

Supported Topics

- **Baxter**
 - Publisher
 - /robot/analog_io/command
 - /robot/digital_io/command
 - /robot/digital_io/<light_component_id>/state
 - /robot/digital_io/<side>_shoulder_button/state
 - /robot/digital_io/<side>_lower_cuff/state
 - /robot/digital_io/<side>_lower_button/state
 - /robot/digital_io/<side>_upper_button/state
 - /robot/limb/<side>/joint_command
 - /robot/end_effector/<side>_gripper/command
 - /robot/head/command_head_nod
 - /robot/head/command_head_pan
 - /robot/set_super_enable
 - /robot/sonar/head_sonar/lights/set_green_level
 - /robot/sonar/head_sonar/lights/set_lights
 - /robot/sonar/head_sonar/lights/set_red_level
 - /robot/sonar/lights/set_red_level
 - /robot/sonar/lights/set_green_level
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 - Subscriber
 - /cameras/<camera>/image
 - /robot/digital_io/<component_id>/state
 - /robot/end_effector/<side>_gripper/state
 - /robot/head/head_state
 - /robot/itb/<component_id>/state
 - /robot/joint_states
 - /robot/limb/<side>/endpoint_state
 - /robot/range/<side>_hand_range/state
 - /robot/range/<component_id>
 - /robot/sonar/head_sonar/lights/green_level
 - /robot/sonar/head_sonar/lights/red_level
 - /robot/sonar/head_sonar/state
 - /robot/state
 - Service
 - /cameras/close
 - /cameras/list
 - /cameras/open
 - /ExternalTools/<side>/PositionKinematicsNode/IKService
- **NAO**
 - Publisher
 - /cmd_vel
 - Subscriber

- /alrosbridge/sonar/right
- **Turtlebot**
 - Publisher
 - /cmd_vel_mux/input/teleop
 - Subscriber
 - /odom