

ROS Terminal

The ROS Terminal provides a space for visualizing what is going on in your environment. In the terminal, you can view the current master and whether or not it is live as well as see your own IP address. The three lists let you see nodes, logs, and servers. Dots next to logs indicate that the server is still running and Xs next to logs indicate an error. Clicking on logs opens an HTML page and clicking on nodes and servers open VIs. These HTML pages and VIs allow you to further interact with your selection by seeing what is being sent back and forth as well as what items are on the queue. The HTML files are stored in your LabVIEW Data folder, generally found under My Documents. You can also use the terminal to close nodes and servers.

