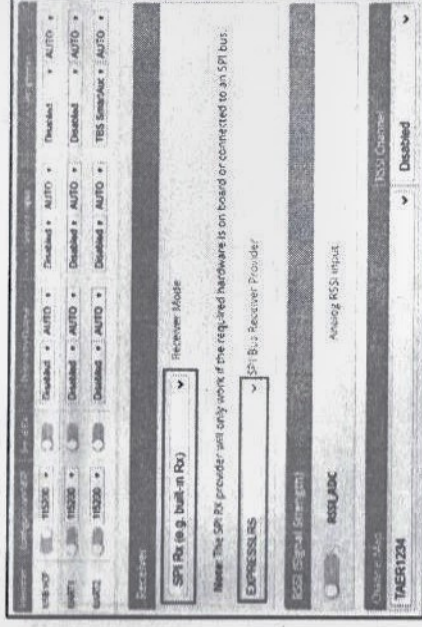


2. Turn on your radio transmitter and running ELRS LUA v2 version, scroll down the menu and hit [Bind]. The Red LED on the flight controller would get to be solid first and then start to blink slowly. it means bind successfully. Reconnect the USB and then you will find link was established.



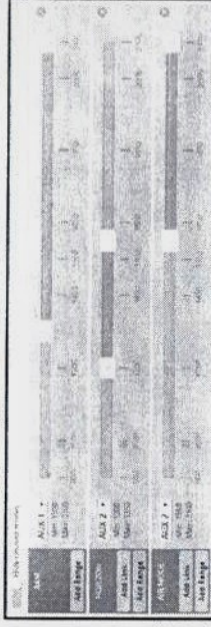
Receiver configuration

Please set Receiver mode to be SPI RX Support from the Configuration tab of the Betaflight Configurator, then select EXPRESSLRS from the SPI Bus Receiver Provider list. Don't enable Serial RX since the CRAZYBEE Flight controller is integrated SPI BUS Receiver.



Arm/Dismantling Motors

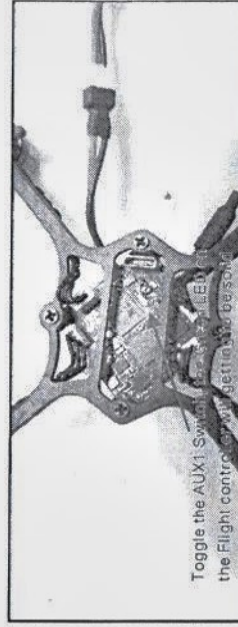
1. The Default mini/SSM switch for Cfx3 is AUX1 (Channel 5), and you can also customize it with Betaflight Configurator.



2. Turn on the Radio transmitter with ELURS TX module installed (Use TX16S as an example) and move to the MIXES interface. Set CH5 channel to "SE" or other aux channel to ARM/DISARM the motor



3. The default channel map for Crux3 ELHS version is TAER1234. Please make sure your transmitter is matched, otherwise it wouldn't be armed. Toggle the AUX1 Switch, the Green LED on the flight controller will getting to be solid, this indicates the motor was armed. And also you can found "Armed" notices displayed on your FPV Goggles or the FPV Monitor. Please make sure keep the Crux3 level before arming. Be careful and Happy flying!



40gram 1s brushless Toophook drone
AIO Flight controller with ELRS Receiver and 5.8G VTX
CADDX ANT Camera
New 1202.5 KV1 1500 brushless motor
Recommend to use 1s 450mah/650mah/660mah/720mah battery
Compatible with Caddx FV Peanut and Jia380 G02
Carrying Caddx peanut Got 4.5 minutes flying time with 1s 650mah battery

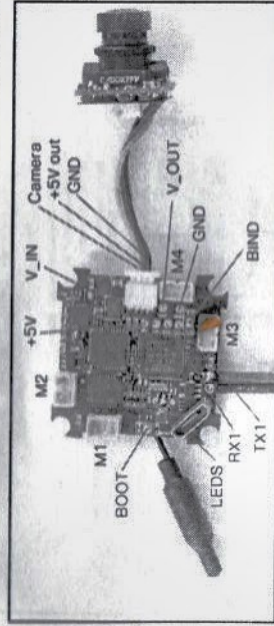
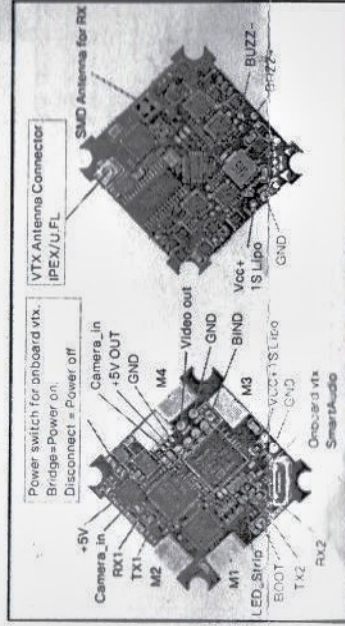
Specifications

Brand Name: Happymodel
Item Name: CruX3 15 ELRS
Wheelbase: 115mm
Size: 97mmx97mmx35mm (without propellers)
Weight: 40g(without battery)

Package Includes

Item Name	Qty
Cru3D Frame and canopy	1
ELRS F4 F4 flight controller built-in SPI Express RS 2.4G receiver	1
Happymodel EXI 202.5 KV1 1500 brushless motor	4
Genfan 75mm Bi-blade Propellers 4cw+4ccw	1
Caddox Ant 1200TVL Global WDR with OSD 2g Ultra Light Nano FPV Camera	1
5.6G 25mw-400mw 48ch vtx (Flight controller built-in)	1
Screw Driver	1
Propeller disassemble tool	1
3D Printed canopy for Insta360 GO2 and Caddox FPV Peanut	1
Happymodel Handbag	1

Flight controller connection diagram



Binding procedure

1. Plug USB to the flight controller and connect to Betaflight configurator. Go to the CLI command tab from Betaflight configurator then type "bind rx" or Go to Receiver tab from Betaflight configurator then hit "Bind Receiver", the red LED on the flight controller will blinking fast, that means the receiver is in bind mode.

Entering CLI Mode, type 'exit' to return, or 'help'

```
## Building AutoComplete Cache... Done!
```

