

内容小结

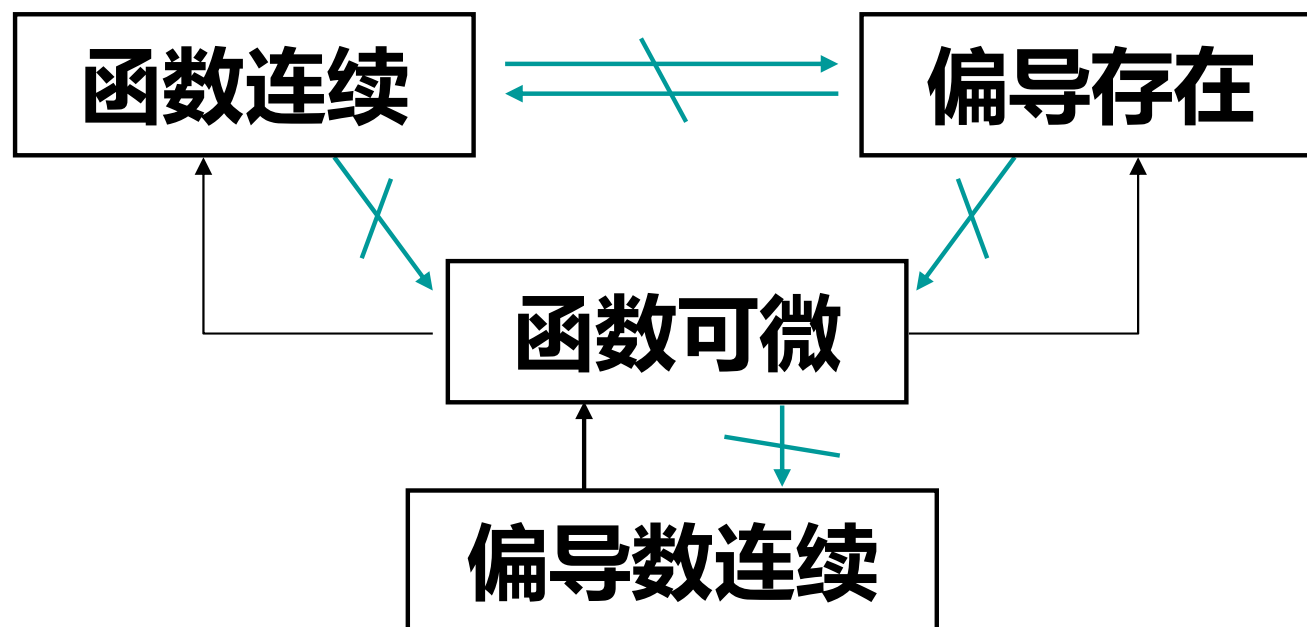
1. 微分定义: ($z = f(x, y)$)

$$\Delta z = \underline{f_x(x, y)\Delta x + f_y(x, y)\Delta y} + o(\rho)$$

$$\rho = \sqrt{(\Delta x)^2 + (\Delta y)^2}$$

$$dz = f_x(x, y)dx + f_y(x, y)dy$$

2. 重要关系:



思考与练习

1. 选择题

函数 $z = f(x, y)$ 在 (x_0, y_0) 可微的充分条件是(D)

(A) $f(x, y)$ 在 (x_0, y_0) 连续;

(B) $f_x(x, y), f_y(x, y)$ 在 (x_0, y_0) 的某邻域内存在;

(C) $\Delta z - f_x(x, y)\Delta x - f_y(x, y)\Delta y$

当 $\sqrt{(\Delta x)^2 + (\Delta y)^2} \rightarrow 0$ 时是无穷小量;

(D) $\frac{\Delta z - f_x(x, y)\Delta x - f_y(x, y)\Delta y}{\sqrt{(\Delta x)^2 + (\Delta y)^2}}$

当 $\sqrt{(\Delta x)^2 + (\Delta y)^2} \rightarrow 0$ 时是无穷小量.

2. 设 $f(x, y, z) = \frac{x \cos y + y \cos z + z \cos x}{1 + \cos x + \cos y + \cos z}$, 求 $df|_{(0,0,0)}$.

解: $\because f(x, 0, 0) = \frac{x}{3 + \cos x}$

$$\therefore f_x(0, 0, 0) = \left(\frac{x}{3 + \cos x} \right)' \Big|_{x=0} = \frac{1}{4}$$

利用轮换对称性, 可得

$$f_y(0, 0, 0) = f_z(0, 0, 0) = \frac{1}{4}$$

$$\begin{aligned} \therefore df|_{(0,0,0)} &= f_x(0, 0, 0) dx + f_y(0, 0, 0) dy + f_z(0, 0, 0) dz \\ &= \frac{1}{4}(dx + dy + dz) \end{aligned}$$

例 试证函数

$$f(x, y) = \begin{cases} xy \sin \frac{1}{\sqrt{x^2 + y^2}}, & (x, y) \neq (0, 0) \\ 0, & (x, y) = (0, 0) \end{cases} \text{在}$$

点 $(0,0)$ 连续且偏导数存在, 但偏导数在点 $(0,0)$ 不连续, 而 f 在点 $(0,0)$ 可微.

思路: 按有关定义讨论; 对于偏导数需分
 $(x, y) \neq (0, 0)$, $(x, y) = (0, 0)$ 讨论.

证 令 $x = \rho \cos \theta, y = \rho \sin \theta,$

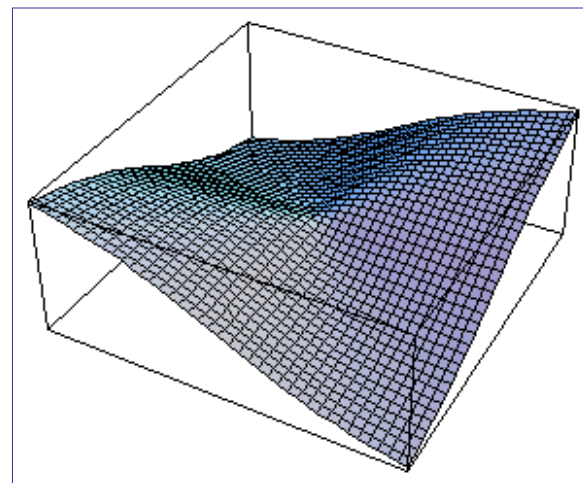
则
$$\lim_{(x,y) \rightarrow (0,0)} xy \sin \frac{1}{\sqrt{x^2 + y^2}}$$

$$= \lim_{\rho \rightarrow 0} \rho^2 \sin \theta \cos \theta \cdot \sin \frac{1}{\rho} = 0 = f(0,0),$$

故函数在点 $(0,0)$ 连续,

$$f_x(0,0) = \lim_{\Delta x \rightarrow 0} \frac{f(\Delta x, 0) - f(0,0)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{0 - 0}{\Delta x} = 0,$$

同理 $f_y(0,0) = 0.$



当 $(x, y) \neq (0, 0)$ 时,

$$f_x(x, y) = y \sin \frac{1}{\sqrt{x^2 + y^2}} - \frac{x^2 y}{\sqrt{(x^2 + y^2)^3}} \cos \frac{1}{\sqrt{x^2 + y^2}},$$

当点 $P(x, y)$ 沿直线 $y = x$ 趋于 $(0, 0)$ 时,

$$\lim_{(x, x) \rightarrow (0, 0)} f_x(x, y)$$

$$= \lim_{x \rightarrow 0} \left(x \sin \frac{1}{\sqrt{2} |x|} - \frac{x^3}{2\sqrt{2} |x|^3} \cos \frac{1}{\sqrt{2} |x|} \right),$$

不存在.

所以 $f_x(x, y)$ 在 $(0,0)$ 不连续.

同理可证 $f_y(x, y)$ 在 $(0,0)$ 不连续.

$$\begin{aligned}\Delta f &= f(\Delta x, \Delta y) - f(0,0) \\ &= \Delta x \cdot \Delta y \cdot \sin \frac{1}{\sqrt{(\Delta x)^2 + (\Delta y)^2}} \\ &= o(\sqrt{(\Delta x)^2 + (\Delta y)^2})\end{aligned}$$

故 $f(x, y)$ 在点 $(0,0)$ 可微 $df|_{(0,0)} = 0$.

*二、全微分在数值计算中的应用

1. 近似计算

由全微分定义

$$\Delta z = \underbrace{f_x(x, y)\Delta x + f_y(x, y)\Delta y}_{dz} + o(\rho)$$

可知当 $|\Delta x|$ 及 $|\Delta y|$ 较小时, 有近似等式:

$$\Delta z \approx dz = f_x(x, y)\Delta x + f_y(x, y)\Delta y$$

(可用于近似计算; 误差分析)

$$f(x + \Delta x, y + \Delta y) \approx f(x, y) + f_x(x, y)\Delta x + f_y(x, y)\Delta y$$

(可用于近似计算)

例3.计算 $1.04^{2.02}$ 的近似值.

解: 设 $f(x, y) = x^y$, 则

$$f_x(x, y) = y x^{y-1}, \quad f_y(x, y) = x^y \ln x$$

取 $x = 1, y = 2, \Delta x = 0.04, \Delta y = 0.02$

则 $1.04^{2.02} = f(1.04, 2.02)$

$$\approx f(1, 2) + f_x(1, 2)\Delta x + f_y(1, 2)\Delta y$$

$$= 1 + 2 \times 0.04 + 0 \times 0.02 = 1.08$$

2. 误差估计

利用 $\Delta z \approx f_x(x, y)\Delta x + f_y(x, y)\Delta y$

令 $\delta_x, \delta_y, \delta_z$ 分别表示 x, y, z 的绝对误差界, 则

z 的绝对误差界约为

$$\delta_z = |f_x(x, y)|\delta_x + |f_y(x, y)|\delta_y$$

z 的相对误差界约为

$$\frac{\delta_z}{|z|} = \left| \frac{f_x(x, y)}{f(x, y)} \right| \delta_x + \left| \frac{f_y(x, y)}{f(x, y)} \right| \delta_y$$

第四节

多元复合函数的求导法则

一元复合函数 $y = f(u), u = \varphi(x)$

求导法则 $\frac{dy}{dx} = \frac{dy}{du} \cdot \frac{du}{dx}$

微分法则 $dy = f'(u) du = f'(u) \varphi'(x) dx$

本节内容:

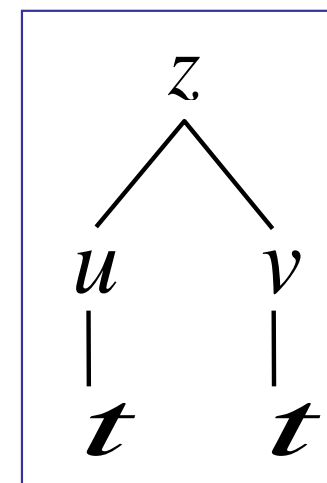
一、多元复合函数求导的链式法则

二、多元复合函数的全微分

一、多元复合函数求导的链式法则

定理. 若函数 $u = \varphi(t)$, $v = \psi(t)$ 在点 t 可导, $z = f(u, v)$ 在点 (u, v) 处可微, 则复合函数 $z = f(\varphi(t), \psi(t))$ 在点 t 可导, 且有链式法则

$$\frac{dz}{dt} = \frac{\partial z}{\partial u} \cdot \frac{du}{dt} + \frac{\partial z}{\partial v} \cdot \frac{dv}{dt}$$



证: 设 t 取增量 Δt , 则相应中间变量有增量 $\Delta u, \Delta v$,

$$\Delta z = \frac{\partial z}{\partial u} \Delta u + \frac{\partial z}{\partial v} \Delta v + o(\rho) \quad (\rho = \sqrt{(\Delta u)^2 + (\Delta v)^2})$$

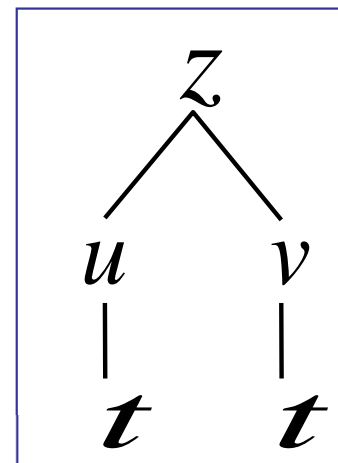
$$\frac{\Delta z}{\Delta t} = \frac{\partial z}{\partial u} \frac{\Delta u}{\Delta t} + \frac{\partial z}{\partial v} \frac{\Delta v}{\Delta t} + \frac{o(\rho)}{\Delta t} \quad (\rho = \sqrt{(\Delta u)^2 + (\Delta v)^2})$$

令 $\Delta t \rightarrow 0$, 则有 $\Delta u \rightarrow 0$, $\Delta v \rightarrow 0$,

$$\frac{\Delta u}{\Delta t} \rightarrow \frac{du}{dt}, \quad \frac{\Delta v}{\Delta t} \rightarrow \frac{dv}{dt}$$

$$\frac{o(\rho)}{\Delta t} = \frac{o(\rho)}{\rho} \sqrt{\left(\frac{\Delta u}{\Delta t}\right)^2 + \left(\frac{\Delta v}{\Delta t}\right)^2} \rightarrow 0$$

($\Delta t < 0$ 时, 根式前加 “-” 号)



$$\frac{dz}{dt} = \frac{\partial z}{\partial u} \cdot \frac{du}{dt} + \frac{\partial z}{\partial v} \cdot \frac{dv}{dt}$$

(全导数公式)

说明: 若定理中 $f(u, v)$ 在点 (u, v) **可微**减弱为**偏导数存在**, 则定理结论不一定成立.

例如: $z = f(u, v) = \begin{cases} \frac{u^2 v}{u^2 + v^2}, & u^2 + v^2 \neq 0 \\ 0, & u^2 + v^2 = 0 \end{cases}$

$$u = t, \quad v = t$$

易知: $\left. \frac{\partial z}{\partial u} \right|_{(0,0)} = f_u(0,0) = 0, \quad \left. \frac{\partial z}{\partial v} \right|_{(0,0)} = f_v(0,0) = 0$

但复合函数 $z = f(t, t) = \frac{t}{2}$

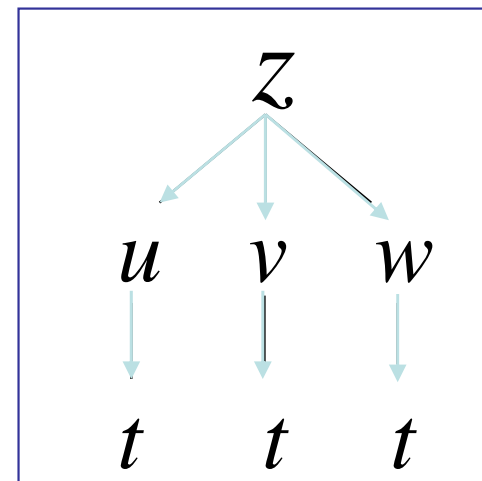
$$\frac{dz}{dt} = \frac{1}{2} \neq \frac{\partial z}{\partial u} \cdot \frac{du}{dt} + \frac{\partial z}{\partial v} \cdot \frac{dv}{dt} = 0 \cdot 1 + 0 \cdot 1 = 0$$

推广： 设下面所涉及的函数都可微 .

1) 中间变量多于两个的情形. 例如, $z = f(u, v, w)$,

$$u = \varphi(t), v = \psi(t), w = \omega(t)$$

$$\begin{aligned}\frac{dz}{dt} &= \frac{\partial z}{\partial u} \cdot \frac{du}{dt} + \frac{\partial z}{\partial v} \cdot \frac{dv}{dt} + \frac{\partial z}{\partial w} \cdot \frac{dw}{dt} \\ &= f_1 \phi' + f_2 \psi' + f_3 \omega'\end{aligned}$$

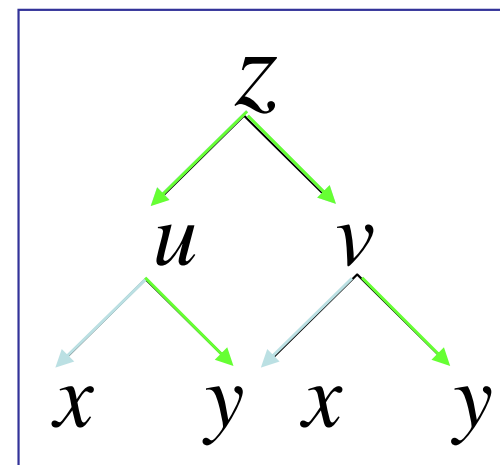


2) 中间变量是多元函数的情形. 例如,

$$z = f(u, v), \quad u = \varphi(x, y), \quad v = \psi(x, y)$$

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial u} \cdot \frac{\partial u}{\partial x} + \frac{\partial z}{\partial v} \cdot \frac{\partial v}{\partial x} = f_1 \varphi_1 + f_2 \psi_1$$

$$\frac{\partial z}{\partial y} = \frac{\partial z}{\partial u} \cdot \frac{\partial u}{\partial y} + \frac{\partial z}{\partial v} \cdot \frac{\partial v}{\partial y} = f_1 \varphi_2 + f_2 \psi_2$$

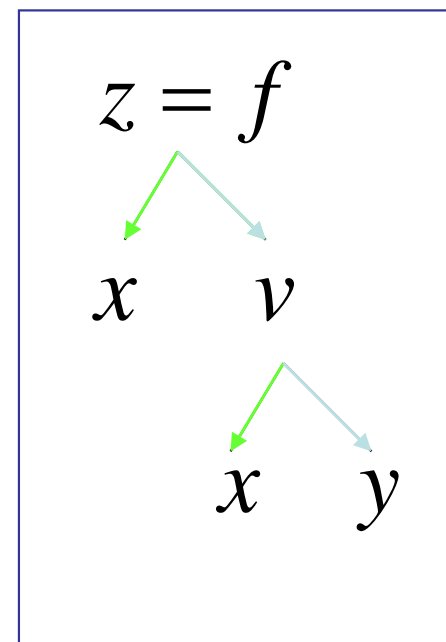


又如, $z = f(x, v)$, $v = \psi(x, y)$

当它们都具有可微条件时, 有

$$\boxed{\frac{\partial z}{\partial x}} = \boxed{\frac{\partial f}{\partial x}} + \frac{\partial f}{\partial v} \cdot \frac{\partial v}{\partial x} = f_1 + f_2 \psi_1$$

$$\frac{\partial z}{\partial y} = \frac{\partial f}{\partial v} \cdot \frac{\partial v}{\partial y} = f_2 \psi_2$$



注意: 这里 $\frac{\partial z}{\partial x}$ 与 $\frac{\partial f}{\partial x}$ 不同,

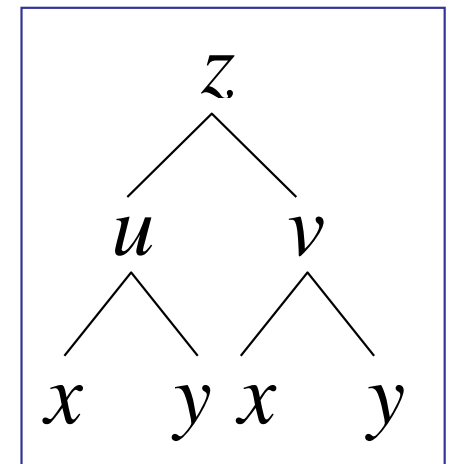
$\frac{\partial z}{\partial x}$ 表示固定 y 对 x 求导, $\frac{\partial f}{\partial x}$ 表示固定 v 对 x 求导

口诀: 分段用乘, 分叉用加, 单路全导, 叉路偏导

例1. 设 $z = e^u \sin v$, $u = xy$, $v = x + y$, 求 $\frac{\partial z}{\partial x}, \frac{\partial z}{\partial y}$.

解:

$$\begin{aligned}\frac{\partial z}{\partial x} &= \frac{\partial z}{\partial u} \cdot \frac{\partial u}{\partial x} + \frac{\partial z}{\partial v} \cdot \frac{\partial v}{\partial x} \\&= e^u \sin v \cdot y + e^u \cos v \cdot 1 \\&= e^{xy} [y \cdot \sin(x + y) + \cos(x + y)] \\ \frac{\partial z}{\partial y} &= \frac{\partial z}{\partial u} \cdot \frac{\partial u}{\partial y} + \frac{\partial z}{\partial v} \cdot \frac{\partial v}{\partial y} \\&= e^u \sin v \cdot x + e^u \cos v \cdot 1 \\&= e^{xy} [x \cdot \sin(x + y) + \cos(x + y)]\end{aligned}$$



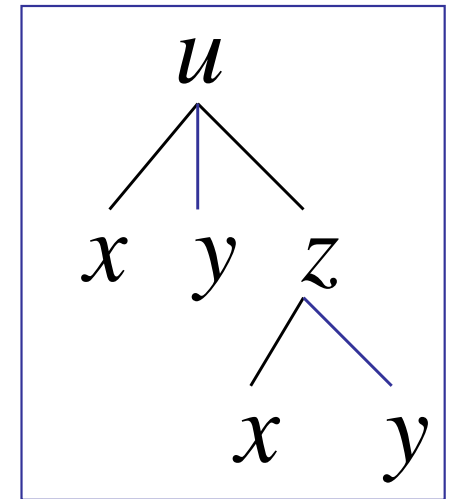
例2. $u = f(x, y, z) = e^{x^2+y^2+z^2}$, $z = x^2 \sin y$, 求 $\frac{\partial u}{\partial x}$, $\frac{\partial u}{\partial y}$

解: $\frac{\partial u}{\partial x} = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial z} \cdot \frac{\partial z}{\partial x}$

$$\begin{aligned} &= 2xe^{x^2+y^2+z^2} + 2ze^{x^2+y^2+z^2} \cdot 2x \sin y \\ &= 2x(1 + 2x^2 \sin^2 y) e^{x^2+y^2+x^4 \sin^2 y} \end{aligned}$$

$$\frac{\partial u}{\partial y} = \frac{\partial f}{\partial y} + \frac{\partial f}{\partial z} \cdot \frac{\partial z}{\partial y}$$

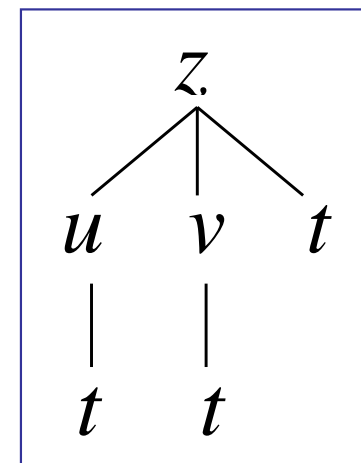
$$\begin{aligned} &= 2ye^{x^2+y^2+z^2} + 2ze^{x^2+y^2+z^2} \cdot x^2 \cos y \\ &= 2(y + x^4 \sin y \cos y) e^{x^2+y^2+x^4 \sin^2 y} \end{aligned}$$



例3. 设 $z = uv + \sin t$, $u = e^t$, $v = \cos t$, 求全导数 $\frac{dz}{dt}$.

解:

$$\begin{aligned}\frac{dz}{dt} &= \frac{\partial z}{\partial u} \cdot \frac{du}{dt} + \frac{\partial z}{\partial v} \cdot \frac{dv}{dt} + \frac{\partial z}{\partial t} \\ &= v e^t - u \sin t + \cos t \\ &= e^t (\cos t - \sin t) + \cos t\end{aligned}$$



注意：多元抽象复合函数求导在偏微分方程变形与验证解的问题中经常遇到，下列两个例题有助于掌握这方面问题的求导技巧与常用导数符号.

例4. 设 $w = f(x + y + z, xyz)$, f 具有二阶连续偏导数,

求 $\frac{\partial w}{\partial x}, \frac{\partial^2 w}{\partial x \partial z}$.

解: 令 $u = x + y + z, v = xyz$, 则

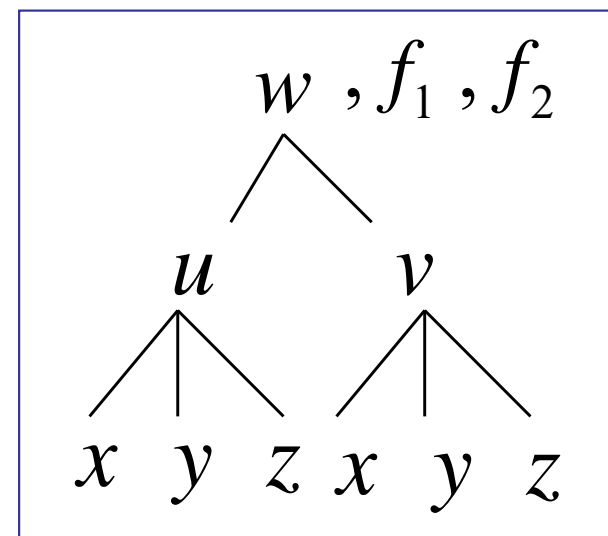
$$w = f(u, v)$$

$$\frac{\partial w}{\partial x} = f_1 \cdot 1 + f_2 \cdot yz$$

$$= f_1(x + y + z, xyz) + \underline{yz f_2(x + y + z, xyz)}$$

$$\underline{\frac{\partial^2 w}{\partial x \partial z} = f_{11} \cdot 1 + f_{12} \cdot xy + y f_2 + yz [f_{21} \cdot 1 + f_{22} \cdot xy]}$$

$$= f_{11} + y(x + z)f_{12} + xy^2z f_{22} + y f_2$$



例5. 设 $u = f(x, y)$ 二阶偏导数连续, 求下列表达式在极坐标系下的形式 (1) $(\frac{\partial u}{\partial x})^2 + (\frac{\partial u}{\partial y})^2$, (2) $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$

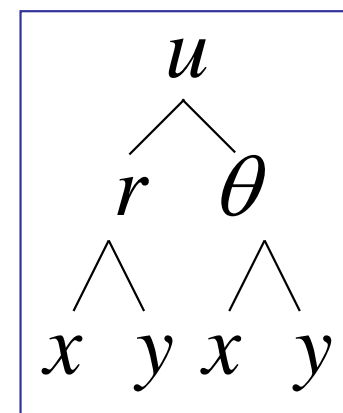
解: 已知 $x = r \cos \theta$, $y = r \sin \theta$, 则

$$r = \sqrt{x^2 + y^2}, \quad \theta = \arctan \frac{y}{x}$$

$$(1) \quad \frac{\partial u}{\partial x} = \frac{\partial u}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial x}$$

$$\frac{\partial r}{\partial x} = \frac{x}{r}, \quad \frac{\partial \theta}{\partial x} = \frac{\frac{-y}{x^2}}{1 + (\frac{y}{x})^2} = \frac{-y}{x^2 + y^2}$$

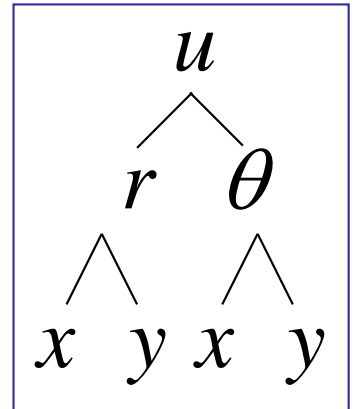
$$= \frac{\partial u}{\partial r} \frac{x}{r} - \frac{\partial u}{\partial \theta} \frac{y}{r^2} = \frac{\partial u}{\partial r} \cos \theta - \frac{\partial u}{\partial \theta} \frac{\sin \theta}{r}$$



$$\frac{\partial u}{\partial y} = \frac{\partial u}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial y}$$

$$\frac{\partial r}{\partial y} = \frac{y}{r}, \quad \frac{\partial \theta}{\partial y} = \frac{\frac{1}{x}}{1 + \left(\frac{y}{x}\right)^2} = \frac{x}{x^2 + y^2}$$

$$\begin{aligned} &= \frac{\partial u}{\partial r} \frac{y}{r} + \frac{\partial u}{\partial \theta} \frac{x}{r^2} \\ &= \frac{\partial u}{\partial r} \sin \theta + \frac{\partial u}{\partial \theta} \frac{\cos \theta}{r} \end{aligned}$$



$$\therefore \left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2 = \left(\frac{\partial u}{\partial r}\right)^2 + \frac{1}{r^2} \left(\frac{\partial u}{\partial \theta}\right)^2$$

已知 $\frac{\partial u}{\partial x} = \frac{\partial u}{\partial r} \cos \theta - \frac{\partial u}{\partial \theta} \frac{\sin \theta}{r}$

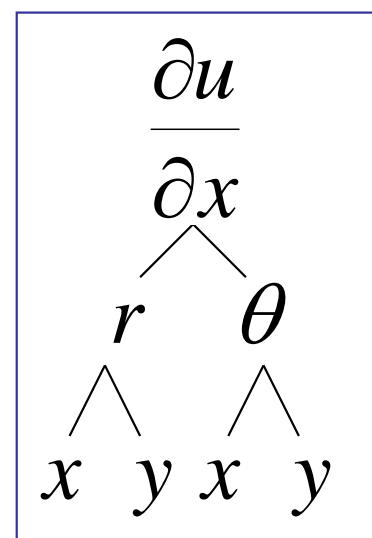
$$(2) \quad \frac{\partial^2 u}{\partial x^2} = \frac{\partial}{\partial r} \left(\frac{\partial u}{\partial x} \right) \cdot \cos \theta - \frac{\partial}{\partial \theta} \left(\frac{\partial u}{\partial x} \right) \frac{\sin \theta}{r}$$

$$= \frac{\partial}{\partial r} \left(\frac{\partial u}{\partial r} \cos \theta - \frac{\partial u}{\partial \theta} \frac{\sin \theta}{r} \right) \cdot \cos \theta$$

$$- \frac{\partial}{\partial \theta} \left(\frac{\partial u}{\partial r} \cos \theta - \frac{\partial u}{\partial \theta} \frac{\sin \theta}{r} \right) \cdot \frac{\sin \theta}{r}$$

$$= \frac{\partial^2 u}{\partial r^2} \cos^2 \theta - 2 \frac{\partial^2 u}{\partial r \partial \theta} \frac{\sin \theta \cos \theta}{r} + \frac{\partial^2 u}{\partial \theta^2} \frac{\sin^2 \theta}{r^2}$$

$$+ \frac{\partial u}{\partial \theta} \frac{2 \sin \theta \cos \theta}{r^2} + \frac{\partial u}{\partial r} \frac{\sin^2 \theta}{r}$$



注意利用
已有公式

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 u}{\partial r^2} \cos^2 \theta - 2 \frac{\partial^2 u}{\partial r \partial \theta} \frac{\sin \theta \cos \theta}{r} + \frac{\partial^2 u}{\partial \theta^2} \frac{\sin^2 \theta}{r^2} + \frac{\partial u}{\partial \theta} \frac{2 \sin \theta \cos \theta}{r^2} + \frac{\partial u}{\partial r} \frac{\sin^2 \theta}{r}$$

同理可得

$$\frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 u}{\partial r^2} \sin^2 \theta + 2 \frac{\partial^2 u}{\partial r \partial \theta} \frac{\sin \theta \cos \theta}{r} + \frac{\partial^2 u}{\partial \theta^2} \frac{\cos^2 \theta}{r^2} - \frac{\partial u}{\partial \theta} \frac{2 \sin \theta \cos \theta}{r^2} + \frac{\partial u}{\partial r} \frac{\cos^2 \theta}{r}$$

$$\begin{aligned} \therefore \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} &= \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} \\ &= \frac{1}{r^2} \left[r \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \frac{\partial^2 u}{\partial \theta^2} \right] \end{aligned}$$