

TP Courbes paramétrées 24/03/2021

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Partie 1

Question 1

```
import numpy as np
import matplotlib.pyplot as plt
```

```
# Question 1 :
```

```
T = np.linspace(0, 2 * np.pi, 1001)
```

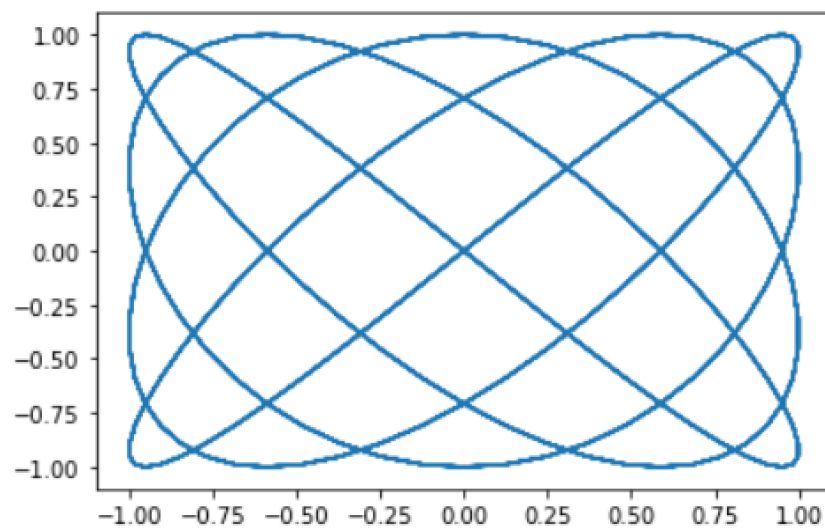
```
X = np.sin(20 * T )
```

```
Y = np.sin(25*T)
```

```
plt.plot(X, Y)
```

```
plt.show()
```

$$\begin{cases} x(t) = \sin(20t) \\ y(t) = \sin(25t) \end{cases}$$



Question 2.a

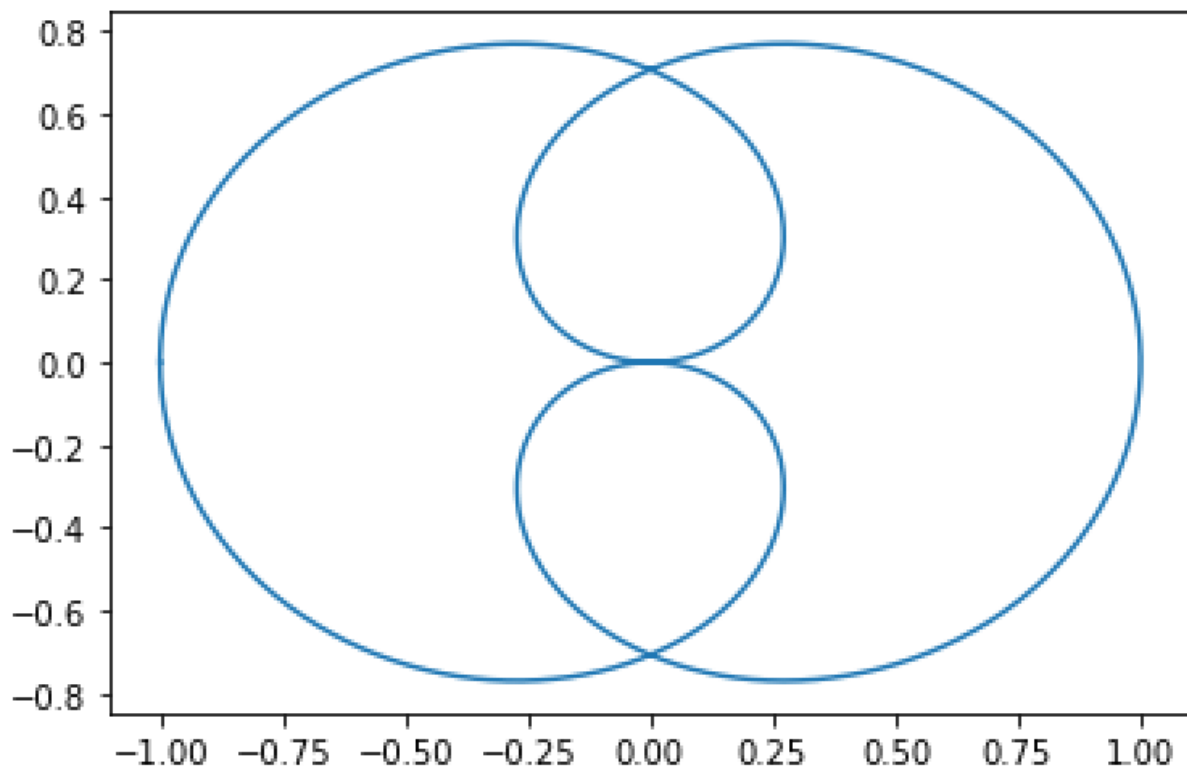
$$(a) \begin{cases} x(t) = -\cos(2t) \cos(t) \\ y(t) = -\sin(2t) \cos(t) \end{cases} \quad t \in [0, 2\pi]$$

```
# Question 2.a

T = np.linspace(0, 2 * np.pi, 1001)

X = - np.cos(2 * T) * np.cos(T)
Y = - np.sin(2 * T) * np.cos(T)

plt.plot(X, Y)
plt.show()
```



Question 2.b

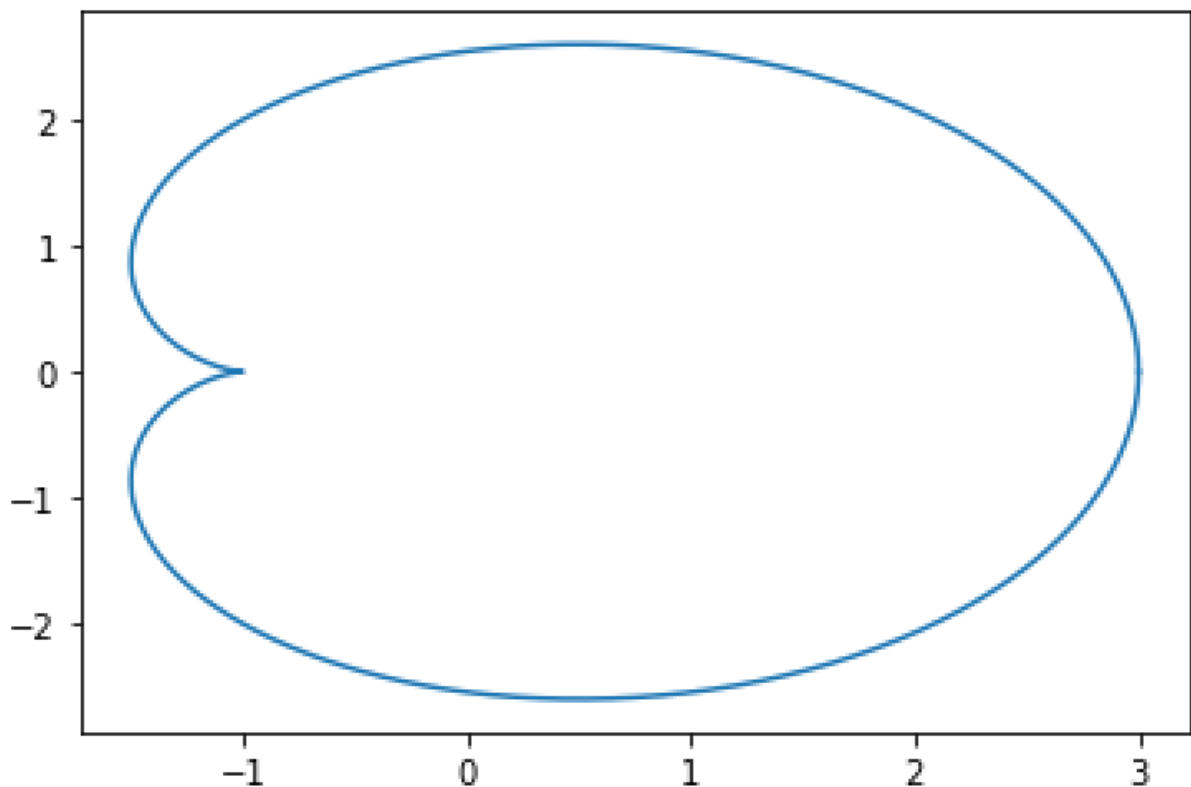
$$(b) \quad \begin{cases} x(t) = 2\cos(t) + \cos(2t) \\ y(t) = 2\sin(t) + \sin(2t) \end{cases} \quad t \in [0, 2\pi]$$

```
# Question 2.b

T = np.linspace(0, 2 * np.pi, 1001)

X = 2 * np.cos(T) + np.cos(2 * T)
Y = 2 * np.sin(T) + np.sin(2 * T)

plt.plot(X, Y)
plt.show()
```



Question 2.c

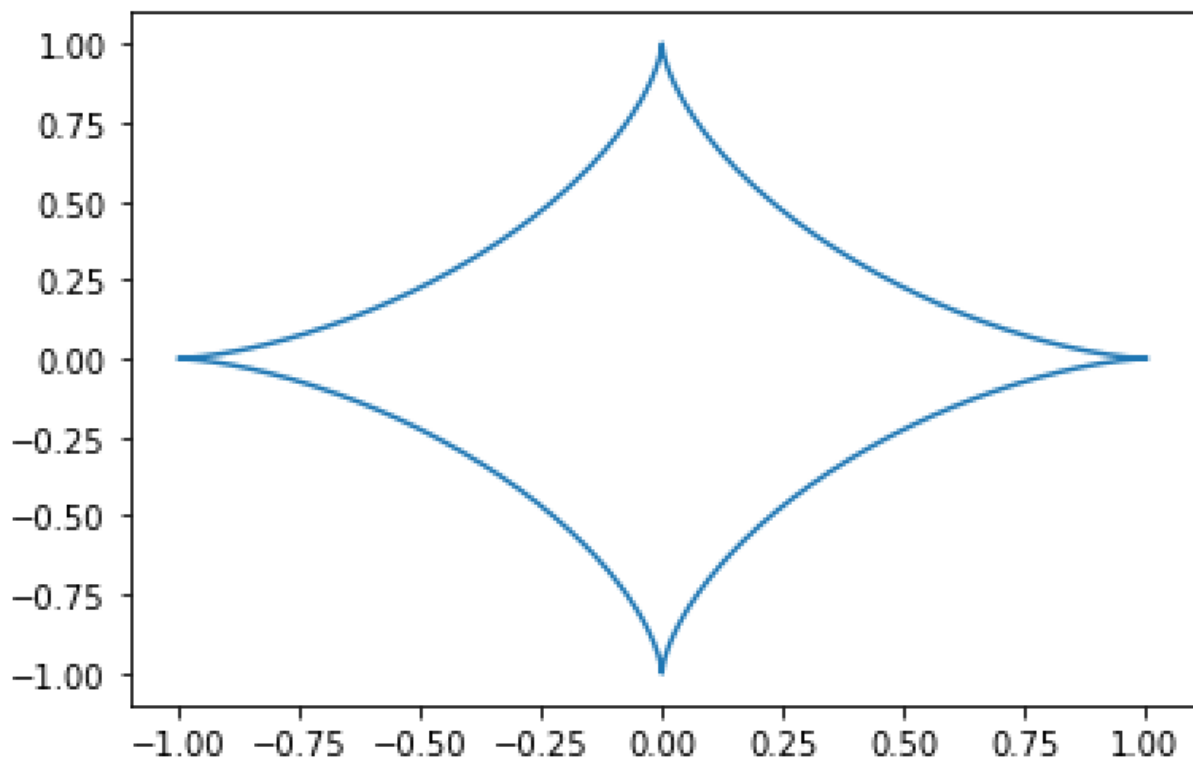
$$(c) \quad \begin{cases} x(t) = \cos^3(t) \\ y(t) = \sin^3(t) \end{cases} \quad t \in [0, 2\pi]$$

```
# Question 2.c

T = np.linspace(0, 2 * np.pi, 1001)

X = np.cos(T) ** 3
Y = np.sin(T) ** 3

plt.plot(X, Y)
plt.show()
```



Question 2.d

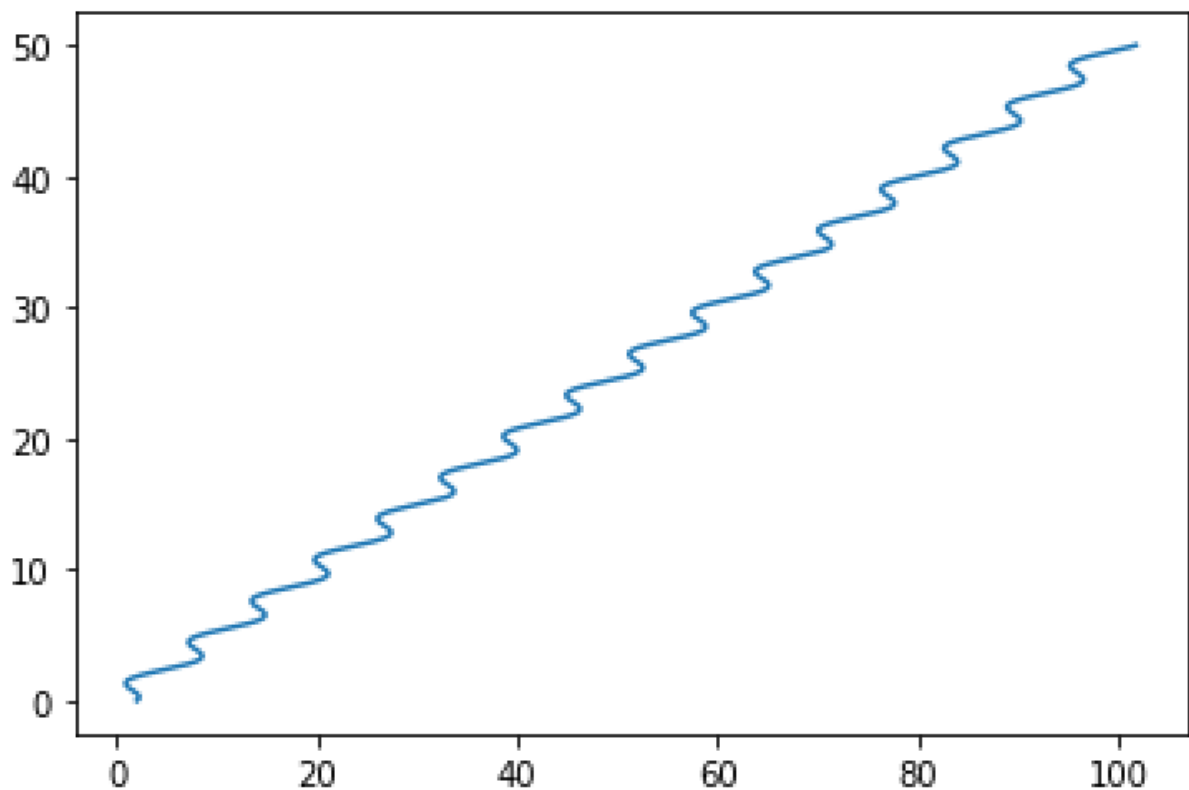
$$(d) \begin{cases} x(t) = t + 2\cos(t) \\ y(t) = \frac{1}{2}t \end{cases} \quad t \in [0, 100]$$

```
# Question 2.d

T = np.linspace(0, 100, 1001)

X = T + (2 * np.cos(T))
Y = 0.5 * T

plt.plot(X, Y)
plt.show()
```



Question 2.e

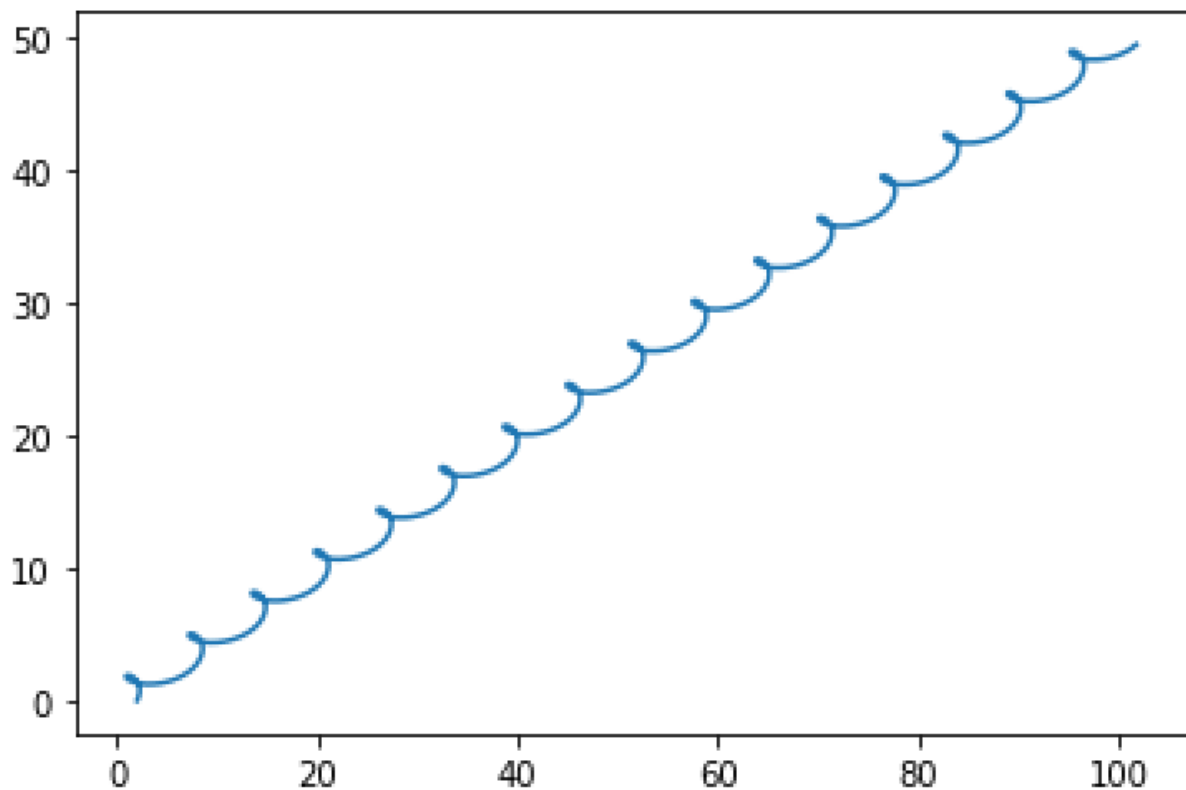
$$(e) \begin{cases} x(t) = t + 2\cos(t) \\ y(t) = \frac{1}{2}t + \sin(t) \end{cases} \quad t \in [0, 100]$$

```
# Question 2.e

T = np.linspace(0, 100, 1001)

X = T + (2 * np.cos(T))
Y = (0.5 * T) + np.sin(T)

plt.plot(X, Y)
plt.show()
```



Question 2.f

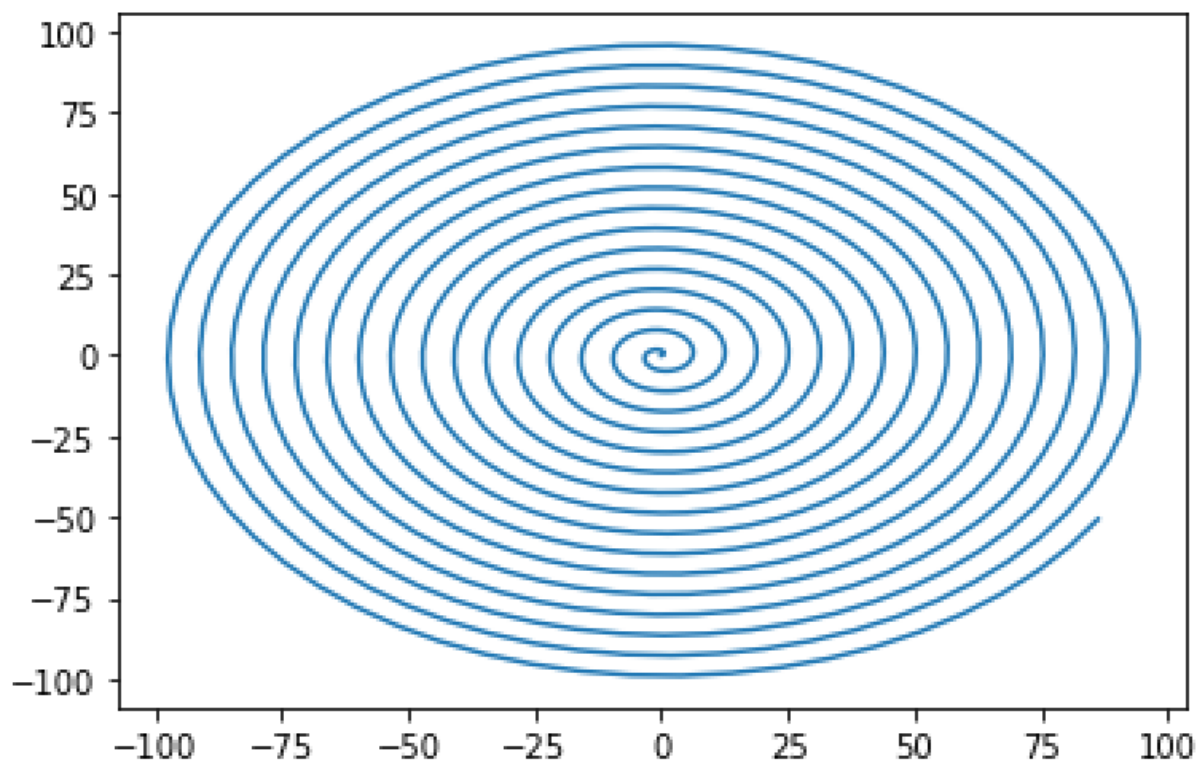
$$(f) \quad \begin{cases} x(t) = t \times \cos(t) \\ y(t) = t \times \sin(t) \end{cases} \quad t \in [0, 100]$$

```
# Question 2.f

T = np.linspace(0, 100, 1001)

X = T * np.cos(T)
Y = T * np.sin(T)

plt.plot(X, Y)
plt.show()
```



Partie 2

Question 1.a

$$\begin{aligned} M(r) &= \begin{cases} x(r) = x_0(1-3r+3r^2-r^3) + x_1(3r-6r^2+3r^3) + x_2(3r^2-3r^3) + x_3(r^3) \\ y(r) = y_0(1-3r+3r^2-r^3) + y_1(3r-6r^2+3r^3) + y_2(3r^2-3r^3) + y_3(r^3) \end{cases} \\ x(r) &= x_0 + r(-3x_0+3x_1) + r^2(3x_0-6x_1+3x_2) + r^3(-x_0+3x_1-3x_2+x_3) \end{aligned}$$

b) En lisant les polynômes précédents, on en déduit

$$B = \begin{pmatrix} 1 & -3 & 3 & -1 \\ 0 & 3 & -6 & 3 \\ 0 & 0 & 3 & -3 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Question 1.b

$$M(r) = P \times B \times \begin{pmatrix} 1 \\ r \\ r^2 \\ r^3 \end{pmatrix}$$

$$= P \times \begin{pmatrix} 1 & -3 & 3 & -1 \\ 0 & 3 & -6 & 3 \\ 0 & 0 & 3 & -3 \\ 0 & 0 & 0 & 1 \end{pmatrix} \times \begin{pmatrix} 1 \\ r \\ r^2 \\ r^3 \end{pmatrix}$$

$$= P \times \begin{pmatrix} 1 - 3r + 3r^2 - r^3 \\ 3r - 6r^2 + 3r^3 \\ 3r^2 - 3r^3 \\ r^3 \end{pmatrix}$$

$$= \begin{pmatrix} x_0 & x_1 & x_2 & x_3 \\ y_0 & y_1 & y_2 & y_3 \end{pmatrix} \times \begin{pmatrix} 1 - 3r + 3r^2 - 3r^3 \\ 3r - 6r^2 + 3r^3 \\ 3r^2 - 3r^3 \\ r^3 \end{pmatrix}$$

$$M(r) = \begin{pmatrix} x_0(1-3r+3r^2-3r^3) + x_1(3r-6r^2+3r^3) + x_2(3r^2-3r^3) + x_3 r^3 \\ y_0(1-3r+3r^2-3r^3) + y_1(3r-6r^2+3r^3) + y_2(3r^2-3r^3) + y_3 r^3 \end{pmatrix}$$

On retombe sur l'expression du début. Donc

$$M(r) = P \times B \times \begin{pmatrix} 1 \\ r \\ r^2 \\ r^3 \end{pmatrix}$$

avec P la matrice des 4 points A_0, A_1, A_2, A_3

$$\text{et } B = \begin{pmatrix} 1 & -3 & 3 & -1 \\ 0 & 3 & -6 & 3 \\ 0 & 0 & 3 & -3 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

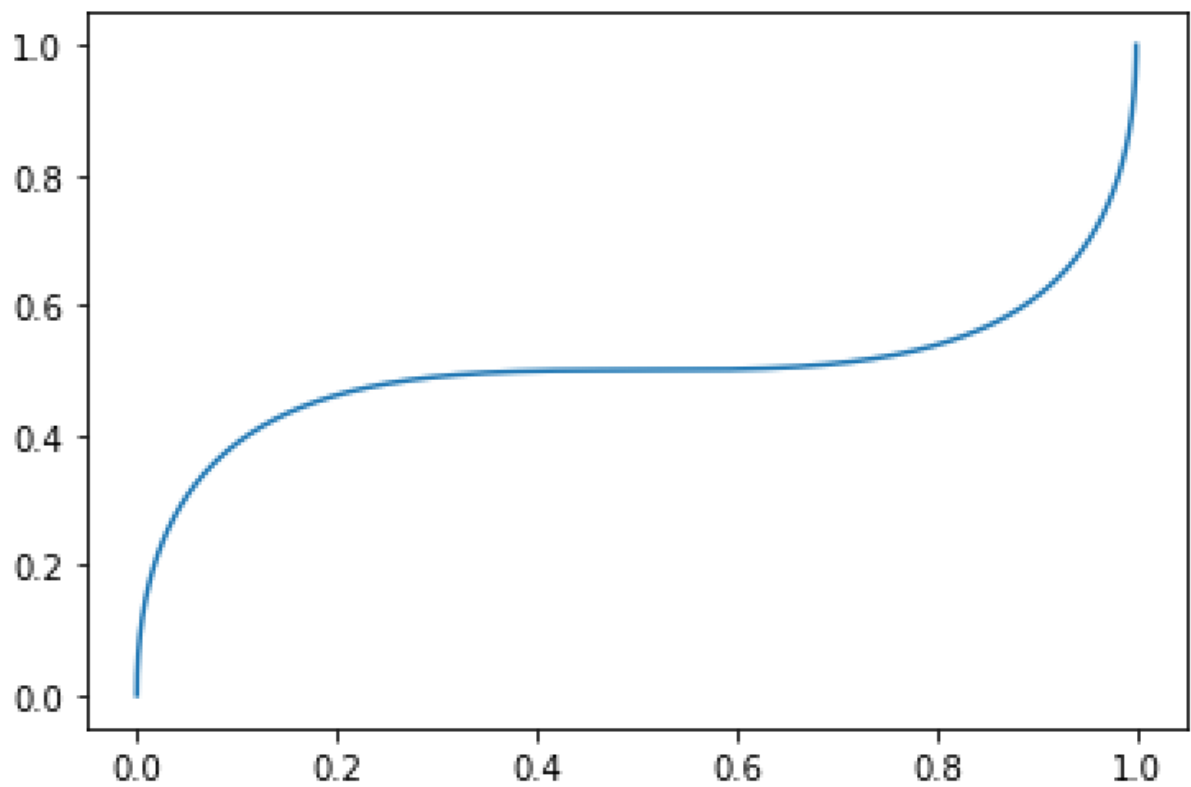
Question 2 (traceur)

```
def traceur (P):  
    B = np.array(  
        [[1, -3, 3, -1],  
         [0, 3, -6, 3],  
         [0, 0, 3, -3],  
         [0, 0, 0, 1]]  
    )  
  
    T = np.linspace(0, 1, 1001)  
  
    Vect = np.array([np.ones(1001), T, T**2, T**3])  
  
    res = np.dot(P, np.dot(B, Vect))  
  
    plt.plot(res[0,:], res[1, :])  
    return res;
```

Question 3.a

```
# Question 3.a
P = np.array(
    [[0., 0, 1, 1],
     [0, 1, 0, 1]]
)

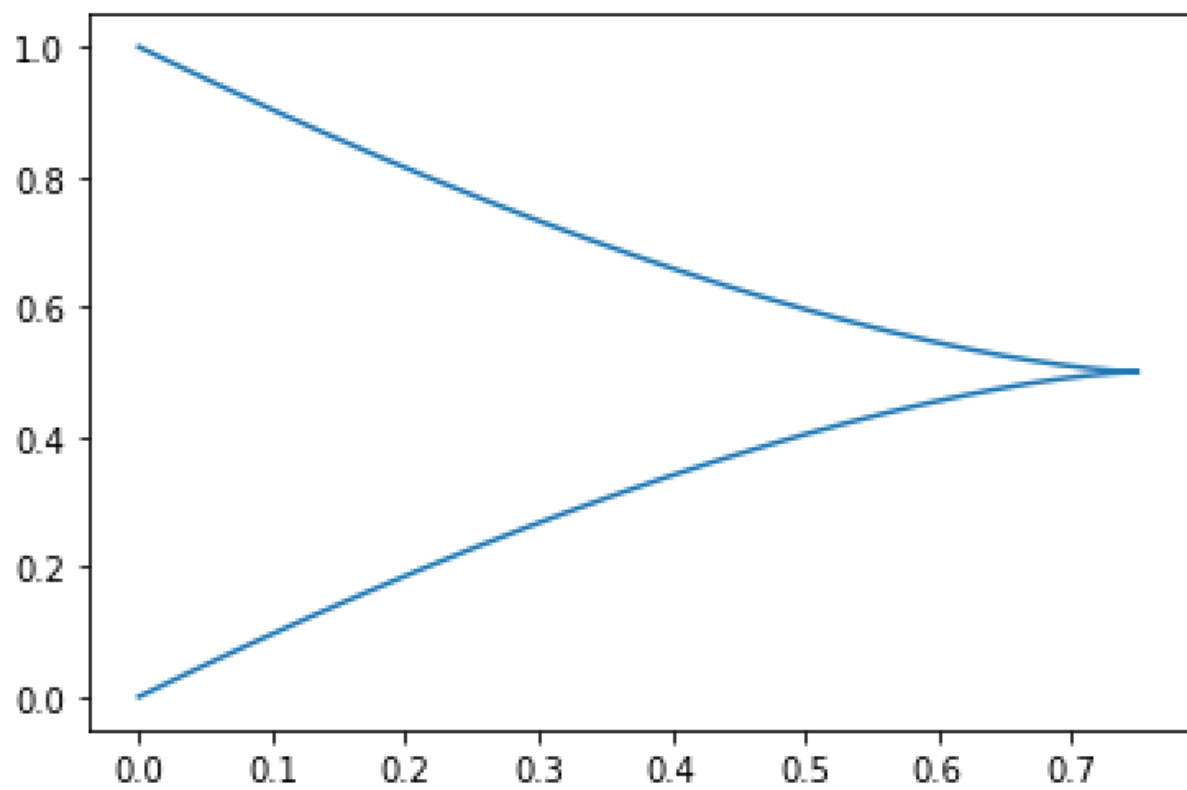
traceur(P)
plt.show()
```



Question 3.b

```
# Question 3.b
P = np.array(
    [[0., 1, 1, 0],
     [0, 1, 0, 1]]
)

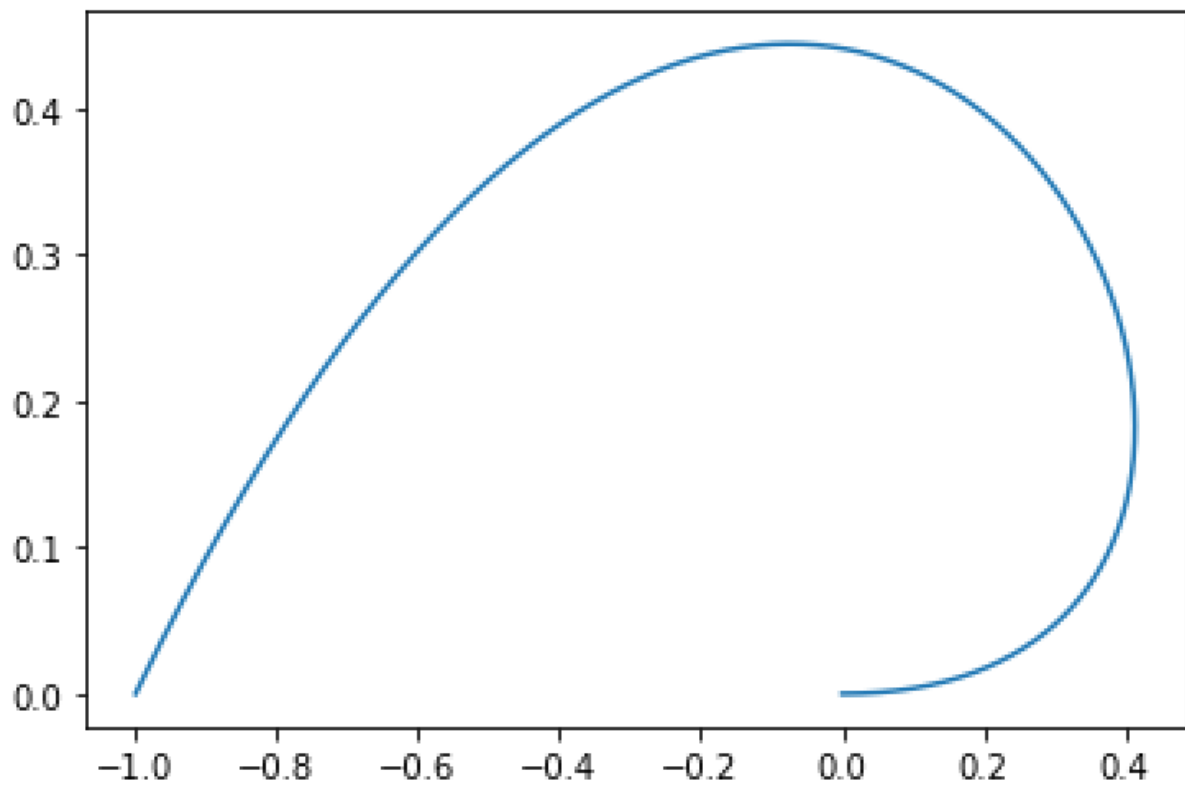
traceur(P)
plt.show()
```



Question 3.c

```
# Question 3.c
P = np.array(
    [[0., 1, 0, -1],
     [0, 0, 1, 0]]
)

traceur(P)
plt.show()
```



Question 3.d

```
# Question 3.d
P = np.array(
    [[0., 1, -3, -1],
     [0, 2, 2, 0]]
)

traceur(P)
plt.show()
```

