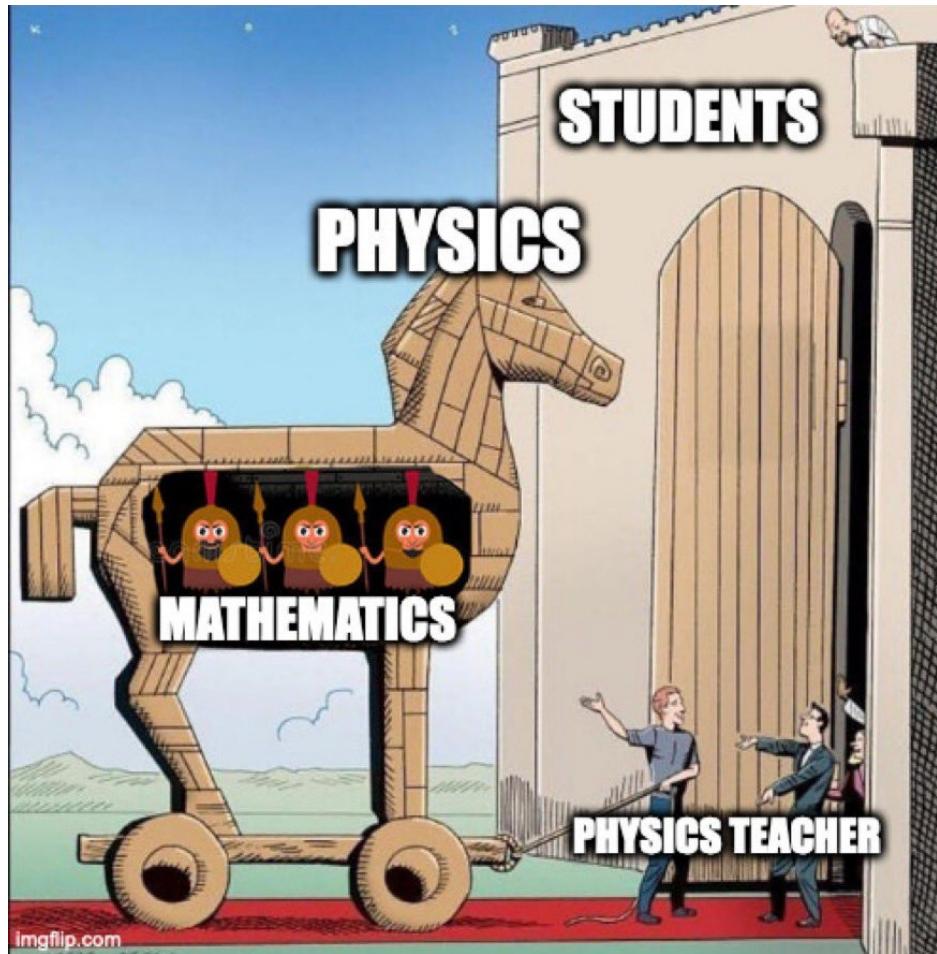
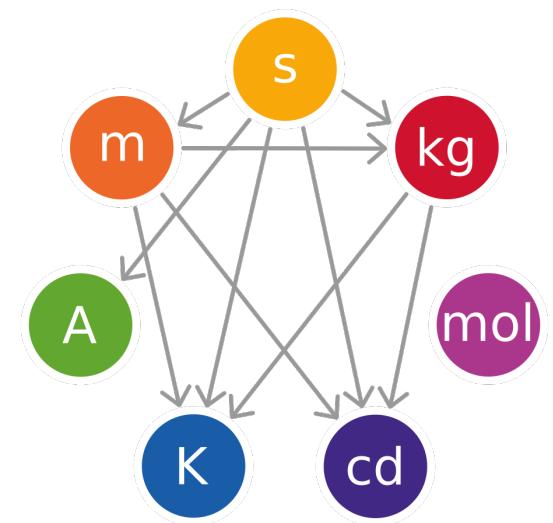


Matematika - Vektoranalízis



Name	Symbol	Quantity	Definition other units	Definition SI base units
radian	rad	plane angle		–
steradian	sr	solid angle		–
hertz	Hz	frequency		s^{-1}
newton	N	force, weight		$m \cdot kg \cdot s^{-2}$
pascal	Pa	pressure, stress	N/m^2	$m^{-1} \cdot kg \cdot s^{-2}$
joule	J	energy, work, heat	$N \cdot m$	$m^2 \cdot kg \cdot s^{-2}$
watt	W	power, radiant flux	J/s	$m^2 \cdot kg \cdot s^{-3}$
coulomb	C	electric charge		$s \cdot A$
volt	V	voltage, electrical potential difference, electromotive force	W/A J/C	$m^2 \cdot kg \cdot s^{-3} \cdot A^{-1}$
farad	F	electrical capacitance	C/V	$m^{-2} \cdot kg^{-1} \cdot s^4 \cdot A^2$
ohm	Ω	electrical resistance, impedance, reactance	V/A	$m^2 \cdot kg \cdot s^{-3} \cdot A^{-2}$
siemens	S	electrical conductance	$1/\Omega$	$m^{-2} \cdot kg^{-1} \cdot s^3 \cdot A^2$
weber	Wb	magnetic flux	J/A	$m^2 \cdot kg \cdot s^{-2} \cdot A^{-1}$
tesla	T	magnetic field strength	Wb/m^2 $V \cdot s/m^2$ $N/(A \cdot m)$	$kg \cdot s^{-2} \cdot A^{-1}$
henry	H	inductance	Wb/A $V \cdot s/A$	$m^2 \cdot kg \cdot s^{-2} \cdot A^{-2}$
degree Celsius	$^{\circ}C$	temperature relative to 273.15 K	$T_K - 273.15$	K
lumen	lm	luminous flux	$cd \cdot sr$	cd
lux	lx	illuminance	lm/m^2	$m^{-2} \cdot cd$
becquerel	Bq	radioactivity (decays per unit time)		s^{-1}
gray	Gy	absorbed dose (of ionizing radiation)	J/kg	$m^2 \cdot s^{-2}$
sievert	Sv	equivalent dose (of ionizing radiation)	J/kg	$m^2 \cdot s^{-2}$
katal	kat	catalytic activity		$s^{-1} \cdot mol$

SI



Prefixes you need to know

Prefixes	Symbol	Factor
Tera	T	10^{12}
Giga	G	10^9
Mega	M	10^6
Kilo	k	10^3
Deca	da	10^1
Deci	d	10^{-1}
Centi	c	10^{-2}
Milli	m	10^{-3}
Micro	μ	10^{-6}
Nano	n	10^{-9}
Pico	p	10^{-12}
Femto	f	10^{-15}

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big units
small units

Tenzori jelleg

TENSOR

(11)

SCALAR

t

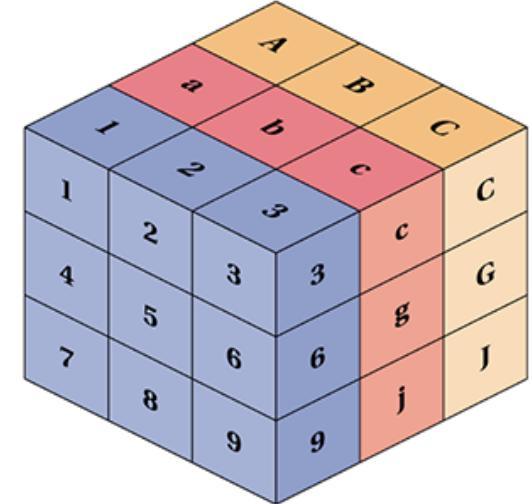
5
1.5
2

4	19	8
16	3	5

MATRIX

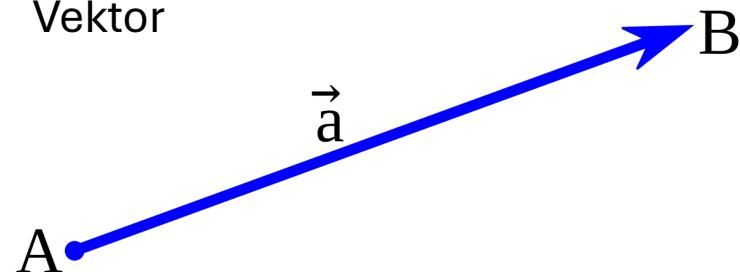
Column Vector
(shape 3x1)

\mathbf{r} / \vec{r} / \underline{r}



$\underline{\epsilon}$

Vektor



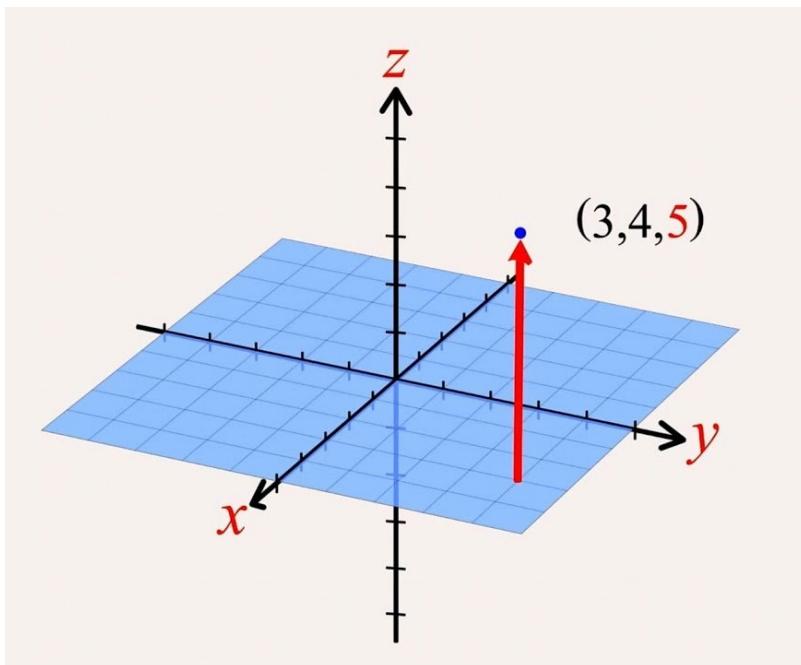
Mátrix – vektor szorzás

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} ax + by \\ cx + dy \end{bmatrix}$$

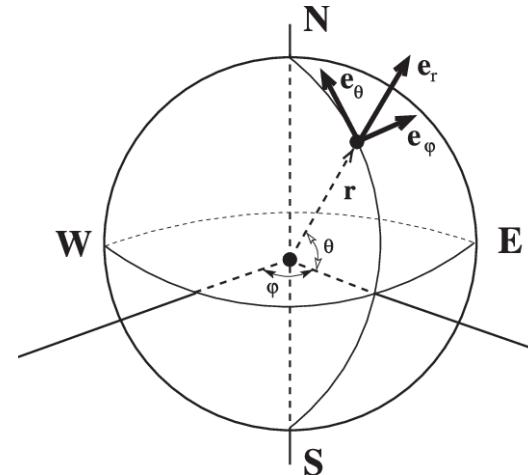
$$\begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} ax + by + cz \\ dx + ey + fz \\ gx + hy + iz \end{bmatrix}$$

Koordináta rendszerek

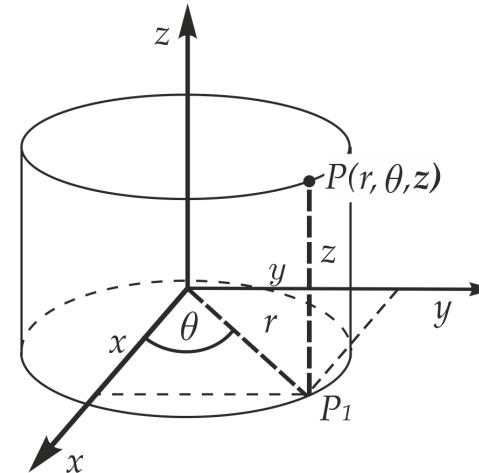
Descartes-féle koordináta-rendszer



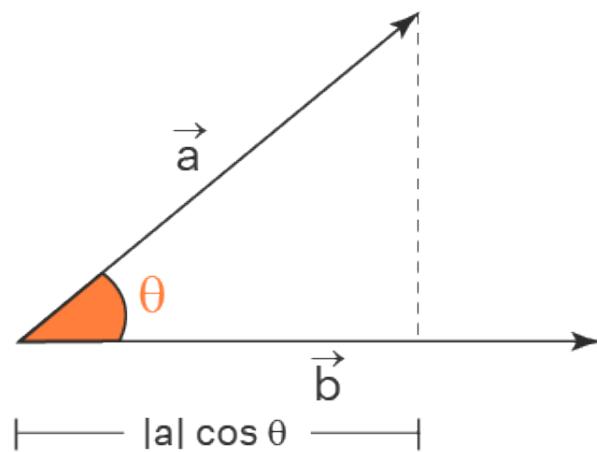
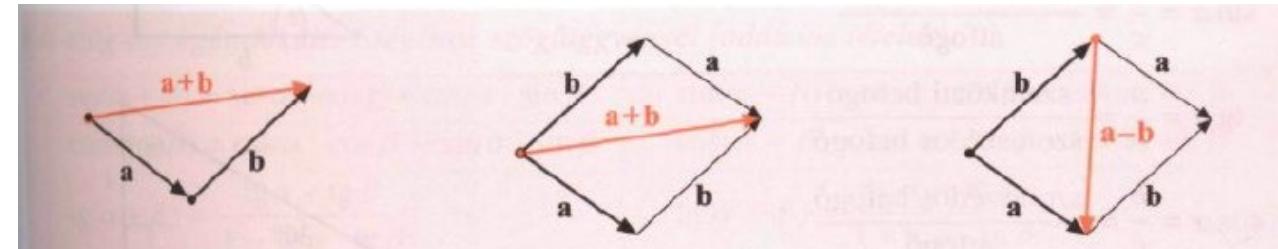
Gömbi koordináta-rendszer



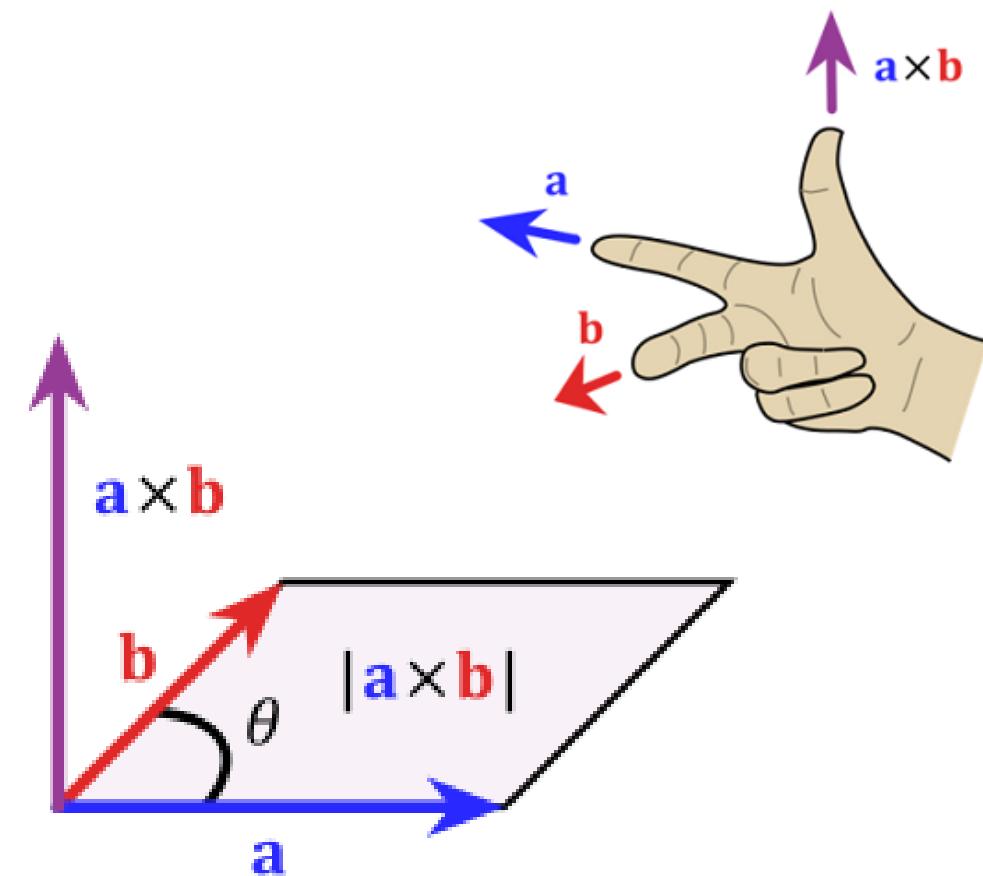
Henger koordináta-rendszer



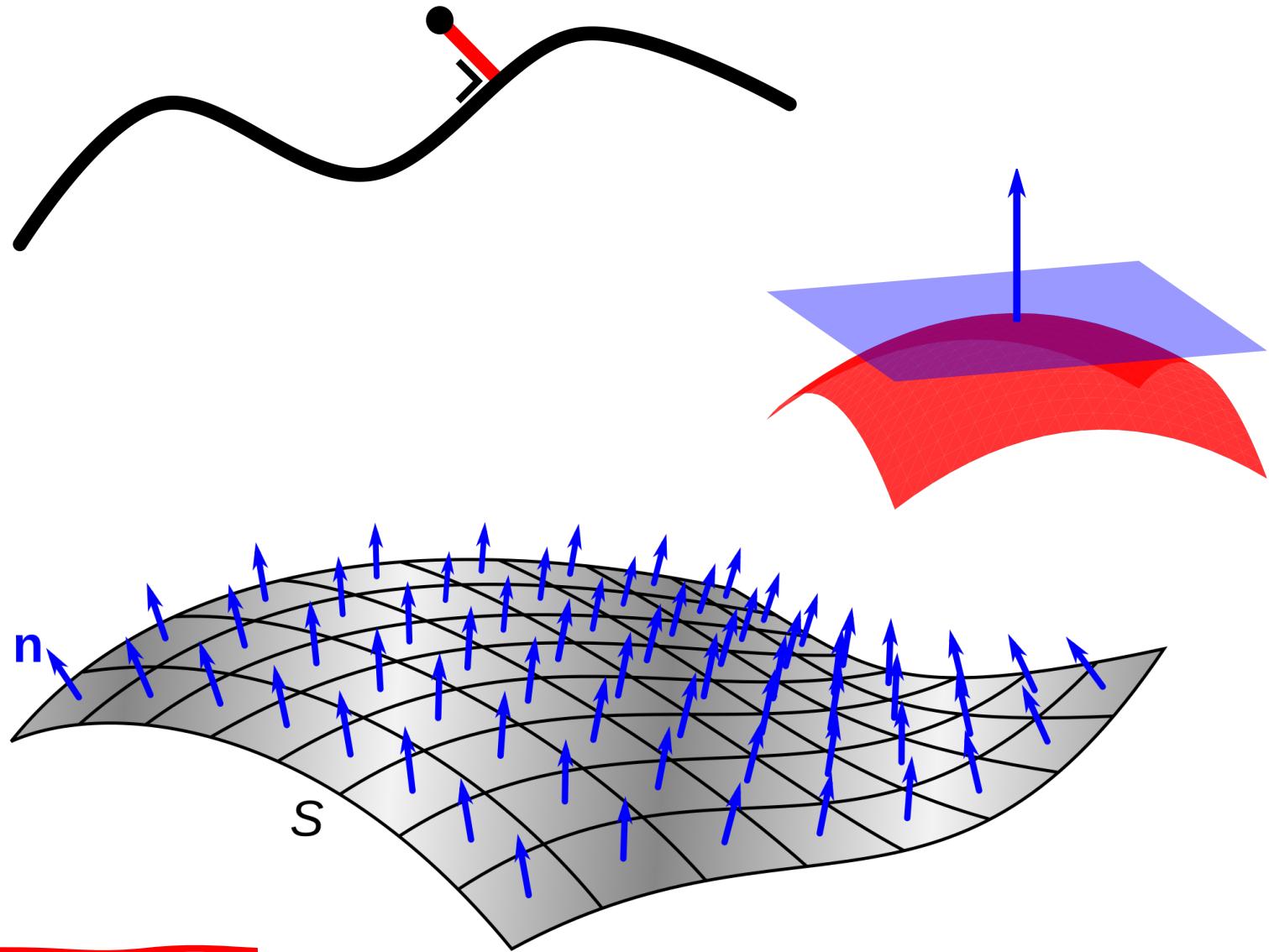
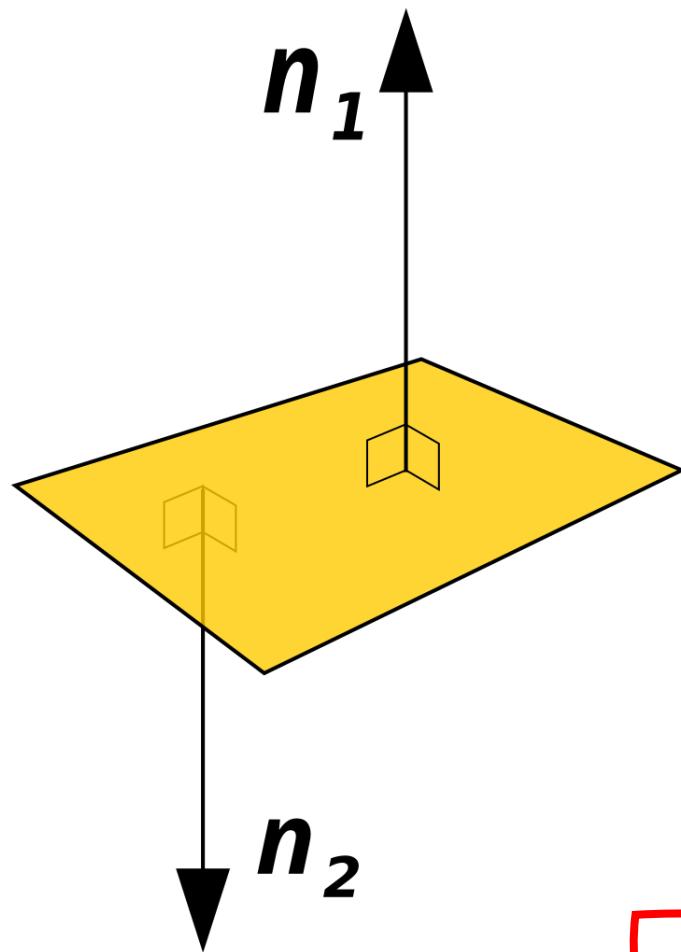
Vektor műveletek



$$\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta$$



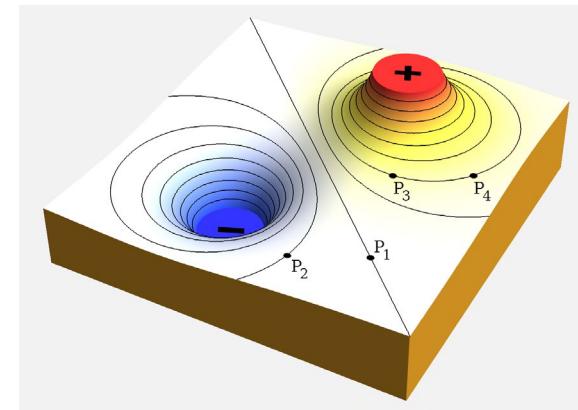
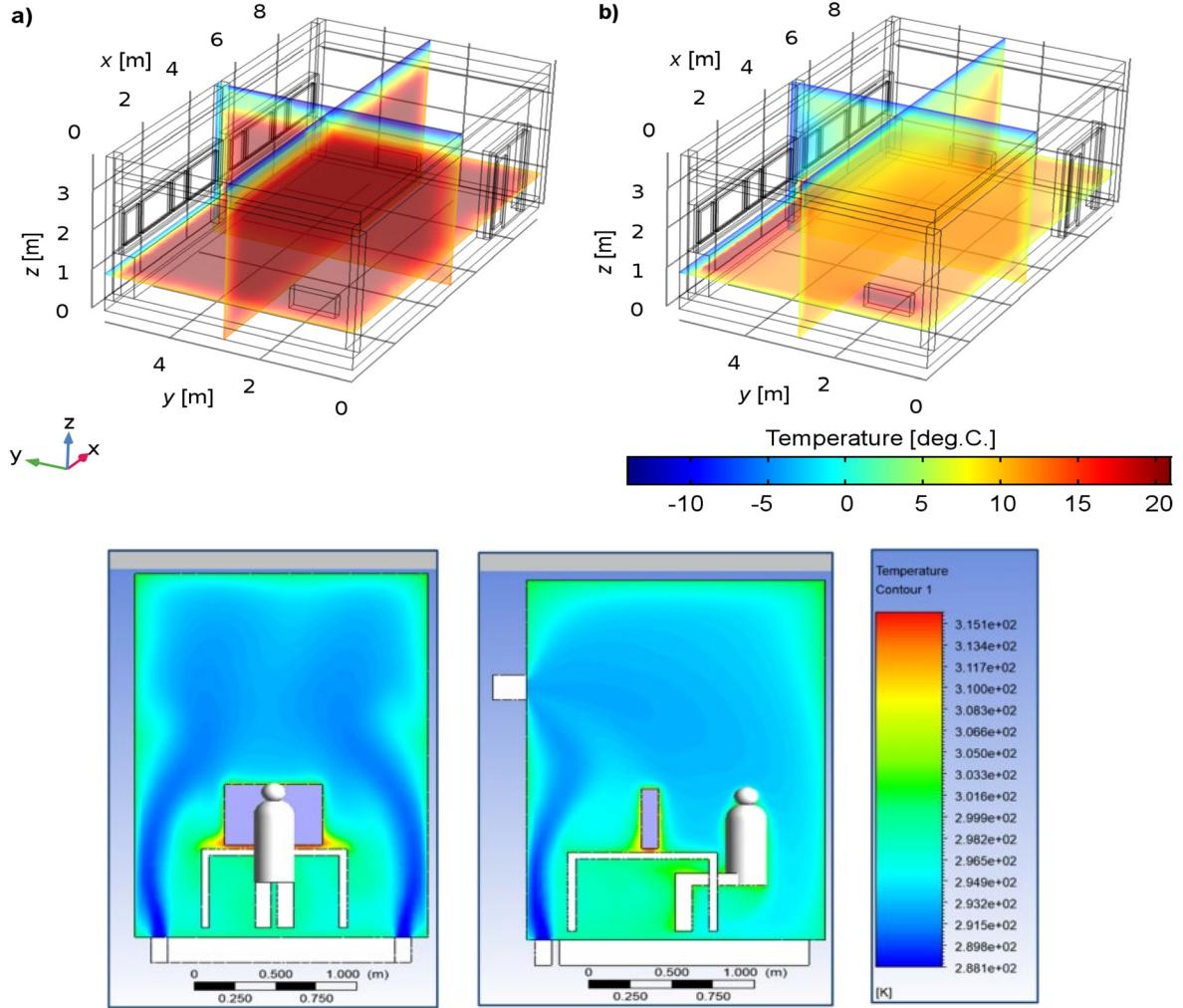
Normál vektor



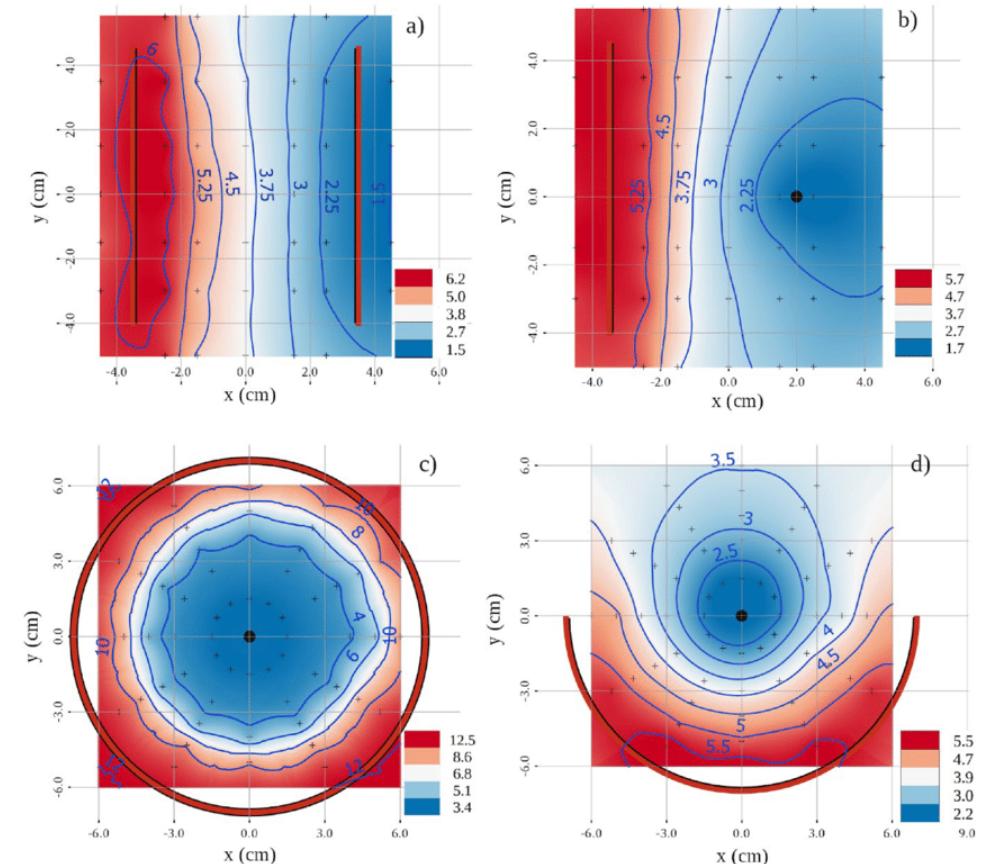
$$\mathbf{A} = A \cdot \mathbf{n}$$

Skalártér

Hőmérséklet ($T(\underline{r})$)

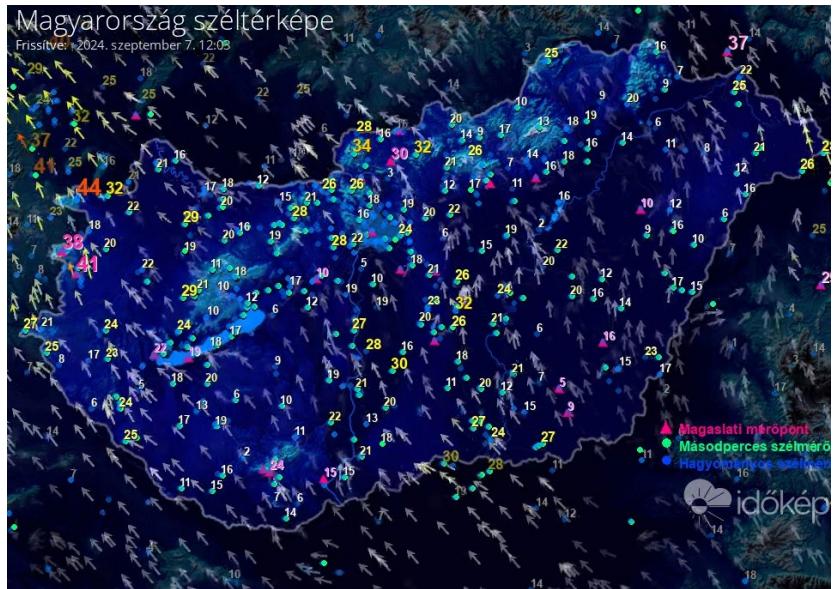


Elekromos potenciál ($U(\underline{r})$)

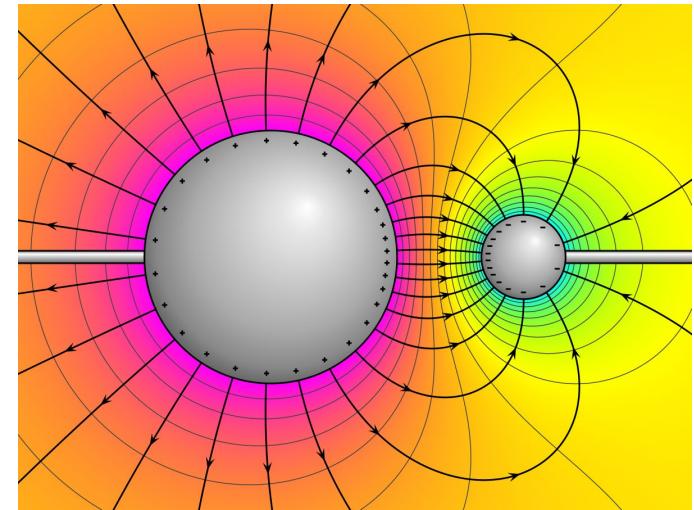


Vektortér

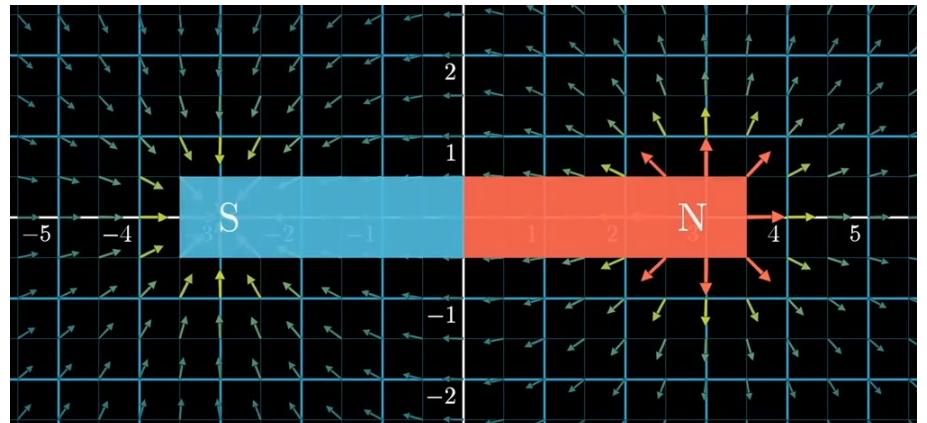
Szélterkép($v(r)$)



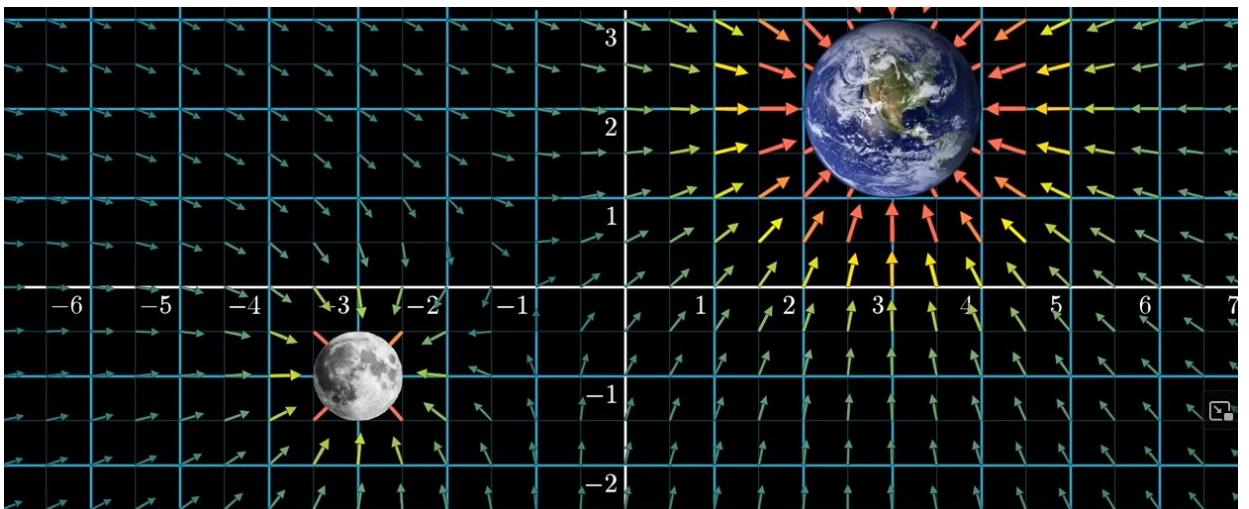
Elekromos tér ($E(r)$)



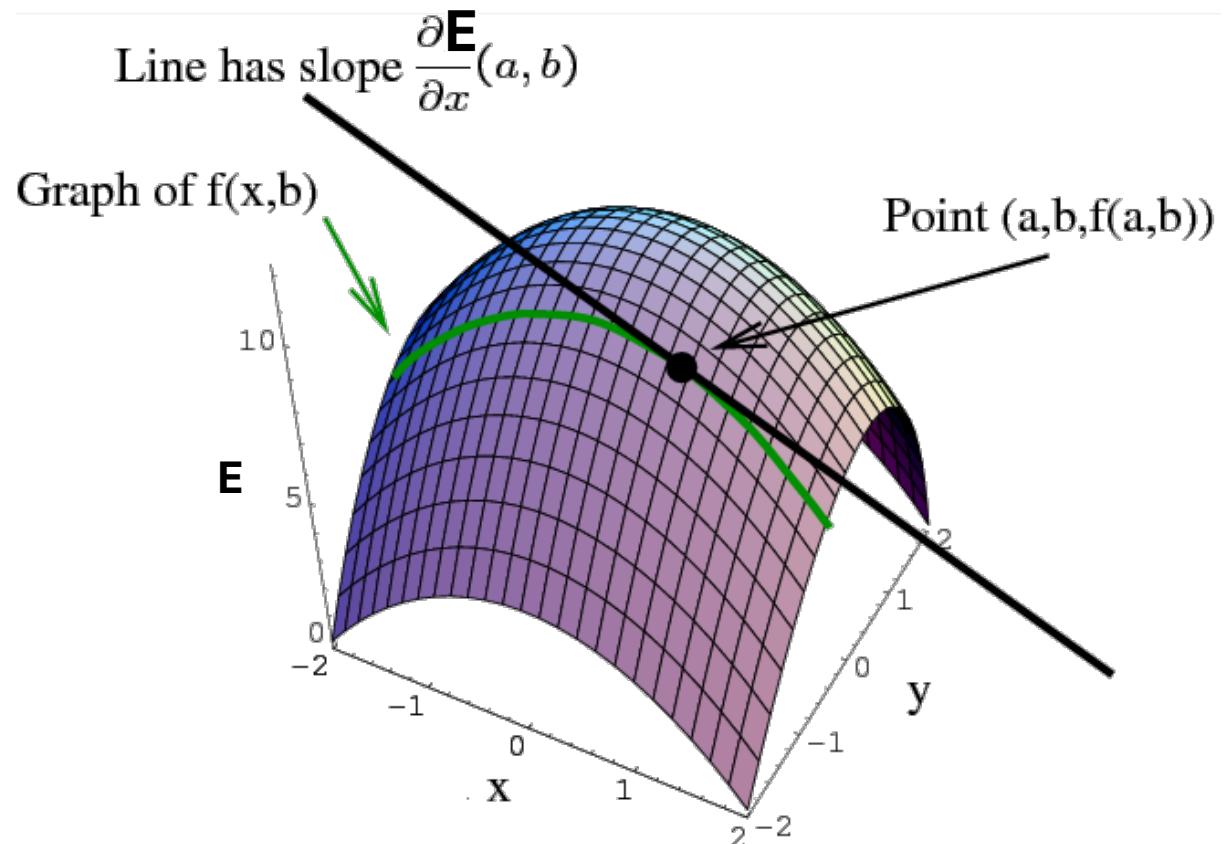
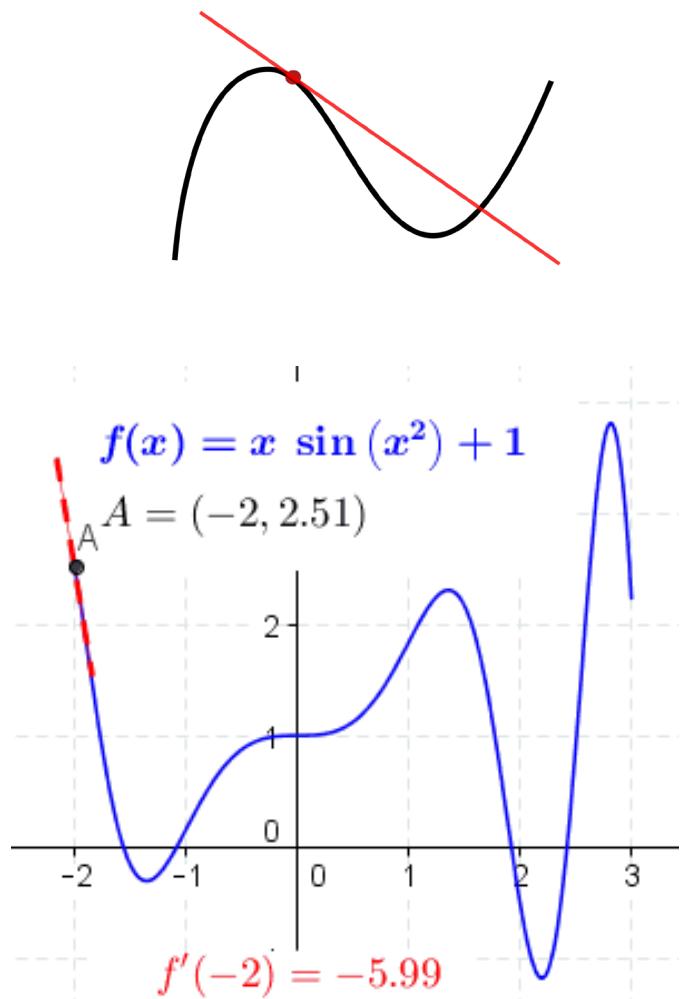
Mágneses tér ($B(r)$)



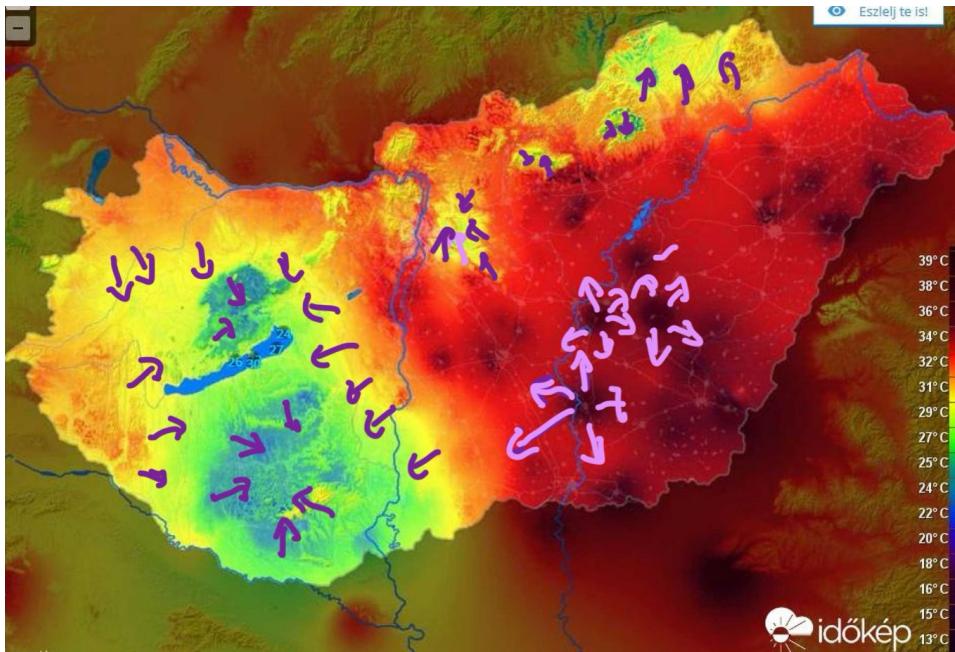
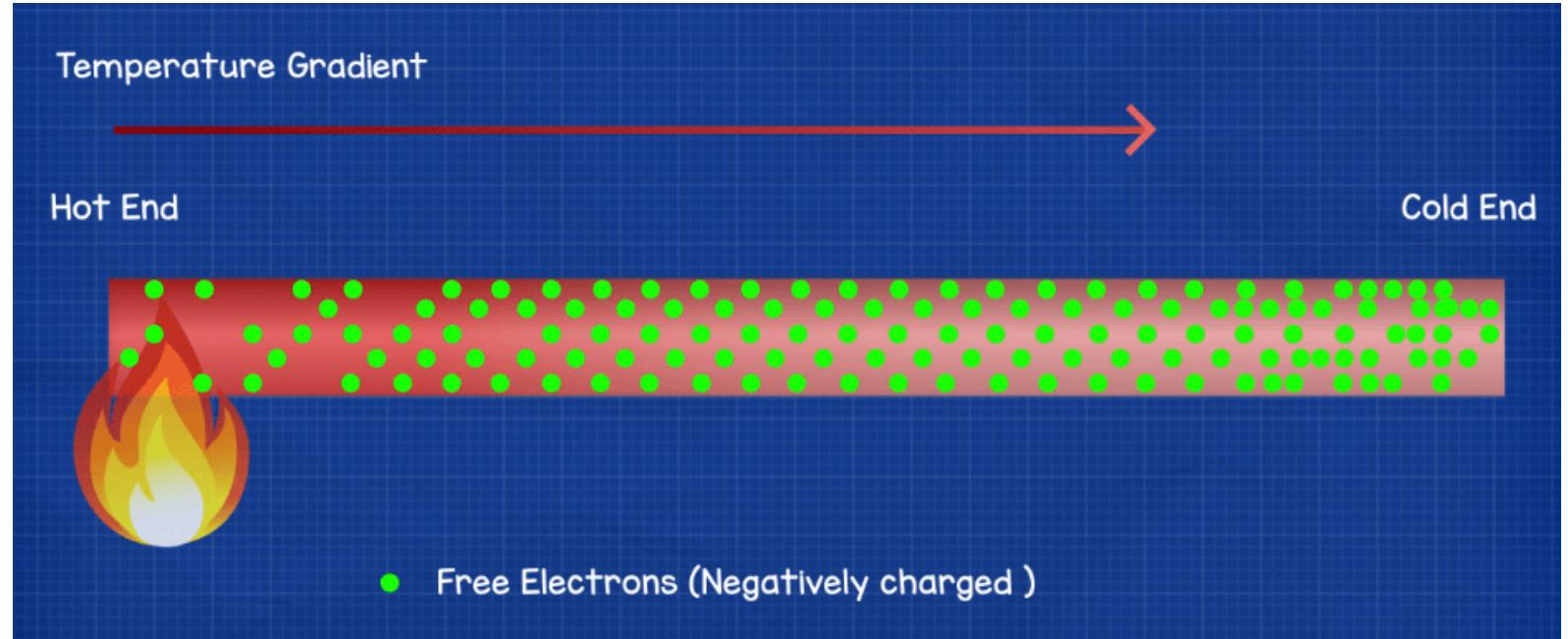
Gravitációs erőtér ($F_g(r)$)



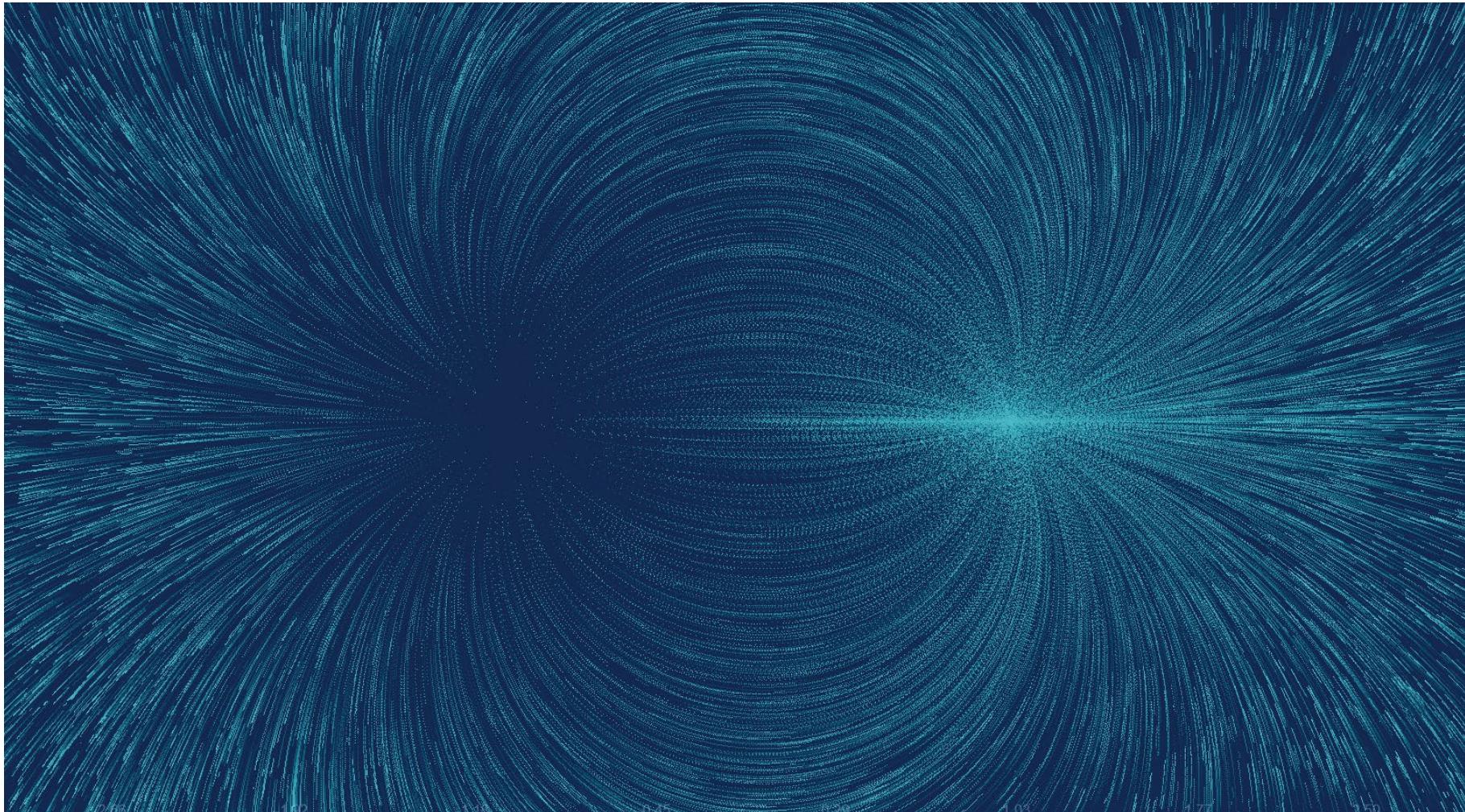
Deriválás



Gradiens



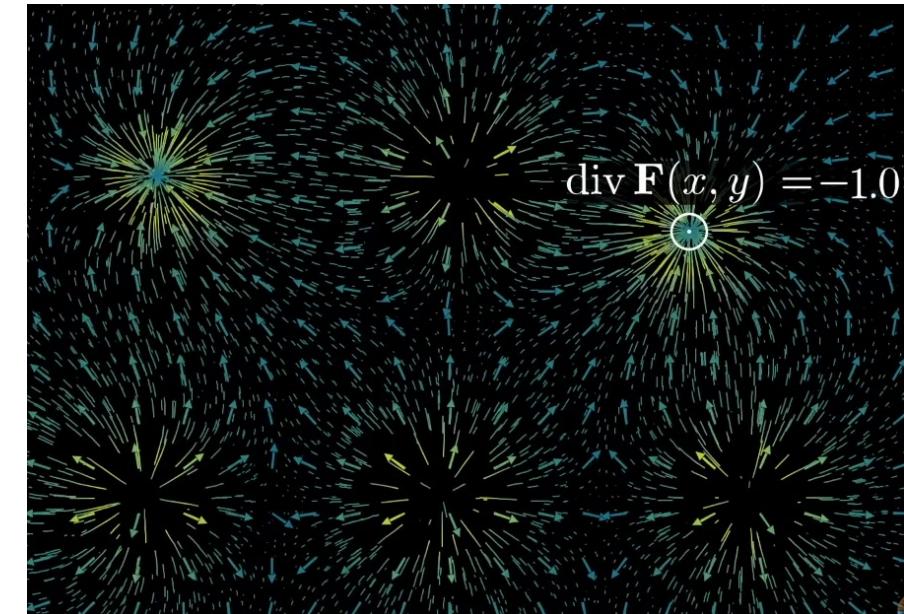
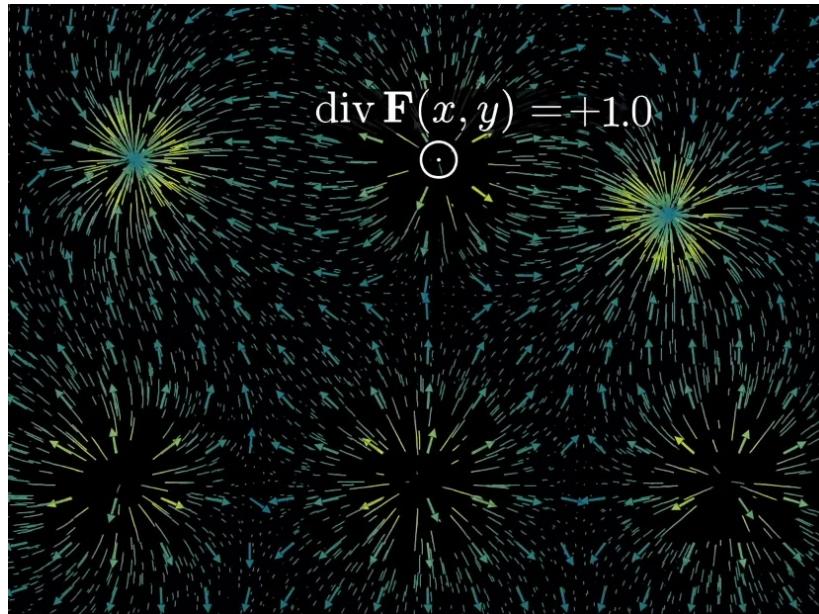
Erővonal ≈ folyadék áramlás



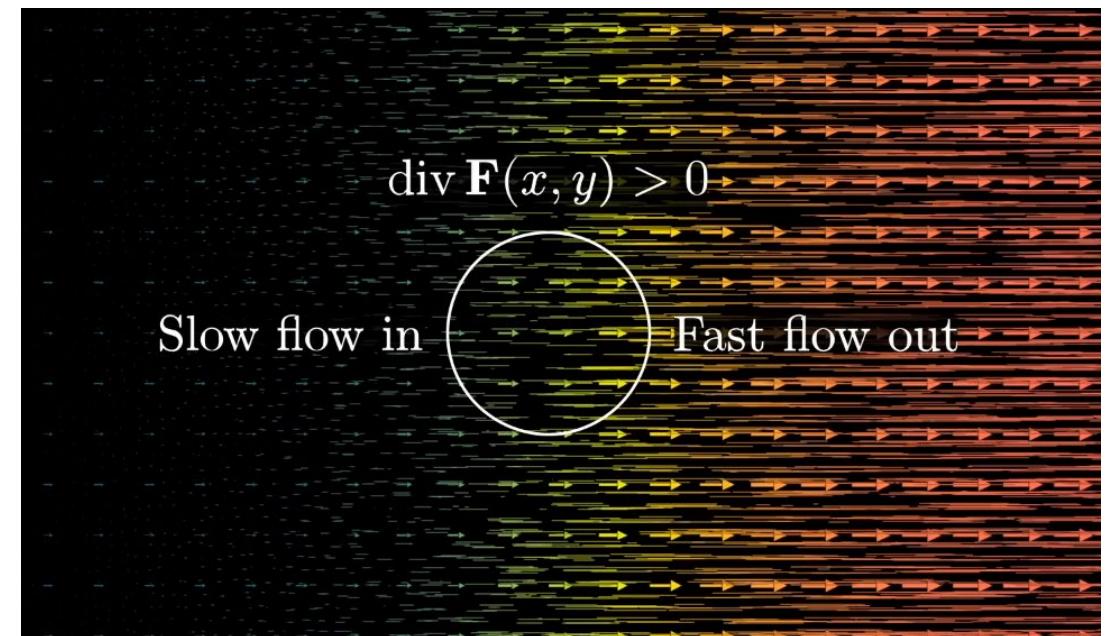
<https://anvaka.github.io/fieldplay/>

```
// p.x and p.y are current coordinates  
// v.x and v.y is a velocity at point p  
  
vec2 E(vec2 p, vec2 pos, float q){  
    vec2 r = p - pos;  
    float dist = length(r);  
    float field = q/(dist*dist);  
    return vec2(field * r.x,field * r.y);  
}  
  
vec2 get_velocity(vec2 p) {  
    vec2 v = vec2(0., 0.);  
  
    // change this to get a new vector field  
    vec2 EField =  
        E(p, vec2(-1.,1.),1.)  
        +E(p, vec2(1.,1.),-1.);  
    //+E(p, vec2(1.,-1.),1.)  
    //+E(p, vec2(-1.,-1.),-1.);  
    v.x = EField.x;  
    v.y = EField.y;  
  
    return v;  
}
```

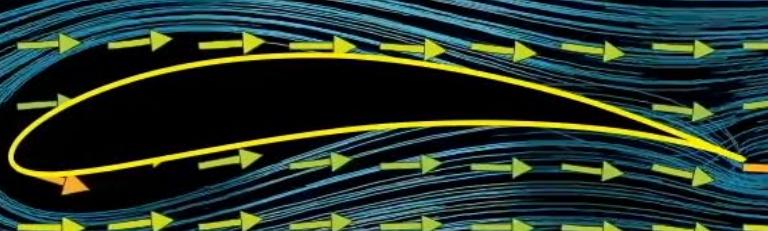
Divergencia



$$\text{div } \mathbf{F} = \nabla \cdot \mathbf{F} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot \begin{pmatrix} F_x \\ F_y \\ F_z \end{pmatrix} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}$$

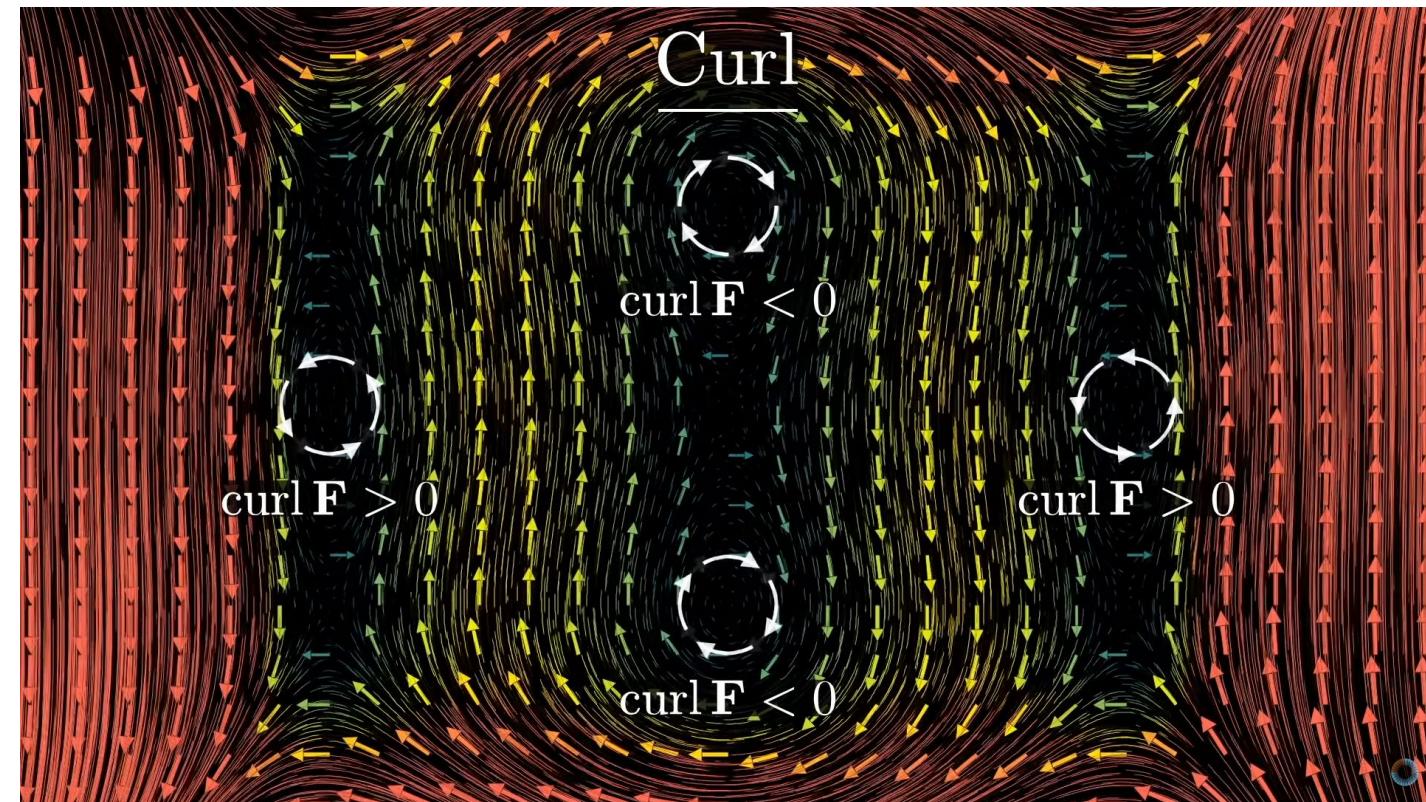
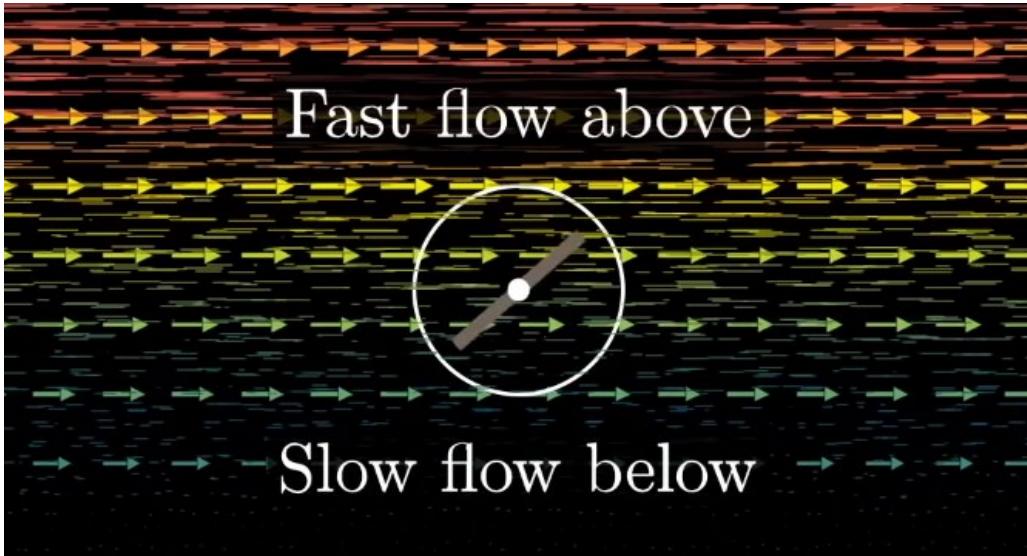


For actual (incompressible) fluid flow:
 $\operatorname{div} \mathbf{F} = 0$ everywhere



Rotació

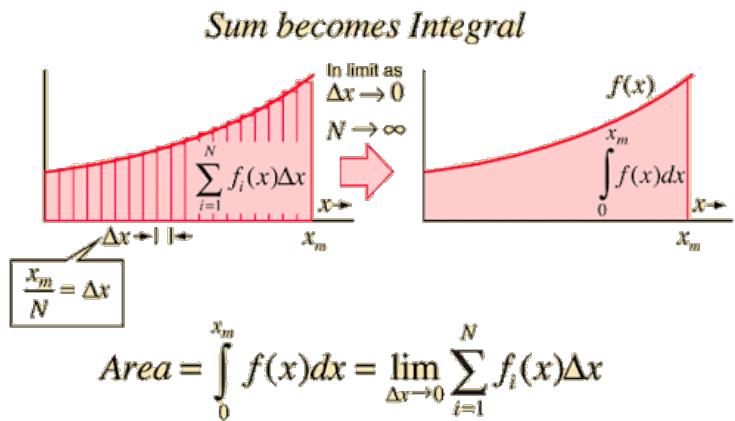
$$\text{rot } \mathbf{F} = \nabla \times \mathbf{F} = \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \times \begin{pmatrix} F_x \\ F_y \\ F_z \end{pmatrix} = \begin{bmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{bmatrix} = \begin{pmatrix} \frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z} \\ -\frac{\partial F_z}{\partial x} + \frac{\partial F_x}{\partial z} \\ \frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \end{pmatrix}$$



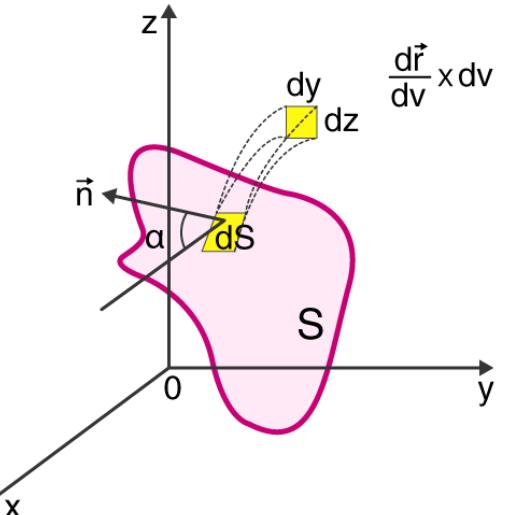
Integrálás

Skalártér
Vektortér

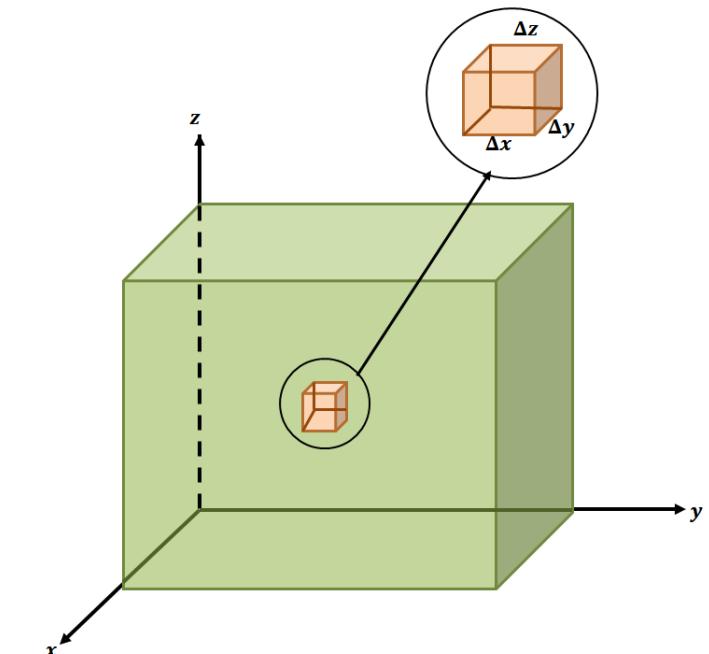
Vonal menti



Felületi



Tér fogatí



26

