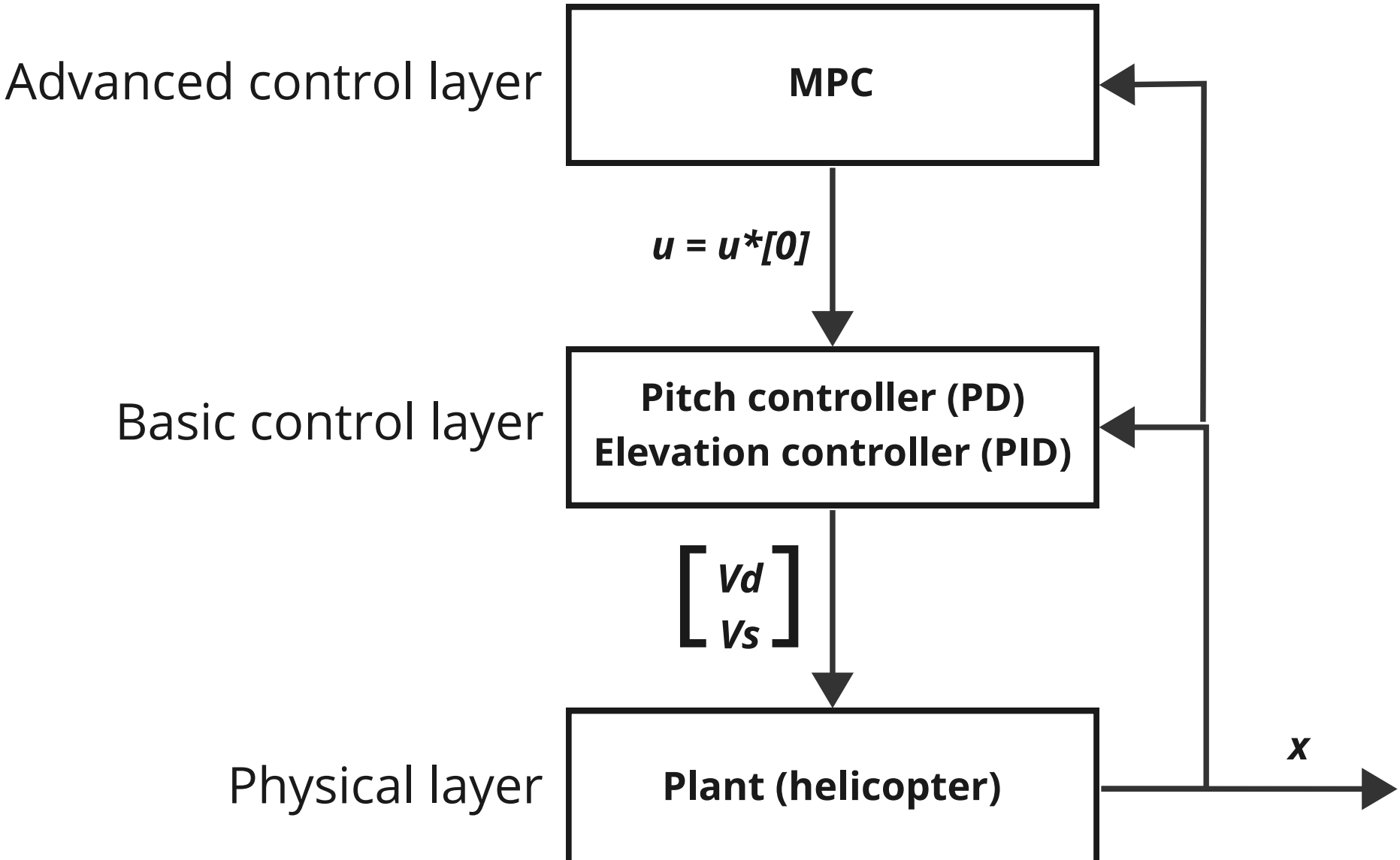
Advanced control layer
MPC
u = u*[0]
Basic control layer
Pitch controller (PD)
Elevation controller (PID)
Vd
Vs
Physical layer
Plant (helicopter)
x