

Learning Recurring Patterns in Large Signals with Convolutional Dictionary Learning

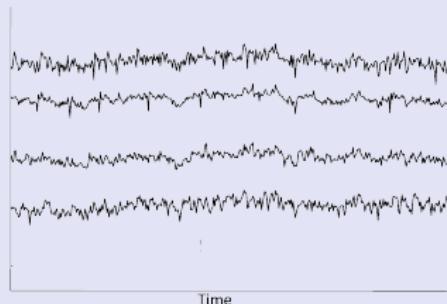
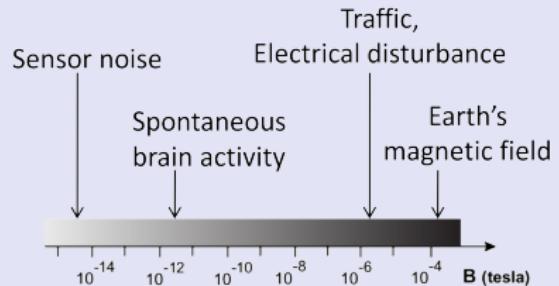
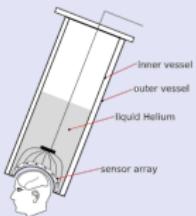
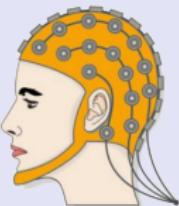
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Studying brain activity through electromagnetic signals

- ▶ Brain (electrical) activity produces an electromagnetic field.
- ▶ This can be measured with EEG or MEG.



Goal: Study Oscillation in Neural Data

Oscillations are believed to play an important role in cognitive functions.

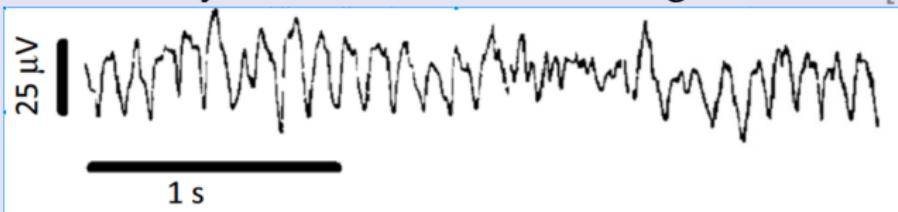
Many studies rely on Fourier or wavelet analyses:

- ▶ Easy interpretation,
- ▶ Standard analysis e.g. canonical bands alpha, beta or theta.

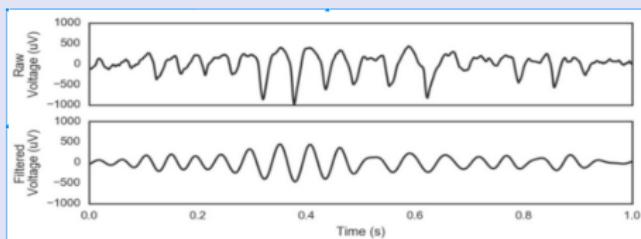
[Buzsaki, 2006]

Goal: Study Oscillation in Neural Data

However, some brain rhythms are not sinusoidal, e.g. mu-waves [Hari, 2006]



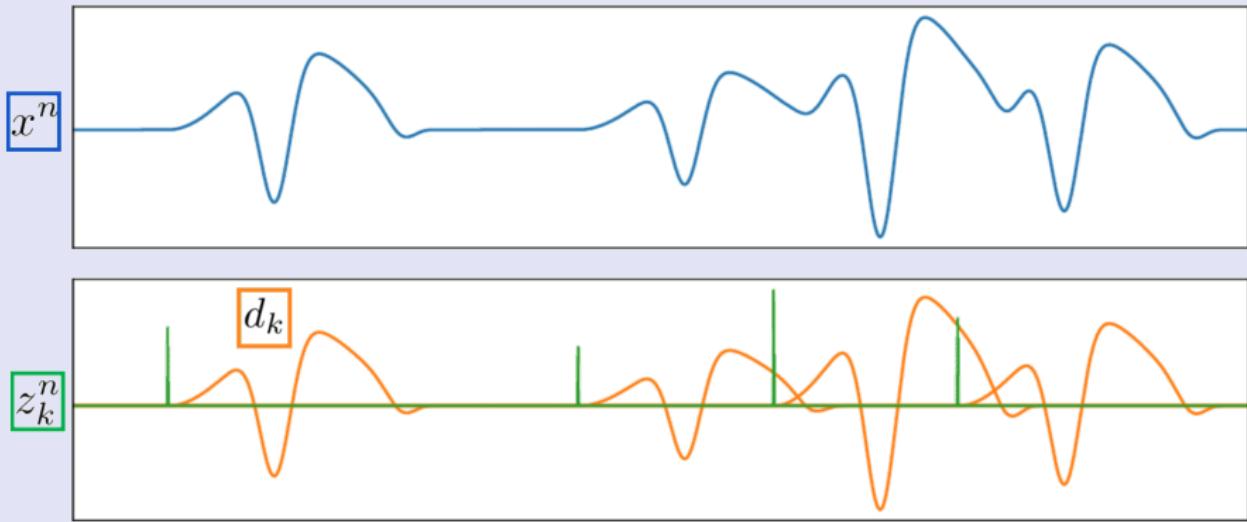
and filtering degrades waveforms



⇒ Can we do better with data-driven approach?

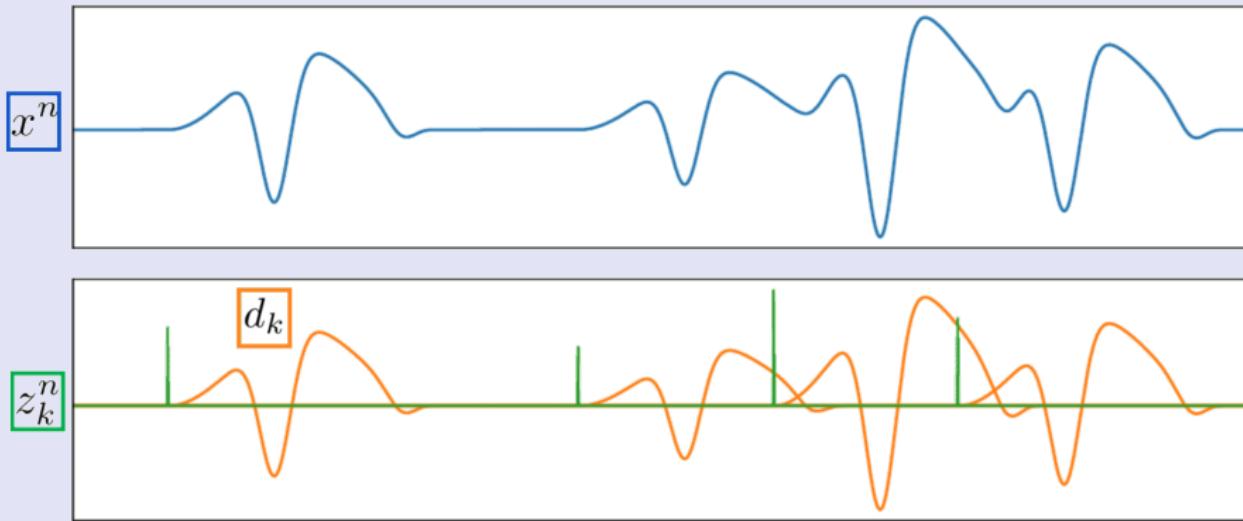
Extracting shift invariant patterns

Key idea: decouple the localization of the patterns and their shape



Extracting shift invariant patterns

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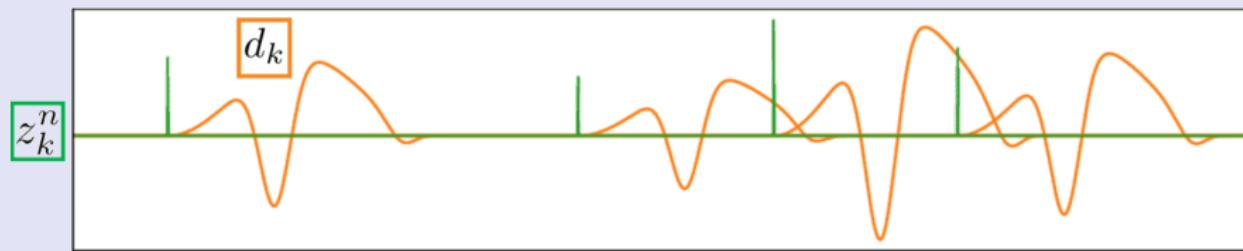


**Convolutional
Representation:**

$$x^n[t] = \sum_{k=1}^K (z_k^n * d_k)[t] + \varepsilon[t]$$

Extracting shift invariant patterns

Key idea: decouple the localization of the patterns and their shape



**Convolutional
Dictionary Learning:**

$$\min_{d,z} \sum_{n=1}^N \frac{1}{2} \left\| x^n - \sum_{k=1}^K z_k^n * d_k \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1,$$

s.t. $\|d_k\|_2^2 \leq 1$

Shift-invariant Patterns in images



Images also have shift-invariant patterns that we might want to detect.

Convolutional Dictionary Learning

Convolutional Dictionary Learning (CDL)

[Grosse et al., 2007]

For a set of N univariate signals x^n , solve

$$\min_{d_k, z_k^n} \sum_{n=1}^N \frac{1}{2} \|x^n - \sum_{k=1}^K z_k^n * d_k\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1 \quad (1)$$

Hypothesis: patterns d_k are not present everywhere in the signal. They are localized in time.

⇒ Sparse activation signals z

Extra hypothesis: the patterns are in the ℓ_2 -ball: $\|d_k\|_2^2 \leq 1$.

The problem 1 is not jointly convex in z_k^n , and d_k it is convex in each block of coordinate.

Alternate minimization (a.k.a. Bloc Coordinate Descent):

- ▶ **Z-step:** given a fixed estimate of the atom, compute the activation signal z_k^n associated to each signal X^n .
- ▶ **D-step:** given a fixed estimate of the activation, update the atoms in the dictionary d_k .

Convolutional Sparse Coding with Locally Greedy Coordinate Descent (LGCD)

References

- ▶ Moreau, T., Oudre, L., and Vayatis, N. (2018). [DICOD: Distributed Convolutional Sparse Coding](#). In *International Conference on Machine Learning (ICML)*, pages 3626–3634, Stockholm, Sweden. PMLR (80)

Convolutional Sparse Coding

N independent problem such that

$$\min_{z_k^n} E(z^n) = \frac{1}{2} \left\| x^n - \sum_{k=1}^K z_k^n * d_k \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1 .$$

This problem is convex in z_k and can be solved with different techniques:

- ▶ Greedy CD [Kavukcuoglu et al., 2010]
- ▶ Fista [Chalasani et al., 2013]
- ▶ ADMM [Bristow et al., 2013]
- ▶ L-BFGS [Jas et al., 2017]

⇒ These methods can be slow for long signals as the complexity of each iteration is at least linear in the length of the signal.

For the Greedy Coordinate Descent, only 1 coordinate is updated at each iteration:

1. The coordinate $z_{k_0}[t_0]$ is updated to its optimal value $z'_{k_0}[t_0]$ when all other coordinate are fixed:

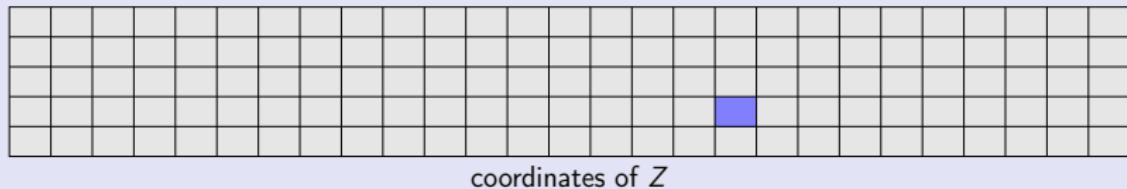
$$z'_k[t] = \max\left(\frac{\beta_k[t] - \lambda}{\|d_k\|_2^2}, 0\right),$$

with $\beta_k[t] = \left[\left(X - \sum_{l=1}^K z_l * d_l + z_k[t] e_t * d_k \right) * d_k^\top \right] [t]$

2. Greedy coordinate selection:

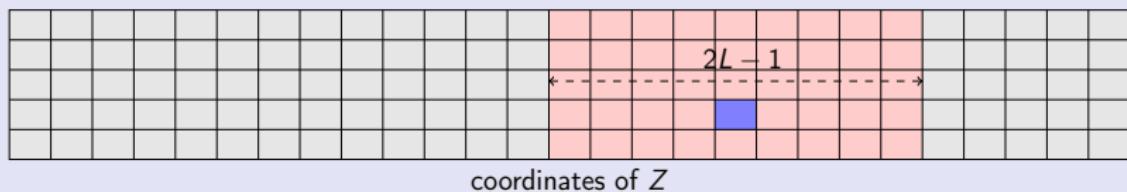
$$(k, t) = \operatorname{argmax}_{(k,t)} |z_k[t] - z'_k[t]|$$

We introduced the LGCD method which is an extension of GCD.



GCD has $\mathcal{O}(KT)$ computational complexity.

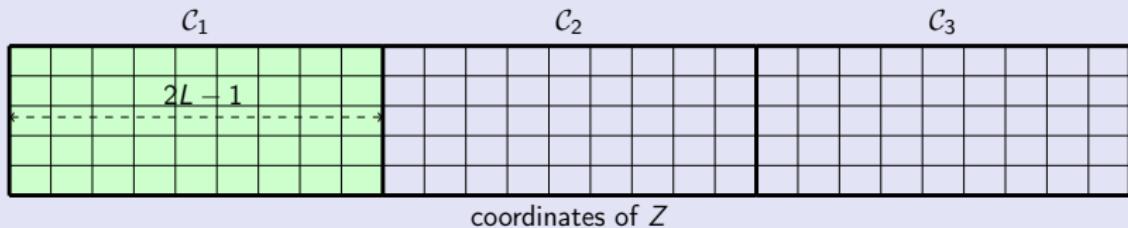
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GCD has $\mathcal{O}(KT)$ computational complexity.

But the update itself has complexity $\mathcal{O}(KL)$

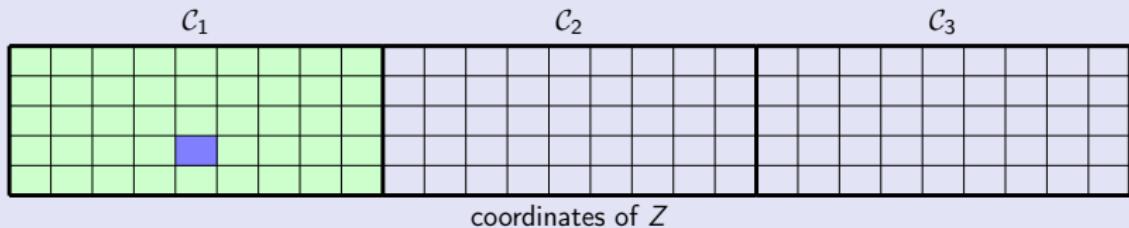
We introduced the LGCD method which is an extension of GCD.



With a partition \mathcal{C}_m of the signal domain $\llbracket 1, K \rrbracket \times \llbracket 0, T \rrbracket$,

$$\mathcal{C}_m = \llbracket 1, K \rrbracket \times \llbracket \frac{(m-1)\tilde{T}}{M}, \frac{m\tilde{T}}{M} \rrbracket$$

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$$\mathcal{C}_m = \llbracket 1, K \rrbracket \times \llbracket \frac{(m-1)\tilde{T}}{M}, \frac{m\tilde{T}}{M} \rrbracket$$

The coordinate to update is chosen greedily on a sub-domain \mathcal{C}_m

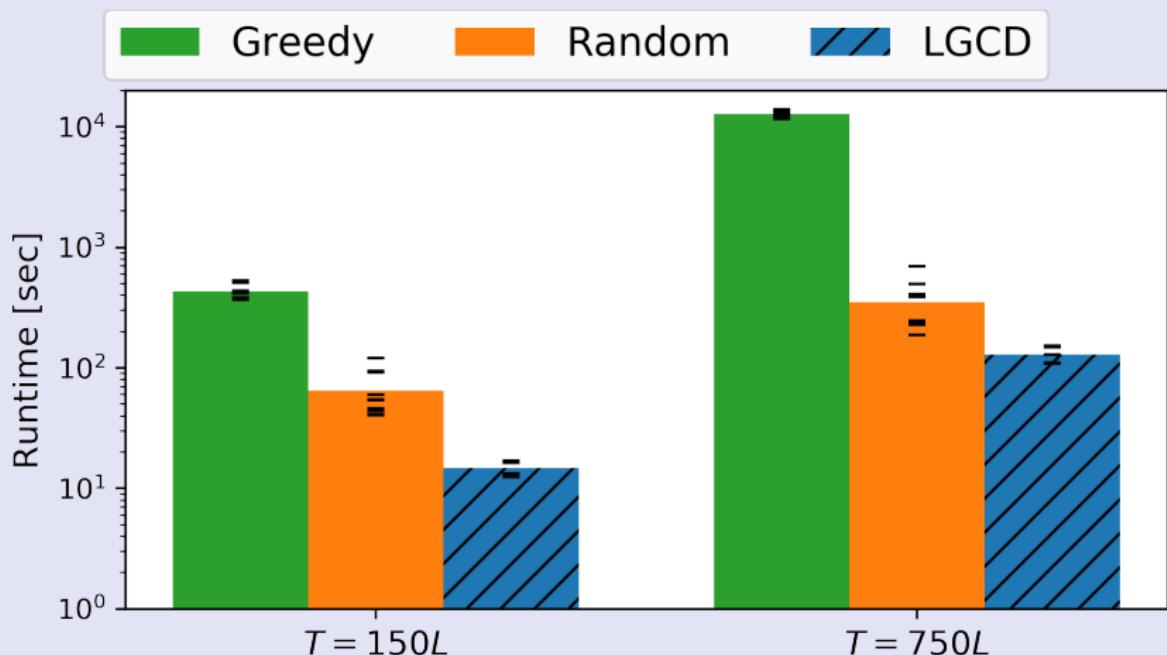
$$\mathcal{O}(\text{Coordinate selection}) = \mathcal{O}(\text{Coordinate Update})$$

The overall iteration complexity is $\mathcal{O}(KL)$ instead of $\mathcal{O}(KT)$.

⇒ Efficient for sparse Z

Fast optimization

Comparison of the coordinate selection strategy for CD on simulated signals
We set $K = 10$, $L = 150$, $\lambda = 0.1\lambda_{\max}$



Distributed optimization for CSC

References

- Moreau, T. and Gramfort, A. (2019). [Distributed Convolutional Dictionary Learning \(DiCoDiLe\): Pattern Discovery in Large Images and Signals](#). *preprint ArXiv (to be submitted)*

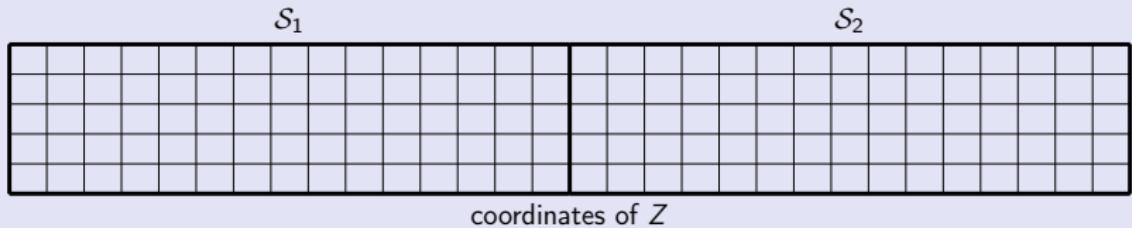
Weak dependence of the coordinate updates

The update of the W coordinates $(k_w, \omega_w)_{w=1}^W$ with additive update $\Delta Z_{k_w}[\omega_w]$ changes the cost by:

$$\Delta E = \underbrace{\sum_{i=1}^W \Delta E_w}_{\text{iterative steps}} - \underbrace{\sum_{w \neq w'} (d_{k_w} * d_{k_{w'}}^\top)[\omega_{w'} - \omega_w] \Delta Z_{k_w}[\omega_w] \Delta Z_{k_{w'}}[\omega_{w'}]}_{\text{interference}},$$

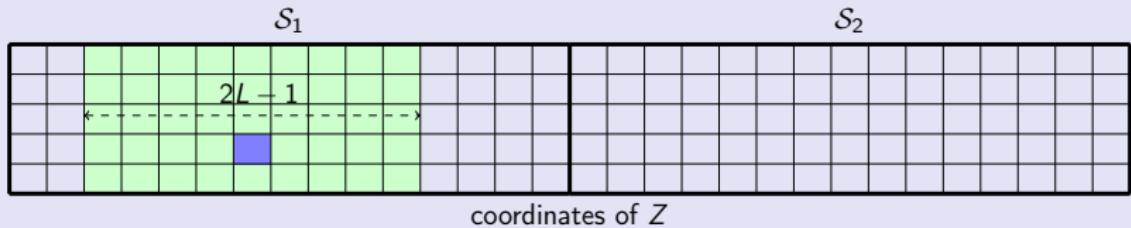
⇒ If the updates are far enough, they can be considered as independent.

Distributed Convolutional Coordinate Descent (DICOD)



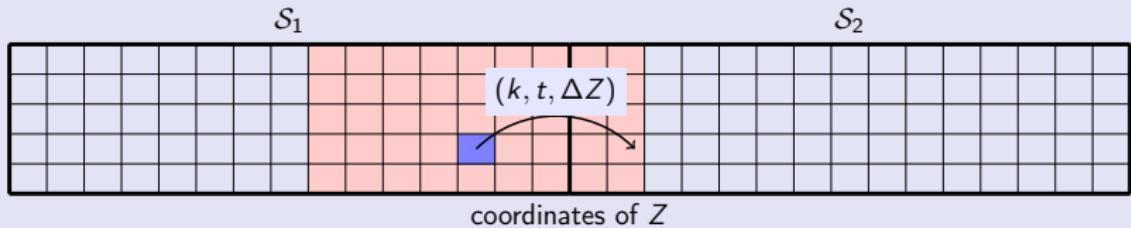
- ▶ Split the coordinates in continuous sub-segment $\mathcal{S}_w = \left[\frac{(w-1)T}{W}, \frac{wT}{W} \right[$.

Distributed Convolutional Coordinate Descent (DICOD)



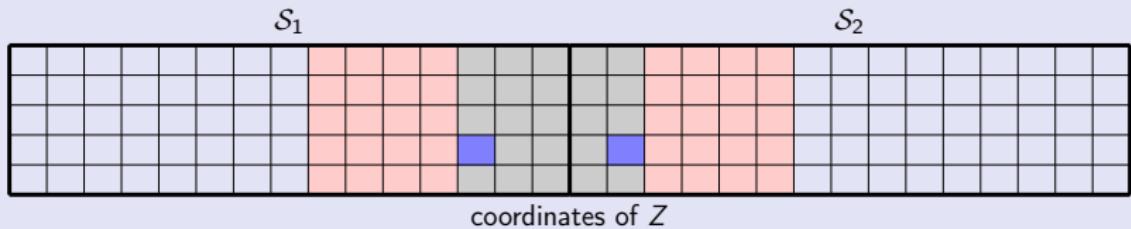
- ▶ Split the coordinates in continuous sub-segment $\mathcal{S}_w = \left[\frac{(w-1)T}{W}, \frac{wT}{W} \right[$.
- ▶ Use Greedy updates in parallel in each sub-segment.

Distributed Convolutional Coordinate Descent (DICOD)



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- ▶ Notify neighbor workers when the update is on the border of \mathcal{S}_w .

Distributed Convolutional Coordinate Descent (DICOD)



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- ▶ Notify neighbor workers when the update is on the border of \mathcal{S}_w .

This algorithm converges to the solution of the CSC for 1D signals but not for higher dimension signals such as images.

Distributed Convolutional Dictionary Learning (DiCoDiLe-Z)

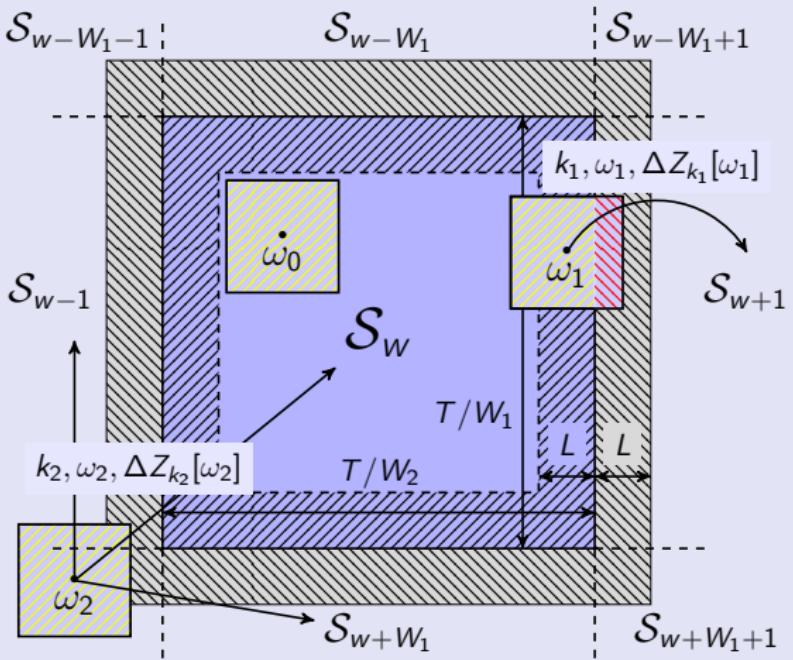
- ▶ Extension of DICOD for high dimensional signals.
- ▶ Use LGCD locally in each workers (better iteration complexity).
- ▶ Use Soft-locks to avoid interference (ensure convergence).

Distributed Convolutional Dictionary Learning (DiCoDiLe-Z)



- ▶ Update candidate ω_0 is independent of other workers as

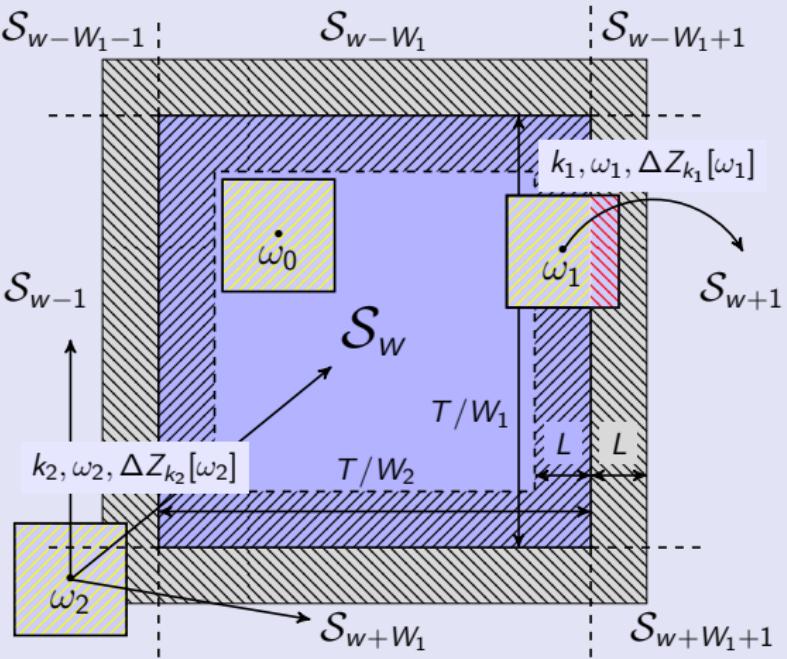
$$\mathcal{V}(\omega_0) \subset \mathcal{S}_w$$



Distributed Convolutional Dictionary Learning (DiCoDiLe-Z)



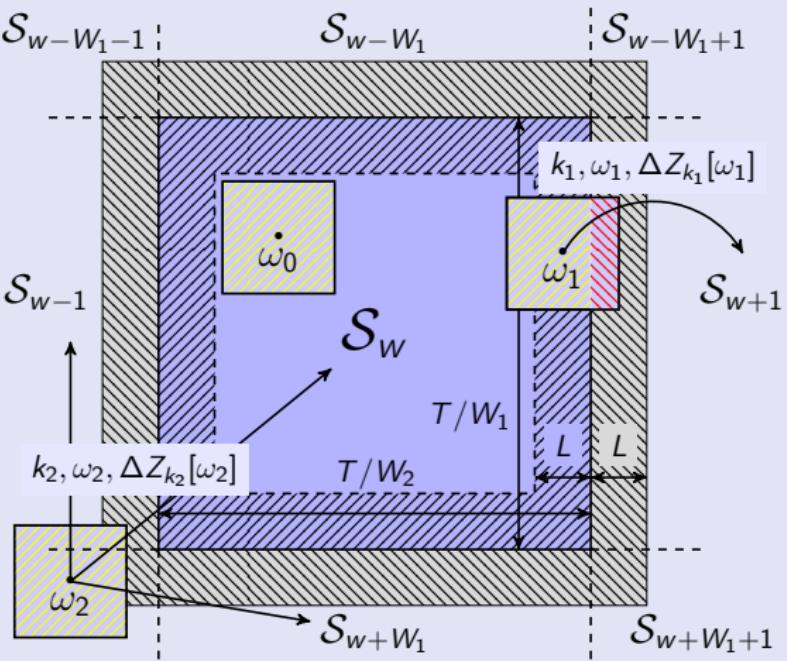
- ▶ Update candidate ω_1 impacts \mathcal{S}_{w+1}
 $\mathcal{V}(\omega_1) \not\subset \mathcal{S}_w$
- ▶ It is accepted only if no better update is possible in the "soft-locked" area.
- ▶ Need to notify \mathcal{S}_{w+1} .



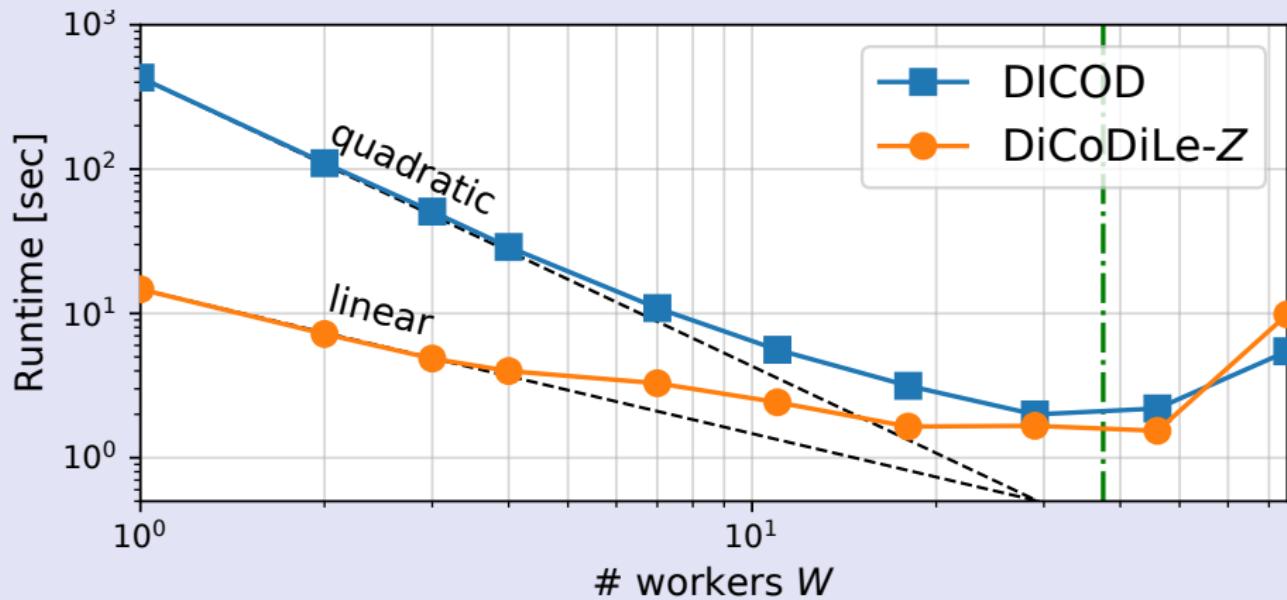
Distributed Convolutional Dictionary Learning (DiCoDiLe-Z)



- ▶ Updates in ω_2 need to notify worker w to maintain consistent estimate in the border zone $\mathcal{B}_L(\mathcal{S}_w)$.
- ▶ Low communication: decentralized and below 1ko.



Numerical speed-up



Running time as a function fo the number of workers W .

Rank-1 Constrained Convolutional Dictionary Learning

References

- ▶ Dupré la Tour, T., Moreau, T., Jas, M., and Gramfort, A. (2018).
[Multivariate Convolutional Sparse Coding for Electromagnetic Brain Signals.](#)
In *Advances in Neural Information Processing Systems (NeurIPS)*, pages 3296–3306, Montreal, Canada

D-step: solving for the atoms

The dictionary update is performed by minimizing

$$\min_{\|d_k\|_2 \leq 1} E(\{d_k\}_k) \triangleq \sum_{n=1}^N \frac{1}{2} \|X^n - \sum_{k=1}^K z_k^n * d_k\|_2^2 . \quad (2)$$

Computing $\nabla_{d_k} E(\{d_k\}_k)$ can be done efficiently

$$\nabla_{d_k} E(\{d_k\}_k) = \sum_{n=1}^N (z_k^n)^\top * \left(x^n - \sum_{l=1}^K z_l^n * d_l \right) = \Phi_k - \sum_{l=1}^K \Psi_{k,l} * d_l ,$$

\Rightarrow Save with Projected Gradient Descent (PGD) with an Armijo backtracking line-search for the d-step [Wright and Nocedal, 1999].

How to extend CSC to multivariate signals?

We can just use multivariate convolution,

$$\underbrace{X[t]}_{\in \mathbb{R}^P} = \sum_{k=1}^K (z_k * D_k)[t] = \sum_{k=1}^K \sum_{\tau=1}^L z_k[t - \tau] \underbrace{D_k[\tau]}_{\in \mathbb{R}^P}$$

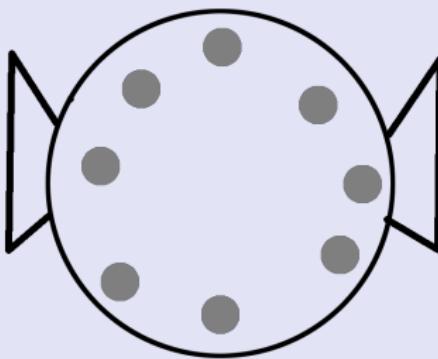
with:

- ▶ X a multivariate signal of length T in \mathbb{R}^P
- ▶ D_k a multivariate signal of length L in \mathbb{R}^P
- ▶ z_k a univariate activation signal of length $\tilde{T} = T - L + 1$

However, this model does not account for the physics of the problem.

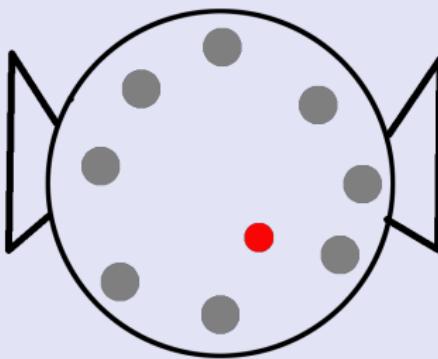
EM wave diffusion

- ▶ Recording here with 8 sensors



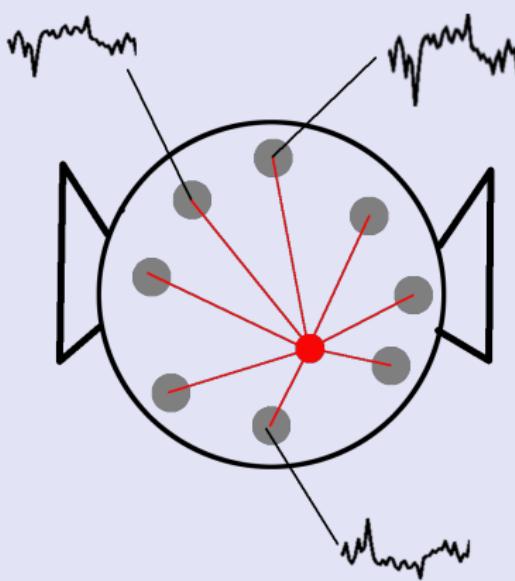
EM wave diffusion

- ▶ Recording here with 8 sensors
- ▶ EM activity in the brain



EM wave diffusion

- ▶ Recording here with 8 sensors
- ▶ EM activity in the brain
- ▶ The electric field is spread **linearly** and **instantaneously** over all sensors (Maxwell equations)



Multivariate CSC with rank-1 constraint

Idea: Impose a rank-1 constraint on the dictionary atoms D_k

To make the problem tractable, we decided to use auxiliary variables u_k and v_k s.t. $D_k = u_k v_k^\top$.

$$\begin{aligned} \min_{u_k, v_k, z_k^n} & \sum_{n=1}^N \frac{1}{2} \left\| X^n - \sum_{k=1}^K z_k^n * (u_k v_k^\top) \right\|_2^2 + \lambda \sum_{k=1}^K \|z_k^n\|_1, \\ \text{s.t. } & \|u_k\|_2^2 \leq 1, \|v_k\|_2^2 \leq 1 \text{ and } z_k^n \geq 0. \end{aligned} \quad (3)$$

Here,

- ▶ $u_k \in \mathbb{R}^P$ is the spatial pattern of our atom
- ▶ $v_k \in \mathbb{R}^L$ is the temporal pattern of our atom

Update in u_k and v_k

The problem is not jointly convex in u_k and v_k .

Use an alternate minimization on these two blocks.

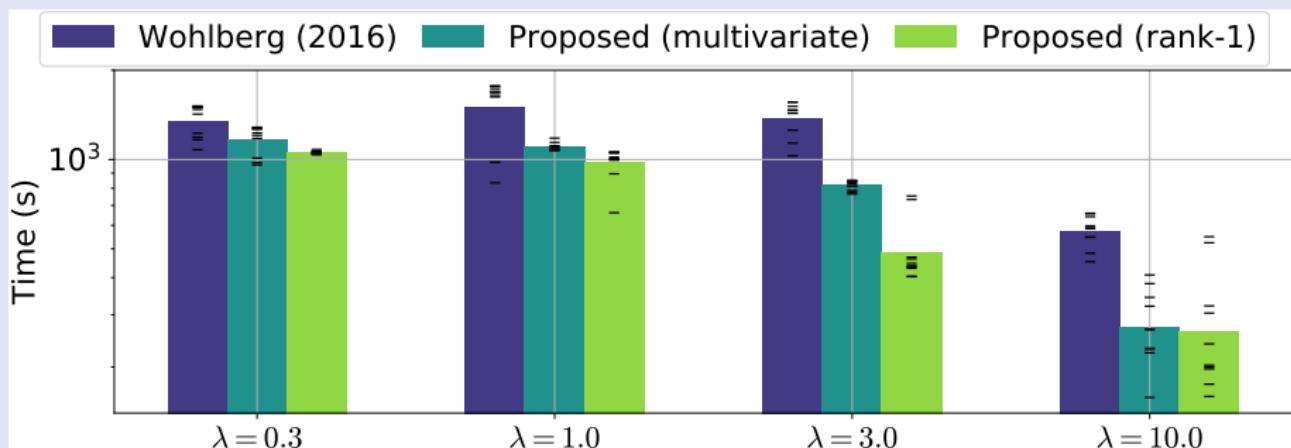
The gradient can also be computed using sufficient statistics ϕ and ψ :

$$\nabla_{u_k} E(\{u_k\}_k, \{v_k\}_k) = \nabla_{D_k} E(\{u_k\}_k, \{v_k\}_k) v_k \in \mathbb{R}^P,$$

$$\nabla_{v_k} E(\{u_k\}_k, \{v_k\}_k) = u_k^\top \nabla_{D_k} E(\{u_k\}_k, \{v_k\}_k) \in \mathbb{R}^L,$$

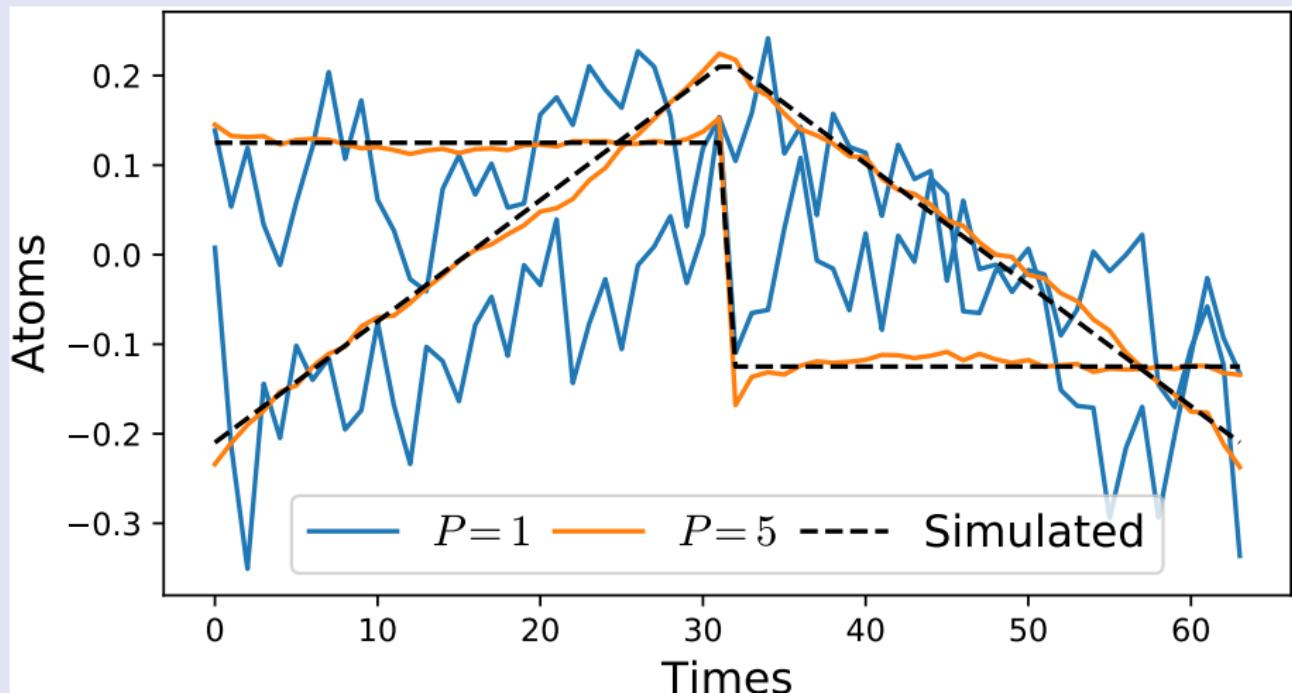
Fast optimization

Comparison with multivariate methods on somato dataset with
 $T = 134,700$, $K = 8$, $P = 5$ and $L = 128$



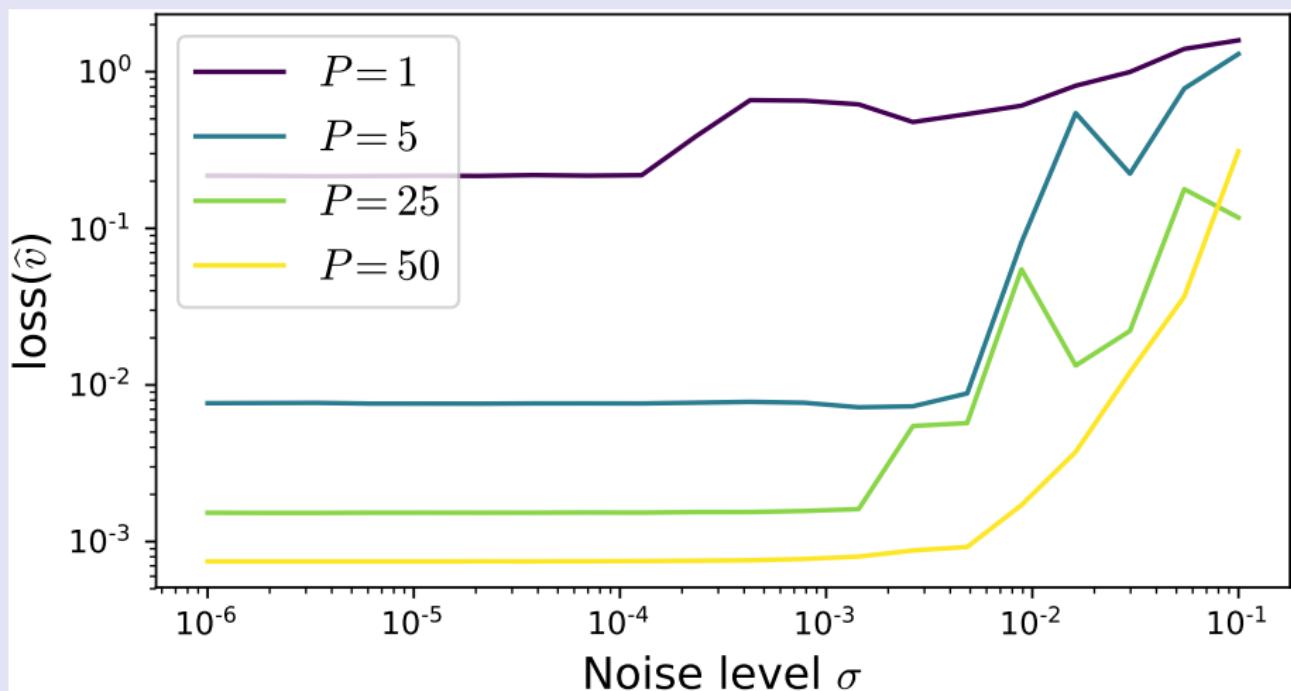
Pattern recovery

Patterns recovered with $P = 1$ and $P = 5$. The signals were generated with the two simulated temporal patterns and with $\sigma = 10^{-3}$.



Pattern recovery

Evolution of the recovery loss with σ for different values of P . Using more channels improves the recovery of the original patterns.



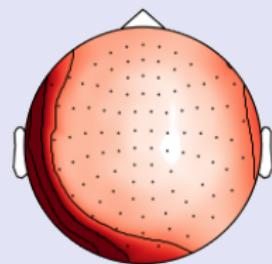
Experiments on REal Data

Good time to wake-up if you got lost in the previous section!

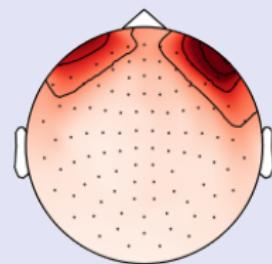
MNE somatosensory data

A selection of temporal waveforms of the atoms learned on the MNE sample dataset.

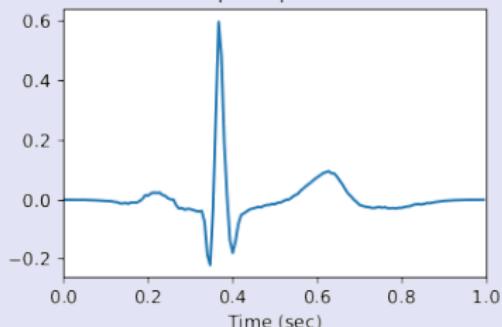
Spatial pattern 0
Explained variance 5.62 %



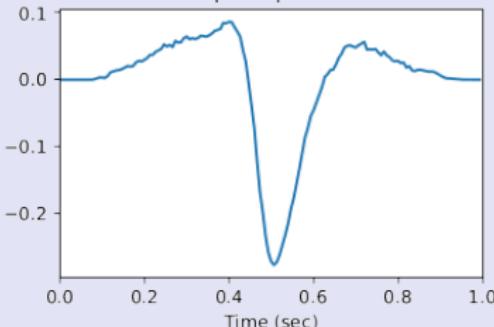
Spatial pattern 1
Explained variance 2.38 %



Temporal pattern 0

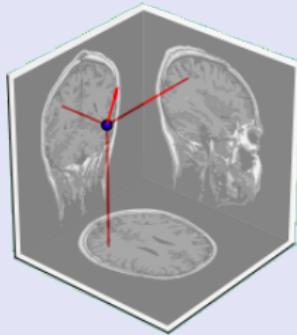
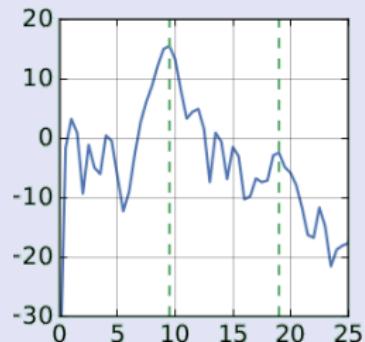
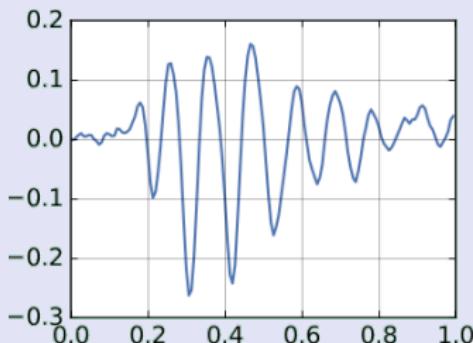


Temporal pattern 1

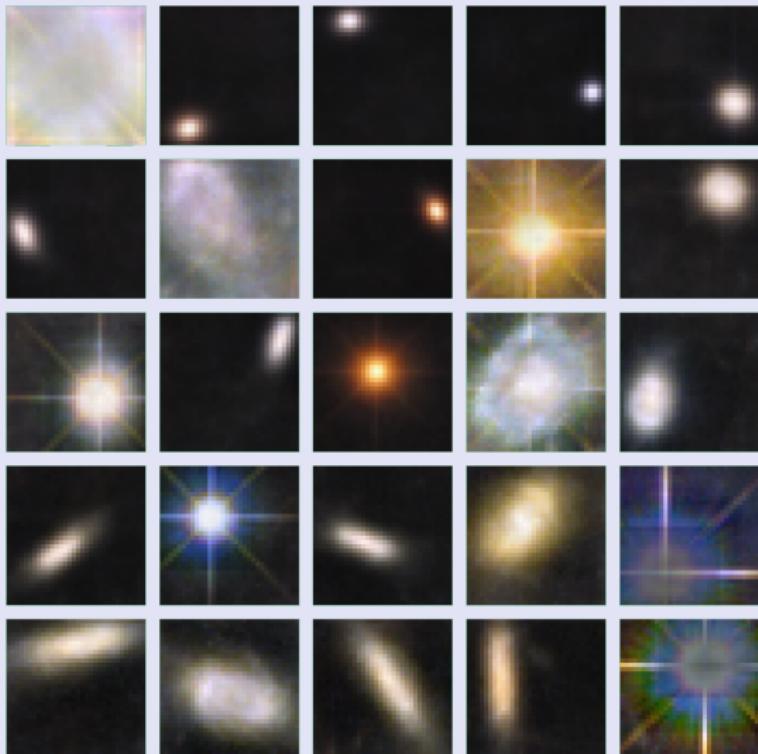


MNE somatosensory data

Atoms revealed using the MNE somatosensory data. Note the non-sinusoidal comb shape of the mu rhythm.



Encoding HST images with CDL



Atoms 32×32 learned with DiCoDiLe on image STScl-H-2016-39-a (resolution 6000×3664).

The atoms are ordered with $\|Z_k\|_1$.

Conclusion

LGCD and DiCoDile: Efficient algorithm to scale Convolutional Dictionary Learning to large signals.

Rank-1 constraints: Adapt the constraints to the type of patterns researched.

Ahead of us:

- ▶ Scale invariant atoms?
- ▶ Pattern detection with extra prior:

Thanks!

Code available online:

alphacsc : [alphacsc.github.io](https://github.com/alphacsc)

DICOD (& DiCoDiLe soon) : github.com/tommoral/dicod

Slides are on my web page:

 tommoral.github.io

 @tomamoral

Reference

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