

## 内容小结

1. 隐函数(组) 存在定理
2. 隐函数 (组) 求导方法

方法1. 代公式

方法2. 利用复合函数求导法则直接计算；

方法3. 利用微分形式不变性；

定理3. 设函数  $F(x, y, u, v), G(x, y, u, v)$  满足:

① 在点  $P(x_0, y_0, u_0, v_0)$  的某一邻域内具有连续偏导数;

②  $F(x_0, y_0, u_0, v_0) = 0, G(x_0, y_0, u_0, v_0) = 0$ ;

③  $J \bigg|_P = \frac{\partial(F, G)}{\partial(u, v)} \bigg|_P \neq 0$

则方程组  $F(x, y, u, v) = 0, G(x, y, u, v) = 0$  在点  $(x_0, y_0)$  的某一邻域内可唯一确定一组满足条件  $u_0 = u(x_0, y_0), v_0 = v(x_0, y_0)$  的单值连续函数  $u = u(x, y), v = v(x, y)$ , 且有偏导数公式 :

$$\frac{\partial u}{\partial x} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(\underline{x}, v)} = -\frac{1}{\begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}} \begin{vmatrix} F_x & F_v \\ G_x & G_v \end{vmatrix}$$

$$\frac{\partial u}{\partial y} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(\underline{y}, v)} = -\frac{1}{\begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}} \begin{vmatrix} F_y & F_v \\ G_y & G_v \end{vmatrix}$$

$$\frac{\partial v}{\partial x} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(u, \underline{x})} = -\frac{1}{\begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}} \begin{vmatrix} F_u & F_x \\ G_u & G_x \end{vmatrix}$$

定理证明略.  
仅推导偏导  
数公式如下:

$$\frac{\partial v}{\partial y} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(u, \underline{y})} = -\frac{1}{\begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix}} \begin{vmatrix} F_u & F_y \\ G_u & G_y \end{vmatrix}$$

设方程组  $\begin{cases} F(x, y, u, v) = 0 \\ G(x, y, u, v) = 0 \end{cases}$  有隐函数组  $\begin{cases} u = u(x, y) \\ v = v(x, y) \end{cases}$ , 则

$$\begin{cases} F(x, y, u(x, y), v(x, y)) \equiv 0 \\ G(x, y, u(x, y), v(x, y)) \equiv 0 \end{cases}$$

两边对  $x$  求导得  $\begin{cases} F_x + F_u \cdot \frac{\partial u}{\partial x} + F_v \cdot \frac{\partial v}{\partial x} = 0 \\ G_x + G_u \cdot \frac{\partial u}{\partial x} + G_v \cdot \frac{\partial v}{\partial x} = 0 \end{cases}$

这是关于  $\frac{\partial u}{\partial x}, \frac{\partial v}{\partial x}$  的线性方程组, 在点  $P$  的某邻域内

系数行列式  $J = \begin{vmatrix} F_u & F_v \\ G_u & G_v \end{vmatrix} \neq 0$ , 故得

$$\frac{\partial u}{\partial x} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(x, v)}$$

$$\frac{\partial v}{\partial x} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(u, x)}$$

同样可得

$$\frac{\partial u}{\partial y} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(y, v)}$$

$$\frac{\partial v}{\partial y} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(u, y)}$$

例4. 设  $xu - yv = 0$ ,  $yu + xv = 1$ , 求  $\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x}, \frac{\partial v}{\partial y}$ .

解: 方程组两边对  $x$  求导, 并移项得

$$\begin{cases} x \frac{\partial u}{\partial x} - y \frac{\partial v}{\partial x} = -u \\ y \frac{\partial u}{\partial x} + x \frac{\partial v}{\partial x} = -v \end{cases}$$

由题设  $J = \begin{vmatrix} x & -y \\ y & x \end{vmatrix} = x^2 + y^2 \neq 0$

故有  $\begin{cases} \frac{\partial u}{\partial x} = \frac{1}{J} \begin{vmatrix} -u & -y \\ -v & x \end{vmatrix} = -\frac{xu + yv}{x^2 + y^2} \\ \frac{\partial v}{\partial x} = \frac{1}{J} \begin{vmatrix} x & -u \\ y & -v \end{vmatrix} = -\frac{xv - yu}{x^2 + y^2} \end{cases}$

练习: 求  $\frac{\partial u}{\partial y}, \frac{\partial v}{\partial y}$

答案:

$$\begin{cases} \frac{\partial u}{\partial y} = -\frac{yu - xv}{x^2 + y^2} \\ \frac{\partial v}{\partial y} = -\frac{xu + yv}{x^2 + y^2} \end{cases}$$

例. 设  $y = y(x)$ ,  $z = z(x)$  是由方程  $z = xf(x+y)$  和  $F(x, y, z) = 0$  所确定的函数, 求  $\frac{dz}{dx}$ . (99 考研)

$$\text{解法一: } \begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = z - xf(x+y) = 0 \end{cases}$$

$$\therefore \frac{dz}{dx} = - \frac{\partial(F, G) / \partial(y, x)}{\partial(F, G) / \partial(y, z)}$$

$$= - \frac{\begin{vmatrix} F_y & F_x \\ -xf' & -f - xf' \end{vmatrix}}{\begin{vmatrix} F_y & F_z \\ -xf' & 1 \end{vmatrix}} = \frac{(f + xf')F_y - xf' \cdot F_x}{F_y + xf' \cdot F_z}$$

解法二： 微分法.

$$z = xf(x+y), \quad F(x, y, z) = 0$$

对方程两边分别求微分:

$$\begin{cases} dz = f dx + x f' \cdot (dx + dy) \\ F_1 dx + F_2 dy + F_3 dz = 0 \end{cases}$$

化简得

$$\begin{cases} (f + x f') dx + x f' dy - dz = 0 \\ F_1 dx + F_2 dy + F_3 dz = 0 \end{cases}$$

消去  $dy$  可得  $\frac{dz}{dx}$ .



例5. 设函数  $x = x(u, v)$ ,  $y = y(u, v)$  在点  $(u, v)$  的某一邻域内有连续的偏导数, 且  $\frac{\partial(x, y)}{\partial(u, v)} \neq 0$

1) 证明函数组  $\begin{cases} x = x(u, v) \\ y = y(u, v) \end{cases}$  在与点  $(u, v)$  对应的点  $(x, y)$  的某一邻域内唯一确定一组单值、连续且具有连续偏导数的反函数  $u = u(x, y)$ ,  $v = v(x, y)$ .

2) 求  $u = u(x, y)$ ,  $v = v(x, y)$  对  $x, y$  的偏导数并证明

$$\frac{\partial(u, v)}{\partial(x, y)} \cdot \frac{\partial(x, y)}{\partial(u, v)} = 1$$

解: 1) 令  $F(x, y, u, v) \equiv x - x(u, v) = 0$

$$G(x, y, u, v) \equiv y - y(u, v) = 0$$

则有 
$$J = \frac{\partial(F, G)}{\partial(u, v)} = \frac{\partial(x, y)}{\partial(u, v)} \neq 0,$$

由定理 3 可知结论 1) 成立.

2) 求反函数的偏导数.

$$\frac{\partial u}{\partial x} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(x, v)} = -\frac{1}{J} \begin{vmatrix} 1 & -\frac{\partial x}{\partial v} \\ 0 & -\frac{\partial y}{\partial v} \end{vmatrix} = \frac{1}{J} \frac{\partial y}{\partial v}$$

$$\frac{\partial u}{\partial y} = -\frac{1}{J} \frac{\partial(F, G)}{\partial(y, v)} = -\frac{1}{J} \begin{vmatrix} 0 & -\frac{\partial x}{\partial v} \\ 1 & -\frac{\partial y}{\partial v} \end{vmatrix} = -\frac{1}{J} \frac{\partial x}{\partial v}$$

同理,

$$\frac{\partial v}{\partial x} = -\frac{1}{J} \frac{\partial y}{\partial u}, \frac{\partial v}{\partial y} = \frac{1}{J} \frac{\partial x}{\partial u}$$

$$\frac{\partial(u, v)}{\partial(x, y)} = \begin{vmatrix} \frac{1}{J} \frac{\partial y}{\partial v} & -\frac{1}{J} \frac{\partial x}{\partial v} \\ -\frac{1}{J} \frac{\partial y}{\partial u} & \frac{1}{J} \frac{\partial x}{\partial u} \end{vmatrix} = \frac{1}{J}$$

$$\therefore \frac{\partial(u, v)}{\partial(x, y)} \cdot \frac{\partial(x, y)}{\partial(u, v)} = 1$$

## 内容小结

### 2. 隐函数 (组) 求导方法

方法1. 代公式

方法2. 利用复合函数求导法则直接计算；

方法3. 利用微分形式不变性；

## 思考与练习

设  $z = f(x + y + z, xyz)$ , 求  $\frac{\partial z}{\partial x}$ ,  $\frac{\partial x}{\partial z}$ ,  $\frac{\partial x}{\partial y}$ .

解法一:

$$z = f(x + y + z, xyz)$$

$$\text{令 } F(x, y, z) = z - f(x + y + z, xyz)$$

$$F_x = -f_1 - yzf_2$$

$$F_y = -f_1 - xzf_2$$

$$F_z = 1 - f_1 - xyf_3$$

$$\implies \frac{\partial z}{\partial x} = \frac{f_1 + yzf_2}{1 - f_1 - xyf_3} \quad \frac{\partial x}{\partial z} = \frac{1 - f_1 - xyf_3}{f_1 + yzf_2}$$

$$\frac{\partial x}{\partial y} = -\frac{f_1 + xzf_2}{f_1 + yzf_2}$$

解法二:  $z = f(x + y + z, xyz)$

$$\begin{aligned} \bullet \quad \frac{\partial z}{\partial x} &= f_1 \cdot \left(1 + \frac{\partial z}{\partial x}\right) + f_2 \cdot \left(yz + xy \frac{\partial z}{\partial x}\right) \\ &\implies \frac{\partial z}{\partial x} = \frac{f_1 + yzf_2}{1 - f_1 - xyf_2} \end{aligned}$$

$$\begin{aligned} \bullet \quad 1 &= f_1 \cdot \left(\frac{\partial x}{\partial z} + 1\right) + f_2 \cdot \left(yz \frac{\partial x}{\partial z} + xy\right) \\ &\implies \frac{\partial x}{\partial z} = \frac{1 - f_1 - xyf_2}{f_1 + yzf_2} \end{aligned}$$

$$\begin{aligned} \bullet \quad 0 &= f_1 \cdot \left(\frac{\partial x}{\partial y} + 1\right) + f_2 \cdot \left(yz \frac{\partial x}{\partial y} + xz\right) \\ &\implies \frac{\partial x}{\partial y} = -\frac{f_1 + xzf_2}{f_1 + yzf_2} \end{aligned}$$

解法三. 利用全微分形式不变性同时求出各偏导数.

$$z = f(x + y + z, xyz)$$

$$dz = f_1 \cdot (dx + dy + dz) + f_2 \cdot (yz dx + xz dy + xy dz)$$

解出  $dx$ :

$$dx = \frac{-(f_1 + xzf_2)dy + (1 - f_1 - xyf_2)dz}{f_1 + yzf_2}$$

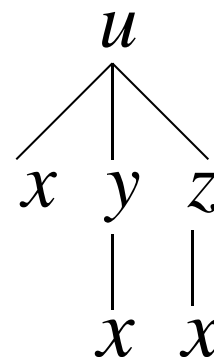
由  $dy, dz$  的系数即可得  $\frac{\partial x}{\partial y}, \frac{\partial x}{\partial z}$ .

备用题 1. 设  $u = f(x, y, z)$  有连续的一阶偏导数，  
又函数  $y = y(x)$  及  $z = z(x)$  分别由下列两式确定：

$e^{xy} - xy = 2$ ,  $e^x = \int_0^{x-z} \frac{\sin t}{t} dt$ , 求  $\frac{du}{dx}$ . (2001考研)

解：两个隐函数方程两边对  $x$  求导，得

$$\begin{cases} e^{xy}(y + xy') - (y + xy') = 0 \\ e^x = \frac{\sin(x-z)}{x-z} (1-z') \end{cases}$$



解得  $y' = -\frac{y}{x}, \quad z' = 1 - \frac{e^x(x-z)}{\sin(x-z)}$

因此  $\frac{du}{dx} = f_1 - \frac{y}{x} f_2 + \left[ 1 - \frac{e^x(x-z)}{\sin(x-z)} \right] f_3$



## 第六节

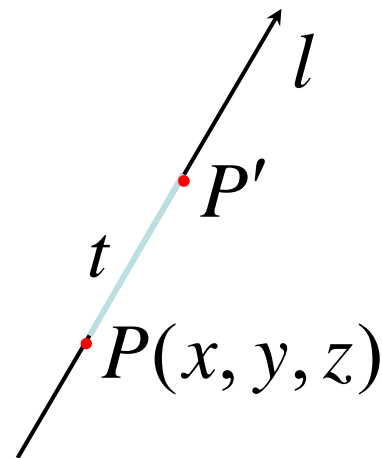
# 方向导数与梯度

一、方向导数

二、梯度

## 一、方向导数

定义: 若函数  $f(x, y, z)$  在点  $P(x, y, z)$  处沿方向  $l$  (方向角为  $\alpha, \beta, \gamma$ ) 存在下列极限:



$$\lim_{t \rightarrow 0^+} \frac{\Delta f}{t}$$

$$= \lim_{t \rightarrow 0^+} \frac{f(x + t \cos \alpha, y + t \cos \beta, z + t \cos \gamma) - f(x, y, z)}{t}$$

记作  $\frac{\partial f}{\partial l}$

则称  $\frac{\partial f}{\partial l}$  为函数在点  $P$  处沿方向  $l$  的方向导数.

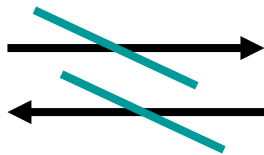
对于二元函数  $f(x, y)$ , 在点  $P(x, y)$  处沿方向  $l$  (方向角为  $\alpha, \beta$ ) 的方向导数定义为

$$\frac{\partial f}{\partial l} = \lim_{t \rightarrow 0^+} \frac{f(x + t \cos \alpha, y + t \cos \beta) - f(x, y)}{t}$$

注意方向导数是单侧极限，与偏导数有所区别。  
当偏导数存在时，

- 当  $l$  与  $x$  轴同向 ( $\alpha = 0, \beta = \frac{\pi}{2}$ ) 时, 有  $\frac{\partial f}{\partial l} = \frac{\partial f}{\partial x}$
- 当  $l$  与  $x$  轴反向 ( $\alpha = \pi, \beta = \frac{\pi}{2}$ ) 时, 有  $\frac{\partial f}{\partial l} = -\frac{\partial f}{\partial x}$

同样，沿  $y$  轴正方向的方向导数为  $\frac{\partial f}{\partial y}$ , 负方向为  $-\frac{\partial f}{\partial y}$ 。

- 方向导数存在  偏导数存在

反例(1)  $z = \sqrt{x^2 + y^2}$

反例(2)  $z = f(x, y) = \begin{cases} \frac{xy}{x^2 + y^2}, & x^2 + y^2 \neq 0 \\ 0, & x^2 + y^2 = 0 \end{cases}$

定理：若函数  $f(x, y, z)$  在点  $P(x, y, z)$  处可微，  
则函数在该点沿任意方向  $l$  的方向导数存在，且有

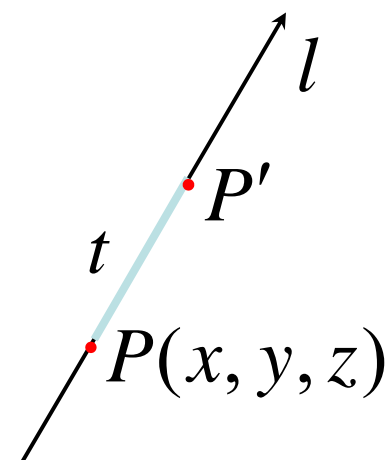
$$\frac{\partial f}{\partial l} = \frac{\partial f}{\partial x} \cos \alpha + \frac{\partial f}{\partial y} \cos \beta + \frac{\partial f}{\partial z} \cos \gamma$$

其中  $\alpha, \beta, \gamma$  为  $l$  的方向角.

证明：由函数  $f(x, y, z)$  在点  $P$  可微，得

$$\begin{aligned} \Delta f &= \frac{\partial f}{\partial x} \Delta x + \frac{\partial f}{\partial y} \Delta y + \frac{\partial f}{\partial z} \Delta z + o(\rho) \\ &= t \left( \frac{\partial f}{\partial x} \cos \alpha + \frac{\partial f}{\partial y} \cos \beta + \frac{\partial f}{\partial z} \cos \gamma \right) + o(\rho) \end{aligned}$$

故 
$$\frac{\partial f}{\partial l} = \lim_{t \rightarrow 0^+} \frac{\Delta f}{t} = \frac{\partial f}{\partial x} \cos \alpha + \frac{\partial f}{\partial y} \cos \beta + \frac{\partial f}{\partial z} \cos \gamma$$



类似地，对于二元函数的情形，若函数 $f(x, y)$ 在点 $P(x, y)$ 可微，则在该点处沿方向 $l$ (方向角为 $\alpha, \beta$ )的方向导数为

$$\frac{\partial f}{\partial l} = f_x(x, y) \cos \alpha + f_y(x, y) \cos \beta$$

• 可微  方向导数存在

反例  $z = \sqrt{x^2 + y^2}$