### **Supported Messages and Services for Parsing**

#### Standard Messages

- o Bool
- ColorRGBA
- Duration
- o Float32
- o Float32MultiArray
- o Float64
- o Float64MultiArray
- Header
- o Int16
- o Int16MultiArray
- o Int32
- o Int32MultiArray
- o Int64
- o Int64MultiArray
- o Int8
- o Int8MultiArray
- o MultiArrayDimension
- MultiArrayLayout
- String
- o Time
- o UInt16
- o UInt16MultiArray
- o UInt32
- UInt32MultiArray
- o UInt64
- UInt64MultiArray
- o UInt8
- UInt8MultiArray

# Geometry Messages

- Accel
- AccelStamped
- AccelWithCovariance
- AccelWithCovarianceSta mped
- o Inertia
- o InertiaStamped
- o Point
- o Point32
- PointStamped
- Pose
- o Pose2D
- PoseStamped

- o PoseWithCovariance
- PoseWithCovarianceSta mped
- Quaternion
- o QuaternionStamped
- Transform
- TransformStamped
- o Twist
- o TwistStamped
- TwistWithCovariance
- TwistWithCovarianceSt amped
- o Vector3
- Vector3Stamped
- Wrench
- WrenchStamped

## Navigation Messages

o Odometry

### Sensor Messages

- o ChannelFloat32
- o Image
- o **JointState**
- o PointCloud
- Range

### • Baxter Core Messages

- AnalogOutputState
- AssemblyState
- o DigitalIOCommand
- o DigitalIOState
- o EndEffectorState
- EndpointState
- o GripperState
- o HeadState
- o ITB
- ListCameras
- SolvePositionIKRespons

e

#### Miscellaneous

- o ArrayLength
- o JointStatesUnits
- MsgExists
- o ErrorCheck
- o PYRtoQuaternion

- $\circ \quad Quaternion To PYR$
- o ServiceError