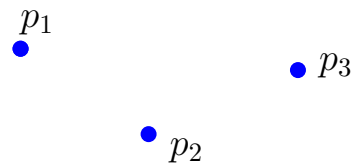


2D CH: In Class Exercises

Task 1: Implementing the [orientation test](#)

Basic formula:

$$x_1(y_2 - y_3) + x_2(y_3 - y_1) + x_3(y_1 - y_2)$$

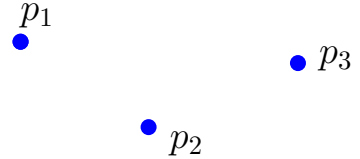


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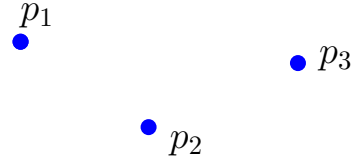
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2D CH: In Class Exercises

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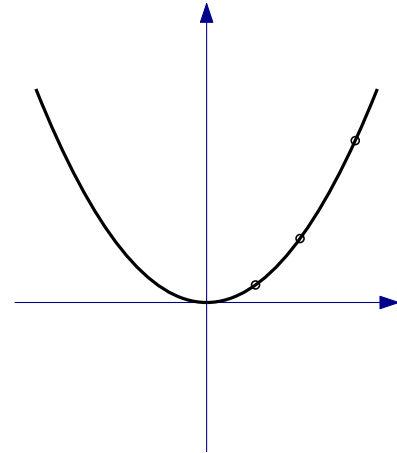
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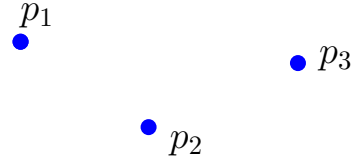


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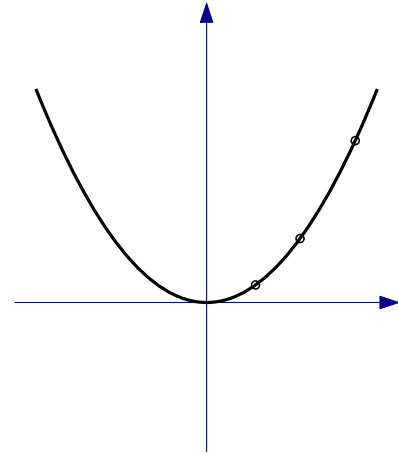
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Check this for $i = 1, \dots, n-2$ and count how many times this holds, for different values of n .

Use 32bit floating point numbers for this test!



2D CH: In Class Exercises

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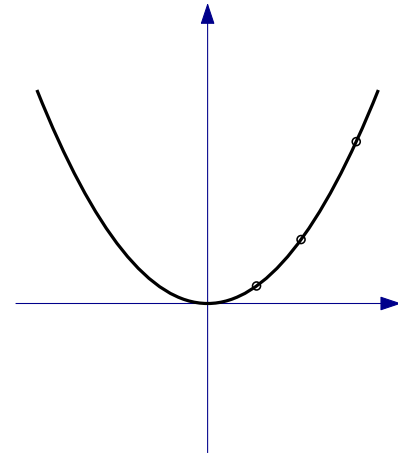
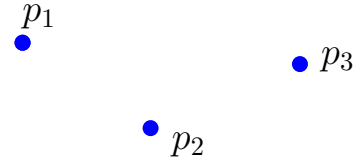
$$x_1(y_2 - y_3) + x_2(y_3 - y_1) + x_3(y_1 - y_2)$$

Task 2: Try with different ways of writing the same formula, for example:

(V2) $x_1y_2 - x_1y_3 + x_2y_3 - x_2y_1 + x_3y_1 - x_3y_2$

or

(V3) $x_1y_2 + x_2y_3 + x_3y_1 - x_1y_3 - x_2y_1 - x_3y_2$



2D CH: In Class Exercises

Task 3: The typical `float` data type is based on IEEE 754, e.g., the `binary32` format. Here, a floating point number f is represented as:

$$f = m \cdot 2^x$$

The standard allocates 24 bits to represent number m and 8 bits for x .

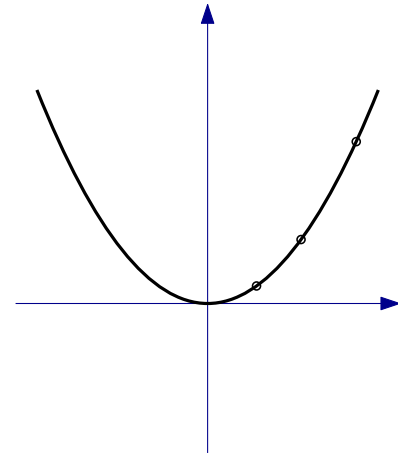
Question 1: If we have two floating points numbers $f_1 = m_1 \cdot 2^{x_1}$ and $f_2 = m_2 \cdot 2^{x_2}$, how many bits do we need to represent $f_1 \cdot f_2$ without error?

Question 2: How many bits do we need to represent $f_1 + f_2$ with no error?

p_1

p_3

p_2



2D CH: In Class Exercises

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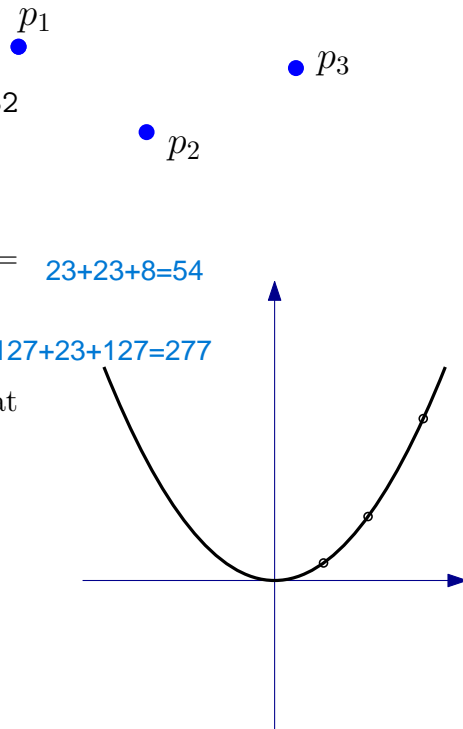
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Question 2: How many bits do we need to represent $f_1 + f_2$ with no error? 127+23+127=277

Take-home Question: How difficult do you think is it to write a code that evaluates the basic formula without any errors?

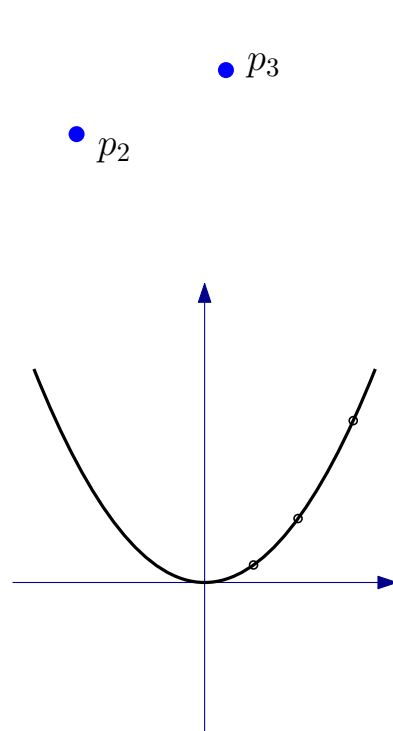


2D CH: In Class Exercises

Question 3: Assume a floating point format, $f = m \times 2^x$, has k bits for representing m and x . Answer the following questions:

- What's the smallest and largest positive numbers we can represent?
- How many bits, asymptotically, do we need to represent $f_1 \times f_2$ or $f_1 + f_2$ exactly for two floating numbers f_1 and f_2 ?
- For $f = f_1 + f_2$, one can argue that at most $O(k)$ bits will be *meaningful*, meaning, the rest will be either a long sequence of all 0s or all 1s. In other words, one can show that the total number of **changes** in the representation of f is $O(k)$, where the number of changes is defined as the number of times the two consecutive bits of f are different.

Come up with k floating point numbers f_1, \dots, f_k , and an arithmetic expression involving them that uses $O(k)$ additions and multiplications such that the result contains $\Omega(2^k)$ changes.



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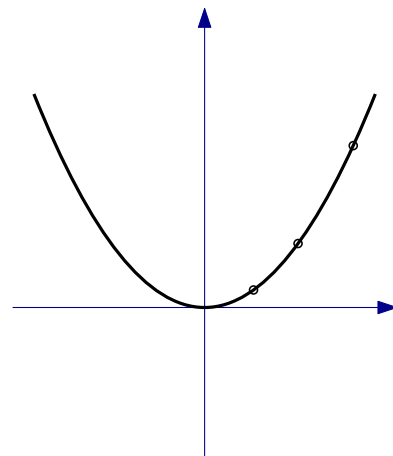
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Hint 1 (white on white text; select to see):

p_1

p_3

p_2



2D CH: In Class Exercises

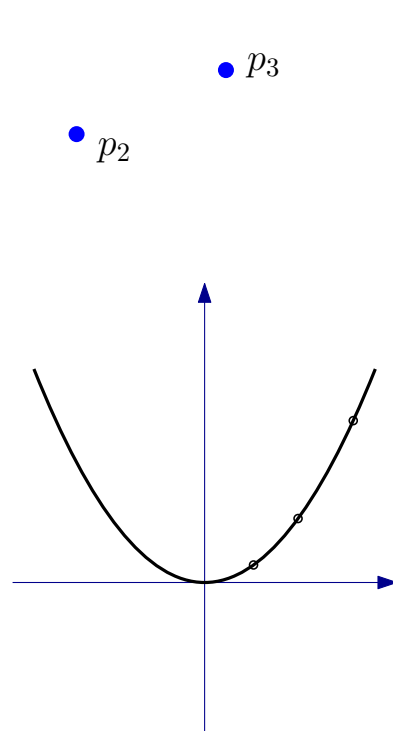
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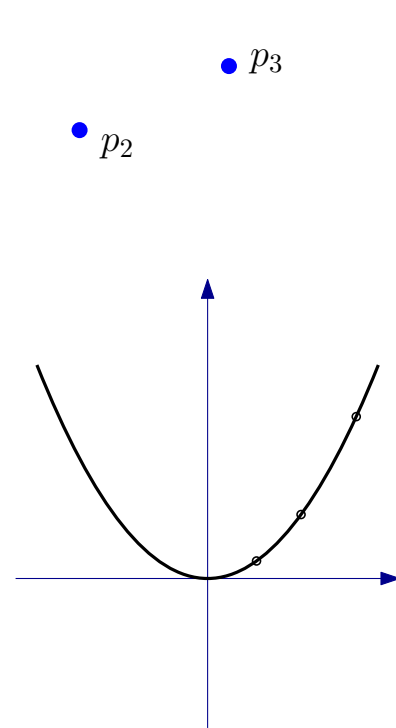
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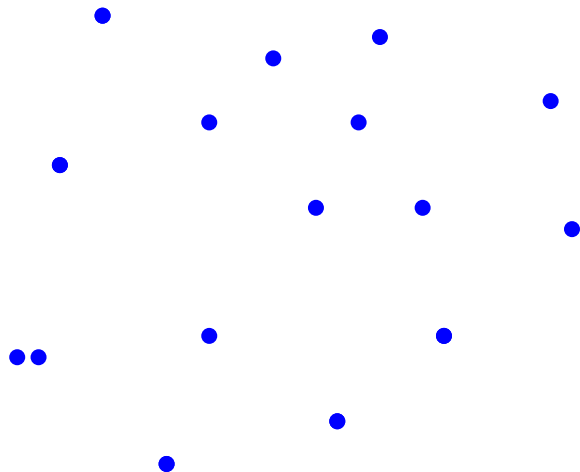
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Challenge question: Come up with a program that uses $O(k)$ additions and multiplications such that it computes a number whose exact representation has at least 2^{2^k} changes.



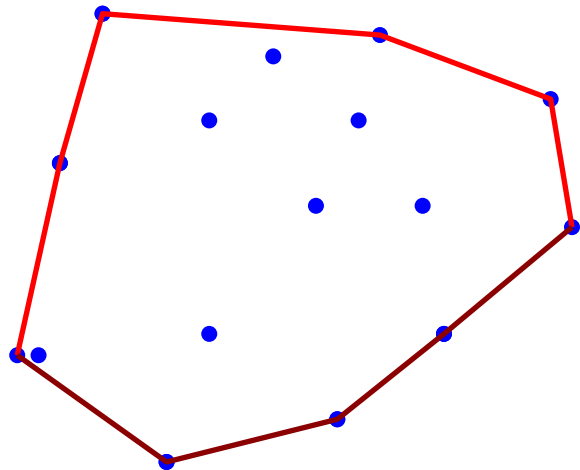
2D CH: In Class Exercises



2D CH: In Class Exercises

Implement Graham's Scan

1. Sort by x -coordinate
2. Initialize **UH** to empty; **UH.add**(p_1, p_2); $s=2$
3. For $i = 3 \rightarrow n$ do
 - 3.1. While $s \geq 2$ & **UH**($s-1$), **UH**(s), p_i make a Left Turn
 - 3.1.1. Remove **UH**(s); $s--$;
 - 3.2. **UH.add**(p_i); $s++$



2D CH: In Class Exercises

Theory Question 1:

Prove that if $\mathcal{C}_1, \dots, \mathcal{C}_n$ are convex, then $\mathcal{C} = \mathcal{C}_1 \cap \mathcal{C}_2 \dots \cap \mathcal{C}_n$ is also convex.

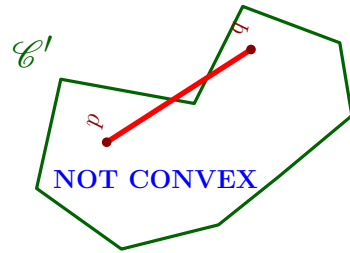
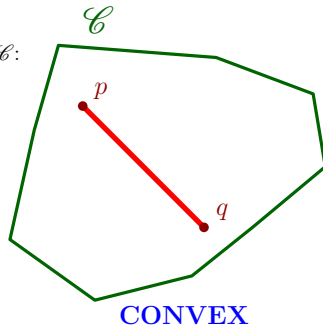
Hints:

We are going to practice with proofs, however, as a starting point, whenever you encounter a theoretical questions that asks for a proof try the following steps.

1. Understand the assumptions. You can use the definitions to fully understand what assumptions you are given.
2. Understand what you need to prove. Once again, you can use the available definitions to fully understand what you need to prove.

In this basic exercise, the two above steps are sufficient to solve the problem. In more complicated problems, more steps will be needed.

\mathcal{C} is **convex** if: for any two points $p, q \in \mathcal{C}$:
 \overline{pq} is inside \mathcal{C}



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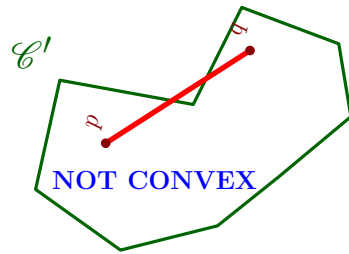
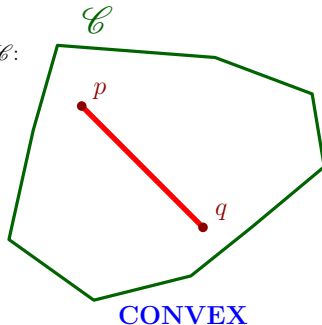
Theory Question 2:

Prove that if \mathcal{C}_1 and \mathcal{C}_2 are convex, then $\mathcal{C} = \mathcal{C}_1 \cup \mathcal{C}_2$ may not be convex.

Hint:

This type of claim can be proven using only a counterexample.

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Exercise: Implement Gift Wrapping (Jarvis March)

1. Initialize:

$p \leftarrow$ the left most point

\vec{r} an upward ray from p

CH.add(p)

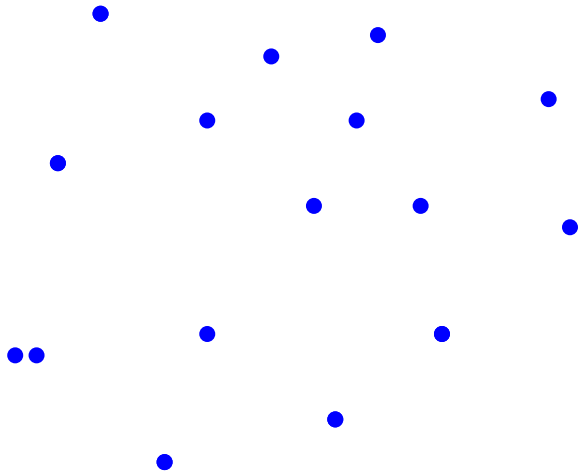
2. Repeat{

2.1. Rotate \vec{r} clockwise around p until
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2.2. **CH.add**(q)

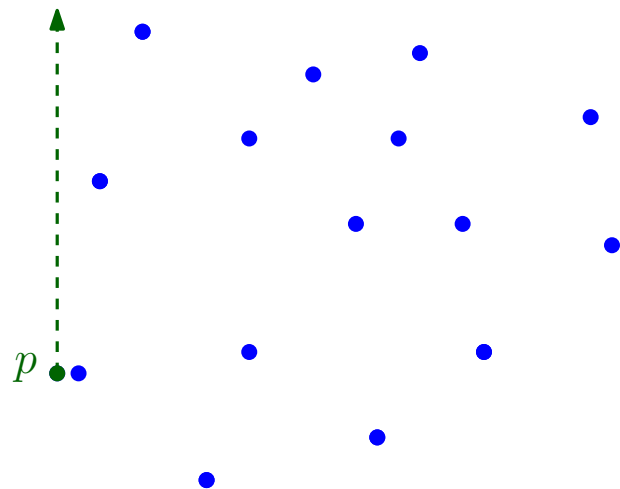
2.3. $p \leftarrow q$

} Until p equals the left most point



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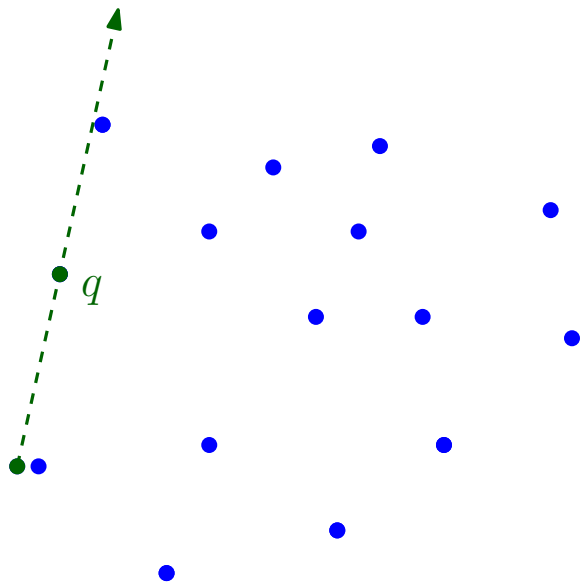
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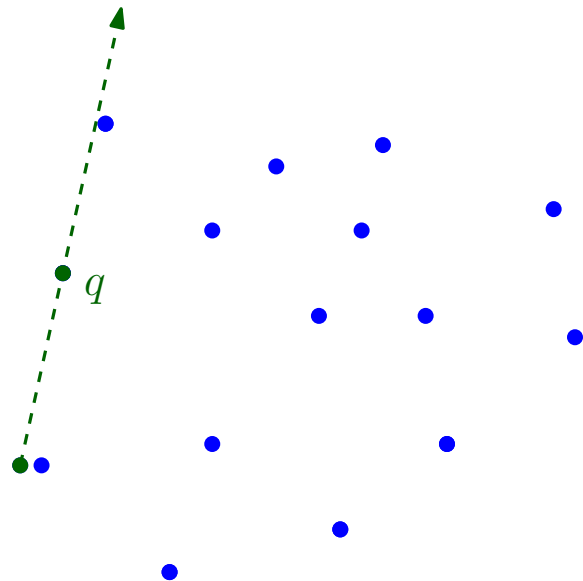
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Step 2.1 is equivalent to finding the point that makes the smallest rotation angle and thus it is equivalent to calculating the rotation angle for every point and taking their minimum.

Before you implement, show that using the sidedness predicate, this can be done **without** explicitly calculating the angle.