



we also call the mechanism to overcome this risk as

Operating system synchronization

Part V: Synchronization risk [1]

Data Inconsistency


By KONG LingBo (孔令波)

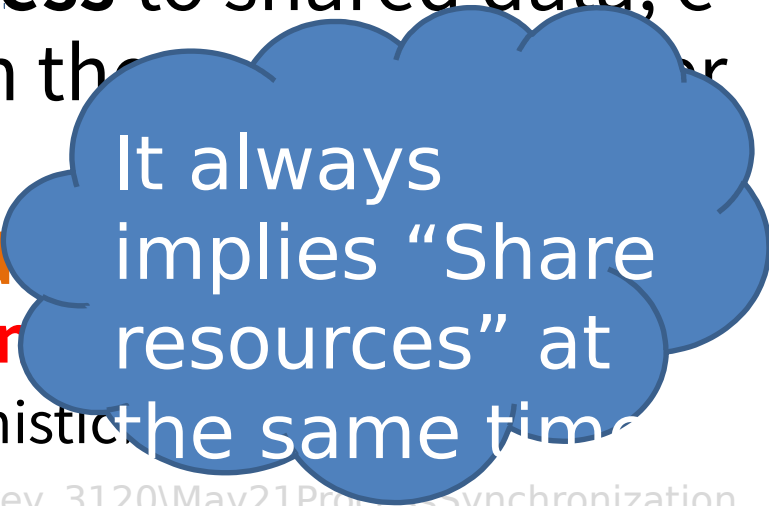
Goals

- Know the related concepts and definitions
 - Race conditions, Critical sections, and Atomic operations etc
- Know the mechanism of different solutions
 - Software solutions – algorithms whose correctness does not rely on any other assumptions.
 - Peterson's algorithm
 - Hardware solutions – rely on some special machine instructions.
 - TestAndSet(), Swap()
 - Operating System solutions – provide some functions and data structures to the programmer through system/library calls.
 - Semaphores
 - Programming Language solutions – Linguistic constructs provided as part of a language
 - Monitors
- Understand the codes for some classic synchronization problems
 - Producer-Consumer, Thinking philosophers, Sleeping barbers

- Background & basic concepts
 - Race conditions, Critical sections, etc.
- Problems & Solutions for synchronization
 - Problems
 - Producer-Consumer problem, Readers-Writers Problem, The Barbershop Problem, Dining philosopher problem
 - Tasks
 - Mutual exclusion, deadlock-free, starvation-free
 - Solutions
 - **LOCK** mechanism is the basis (for mutual exclusion)
 - **PV** (Signal-Wait) operations are the first classic prototype
 - **SEMAPHORE/MONITOR** (for efficiency & convenience)

Problems with Concurrent Execution

- Concurrent processes (or threads) often need to **share data** (maintained either in shared memory or files) and **resources**
 - If there is no proper policy to assign resources among processes, it may result in that all the processes get blocked ☾ **Deadlock** [死锁]
- If there is **no controlled access** to shared data, execution of the processes on the same computer will leave  **Cooperation**
 - **The results will then depend on whether the data were modified** ☾ **Data Integrity**
 - i.e. the results are non-deterministic

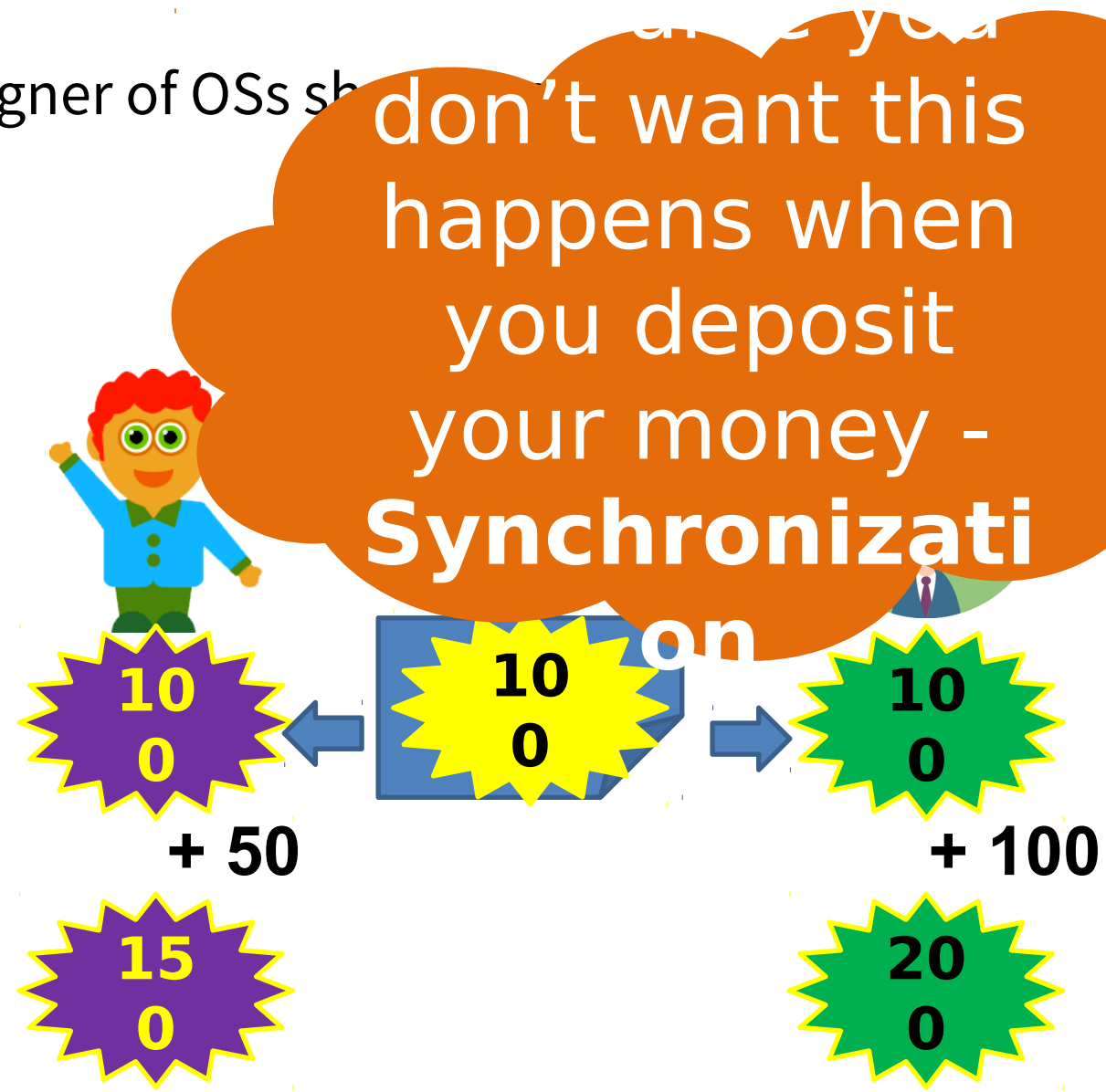


It always implies “Share resources” at the same time

and you

Some functions the designer of OSs should

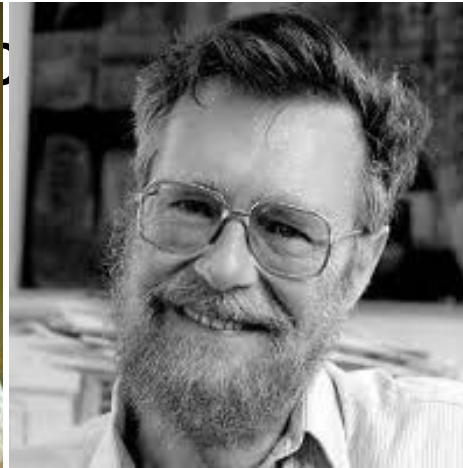
- Resource competition
 - **Data inconsistency** is another issue we should consider carefully when competing.



Summarized as **Mutual Exclusion** [互斥] problem

http://en.wikipedia.org/wiki/Mutual_exclusion

- Mutual exclusion, in computer science, refers to the problem of **ensuring that no two processes or threads** (henceforth referred to only as processes) **can be in their code to access the shared data among those processes at the same time**



stra in 19

Died at

August 6, 2002

(aged 72)

ijkstra

For memorizing: Edsger Dijkstra

- Among his contributions to computer science are
 - the **shortest path algorithm**, also known as **Dijkstra's algorithm**;
 - Reverse Polish Notation and related Shunting yard algorithm;
 - **the THE multiprogramming system**, an important early example of structuring a system as a set of layers;
 - **Banker's algorithm**;
 - and the **semaphore construct** for coordinating multiple processors and programs.

We call that situation as Race Condition

- A situation in which multiple threads or processes read and write a shared data item and **the final result depends on the relative timing of their execution**

Initial balance: \$100

Thread 1: deposit(10)

Load R1, balance

Add R1, amount

Store R1, balance

What is the final balance?



Thread 2: deposit(20)

Load R1, balance

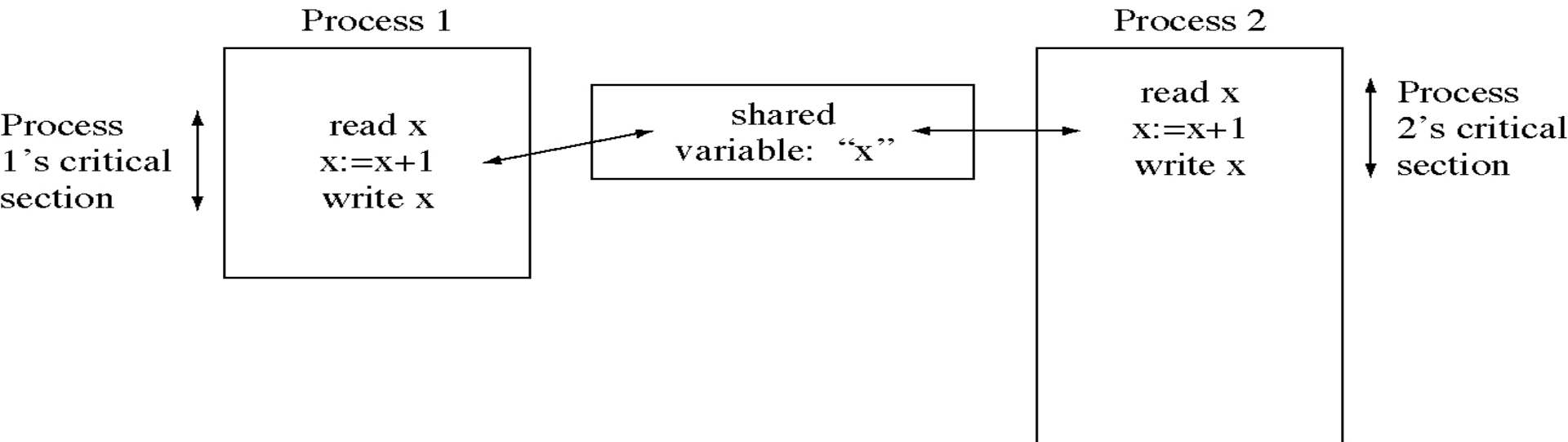
Add R1, amount


Store R1, balance

A condition in which the value of a shared data item d_s resulting from execution of operations a_i and a_j on d_s in interacting processes may be different from both $f_i(f_j(d_s))$ and $f_j(f_i(d_s))$.

We call those codes as Critical sections

- A **section of code within a process** that requires **access shared resources** and which may not be executed while another process in a corresponding section of code





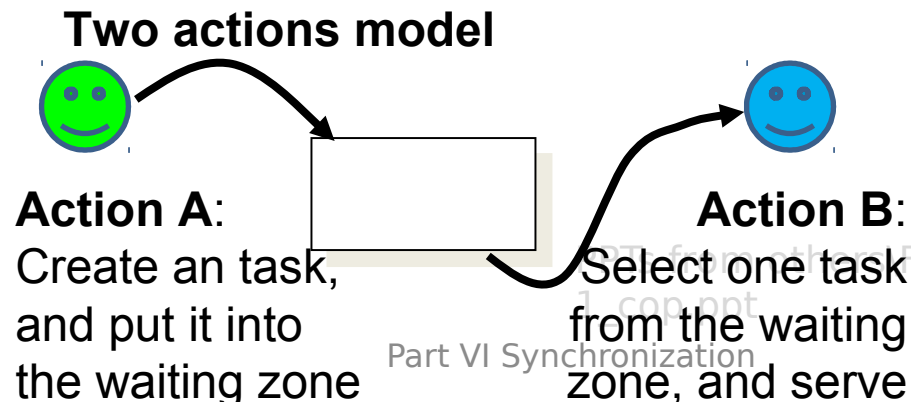
We
investigate
the P-C
model first

CLASSIC SYNCHRONIZATION MODELS

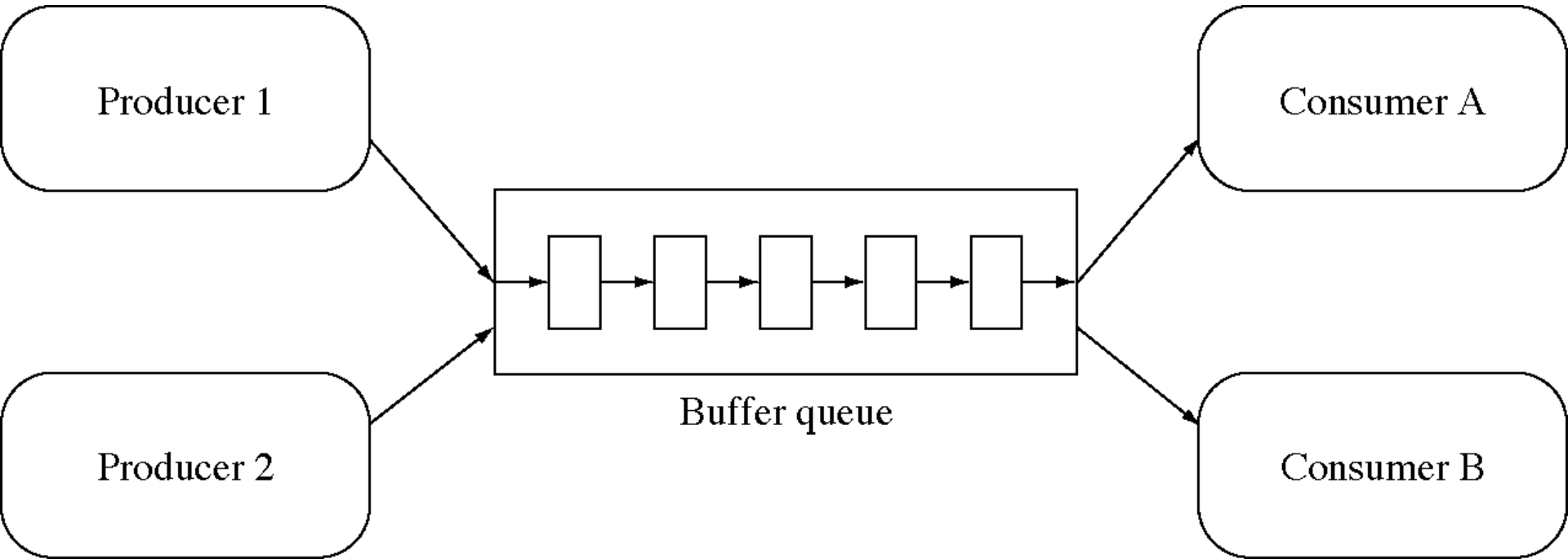
- **Producer-Consumer model**
- **Readers-Writers Problem**
- **The Barbershop Problem**
- **Dining philosopher problem**

Producer/Consumer (P/C) Problem

- Producer/Consumer is a common paradigm for **cooperating processes** in OS
 - Producer process produces information that is consumed by a Consumer process.
- **Example 1:** a print program produces characters that are consumed by a printer.
- **Example 2:** an assembler produces object modules that are consumed by a loader.



Multiple Producers and Consumers



The key of synchronization

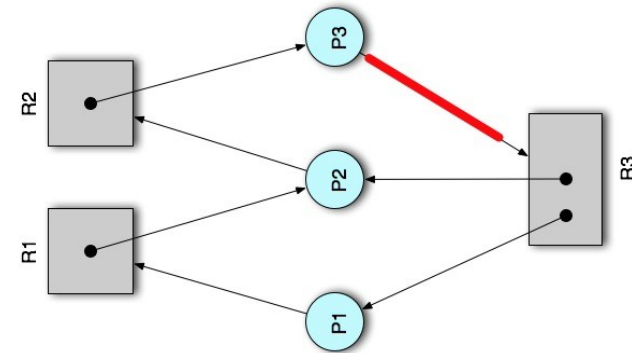
**TO CONTROL THE EXECUTION OF CRITICAL
SECTIONS AMONG CONCURRENT PROCESSES
S/THREADS**

 Ensuring **Mutual Exclusion**

But we also should avoid **For EFFICIENCY**

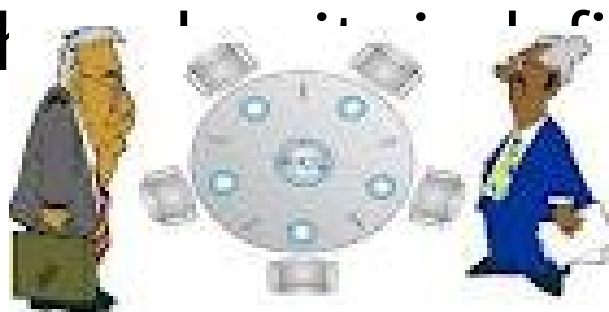
- **Deadlock**

- None of the involved processes could move forward



- **Starvation**

- Some process is never executed!
- Process/thread waits indefinitely



Rules for robust synchronization

- Of course, Mutual exclusion should be guaranteed (**consistency**) [互斥]
 - Only one thread in critical section at a time
- Progress (**deadlock-free**) [有空让进]
 - If several simultaneous requests, must allow one to proceed
 - Must not depend on threads outside critical section
- Bounded (**starvation-free**) [有限等待]
 - Must eventually allow each waiting thread to enter

Synchronization

- Background & basic concepts
 - Multiprogramming/Concurrency + Cooperation
 - Race conditions, Critical sections, and Atomic operations etc.
- Problems & Solutions for synchronization
 - Problems
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 - Tasks
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 - **LOCK** mechanism is the basis (for mutual exclusion)
 - **PV** (Signal-Wait) operations are the first classic prototype
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Types of solutions to CS problem

- **Software** solutions –
 - algorithms whose correctness does not rely on any other assumptions.
- **Hardware** solutions –
 - rely on some special machine instructions.
- **Operating System** solutions –
 - provide some functions and data structures to the programmer through system/library calls.
- **Programming Language** solutions –
 - Linguistic constructs provided as part of a language.

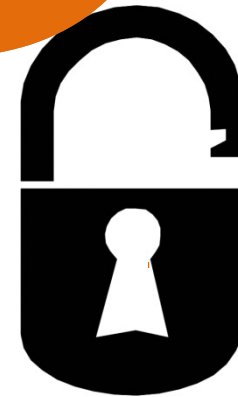
**ALL ARE DERIVED FROM
LOCK MECHANISM!**

Solution
Locks

You also should
ensure the
“acquire” and
“release” are
primitive
operations.

Problem using
Solution is:

do {
 acquire lock
 critical section
 release lock
 remainder section
} while (TRUE);



Software Solutions

- We consider first the case of **2** processes:
 - **Peterson's algorithm** is correct.
- Then we generalize to **n** processes:
 - The **Bakery algorithm**.
- Initial notation:
 - Only 2 processes, P_0 and P_1
 - When usually just presenting process P_i (Larry, I, i), P_j (Jim, J, j) always denotes other process ($i \neq j$).

The Critical-Section Problem:

2-Processes: Algorithm N (Peterson 1981)

981)

- Process P_i

do {

flag[i] = true;

turn = j;

while (flag[j] and turn = j) ;

critical section

flag[i] = false;

remainder section

} while (1);

- Meets all three requirements; solves the critical-section problem for two processes.

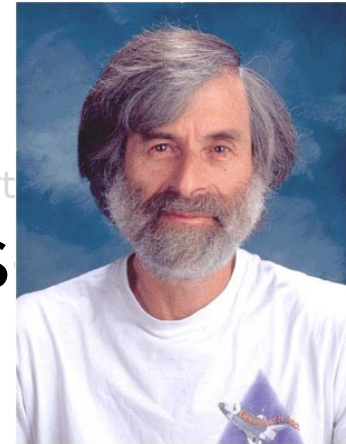
Interrupt could happen between any two near statements

Peterson's Algorithm: Proof of Correctness

- **Mutual exclusion** holds since:
 - For both P_0 and P_1 to be in their CS
 - both $\text{flag}[0]$ and $\text{flag}[1]$ must be true **and** $\text{turn}=0$ and $\text{turn}=1$ (at same time) ⊗ this is **impossible**

How about for N-processes?



http://en.wikipedia.org/wiki/Leslie_Lamport



- Critical section for n processes
 - We have **Bakery algorithm**
 - It is also known as **Lamport's** bakery algorithm.
- Dr. **Leslie Lamport**
 - I know him because of his work.
 - You can check some information on my [homepage](#).

You could learn this by yourself and finish a report.

Drawbacks of Software Solutions

- Even software solutions are very delicate , they are complicated to program 
- **Busy waiting** (wasted CPU cycles)
 - It would be more efficient to **block** processes that are waiting (just as if they had requested I/O).
 - This suggests implementing waiting functions using semaphores & Monitors

in DBMS, the
SELF-SPIN LOCK
[自旋锁]

Is a kind of
BUSY WAITING
lock

Hardware solutions

- Many systems provide hardware support for critical section code.
- Uniprocessors – could **disable interrupts**:
 - Currently running code would execute without preemption.
 - Generally too inefficient on multiprocessor systems.
- Modern machines provide special **atomic** (**non-interruptible**) hardware instructions:
 - Either test memory word and set value at once.
 - Or swap contents of two memory words.

PPTs from others\From Ariel J. Frank\OS381\os4-3_cop.ppt

Hardware Solution ①: Disable Interrupts

Process P_i :

repeat

 disable interrupts

 critical section

 enable interrupts

 remainder section

forever

- On a **uniprocessor**, mutual exclusion is preserved : while in C S, **nothing** else can run
 - **because preemption impossible**
- On a multiprocessor: mutual exclusion is not achieved
 - **Interrupts are “per-CPU”** (interrupts are not disabled on other processors).
- Generally not a practical solution for user programs, but could be used **inside** an OS

Hardware Solution ②: **Special Machine Instructions**

- Normally, the memory system restricts access to any particular memory word to one CPU at a time
- Useful extension:
 - machine instructions that perform 2 actions *atomically* on the same memory location (ex: testing and writing)
- The execution of such an instruction is *mutually exclusive on that location* (even with multiple CPUs)
- These instructions can be used to provide mutual exclusion
 - but need more complex algorithms for satisfying the requirements

Test-and-Set Synchronization Hardware

- Test and set (modify) the content of a word atomically (a Boolean version):

```
boolean TestAndSet(boolean *target) {  
    boolean rv = *target;  
    *target = TRUE;  
    return rv;  
}
```

- The Boolean function represents the essence of the corresponding machine instruction.

Mutual Exclusion with Test-and-Set

- Shared data:

boolean lock = FALSE;

- Process P_i

do {

while (TestAndSet(&lock));

critical section

lock = FALSE;

remainder section

}

Swap Synchronization Hardware

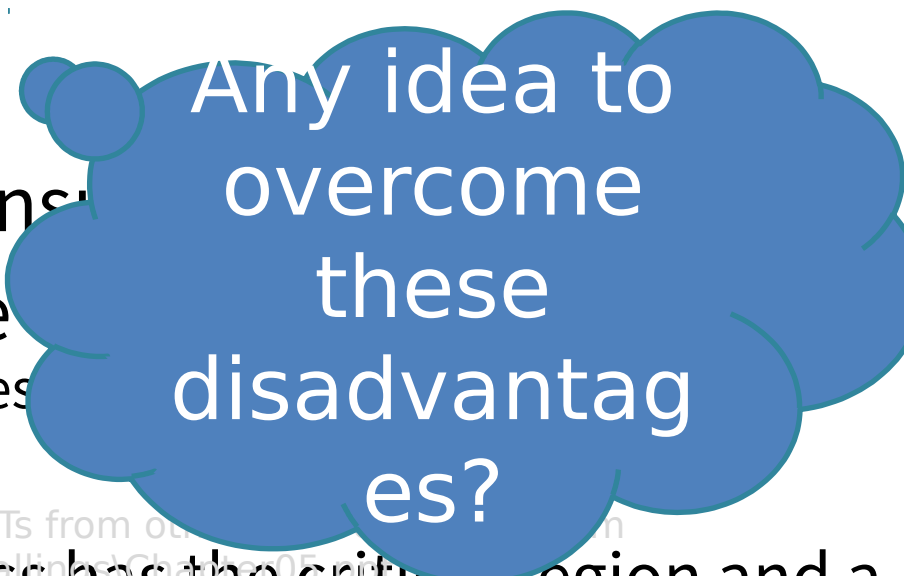
- Atomically swap two variables:

```
void Swap(boolean *a, boolean *b) {  
    boolean temp = *a;  
    *a = *b;  
    *b = temp;  
}
```

- The procedure represents the essence of the corresponding machine instruction.

Machine Instructions for Mutual Exclusion

- Advantages
 - Applicable to any number of processes on either a single processor or multiple processors sharing main memory
 - It is simple and therefore easy to verify
- Disadvantages
 - Busy-waiting consumes processor time
 - Starvation is possible if a process is in the critical region and more than one process is waiting
 - Deadlock
 - If a low priority process has the critical region and a higher priority process needs, the higher priority process will obtain the processor to wait for the critical region



Any idea to overcome these disadvantages?

PPTs from other courses in
Stallings, Chapter 05, pp. 31-34

Lock + Manager + Waiting Room



- If A tries to use the shared variable, its request will be trapped by the manager, and it's manager's responsibility to check if the variable has been occupied or not

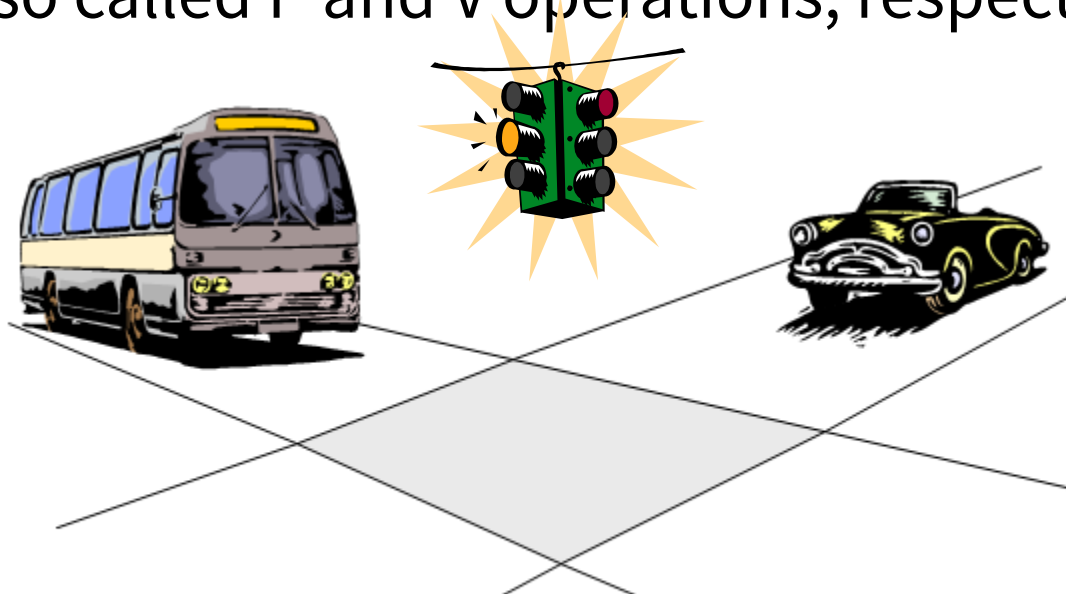
- If yes, A will be put in waiting room; otherwise, A goes into its CS

- After A finishes its job, it should release the lock, and manager will check if there are waiting processes in WR for this lock (resource)



Operating System solutions

- Semaphore [信号量]
 - Software construct that can be used to enforce mutual exclusion
 - Contains a protected variable
 - Can be accessed only via wait and signal commands
 - Also called P and V operations, respectively



Semaphores

- A Semaphore **S** is an integer variable that, apart from initialization, can only be accessed through 2 *atomic and mutually exclusive* operations:
 - wait(S)
 - sometimes called **P()**
 - Dutch *proberen*: “to test”
 - signal(S)
 - sometimes called **V()**
 - Dutch *verhogen*: “to increment”

Semaphore & Edsger W. Dijkstra

http://en.wikipedia.org/wiki/Edsger_Dijkstra
http://en.wikipedia.org/wiki/Semaphore_%28programming%29



May 11, 1930 – August 6, 2002

http://en.wikipedia.org/wiki/Dijkstra%27s_algorithm

- Invented in the 1965
 - **Basis of all contemporary OS synchronization mechanisms**
- In computer science, a semaphore is a protected variable or abstract data type that constitutes a classic method of controlling access by several processes to a common resource in a parallel programming environment.
 - A semaphore generally takes one of two forms: **binary** and **counting**.
- Either semaphore type may be employed to prevent a race condition.
 - On the other hand, a semaphore **is of no value in preventing resource deadlock**, such as the dining philosophers problem.

```
struct binary_semaphore {
    enum {zero, one} value;
    queueType queue;
};

void semWaitB(binary_semaphore s)
{
    if (s.value == 1)
        s.value = 0;
    else
    {
        place this process in s.queue;
        block this process;
    }
}

void semSignalB(semaphore s)
{
    if (s.queue.is_empty())
        s.value = 1;
    else
    {
        remove a process P from s.queue;
        place process P on ready list;
    }
}
```

Figure 5.4 A Definition of Binary Semaphore Primitives

We can use BS to

1. Support **Mutual Exclusion [MU]** for critical section problem of course

– Shared data:

semaphore mutex; // initialized to 1

– Process P_i :

```
do {  
    wait(mutex);  
    critical section;  
    signal(mutex);  
    remainder section  
} while (TRUE);
```

```
void semWaitB(binary_semaphore s)  
{  
    if (s.value == 1)  
        s.value = 0;  
    else  
    {  
        place this process in s.queue;  
        block this process;  
    }  
}
```

We can also use BS to

2. Support **ordered execution** of two processes (**Order Scheduling** [Sc]
- Execute B in P_j only after A
 - Use semaphore $flag$ initialized to 1
 - Code:

P_i P_j



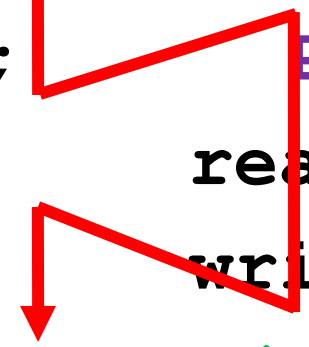
A *wait(flag)*
signal(flag) B

P_j will wait P_i to finish A first, then P_j can execute B

```
semaphore s1 = 0;
```

```
semaphore s2 = 0;
```

```
A() {      B() {  
    write(x); P(s1);  
    V(s1);    read(x);  
    P(s2);    write(y);  
    read(y);  V(s2);  
}
```



```
}
```

```
struct semaphore {
    int count;
    queueType queue;
}

void semWait(semaphore s)
{
    s.count--;
    if (s.count < 0)
    {
        place this process in s.queue;
        block this process
    }
}

void semSignal(semaphore s)
{
    s.count++;
    if (s.count <= 0)
    {
        remove a process P from s.queue;
        place process P on ready list;
    }
}
```

Figure 5.3 A Definition of Semaphore Primitives

Counting semaphores

- Initialized with values **larger than one**
- Can be used to **control the competition a**
ccess to a pool of identical resources
 - Decrement the semaphore's counter when taking resource from pool \approx wait()
 - If no resources are available, thread is blocked until a resource becomes available
 - Increment the semaphore counter when returning it to pool \approx signal()
 - If there are processes blocked, wake up one of them

Two types of competitions –
ME and OrderS

Implementation

- A semaphore can be defined as a C struct along these lines:

```
typedef struct {  
    int value;  
    struct process *list;  
} semaphore
```

Implementation

- `down()` operation can be defined as

```
down(semaphore *S) {  
    S->value--;  
    if (S->value < 0) {  
        add this process to S->list;  
        block();  
    }  
}
```

- The `block()` operation suspends the process that invokes it.

Implementation

- `up()` operation can be defined as

```
up(semaphore *S) {  
    S->value++;  
    if (S->value ≤ 0) {  
        remove process P from S->list;  
        wakeup(P);  
    }  
}
```

- The `wakeup()` operation sends a signal that represents an event that the invoking process is no longer in the critical section

Implementation

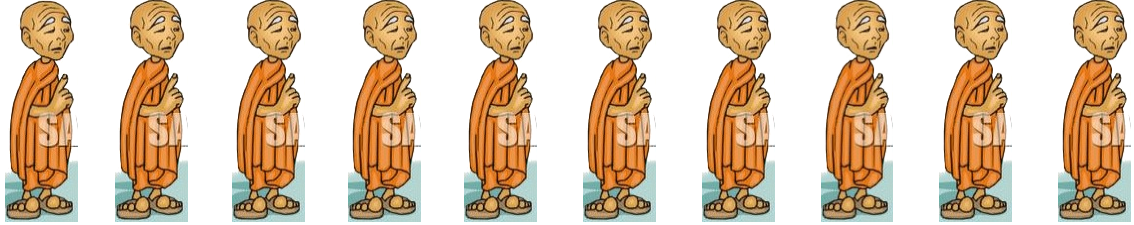
- ❑ BTW, the implementation just described is how Linux implements semaphores
- ❑ The **up** and **down** operations represent require access to a **critical section** which is the semaphore variable
- ❑ Need hardware/OS support e.g.,
 - Signals, TSL
 - Signals allow for a "message" to be sent to processes

DETAILED EXAMPLE FOR CS PROBLEM

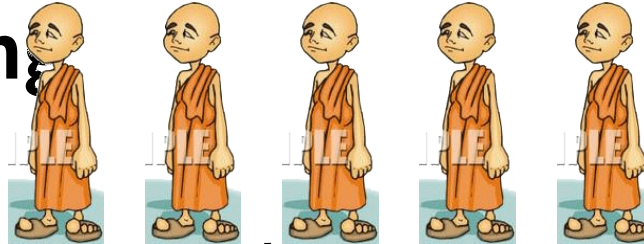
A story: monks drink water

- Many monks

- Some are **old**

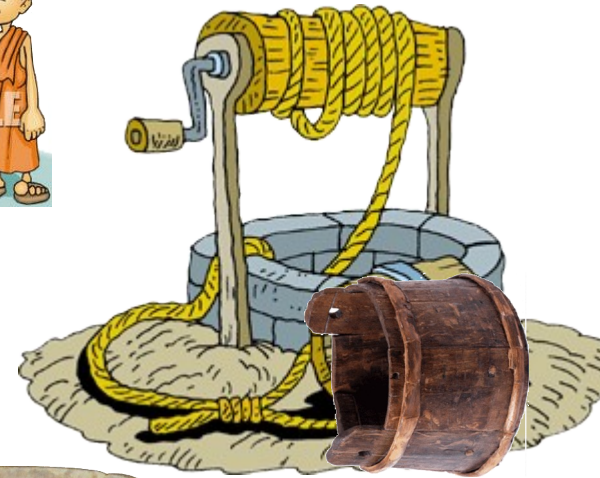


- Some are **young**



- One well

- Only one bucket in well every y time



- One Vat

- Can contain 10 buckets of water

- One bucket to put water into and fetch water from the vat



- Three buckets in total

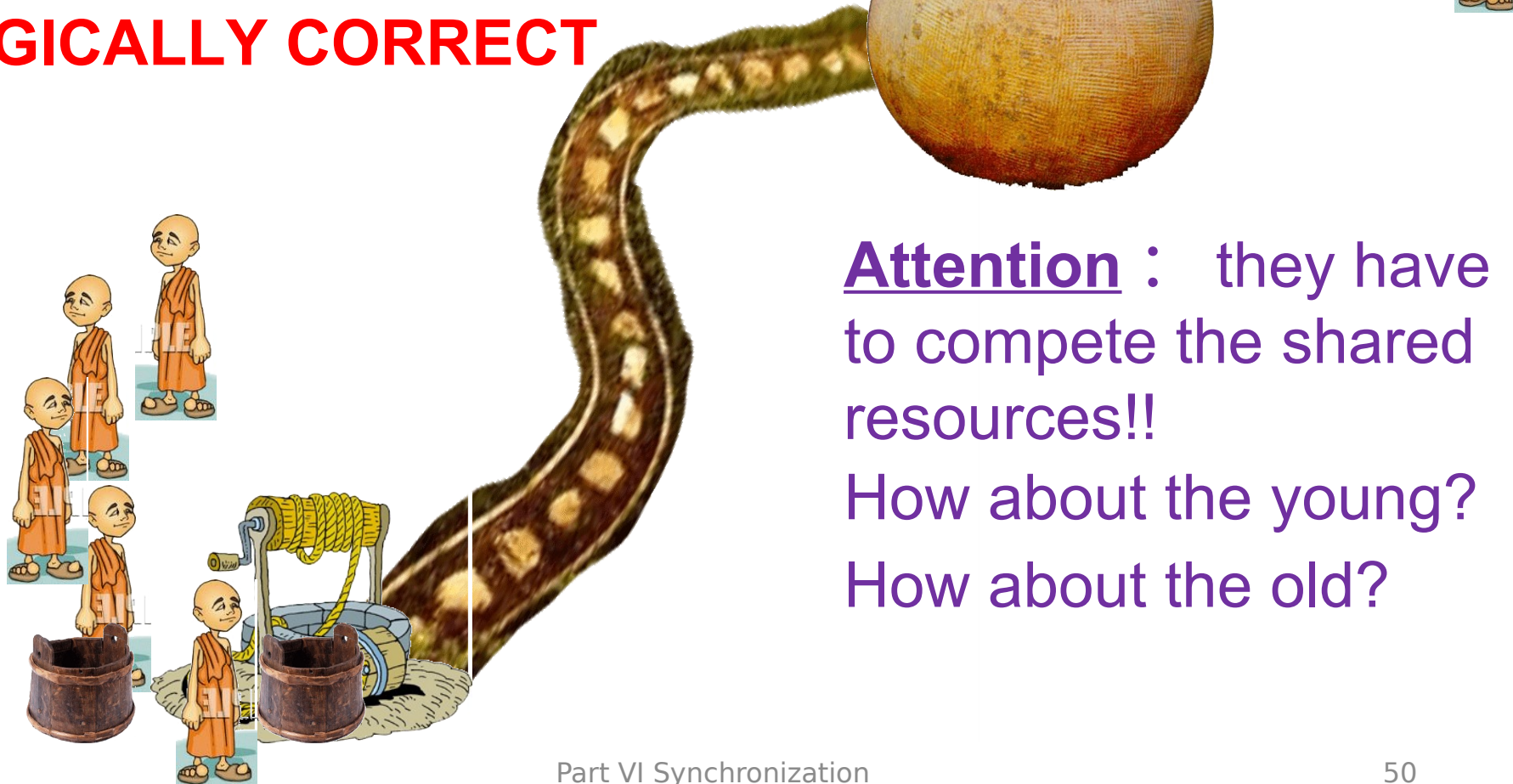


General rules to cope with CS problem using semaphores

1. Find the types of **actors**
 - To determine the **processes**
2. Recognize the shared **resources** between actors ☾ initial values of semaphores
3. Infer the **constraints** based on the situations when actors use those shared resources
 - **ME or SCH?**
 - To determine semaphores and their initial values
 - To determine the code (nested for ME, and scattered for SCH)

Good habits: write down the detailed steps of the actors to carry out the story, especially clarifying the constraints they should obey

LOGICALLY CORRECT



Attention : they have to compete the shared resources!!

How about the young?
How about the old?

In our story

1. Find the types of actors

- Two types **actors** (processes): young monks and old monks
 - The young picks a bucket, goes to the well to fetch water and puts the water into the vat
 - The old picks a bucket to get water from the vat

2. Recognize **the shared resources** between actors

- Three types of shared resources:
 - **Vat**: among all monks
 - **Well**: among young monks
 - **3 buckets**: among all monks (because all monks should get one bucket to pick water from the well or v

In our story (cont')

3. Infer the **constraints** based on the situations when actors use those shared resources (**ME** or **SCH**?) – checking SCH is always first!

– Conclude the action scripts

- For young:

1. Check if the vat could contain more buckets of water. No, no more action – wait the old to consume the water (at first, the vat could contain **10** buckets of water (€ **SCH** for the young)).
2. Compete a bucket (€ **ME**: share buckets with other monks)
3. Go to the well and get a bucket of water from the well (€ **ME** of well: only one bucket could access the well every time)
4. Try to pour the bucket of water back to vat (€ **ME** of vat:)
5. Release the bucket
6. Inform the old that they could consume the water (≈ **SCH**: f or the old: initially, the vat has 0 bucket of water) .

In our story (cont')

3. Infer the constraints based on the situations when actors use those shared resources (ME or SCH?) – checking SCH is always first!

– Conclude the action scripts

- For old:

1. Check if the vat contains water or not (☹ **SCH**: for the old: initially, the vat has 0 bucket of water)
2. Compete a bucket (☹ **ME**: share buckets with other monks)
3. Try to fetch a bucket of water from the vat (**ME** of vat:)
4. Release the bucket
5. Inform the young because the vat now could contain one more bucket of water (☺ **SCH**: for the young)

In our story (cont')

4. Use semaphores to finish those processes

- Binary semaphores for **ME**: Well, vat
- Counting semaphore: idleBuckets (=3) for **ME**, Vat CouldContain (= 10), WaterInVat (= 0) for **SCH**
 - For young:
 1. when **VatCouldContain=0**, the young should not compete the buckets;
 2. Once a young gets a bucket, he should finish 2 steps wholly: fetch a bucket of water and put that water into the vat
 3. Once he finishes, the occupied bucket will be released and the **WaterInVat** will be incremented
 - For old:
 1. when **WaterInVat=0**, the old should not compete the buckets
 2. Once an old get a bucket, he drinks that water, releases that bucket and decremented the **VatCouldContain**

- For the young:

P(VatCouldContain) // **initial = 10**

P(idleBuckets); // initial = 3

P(well);

// get a bucket of water

V(well);

P(vat);

// put the water into the vat

V(vat);

V(idleBuckets);

V(WaterInVat); // **initial = 0**



- For the old:

P(WasterInVat) // **initial = 0**

P(idleBuckets); // initial = 3

P(vat);

// get a bucket and drink the water

V(vat);

V(idleBuckets);

V(VatCouldContain); // **initial = 10**



CLASSICAL PROBLEMS OF SYNCHRONIZATION


- Bounded-buffer
 - (有限缓存问题)
- Readers-writers
 - (读者 - 著者问题)
- Dining-philosophers problem
 - (哲学家就餐问题)
- Barbershop problem
 - (理发师问题)

Your turn to
read and
understand
these classic CS
problems!



PPTs from others\OS PPT in English\ch07.ppt

Be careful: Deadlock and Starvation

- **Deadlock** – two or more processes are waiting indefinitely for an event that can be caused by only one of waiting processes.
 - Let S and Q be two semaphores initialized to 1
 - P_0 P_1
 - $wait(S); wait(Q);$
 - $wait(Q); wait(S);$
 - 
 - $signal(S); signal(Q);$
 - $signal(Q) signal(S);$
- **Starvation** – indefinite blocking. A process may never be removed from the semaphore queue (say, if LIFO) in which it is suspended.
- **Priority Inversion** – scheduling problem when lower-priority process holds a lock needed by higher-priority processes

Programming Language solutions: Monitors

- Monitor: Hide Mutual Exclusion
 - No need for users to explicitly call the related functions
 - Declare a monitor which hide the details of synchronization, and provide friendly interface
 - Only one process may be active within the monitor at a time.
- Found in many concurrent programming languages:
 - Concurrent Pascal, Modula-3, C++, Java...
- Can also be implemented by semaphores.

```
procedure Producer
begin
  while true do
  begin
    produce an item
    ProdCons.Enter();
  end;
end;

procedure Consumer
begin
  while true do
  begin
    ProdCons.Remove();
    consume an item;
  end;
end;
```

```
monitor ProdCons
  condition full, empty;

  procedure Enter;
  begin
    if (buffer is full)
      wait(full);
    put item into buffer;
    if (only one item)
      signal(empty);
  end;

  procedure Remove;
  begin
    if (buffer is empty)
      wait(empty);
    remove an item;
    if (buffer was full)
      signal(full);
  end;
```

Condition variable != Semaph

or

- Condition variables provide a mechanism to wait for events (a “rendezvous point”)
 - ♦ Resource available, no more writers, etc.
- Condition variables support three operations:
 - ♦ **Wait** – release monitor lock, wait for C/V to be signaled
 - » So condition variables have wait queues, too
 - ♦ **Signal** – wakeup one waiting thread
 - ♦ **Broadcast** – wakeup all waiting threads
- Note: Condition variables are not boolean objects
 - ♦ “if (condition_variable) then” ... does not make sense
 - ♦ “if (num_resources == 0) then wait(resources_available)” does

Monitors in Java

- Every object of a class that has a *synchronized* method has a monitor associated with it
 - Any such method is guaranteed by the Java Virtual Machine execution model to execute mutually exclusively from any other synchronized methods for that object
- Access to individual objects such as arrays can also be synchronized
 - also complete class definitions
- *One* condition variable per monitor
 - *wait()* releases a lock, i.e, enters holding area
 - *notify()* signals a process to be allowed to continue
 - *notifyAll()* allows all waiting processes to continue

Monitors in Java

- A lock and condition variable are in every Java object
 - ◆ No explicit classes for locks or condition variables
- Every object is/has a monitor
 - ◆ At most one thread can be inside an object's monitor
 - ◆ A thread enters an object's monitor by
 - » Executing a method declared “synchronized”
 - Can mix synchronized/unsynchronized methods in same class
 - » Executing the body of a “synchronized” statement
 - Supports finer-grained locking than an entire procedure
 - Identical to the Modula-2 “LOCK (m) DO” construct
- Every object can be treated as a condition variable
 - ◆ `Object::notify()` has similar semantics as `Condition::signal()`

- example:

```
class DataBase {  
    public synchronized void write ( . . . ) { . . . }  
    public synchronized read ( . . . ) { . . . }  
    public void getVersion() { . . . }  
}
```

- once a thread enters either of the *read* or *write* methods, JVM ensures that the other is not concurrently entered for the same object
- *getVersion* could be entered by another thread since not synchronized
- code could still access a database safely by locking the call rather than by using synchronized methods:

```
DataBase db = new DataBase();  
synchronized(db) { db.write( . . . ); }
```

Monitor as a Mini-OS

- The concept of a monitor is very similar to an operating system.
 - One can consider the initialization as those data that are initialized when the system is booted up, the private data and code as the internal data structures and functions of an operating system, and the monitor procedures as the **system calls**.
 - User programs are, of course, threads that make service requests.
 - Therefore, a monitor can be considered a mini-OS with limited services.