

Planarity

Given two positive integers n and m , construct a random simple graph with n vertices and m edges and determine whether the graph is planar. If it is, draw it in such a way that there are no crossing edges. If it is not, determine the thickness of the graph.

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- ▶ simple graph
- ▶ planarity
- ▶ plane graph
- ▶ thickness

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- ▶ planarity – a graph that is planar can be drawn such that no edges cross each other
- ▶ plane graph – the actual drawing
- ▶ thickness – the smallest number of planar graphs into which the edges of G can be partitioned

Al Gore Rhythms

- ▶ Planarity check
- ▶ Thickness algorithm
- ▶ Drawing algorithm
- ▶

AI Gore Rhythms

- ▶ Planarity check – we made a not-so-efficient algorithm
- ▶ Thickness algorithm
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AI Gore Rhythms

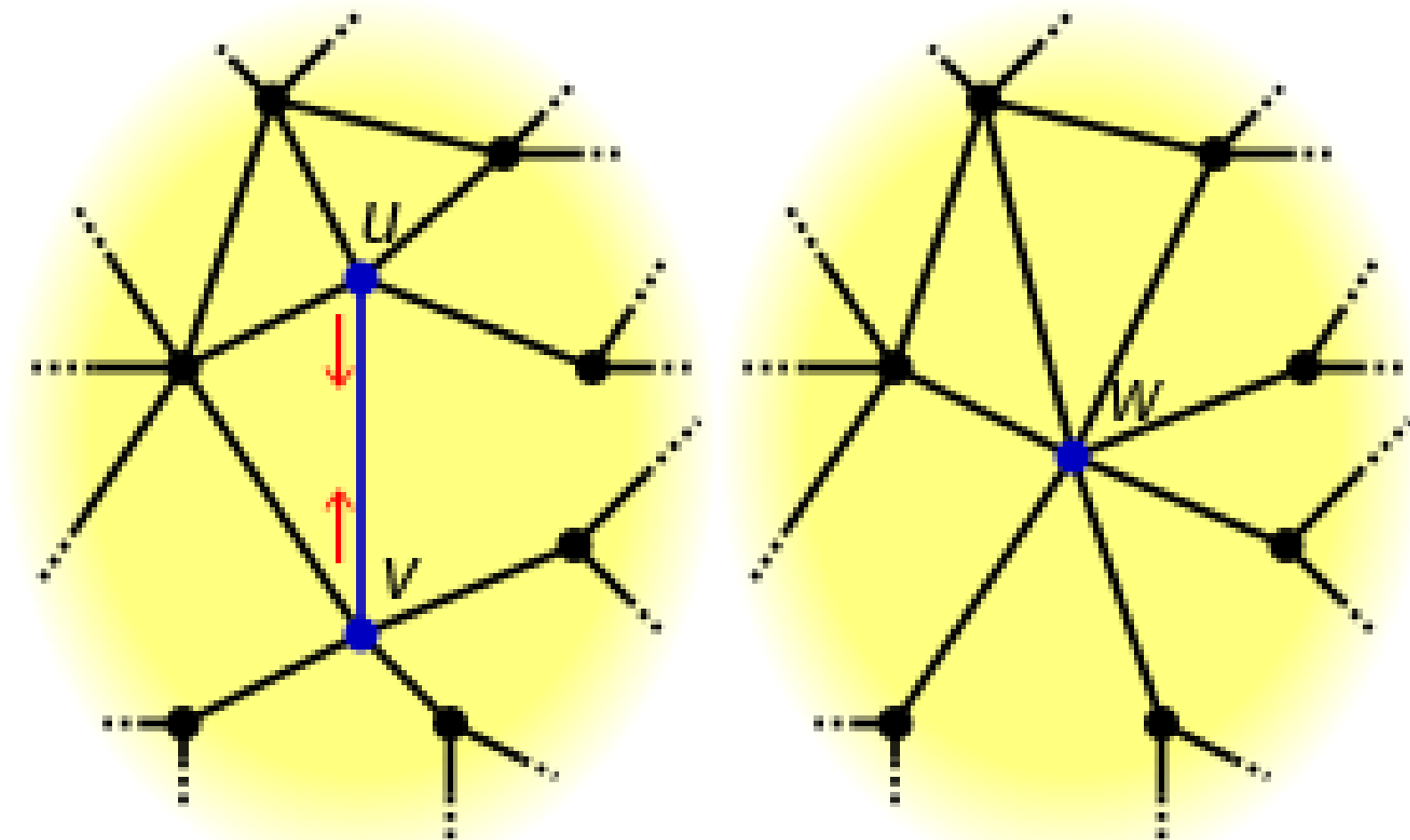
- ▶ Planarity check – we made a not-so-efficient algorithm
- ▶ Thickness algorithm – works on some graphs
- ▶ Drawing algorithm – we didn't write a drawing algorithm
- ▶ But we create did the script using libraries

Demo

Stellingen

- Een graaf is planair dan en slechts dan als hij niet ofwel K_5 of $K_{3,3}$ als *minor* heeft
- De minor H uit G is een graaf die uit G gemaakt kan worden door de volgende operaties:
 - Een edge verwijderen
 - Een vertex verwijderen
 - *Edge contraction*

Edge Contraction



Stellingen

- Een graaf is planair dan en slechts dan als al zijn *biconnected* componenten planair zijn
 - *Biconnected* betekend dat er geen enkele vertex kan worden weggehaald zodat de graaf niet meer *connected* is.

Stellingen

- Voor een planaire graaf met $v \geq 3$ geldt:
 $e < 3v - 6$
- Voor een planaire graaf met $v \geq 3$ zonder
cyclen van lengte 3 geldt: $e < 2v - 4$
- Voor v het aantal vertices en e het aantal edges

Algoritme

- Allereerst wordt de graaf gesplits in zijn *biconnected* componenten
- Voor ieder component wordt bepaald of het K_5 of $K_{3,3}$ als *minor* bevat
- Dit doen we door alle mogelijke *minors* af te gaan en te kijken of deze *isomorph* zijn aan K_5 of $K_{3,3}$
- $O(2^n)$

Algoritme

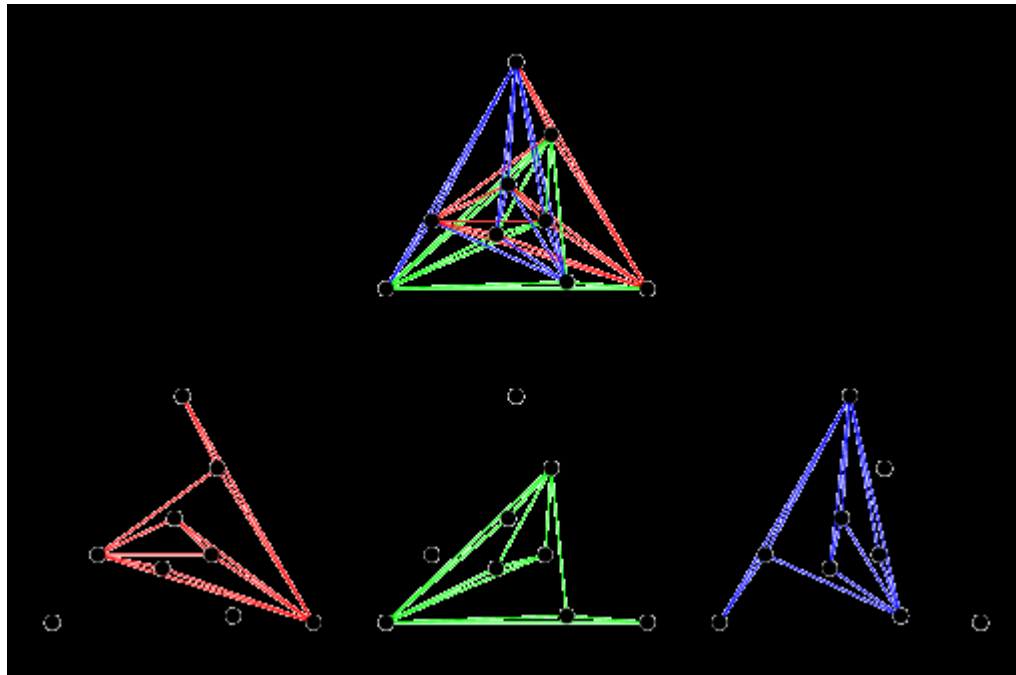
- We kunnen het algoritme nog optimalizeren:
- Wanneer de vergelijkingen $e < 3v - 6$ of $e < 2v - 4$ niet gelden voor een graaf, is de graaf niet planair
- Dus heeft de graaf K_5 of $K_{3,3}$ als *minor*
- Wanneer we dus een *minor* van G vinden waarvoor de vergelijkingen niet gelden, is G ook niet planair

Algoritme

- Dus gaan we eerst de *minors* proberen te maken uit G die zoveel mogelijk edges hebben met zo min mogelijk vertices
- Dus we proberen e te maximaliseren, en v te minimaliseren
- Is alleen sneller voor niet-planaire grafen, voor planaire grafen moeten nog steeds alle *minors* doorlopen worden

Thickness

- Kleinste aantal planaire deelgrafen waarin je de de edges van een graaf kan verdelen.



Thickness

- Eerste algoritme: complexiteit te groot

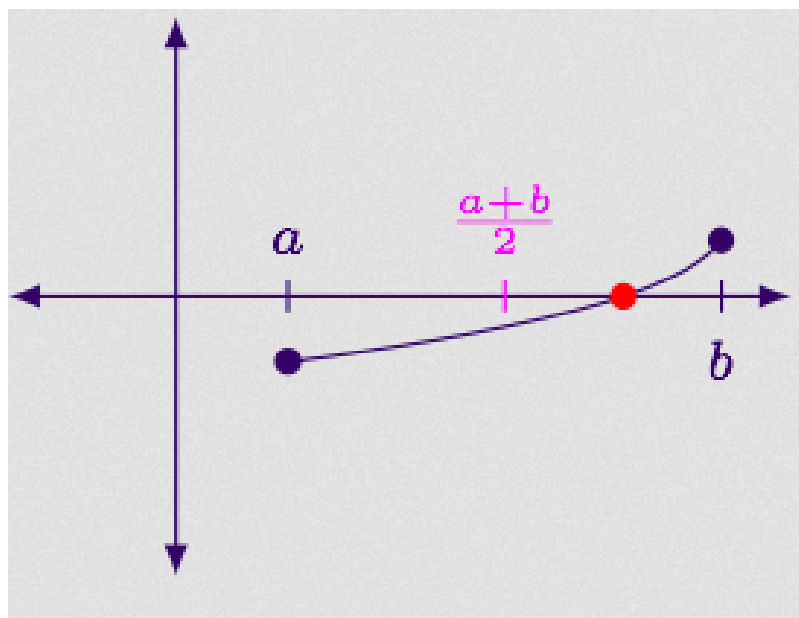
Thickness

- Eerste algoritme: complexiteit te groot

$$e(e!)^2(e^4 + n^2)$$

Thickness

Thickness-Bisection algoritme:



Thickness

Thickness-Bisection algoritme:

```
e          thickness is smaller than this
e-1        thickness is smaller than this
e-2 max,    thickness could be smaller than this
.          |
.          V
.          <- avg = (min + max) / 2
.          ^
.          |
3 min      thickness is larger than this
2          thickness is larger than this
1          thickness is larger than this
```

Thickness

Thickness-Bisection algoritme:

- Bepaal of de thickness groter of kleiner dan avg is:
 - Ga alle verdelingen van de graaf in avg delen af
 - Als je een verdeling hebt gevonden met allemaal panairre grafen, is de thickness kleiner dan of gelijk aan avg
 - Anders is de thickness groter dan avg

Thickness

- Testset: K_n , $K_{n,n}$, één vertex, wheel graph

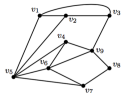
Demo bisection algoritme

Planarity decision algorithm

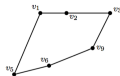
Demoucron, Malgrange and Pertuiset (1964)

Start with from a graph G

- ▶ Take from a graph G a subgraph H
- ▶ H is any cycle from G (so H is planar)
- ▶ We iteratively extend H to G
- ▶ We determine S , a set of
 - ▶ edge not in H but endpoints are in H
 - ▶ connected component in G , not in H , with the vertices of attachment
- ▶ We select a fragment S_i and a face which can accept S_i



Graph G

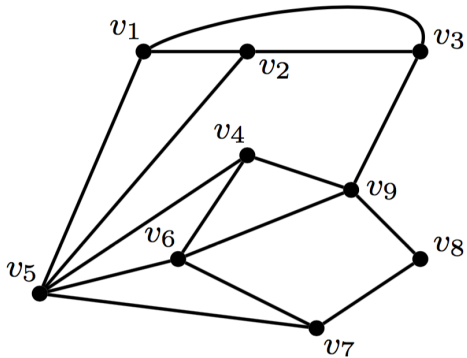


Subgraph H of G

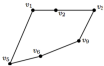
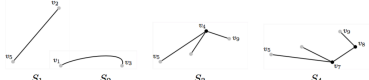
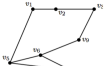
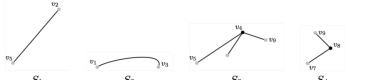
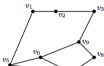
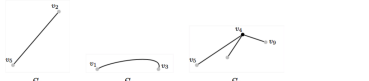
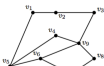
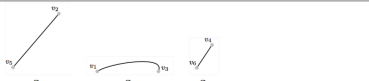


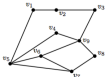
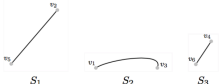
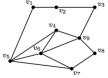
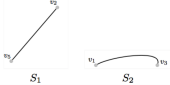
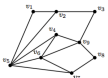

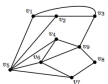
H -fragments

- 1. Choose a H
- 2. Compute all faces of H
- 3. Compute the fragments
- 4. If there are no fragments, the graph is planar
- 5. Compute admissible faces for fragments
- 6. If there is a fragment without an admissible face, the graph is not planar
- 7. If there is a fragment only one admissible face, embed it, go to 2
- 8. Chose a fragment and embed it



Graph G

	$F_1 = 1234965$ $F_2 = 1234965$		$F(S_1) = 1, 2$ $F(S_2) = 1, 2$ $F(S_3) = 1, 2$ $F(S_4) = 1, 2$
	$F_1 = 123965$ $F_2 = 567$ $F_3 = 1239675$		$F(S_1) = 1, 3$ $F(S_2) = 1, 3$ $F(S_3) = 1, 3$ $F(S_4) = 3 \text{ c}$
	$F_1 = 123965$ $F_2 = 567$ $F_3 = 6987$ $F_4 = 1239875$		$F(S_1) = 1, 4$ $F(S_2) = 1, 4$ $F(S_3) = 1$
	$F_1 = 123945$ $F_2 = 567$ $F_3 = 6987$ $F_4 = 5496$ $F_5 = 1239875$		$F(S_1) = 1, 5$ $F(S_2) = 1, 5$ $F(S_3) = 2$

	$F_1 = 123945$ $F_2 = 567$ $F_3 = 6987$ $F_4 = 5496$ $F_5 = 1239875$		$F(S_1) = 1, 5$ $F(S_2) = 1, 5$ $F(S_3) = 2$
	$F_1 = 123945$ $F_2 = 567$ $F_3 = 6987$ $F_4 = 465$ $F_5 = 496$ $F_6 = 1239875$		$F(S_1) = 1, 6$ $F(S_2) = 1, 6$
	$F_1 = 125$ $F_2 = 23945$ $F_3 = 567$ $F_4 = 6987$ $F_5 = 465$ $F_6 = 496$ $F_7 = 1239875$		$F(S_1) = 7$
	$F_1 = 125$ $F_2 = 23945$ $F_3 = 567$ $F_4 = 6987$ $F_5 = 465$ $F_6 = 496$ $F_7 = 123$ $F_8 = 139875$		