2 + 2 x_3 \le 3
##
##
                  x_1, x_3 are non-negative integers
##
                  x_2 is a non-negative real number
obj <- c(3, 1, 3)
mat <- matrix(c(-1, 0, 1, 2, 4, -3, 1, -3, 2), nrow = 3)
dir <- c("<=", "<=", "<=")
rhs <- c(4, 2, 3)
types <- c("I", "C", "I")
max <- TRUE
Rglpk_solve_LP(obj, mat, dir, rhs, types = types, max = max)
## Same as before but with bounds replaced by
## -Inf < x_1 <= 4
   0 <= x_2 <= 100
   2 <= x_3 < Inf
bounds <- list(lower = list(ind = c(1L, 3L), val = c(-Inf, 2)),
               upper = list(ind = c(1L, 2L), val = c(4, 100)))
Rglpk_solve_LP(obj, mat, dir, rhs, bounds, types, max)
```

```
## Examples from the GLPK manual
## Solver output enabled
## 1.3.1
## maximize: 10 x_1 + 6 x_2 + 4 x_3
## subject to: x_1 + x_2 + x_3 \le 100
              10 x_1 + 4 x_2 + 5 x_3 \le 600
##
               2 x_1 + 2 x_2 + 6 x_3 <= 300
##
                 x_1, x_2, x_3 are non-negative real numbers
obj <- c(10, 6, 4)
mat \leftarrow matrix(c(1, 10, 2, 1, 4, 2, 1, 5, 6), nrow = 3)
dir <- c("<=", "<=", "<=")
rhs <- c(100, 600, 300)
max <- TRUE
Rglpk_solve_LP(obj, mat, dir, rhs, max = max, control = list("verbose" =
TRUE, "canonicalize_status" = FALSE))
```

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