

Multi-Step Object Re-Identification on Edge Devices: A Pipeline for Vehicle Re-Identification

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Abstract—A method that leverages a multi-step process focused on extracting and using object features for object re-identification is described. The proposed pipeline includes steps such as: detecting an object, converting its features into a vector embedding, storing this embedding in a vector database, and then querying the database to find the same or similar objects based on their feature embeddings. This approach allows for the identification of the same object across different images or cameras, even in varying locations, such as in Vehicle Re-Identification scenarios. For situations where re-identification needs to happen in outdoor environments or on-the-go, implementing this process on edge devices becomes crucial. Therefore, multiple ways to tailor the pipeline and its outputs for edge devices are outlined and investigated. The presentation provides a detailed explanation of the pipeline's structure and how it functions on edge devices, along with the experimental setup demonstrating its application, particularly in vehicle re-identification.

Index Terms—Re-Identification, Feature extractions, Vector embeddings, Neural networks, Edge devices, Vector databases

I. INTRODUCTION

Monitoring and recognizing objects in photos and videos has long been a field of interest for many. It has also become a well researched topic ever since computer vision has accelerated its possibilities, in the last decade especially. With computer vision came object classification, which helped us classify images based on the object depicted. That gave us the answer to the question: "What is the object in the image?" Later on came great progress in object detection. That could answer the questions of: "Where are the objects in the image?" and "What are the objects in the image". These were great leaps forward if the job was to pay attention to only objects of a specific class and there were multiple of them in a frame. In this article, however, the authors are looking for a solution that could see these objects of a single class and differentiate between them, using the specific features that exist only for a single individual in a class. This problem is called object Re-Identification - the correct identification of an individual object in any number of scenes, where there are usually more of this class objects visible.

II. RELATED WORK

III. PROPOSED METHOD

IV. EXPERIMENTS AND RESULTS

V. DISCUSSION

VI. CONCLUSION

REFERENCES