

# Operating system

## Part III: Process [ 进程 ] & Thread

[ 线程 ]

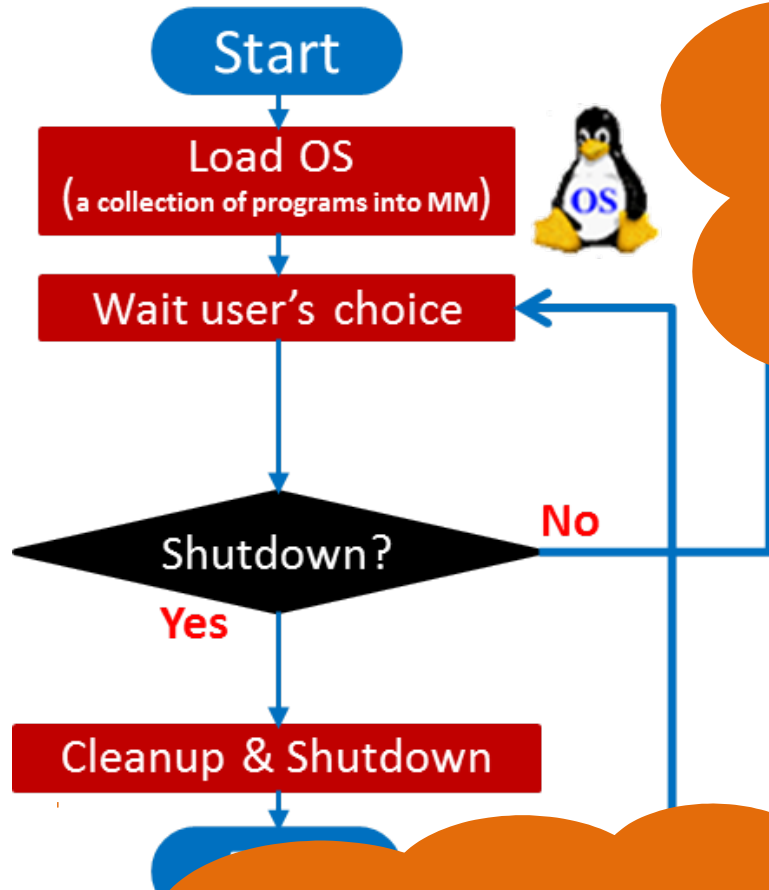
Know data structures to maintain the resources needed  
when executing your program

By KONG LingBo ( 孔令波 )

# Processes

- To understand the execution of your program
  - Process [ 进程 ] is the traditional concept
    - The identification to manage the needed information to run one program (**OS' s or user' s**)
      - **PCB** is the data structure to record the necessary information: resources (MM, ownership, security, ...), execution stages/states, ...
    - Additional data structures and algorithms are needed to manage the concurrent execution of many programs
      - Queues, and schedulers
      - Inter-process communication (IPC)
  - Thread [ 线程 ] is the modern concept
    - The idea could be seen as **MULTIPLEX**ing **process**, *namely that your program is constructed to have more than one execution units*
      - CPU is occupied by the process, however the usage of the CPU is shared among the internal execution units (threads)
        - » The resources assigned to the process could be shared by those threads.

We have learned that to call the collection of necessary resources to execute your program + program itself as



**PROCESS [进程]**

During the execution of a program, the OS must respond to user's input.



**1:1:M = 1 CPU, 1 MM, Many IO devices**

How exactly are those programs controlled by OS?

# The execution of your program needs some support

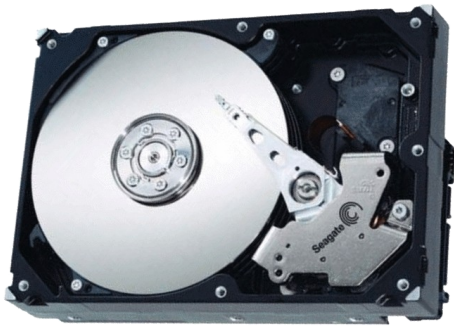
## Programs are stored as Files in storage media

## Program

```
X=1;
Y= 2;
Z= X+Y;
```

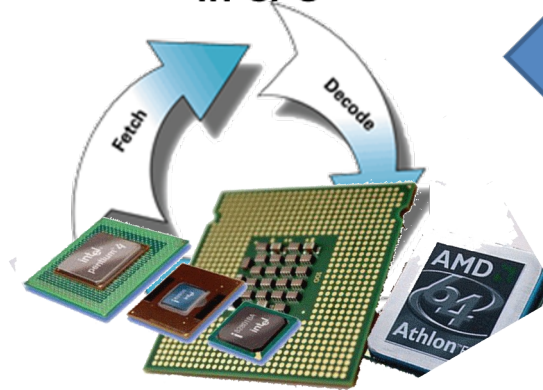
## Machine code

```
156C→0001010101101100
166D→0001011001101101
5056→0101000001010110
306E→0011000001101110
C000→1100000000000000
```

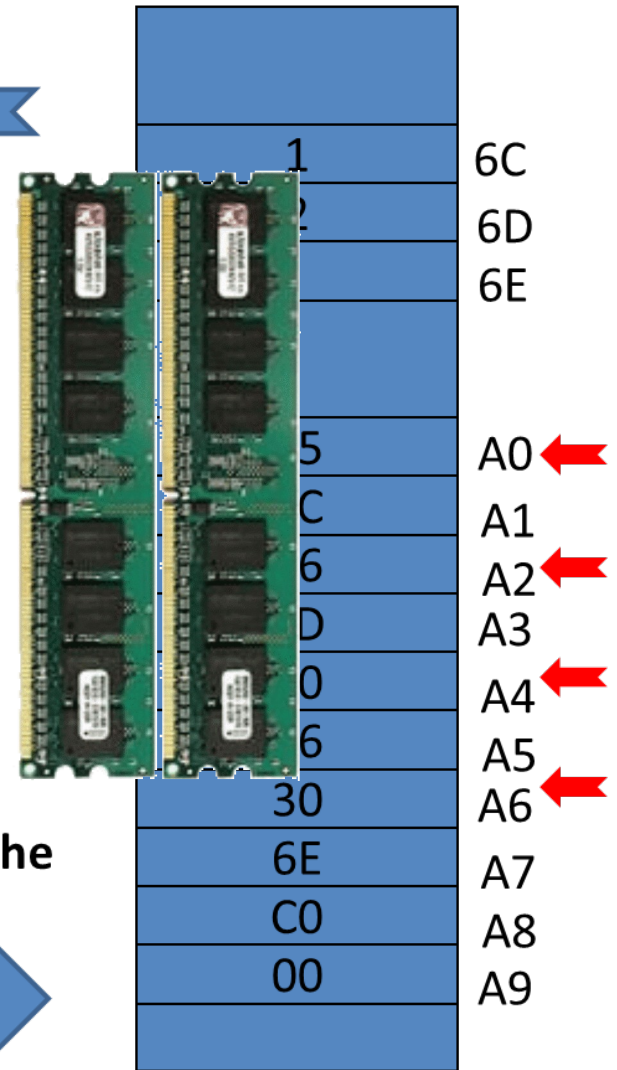


# HDD

**execute instructions serially  
in CPU**



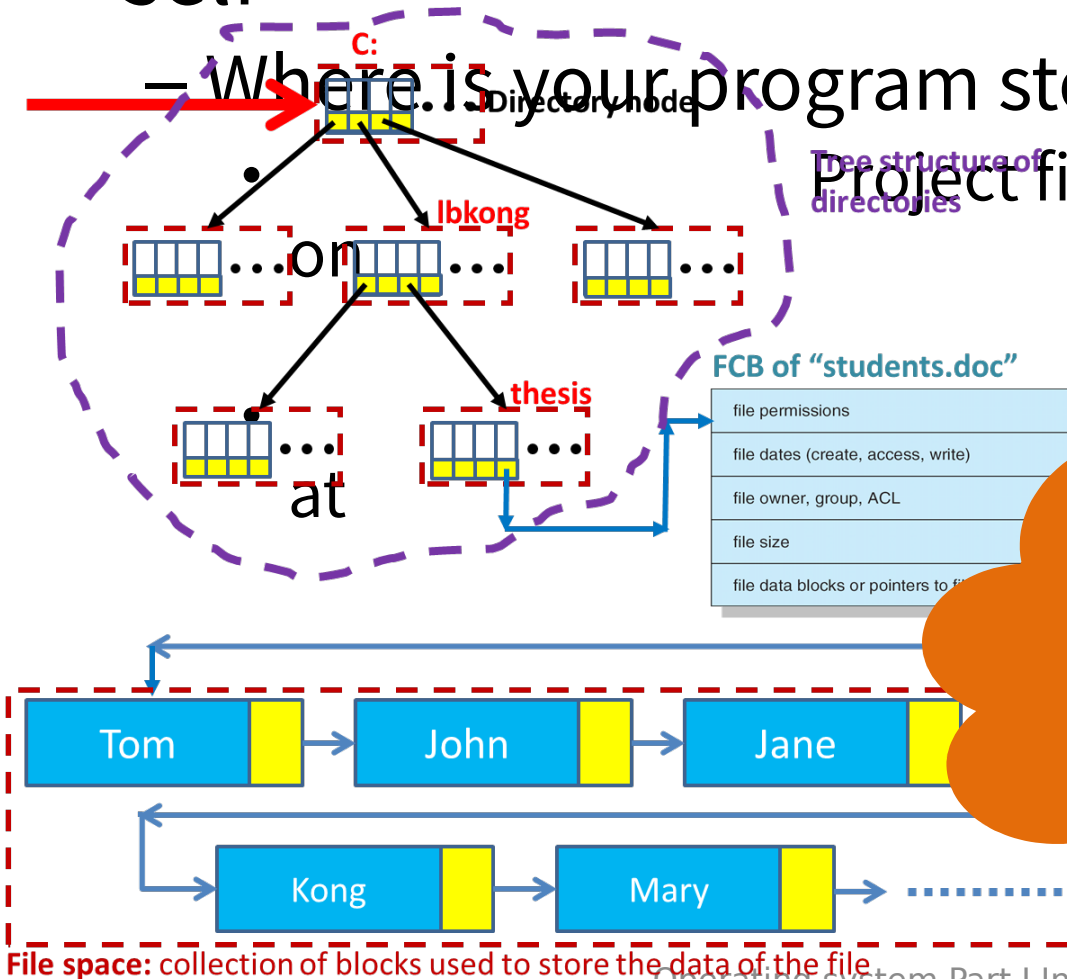
## Put executable codes into the memory of the computer



Instructions are mapped into the address space of memory

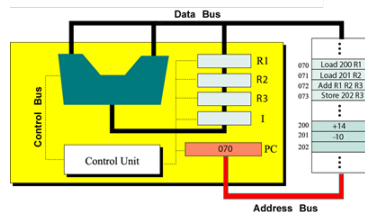
- To support the execution of a program, we need to record some information (define some data structure) – besides the program itself

– Where is your program stored in the HDD?

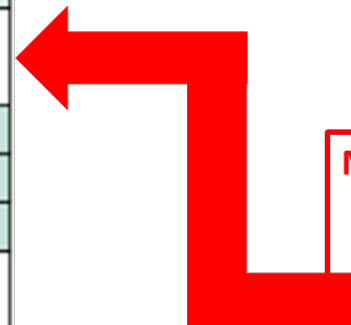


- Where could we copy the program in MM?
- We need information about the usage of MM first
- If available, the program is copied into MM
- We need information to locate the instructions in M

We'll learn  
this how in  
later chapter:  
**MM**



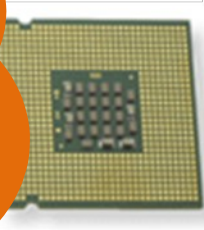
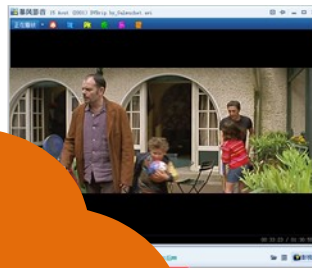
	⋮
070	Load 200 R1
071	Load 201 R2
072	Add R1 R2 R3
073	Store 202 R3
	⋮
200	+14
201	-10
202	
	⋮



Machine code	
[00]	14 (should be bin)
[01]	-10
[02]	(used later)
[03]	0001 00000000
[04]	0010 00000001
[05]	0011
[06]	0100 00000010

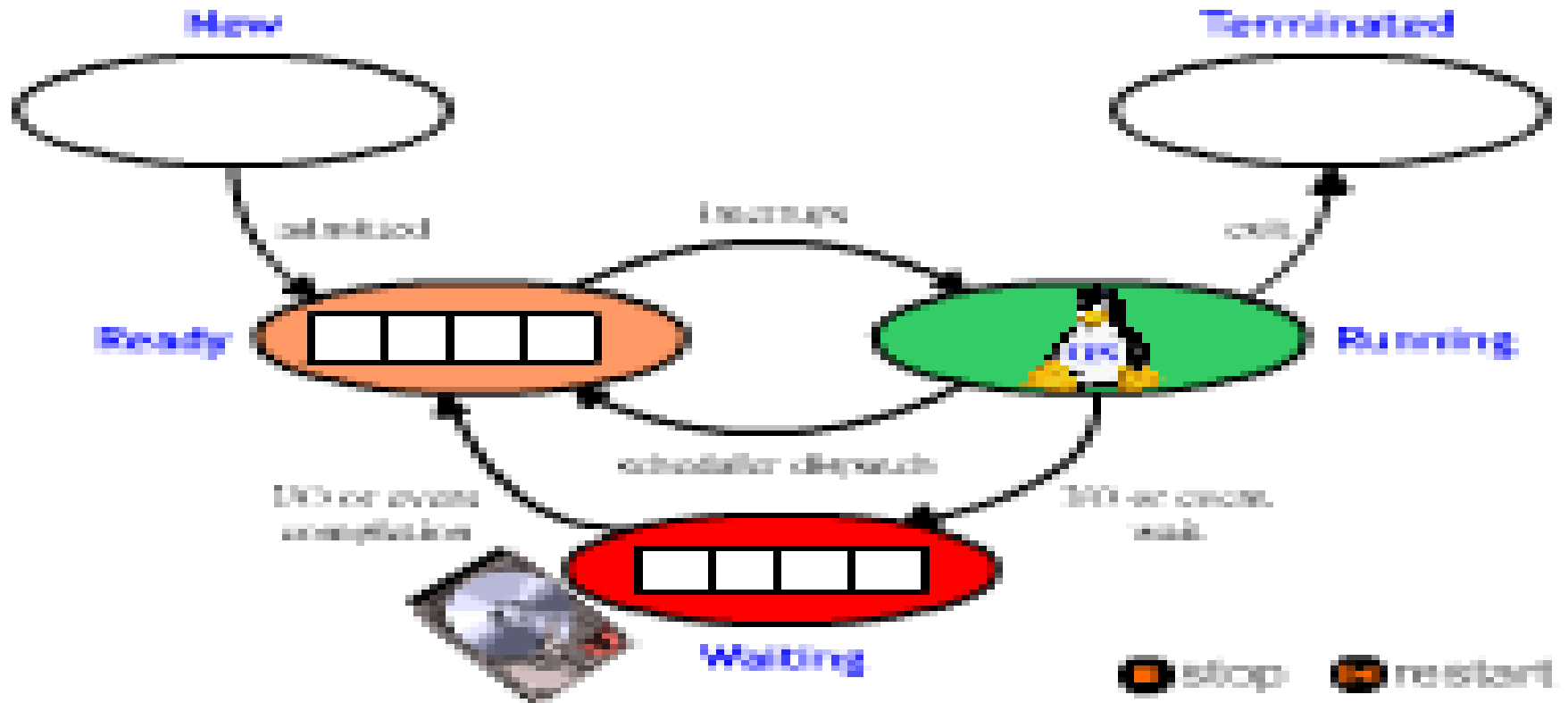
- We also need to record the information of current instruction for CPU switching
  - The address of the instruction when CPU is switched, like 1031

we learn this  
how in later  
chapter: **CPU  
Scheduling**



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# The execution of your program is alive



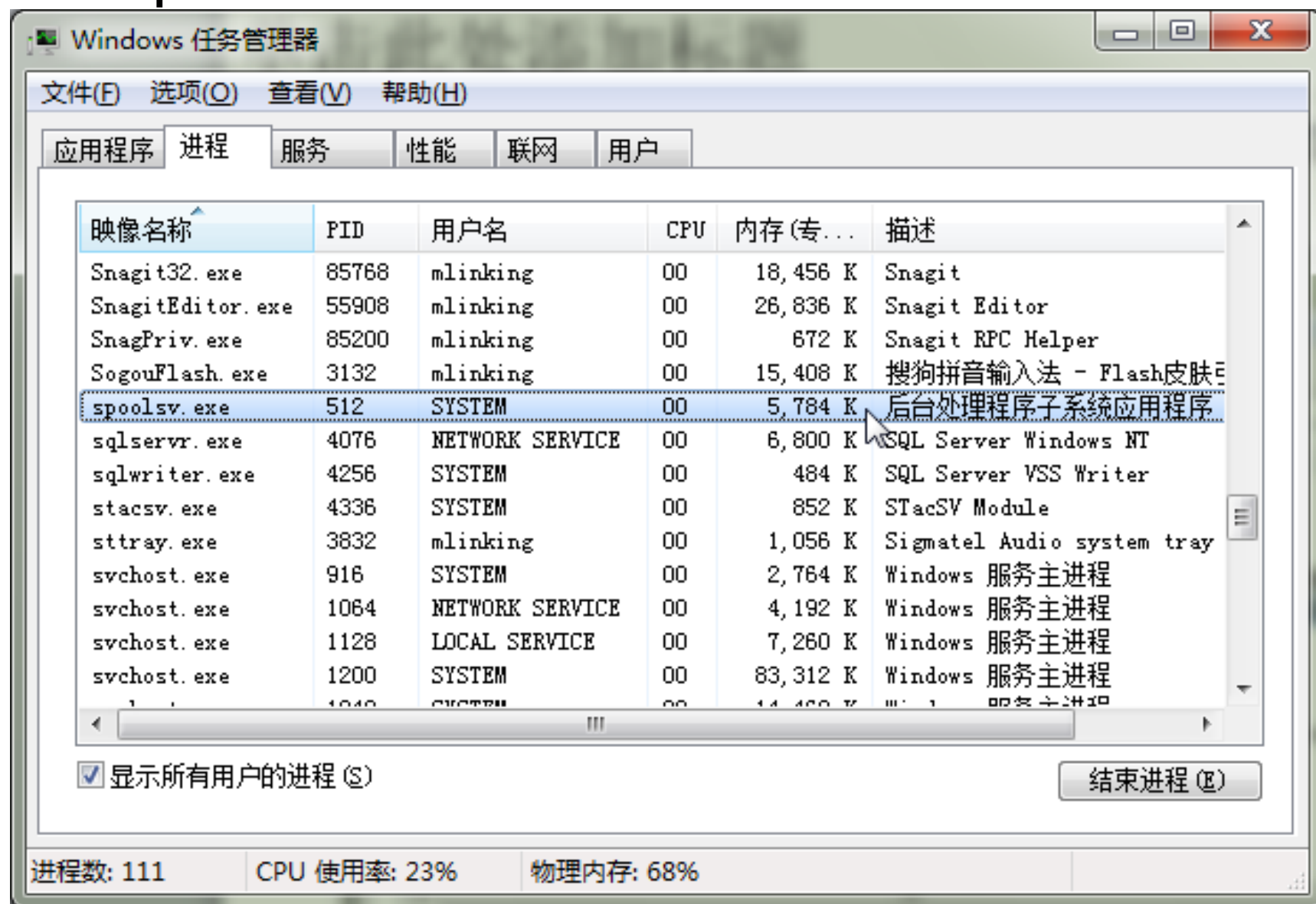


- You have learned how to record that kind of information in programming.
  - Design the **data structure**!
- PCB (Process Control Block) is the one used/named data structure
  1. Process **location** information
  2. Process **identification** information
  3. Process **state** information
  4. Process **control** information

# PCB: Process **Location** Information

- Process **Location** Information: Each process image in memory
  - may **not** occupy a contiguous range of addresses (depends on memory management scheme used, which will be discussed in later MM part).
    - both a private and shared memory address space can be used.
- Process **Identification** Information: A few numeric identifiers may be used
  - Unique process identifier (PID) –
    - indexes (directly or indirectly) into the process table.
  - User identifier (UID) –
    - the user who is responsible for the job.
  - Identifier of the process that created this process (PPID).

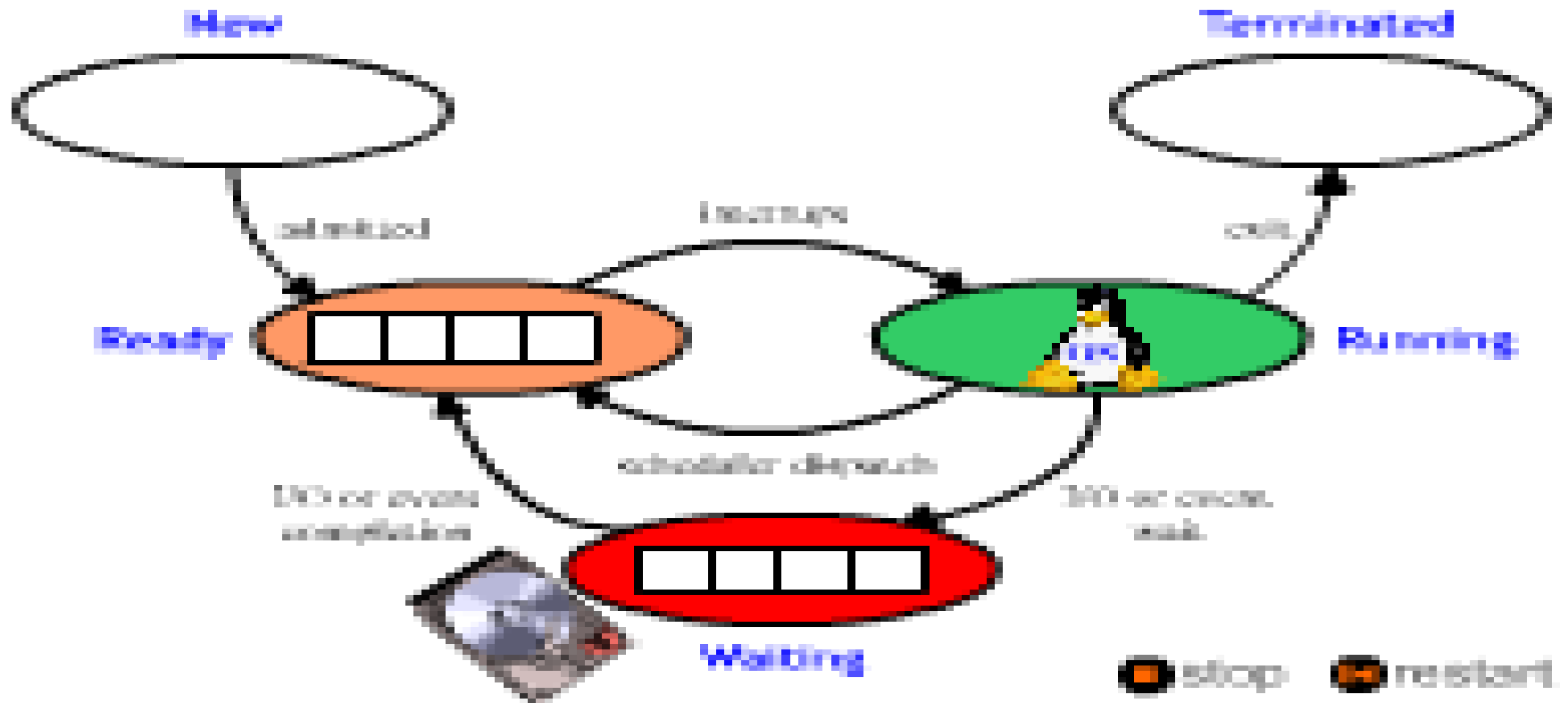
- The process!



Q. What's the meaning of "Control"

- Processor **State** Information:
  - User-visible registers
  - Control and status registers
  - Stack pointers
- Process **Control** Information: Scheduling and state information
  - Process state (i.e., running, ready, blocked...)
  - Priority of the process
  - Relationship with other processes
    - the process is waiting (if blocked).
    - other PCBs for process queues, parent-child relationships and other structures

# The execution of your program is alive



Program execution is dynamic ☾ Process has **states**

- As a process executes, it changes state

- The state of a process is defined by the current activity of that process.

- Each process may be in one of the following states:

- **New**. The process is being created.

- **Running**. Instructions are being executed ≈ Get **CPU**.



- **Waiting**. The process is waiting for some event to occur (such as an I/O completion or reception of a signal).

- **Ready**. The process is waiting to be assigned to a processor.



- **Terminated**. The process has finished execution.

we'll learn  
this how in  
later chapter:  
**CPU  
Scheduling**

# Process Transitions (1)

- Ready  Running
  - When it is time, the dispatcher selects a new process to run.
- Running  Ready
  - the running process has expired his time slot.
  - the running process gets interrupted because a higher priority process is in the ready state.

# Process Transitions (2)

- Running  Waiting
  - When a process requests something for which it must wait:
    - a service that the OS is not ready to perform.
    - an access to a resource not yet available.
    - initiates I/O and must wait for the result.
    - waiting for a process to provide input.
- Waiting  Ready
  - When the event for which it was waiting occurs.



# PCB defined in Linux

- PCB in Linux is defined using a struct **task\_struct**
  - There are many parameters in Linux's PCB
  - The size of each PCB is usually a little larger than 1KB
- ```

struct task_struct{
    ...
    unsigned short uid;
    int pid;
    int processor;
    ...
    volatile long state;
    long priority;
    unsigned long rt_priority;
    long counter;
    unsigned long flags;
    unsigned long policy;
    ...
    Struct task_struct *next_task, *prev_task;
    Struct task_struct *next_run,*prev_run;
    Struct task_struct *p_opptr, *p_pptr, *p_cptr,
    *pysptr, *p_ptr;
};
  
```

(2)int pid is the ID of the current process

(3)int processor: the CPU used by the current process. Support multi-processor

(4)volatile long state: corresponds to the states defined as follows :

**Running** (TASK-RUNING): 可运行状态 ;

**Interruptible** state (TASK-IntERRUPTIBLE): 可中断阻塞状态

**Uninterruptible** state (TASK-UNINTERRUPTIBLE): 不可中断阻塞状态

**Zombie** (TASK-ZOMBIE): 僵死状态

**Stopped** (TASK\_STOPPED): 暂停态

**Swapping** (TASK\_SWAPPING): 交换态

(5)long priority [ 进程的优先级 ]

(6)unsigned long rt\_priority [ 实时进程的优先级, 对于普通进程无效 ]

(7)long counter: a counter for counting the priority

(8) unsigned long policy: you could infer the related operations for PCB data structure. You've been trained in DSA course

scheduling :  
 SCHED\_OTHER( =0) [ 优先级轮转法 ]  
 SCHED\_FIFO( =1) RT [ 实时进程优先级轮转法 ]  
 SCHED\_RR( =2) RT Priority algorithm [ 实时进程优先级轮转法 ]

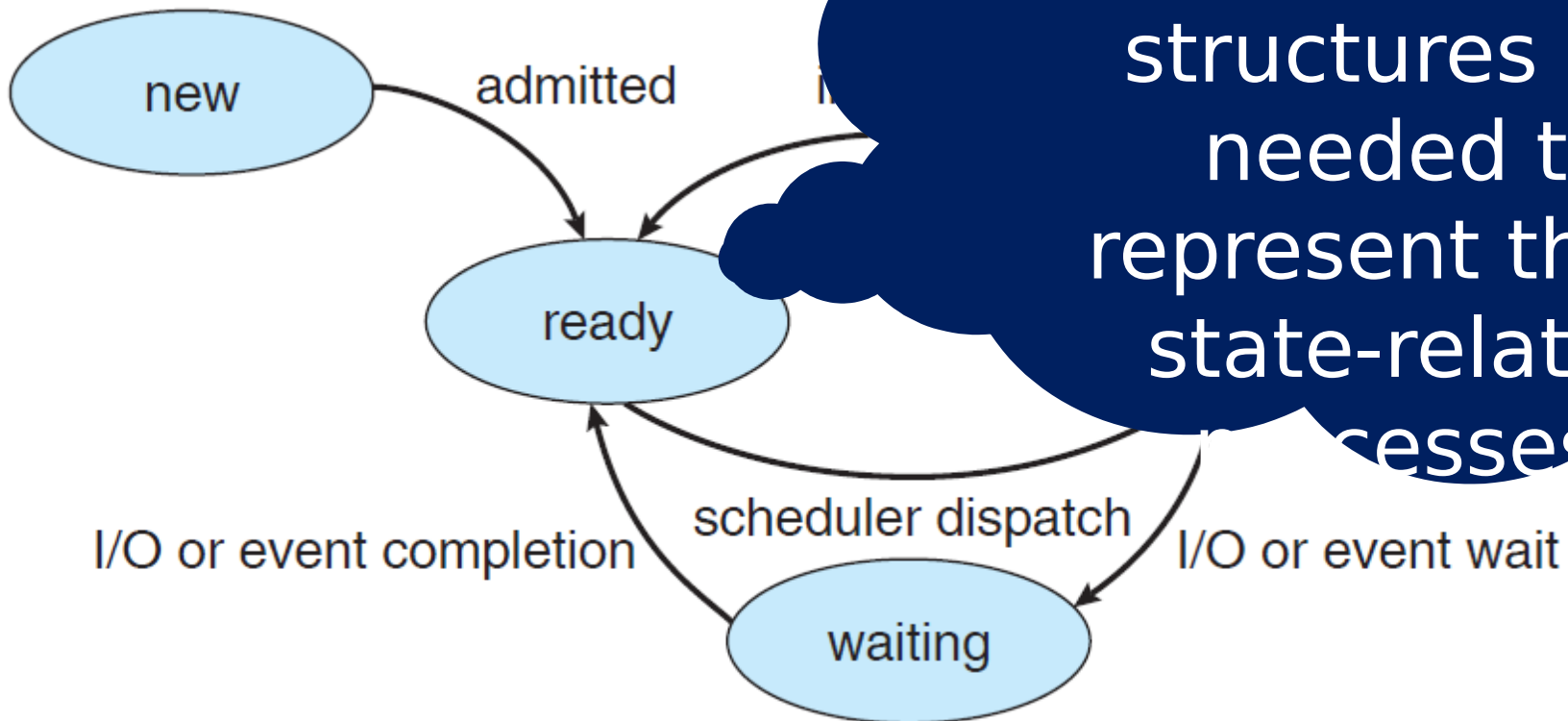
(9) struct task\_struct \*next\_task, \*prev\_task: pointers for PCB's **Double linked lists** [ 进程 PCB 双向链表的前后项指针 ]

(10) struct task\_struct \*next\_run, \*prev\_run: pointers for the PCBs in ready queue [ 就绪队列双向链表的前后项指针 ]

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      - **PCB** is the data structure to record the necessary information: resources (MM, ownership, security, ...), execution stages/states, ...
    - Additional data structures and algorithms are needed to manage the concurrent execution of many programs
      - Queues, and schedulers
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  - Thread[ 线程 ] is the modern concept
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      - CPU is occupied by the process, however the usage of the CPU is shared among the internal execution units (threads)
        - » The resources assigned to the process could be shared by those threads.

# Five-State Model



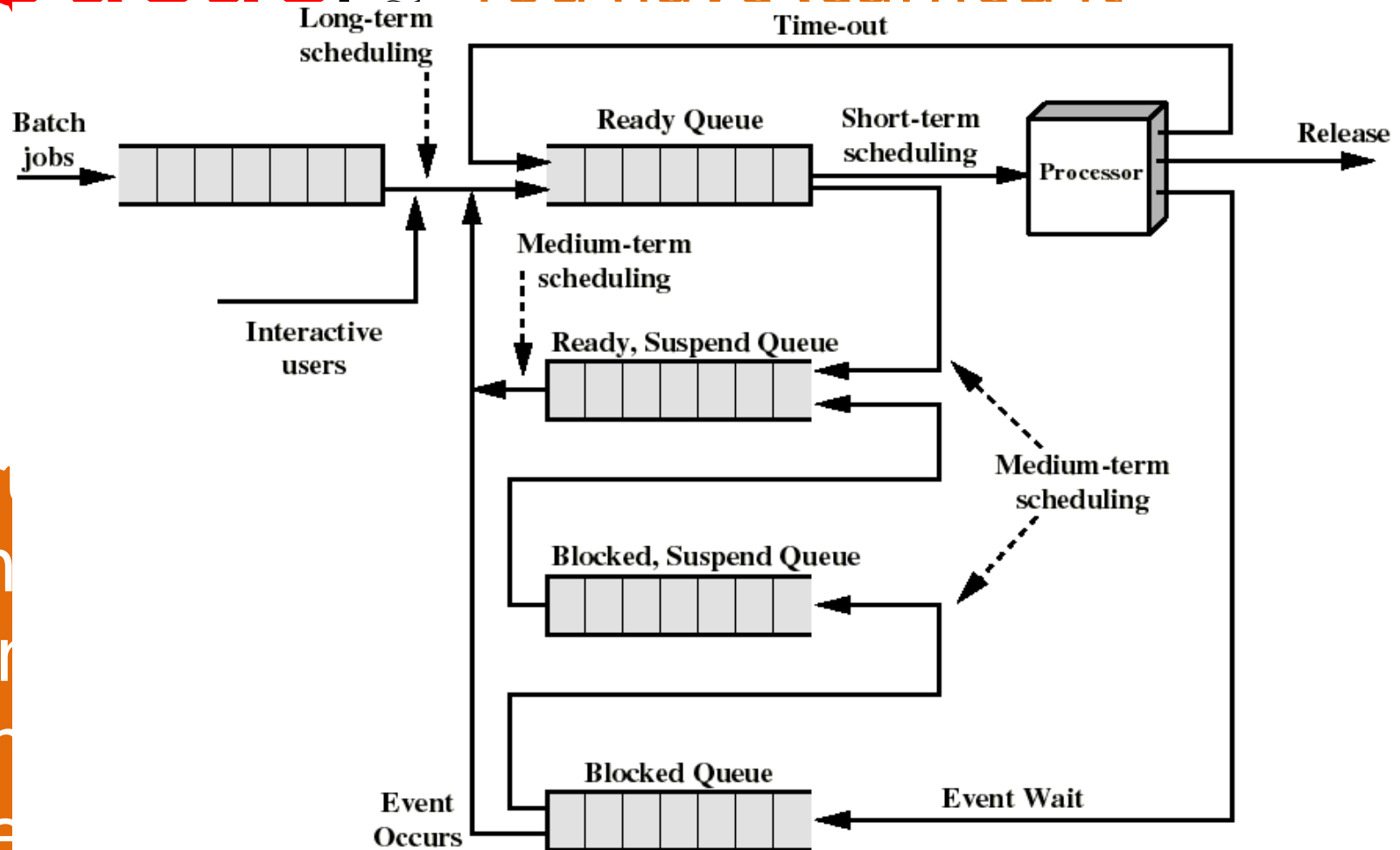
**Figure 3.2** Diagram of process state.

It's also OK to use following 5 states:  
Running, Ready, **Blocked**, New, **Exit**

# Supplement:

Data structures to manage those state-related processes

- **Queue!** You have learned it



rem  
to r  
am  
que

# Three kinds of schedulers

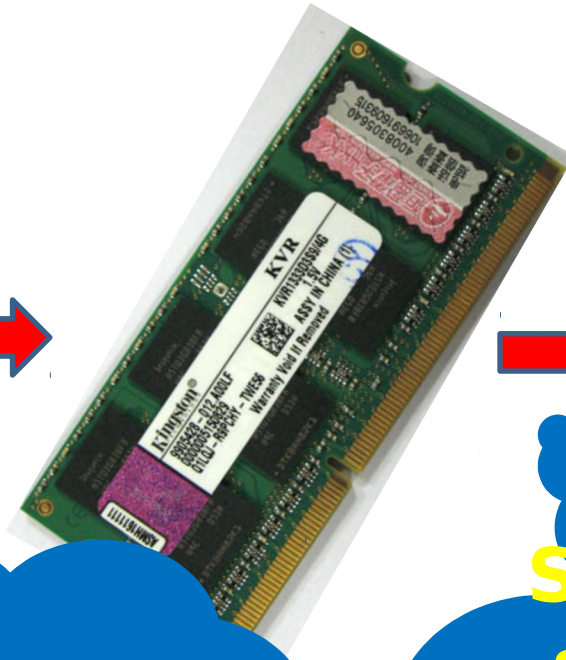
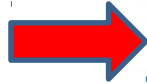
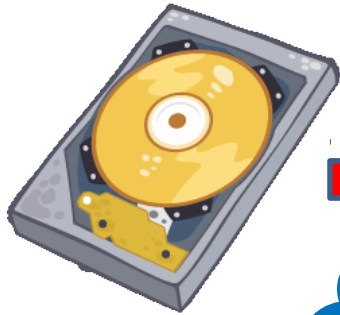
1. Long-term scheduler (**jobs scheduler**) – selects which programs/processes should be brought into the **ready queue**.
2. Medium-term scheduler (**emergency scheduler**) – selects which job/process should be **swapped** out if system is loaded.
3. Short-term scheduler (**CPU scheduler**) – selects which process should be **executed** next and allocates CPU.

PPTs from others\From Ariel J. Frank\OS381\os3-2.ppt

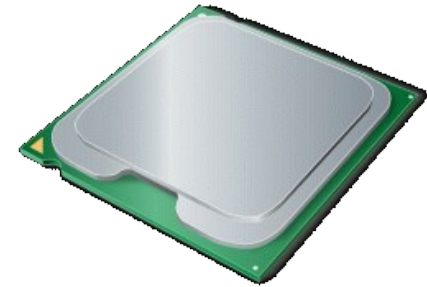
Those queues are used by  
Three kinds of schedulers

## Main Memory

**Storage media**  
(Magnetic disk)



**CPU**



**Long-term scheduler**  
determines  
which **jobs** could  
be transited into  
main memory

**Short-term scheduler**  
determines  
which  
**processes** could  
get the usage  
of CPU



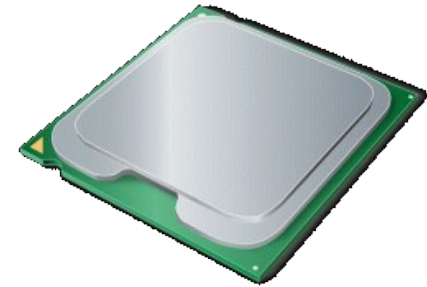
# Three kinds of schedulers

**Main Memory**

**Storage media**  
(Magnetic disk)



**CPU**



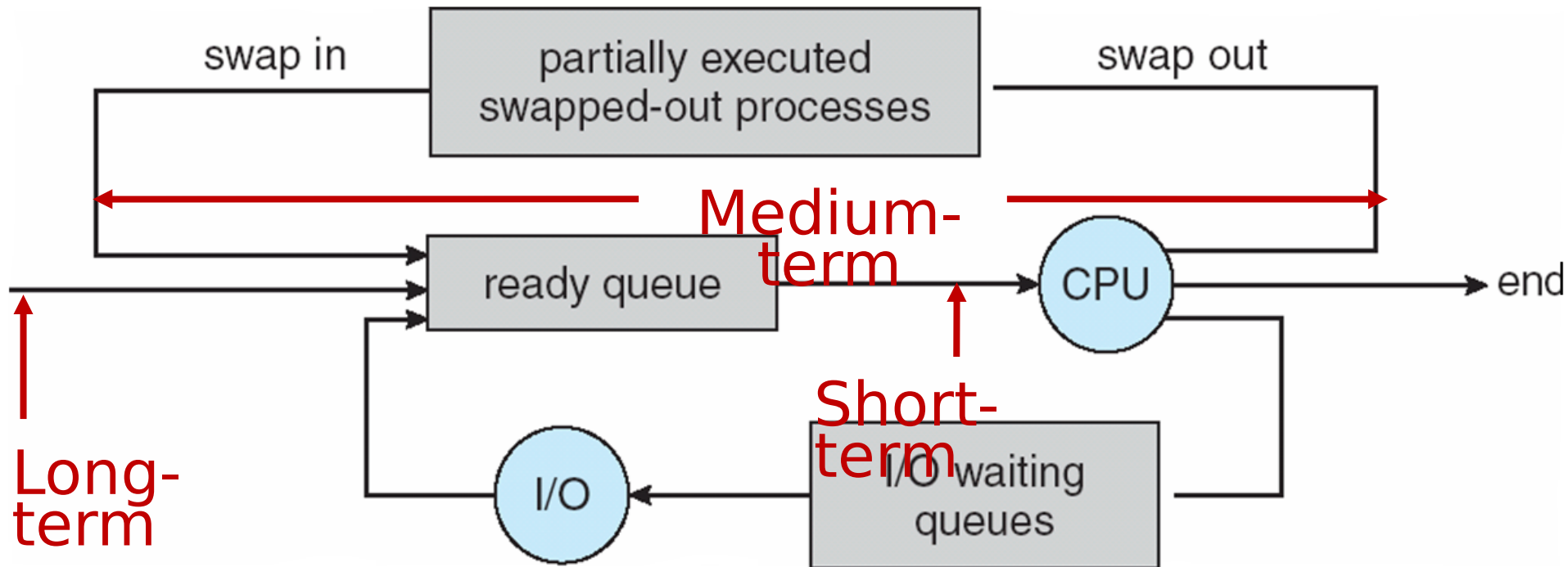
**Mid-term scheduler**

is responsible to swap some processes out of memory or CPU usage

Data structures to store the swapped out processes

# Medium-Term Scheduling

## — Addition of Medium Term Scheduling



\* **Queueing diagram** : A common representation for discussion for of process scheduling is a queueing diagram

# Summary: Sketch of the control for processes

- The execution of a process goes through several states
  - New, Ready, Running, Waiting, Terminated [**Five state model**]
- There are many different models for state transitions

- **Two state model:**

- Running, Not-running

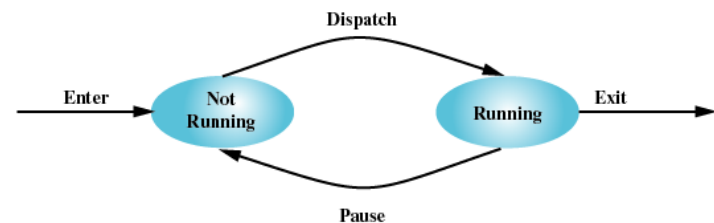
- **Three state model:**

- Ready, Running, blocked

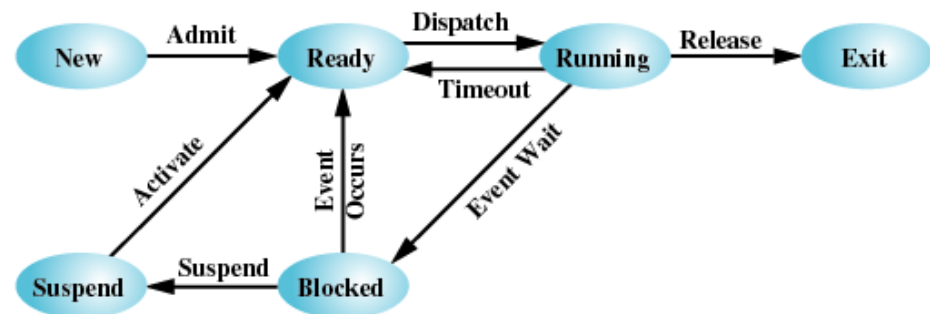
- **Five state model**

- **Six state model**

- Other models



(a) State transition diagram



(a) With One Suspend State

# Suspended Processes

- Processor is faster than I/O so all processes could be waiting for I/O
- **Swap** these processes **to disk** to free up more memory
- Blocked state becomes suspended state  
in **swapped to disk**
- Two new states
  - Blocked/Suspended
  - Ready/Suspended

select which process is swapped out, corresponds to the **midterm scheduling** [中]

# Processes

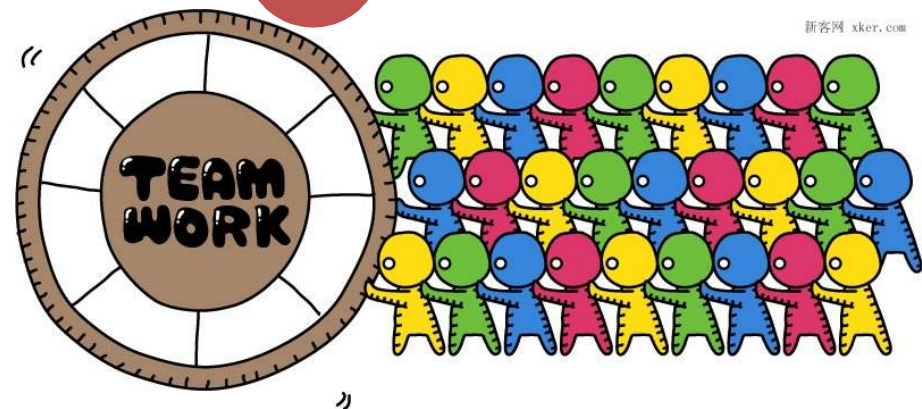
- To understand the execution of your program
  - Process [ 进程 ] is the traditional concept
    - The identification to manage the needed information to run one program
      - **PCB** is the data structure to record the necessary information: resources (MM, ownership, security, ...), execution stages/states, ...
    - Additional data structures and algorithms are needed to manage the concurrent execution of many programs
      - Queues, and schedulers
      - Inter-process communication (IPC)
  - Thread[ 线程 ] is the modern concept
    - The idea could be seen as **MULTIPLEXing process**, *namely that your program is constructed to have more than one execution units*
      - CPU is occupied by the process, however the usage of the CPU is shared among the internal execution units (threads)
        - » The resources assigned to the process could be shared by those threads.

# Concurrency OF COURSE is of course not

- Concurrent process system allows for the (usually or destructively)
  - The simplest example: two processes are

FREE! The cooperation leads to complexity – deadlock and data inconsistency in later chapters

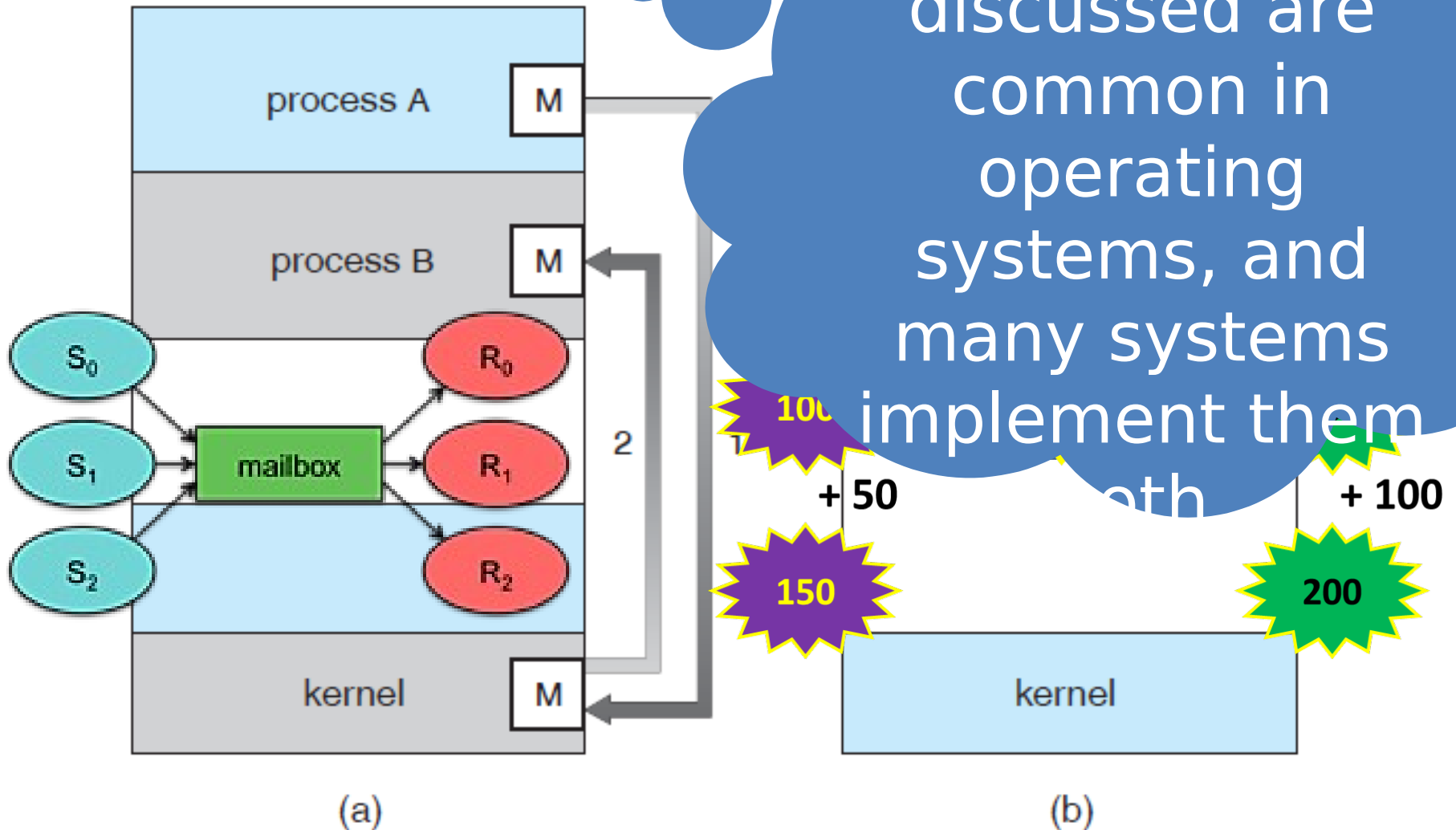
- Reasons for cooperating processes
  - Several processes may need to access the same data (such as stored in a file)
  - Information sharing
  - Computation speed-up
  - Modularity
  - Convenience



# IPC: Inter-Process Communication

- Cooperating processes require an inter-process communication (IPC) mechanism that will allow them to exchange data and information.
- There are two fundamental models of inter-process communication:
  - Shared memory
  - Message passing
    - message passing interfaces, mailboxes and message queues
    - sockets, STREAMS, pipes

# IPC: two fundamental types



**Figure 3.13** Communications models. (a) Message passing. (b) Shared memory.



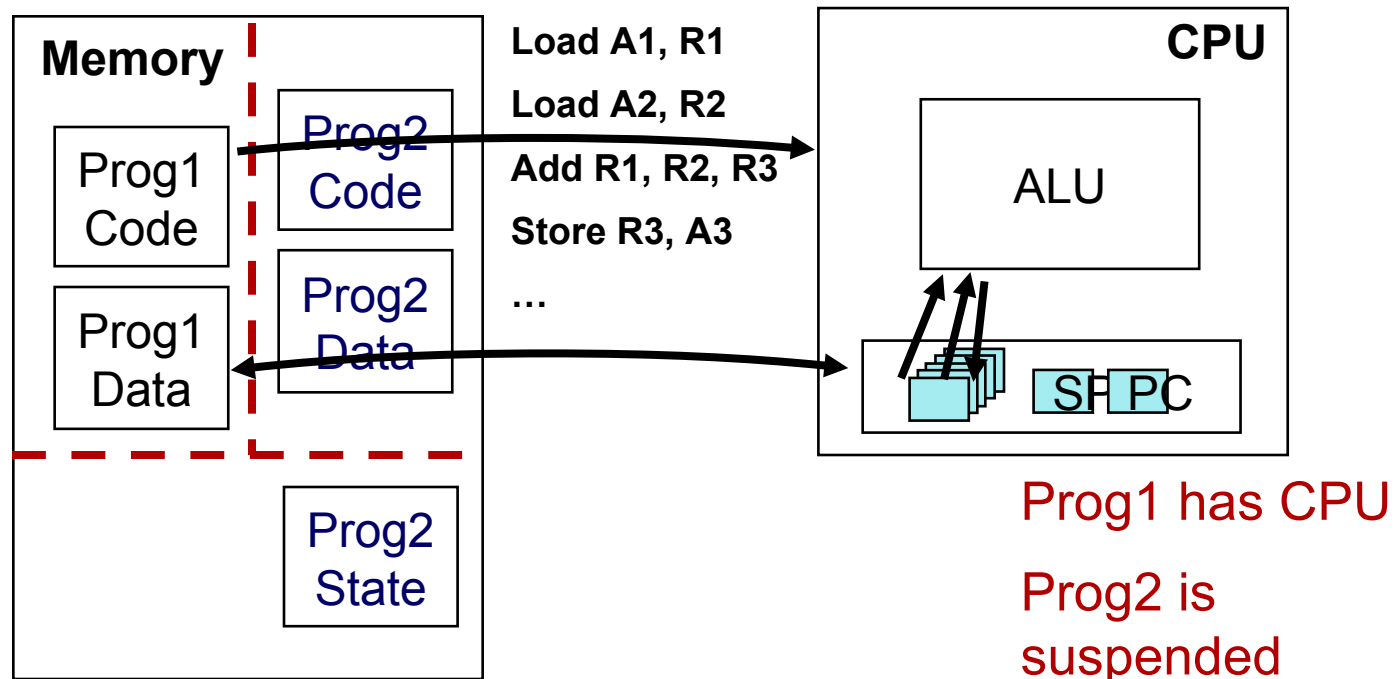
# Processes

- To understand the execution of your program
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        - » The resources assigned to the process could be shared by those threads.

# Process switching is **EXPENSIVE!**

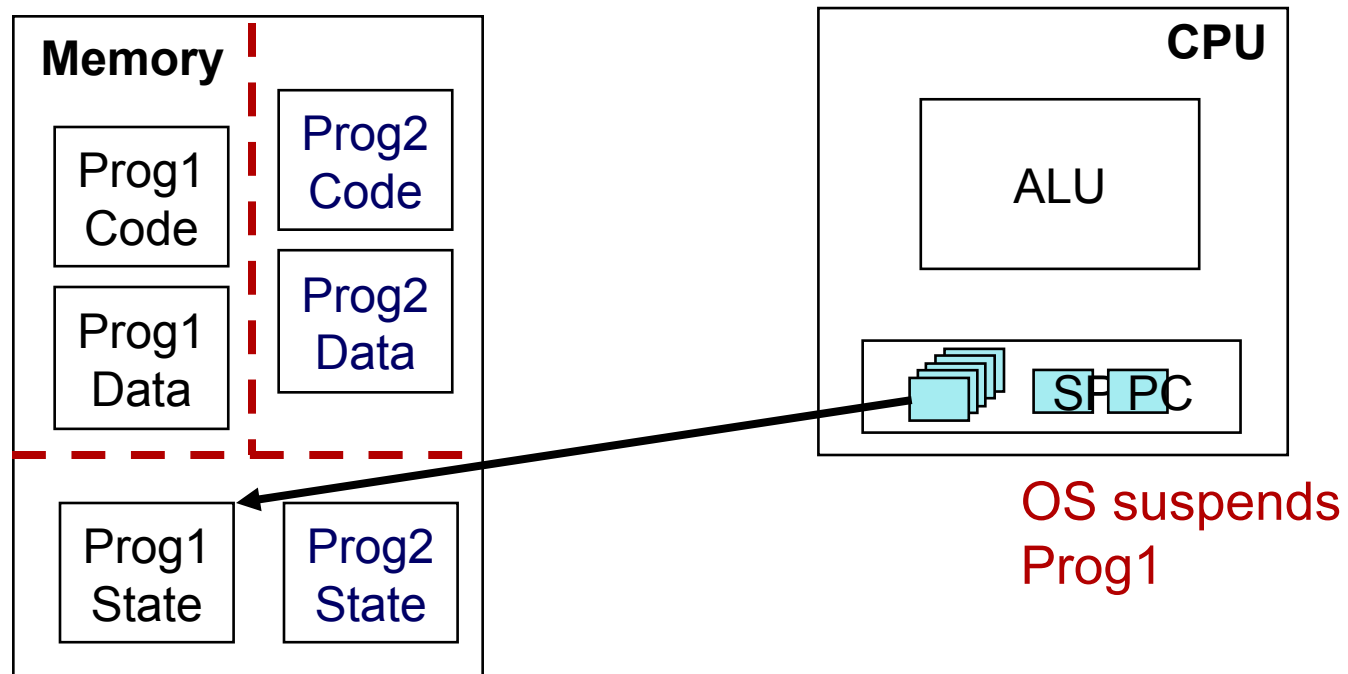
## Context Switching

- Program instructions operate on operands in memory and (temporarily) in registers



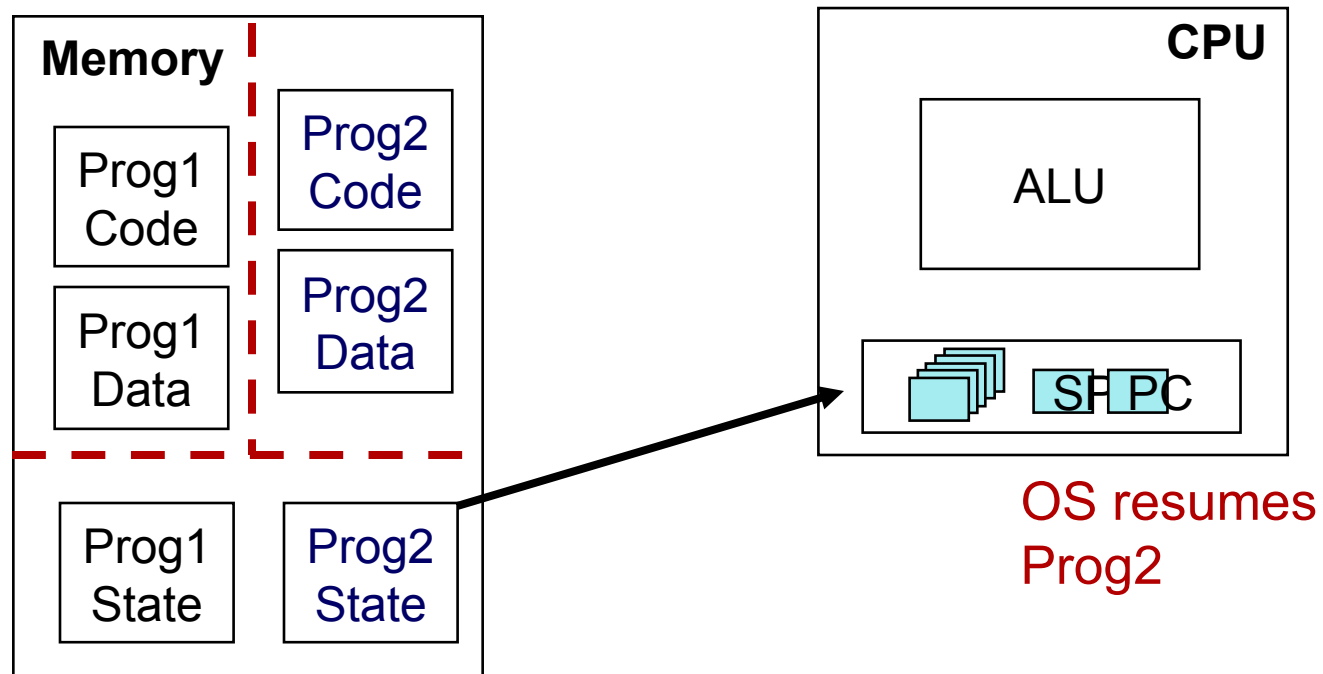
# Context Switching

- Saving all the information about a process allows a process to be temporarily suspended and later resumed from the same point



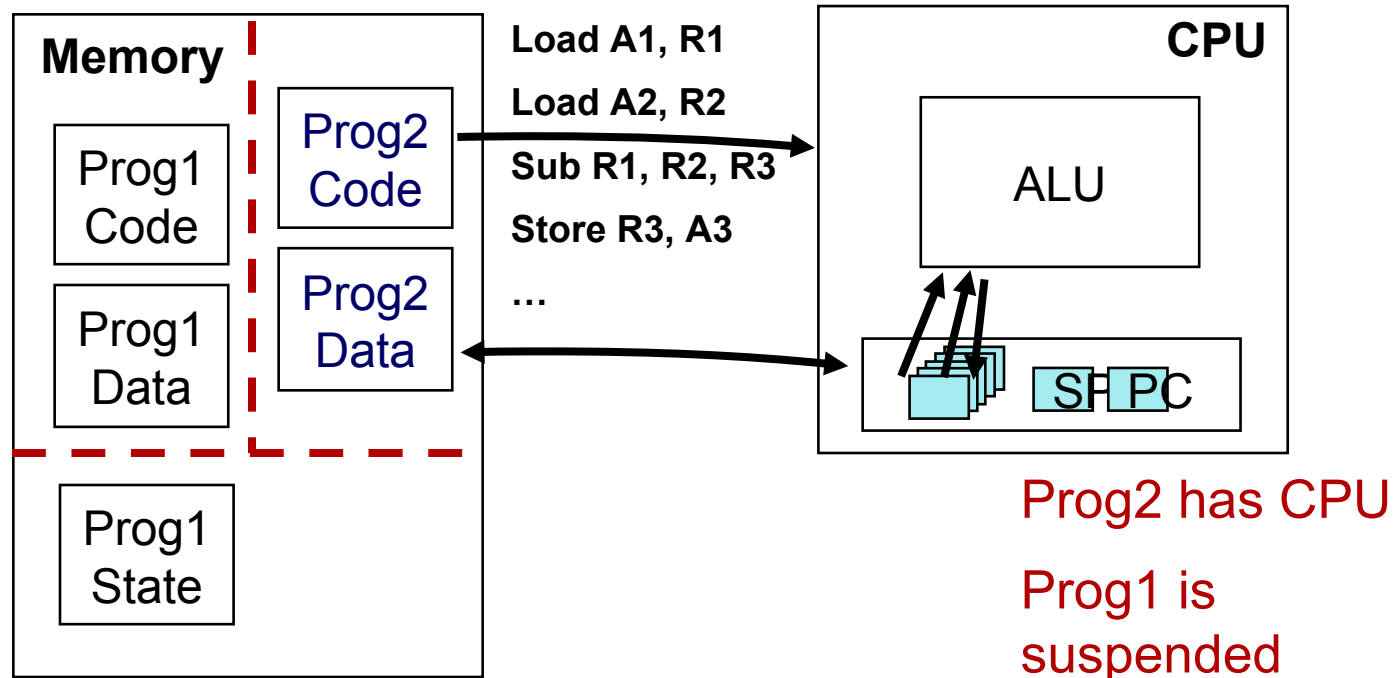
# Context Switching

- Saving all the information about a process allows a process to be temporarily suspended and later resumed



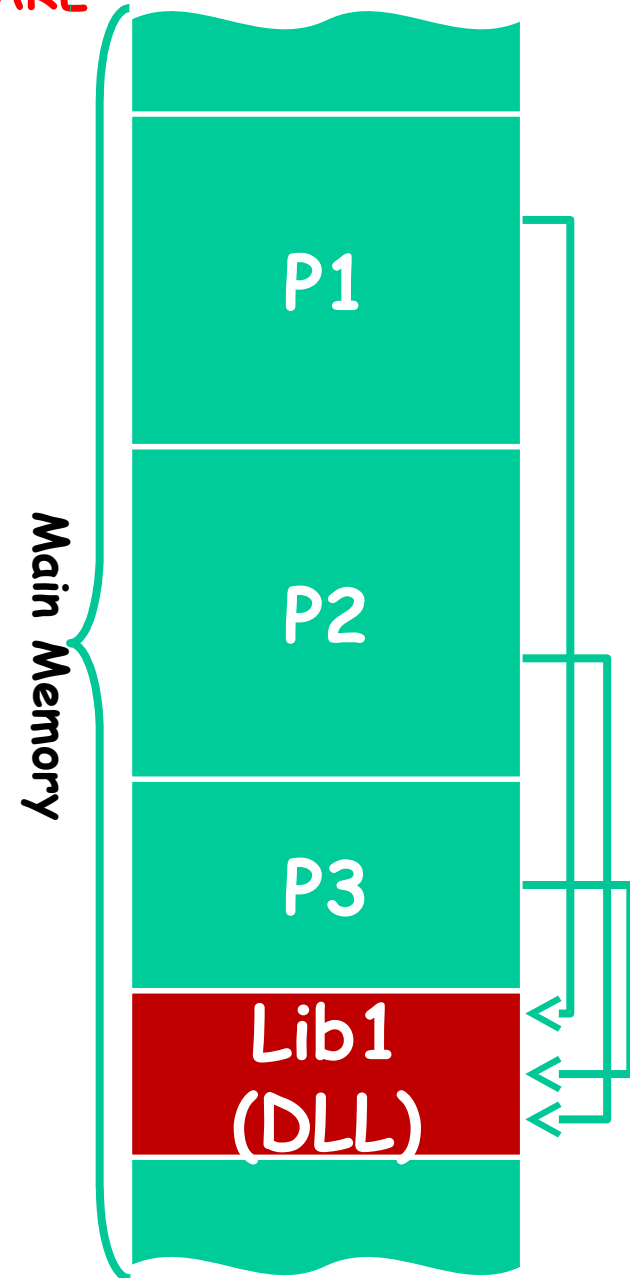
# Context Switching

- Program instructions operate on operands in memory and in registers



How to overcome the cost? **SHARE**  
- Analogous with DLL

- ❑ Three programs (P1, P2, P3) share same DLL (lib1)
- ❑ Namely, there is only a copy of the functions defined in lib1 in the MM
- ❑ And, those programs may access different function in lib1
  - ① So, each program should remember some information of the target functions (called **CONTEXT**[上下文]) in lib1



## SHARE + CONTEXT: multiple services in one program

- We can use 1 CPU + 1 MM space + 1 HD to support **MULTIPROGRAMMING** - the basis of modern OSs, namely concurrently running many processes
- How about providing multiple services with one program? (**MULTISERVING?**)
  - If so, there is **only one copy of the instructions** of those server programs or MS Word in MM, which can provide services for many users/requests
- 👤 This is obviously **economical** and **efficient** way!

# Here comes **thread**

- Concept of Process has two facets.
- A Process is:
  - A Unit of resource ownership – process is allocated:
    - a virtual address space for the process image
    - control of some resources (files, I/O devices...)
  - A Unit of execution/dispatching - process is an execution path through one or more programs (functions, code segments)
    - may be interleaved with other processes
    - execution state (Ready, Running, Blocked...) and dispatching priority

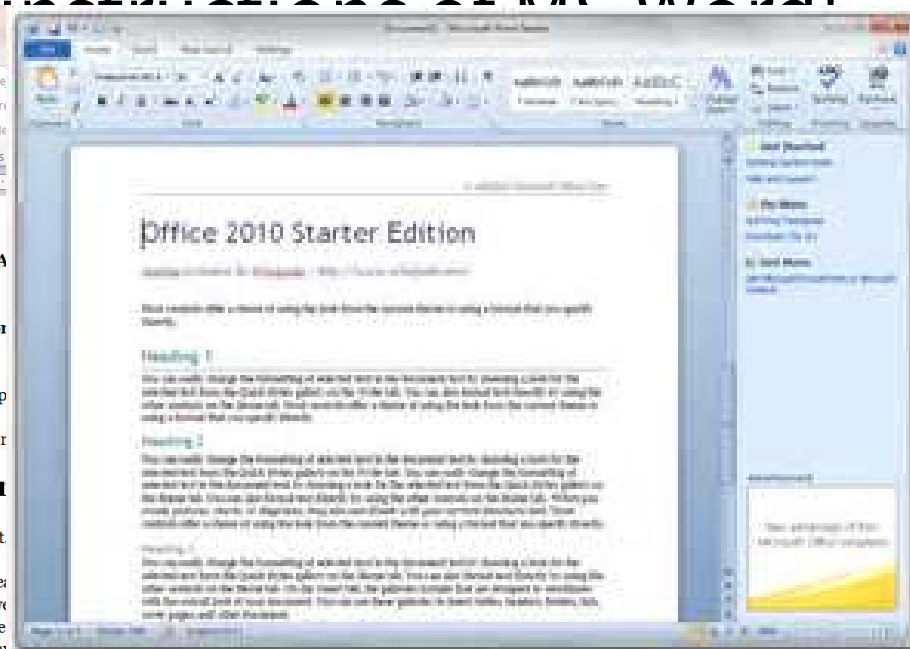
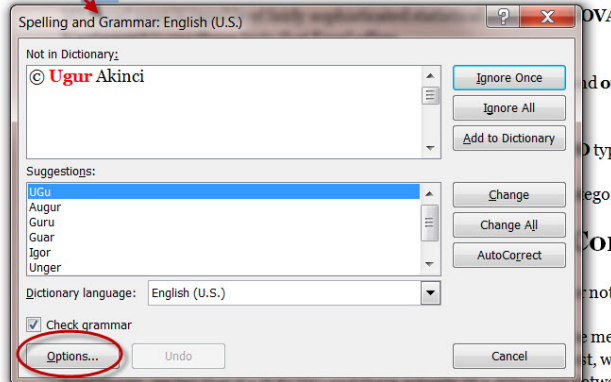
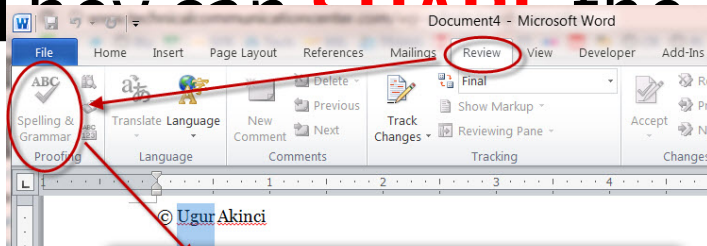


- These two characteristics are treated separately by some recent operating systems:
  - The unit of **resource ownership** is referred to as a **Task** or (for historical reasons) also as a **Process**.
  - **The unit of dispatching** is referred to a **Thread**.
- Ⓟ A thread is an execution unit inside a process/program, which could be scheduled directly for CPU (this depends on the OS)
  - Several threads can exist as services in the same task/process.

# You've experienced THREAD

- MS Word
  - If you want to edit **M** documents, it is definitely too expensive to run **M** MS Words for those documents!

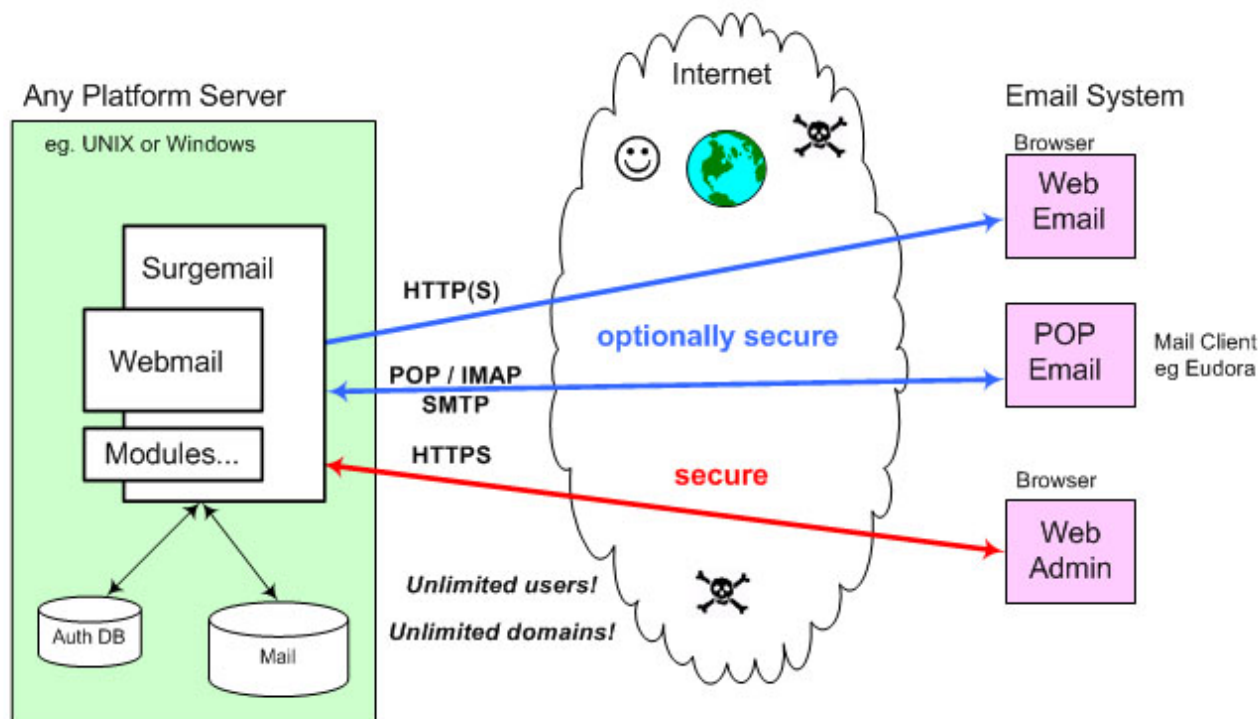
They can **SHARE** the instructions of MS Word!



the categories of independent variables. That's one and the same thing as sa

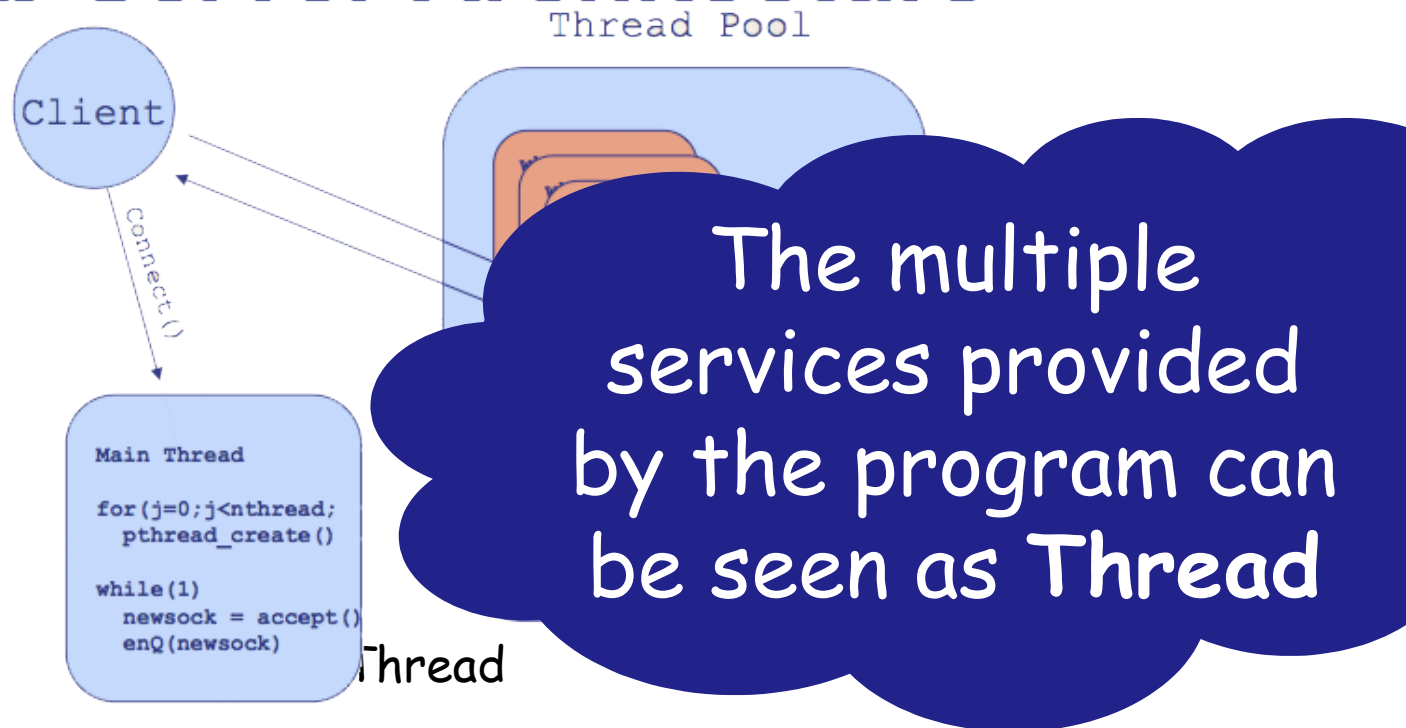
Thread now is popular, especially for high performance servers

- **Web server, FTP server, DBMS server, e-mail server, ...**
  - **N** users access those servers, and if we prepare **N** server processes for each user.
    - It's definitely too expensive to create many servers to respond to these users
  - They can **SHARE** the instructions of the server

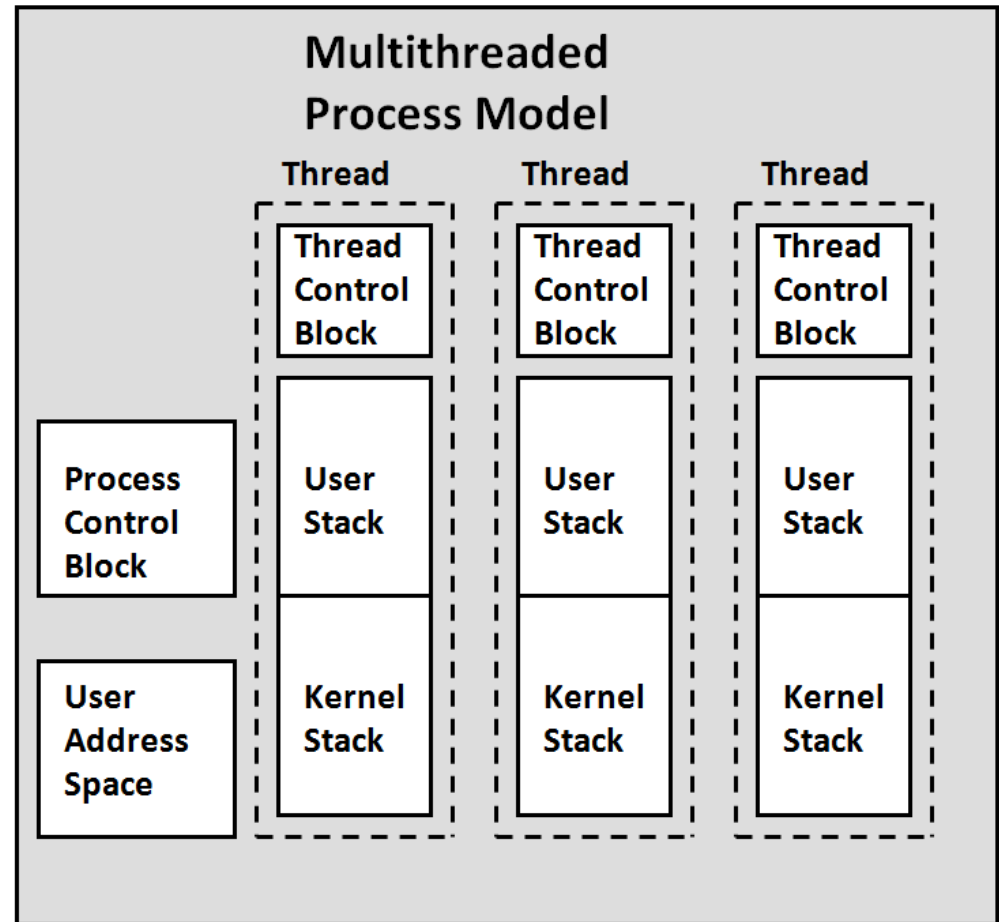
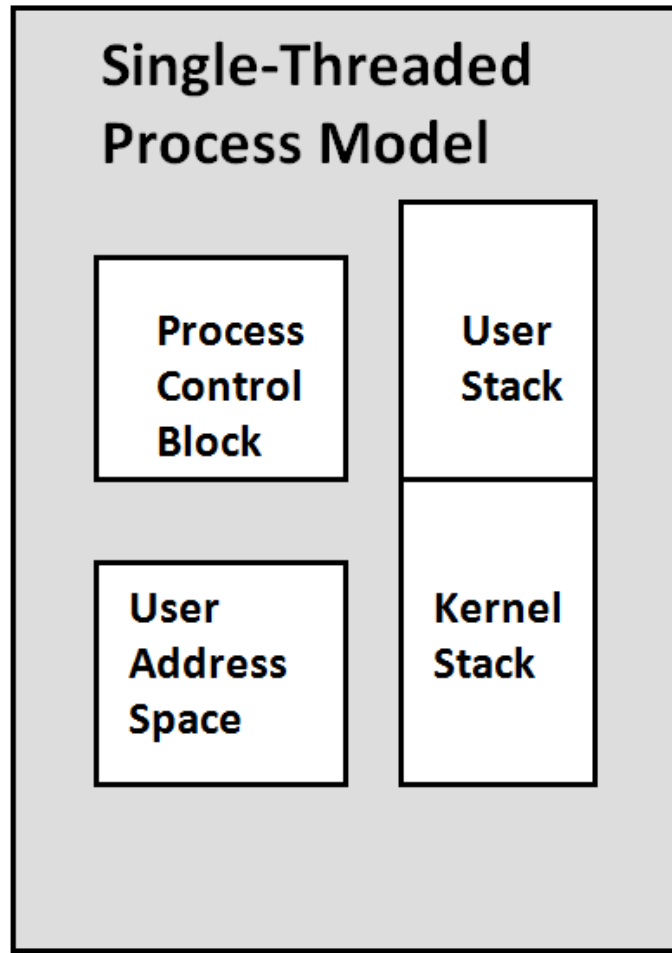


- Here is a sketch of Web server architecture
  - Web server runs as a daemon ['di:mən] program
  - When a client connects the server, the server provides the service for the client

## Web Server Architecture



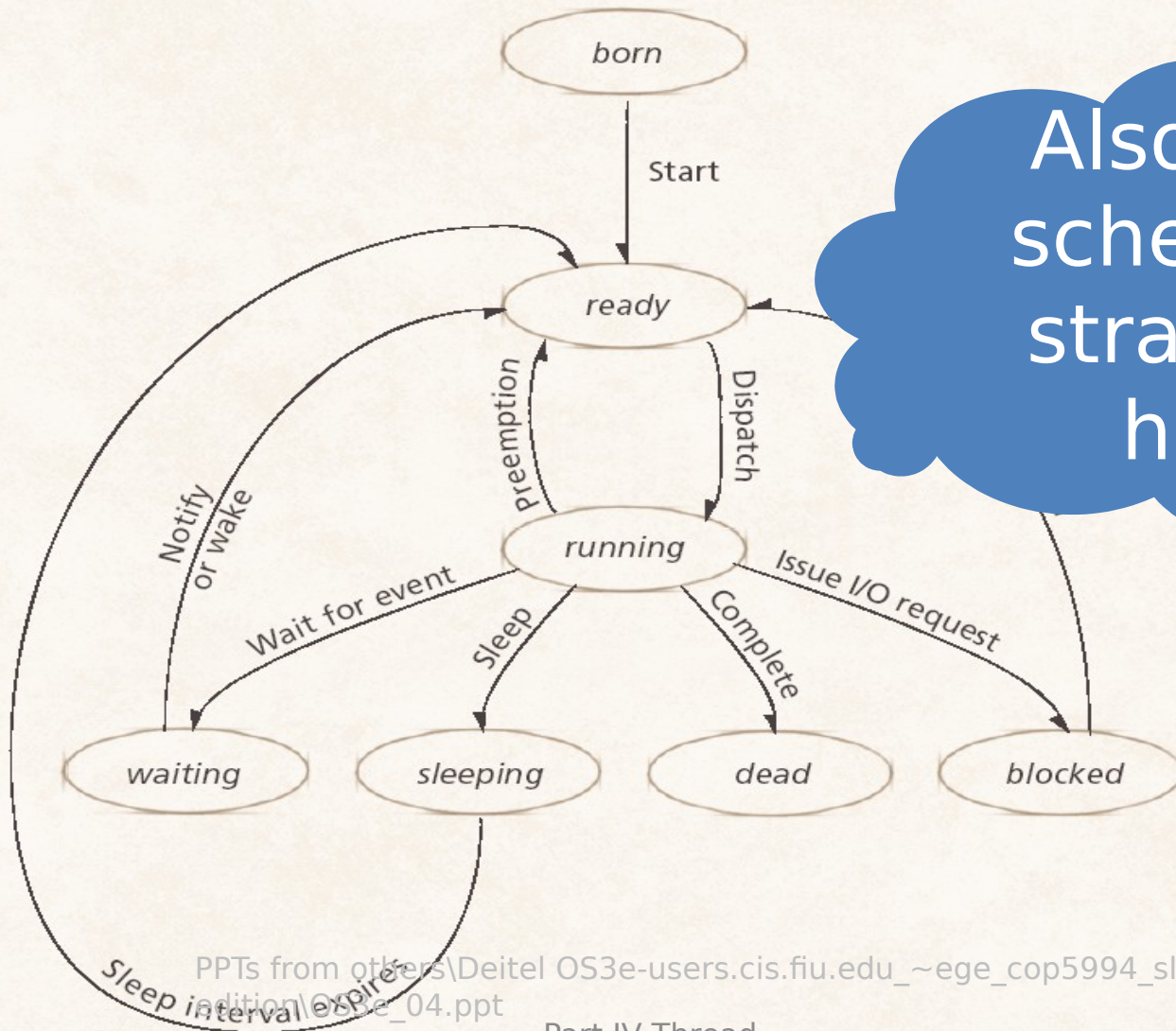
# Single Threaded and Multithreaded Process Models



Thread Control Block (TCB)

contains a register image, thread priority and thread state information

# Thread States: Life Cycle of a Thread



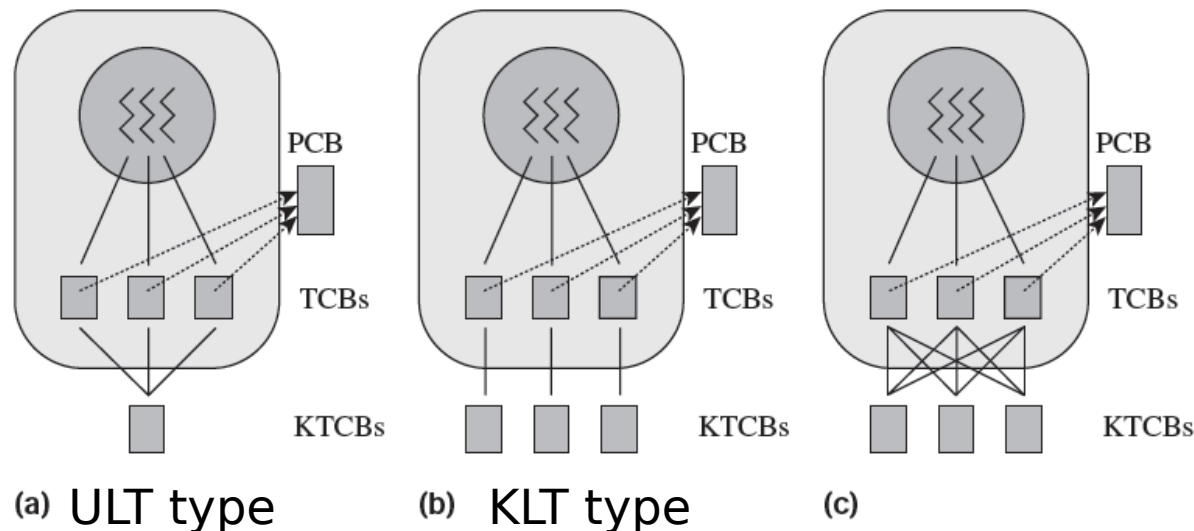
Also need scheduling strategies here!

# Thread Operations

- Threads and processes have **common** operations
  - **Create, Exit** (terminate), **Suspend, Resume, Sleep, Wake**
- Thread operations **do not correspond precisely to** process operations
  - Cancel
    - Indicates that a thread should be terminated, but does not guarantee that the thread will be terminated
    - Threads can mask the cancellation signal
  - Join
    - A primary thread can wait for all other threads to exit by joining them
    - The joining thread blocks until the thread it joined exits

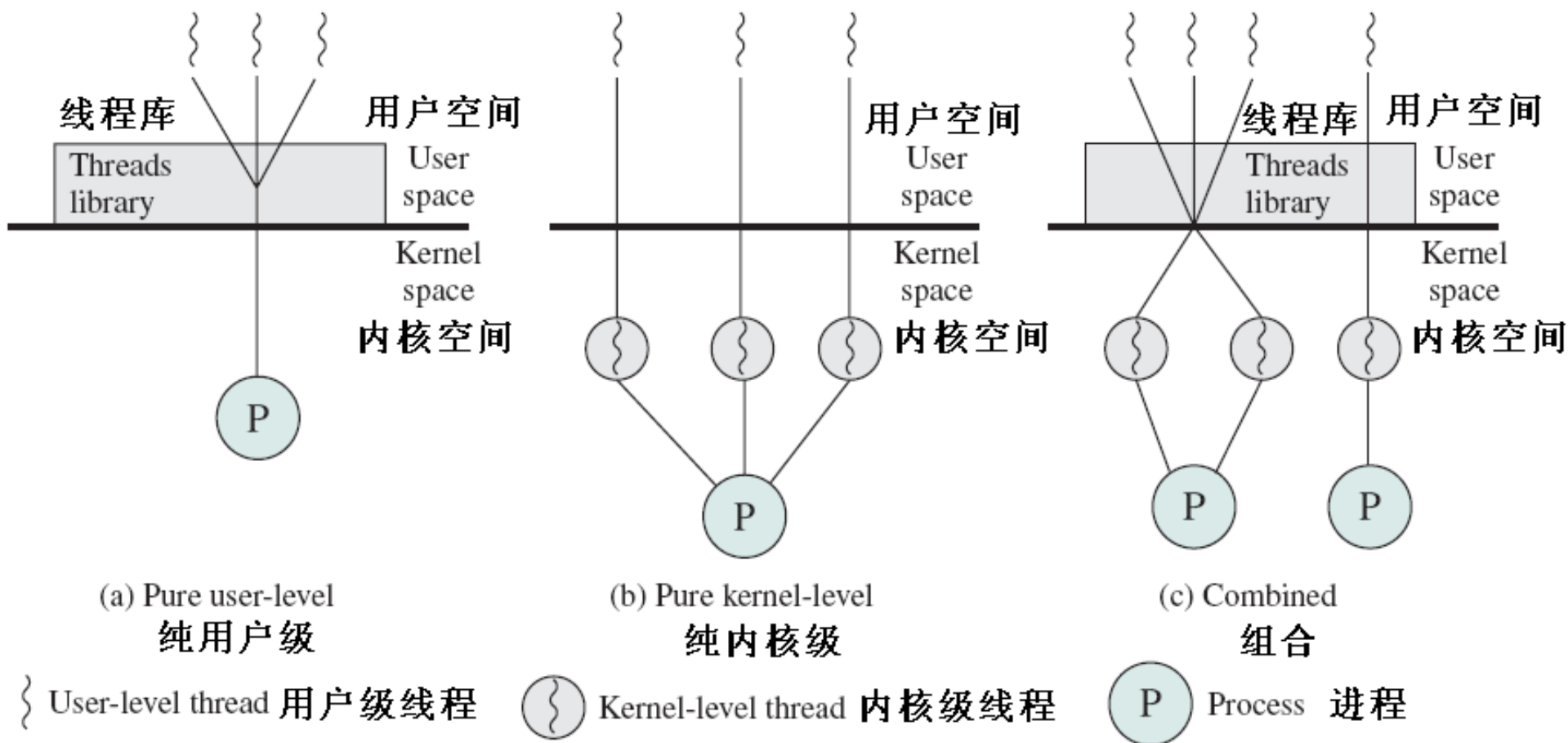
# Thread libraries

- To implement threads, a threading library (either in **user space** or **kernel space**) is responsible for handling the saving and switching of the execution context from one thread to another.
  - We have ULT (User-Level Thread) and KLT (Kernel-Level Thread).
- Multithreaded application



**Figure 5.17** (a) Many-to-one; (b) one-to-one; (c) many-to-many associations in hybrid threads.





## User-Level and Kernel-Level Threads 用户级与内核级线程

# Threads library

- Contains code for:
  - creating and destroying threads
  - passing messages and data between threads
  - scheduling thread execution
    - pass control from one thread to another
  - saving and restoring thread contexts
- ULT can be implemented on **any** Operating System, because **no kernel services are required** to support them
  - POSIX Pthreads, Mach C-threads, Solaris UI-threads

PPTs from

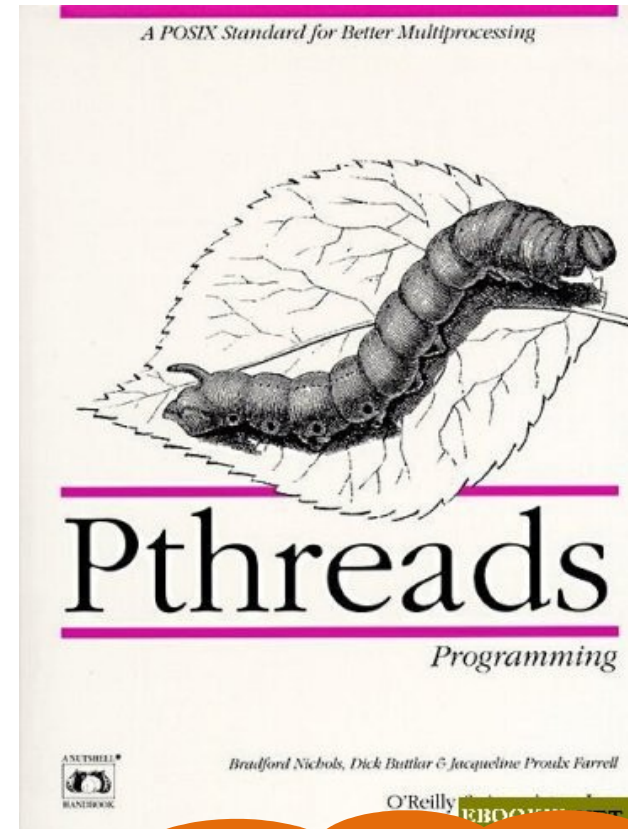
others\flame.cs.dal.ca\_~hawkey\_3120\June30Threads.ppt

Part IV Thread



# POSIX and Pthreads

- **Pthreads**, the threads extension of the POSIX standard, may be provided as **either a user- or kernel-level library**
  - POSIX states that processor registers, stack and signal mask are maintained individually for each thread
  - POSIX specifies how operating systems should deliver signals to Pthreads in addition to specifying several thread-cancellation modes



We've seen  
Java thread

# Win32 Threads (Windows XP)

- The **Win32** thread library is a **kernel-level library** available on Windows systems
  - Actual unit of execution dispatched to a processor
  - Execute a piece of the process' s code in the process' s context, using the process' s resources
  - Execution context contains
    - Runtime stack
    - State of the machine' s registers
    - Several attributes

**+bonus**

# Java Threads

- Java allows the application programmer to create threads that can port to many computing platforms
- Threads
  - Created by class Thread
  - Execute code specified in a Runnable object's run method
- Java supports operations such as naming, starting and joining threads

- The **Java** thread API allows threads to be created and managed **directly in Java programs**
  - However, because in most instances the JVM is running on top of a host operating system, the Java thread API is generally implemented using a thread library available on the host system.
- ☾ This means that **on Windows systems, Java threads are typically implemented using the Win32 API**; UNIX and Linux systems often use Pthreads

# Java Threads

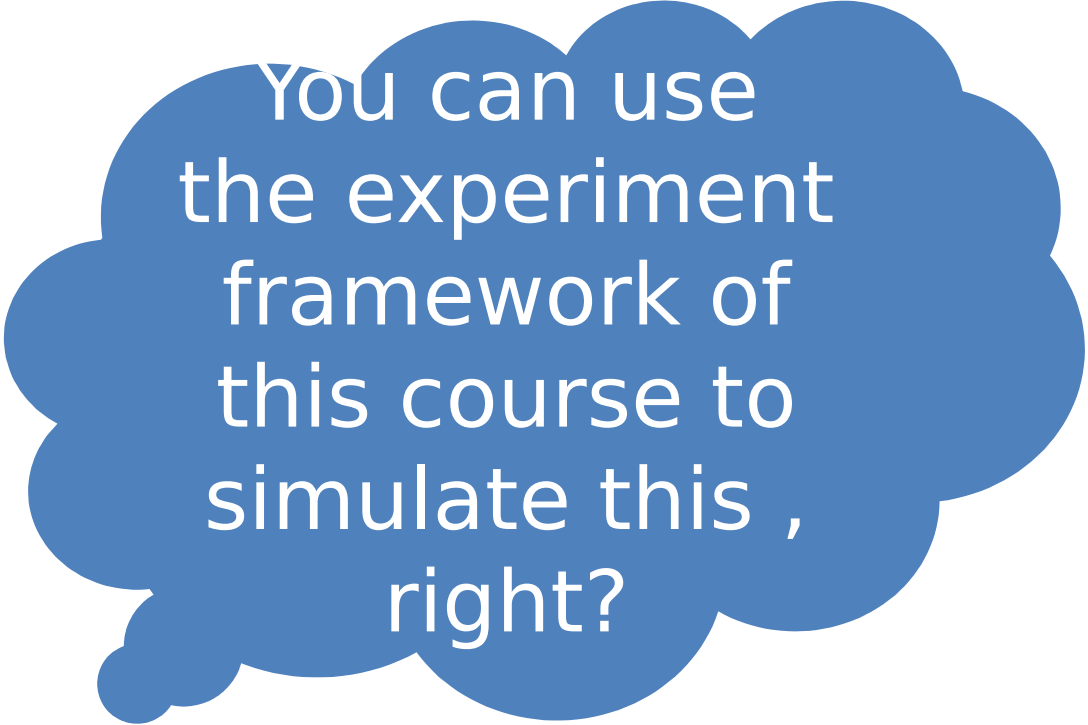
- Example showing interleaved thread execution :

```
class SimpleThread extends Thread {  
    public SimpleThread (String str) {           // superclass constructor  
        super (str);  
    }  
    public void run () {  
        for (int i=0; i<10; i++) {  
            System.out.println (i + " " + getName() );  
            try { sleep ((int) (Math.random  
( ) * 1000));  
            catch (InterruptedException e) {  
            }  
            System.out.println ( "Finished " +  
        }  
    }  
}  
  
class TwoThreadsTest {  
    public static void main (String[ ] args) {  
        new SimpleThread ( "Edinburgh" ).start ();  
        new SimpleThread ( "Glasgow" ).start ();
```



- main method starts two threads by calling the start method
  - output something like :

```
0 Edinburgh
0 Glasgow
1 Glasgow
1 Edinburgh
2 Edinburgh
3 Edinburgh
2 Glasgow
3 Glasgow
4 Glasgow
4 Edinburgh
5 Glasgow
5 Edinburgh
6 Glasgow
7 Glasgow
8 Glasgow
6 Edinburgh
7 Edinburgh
8 Edinburgh
9 Edinburgh
Finished Edinburgh
9 Glasgow
Finished Glasgow
```



You can use  
the experiment  
framework of  
this course to  
simulate this ,  
right?