```
In [1]: # Problem 1
        import numpy as np
        import pandas as pd
        import matplotlib.pyplot as plt
        from sklearn.datasets import load wine
        from sklearn.decomposition import PCA
        from sklearn.model selection import train test split
        from sklearn.svm import SVC
        from sklearn.tree import DecisionTreeClassifier, plot tree
        from sklearn.metrics import accuracy score, precision score, recall score, or
        # Load Wine dataset
        data = load wine()
        X = data.data
        y = data.target
        feature names = data.feature names
        # 1(a) PCA - First 2 principal components
        pca = PCA(n components=2)
        X pca = pca.fit transform(X)
        # 1(b) Explained variance ratio
        explained variance = pca.explained variance ratio
        print("Explained variance ratio of first two components:", explained variance
        # 1(c) SVM on PCA components
        X train pca, X test pca, y train, y test = train test split(X pca, y, test s
        svm = SVC()
        svm.fit(X train pca, y train)
        y pred svm = svm.predict(X test pca)
        # 1(d) Decision tree on original features
        X_train, X_test, _, _ = train_test_split(X, y, test_size=0.4, random_state=4
        tree = DecisionTreeClassifier(max depth=3, random state=42)
        tree.fit(X train, y train)
        y pred tree = tree.predict(X test)
        # Metrics
        print("\nSVM Classifier Metrics:")
        print("Accuracy:", accuracy_score(y_test, y_pred_svm))
        print("Precision (macro):", precision_score(y_test, y_pred_svm, average='mac
        print("Recall (macro):", recall score(y test, y pred svm, average='macro'))
        print("\nDecision Tree Classifier Metrics:")
        print("Accuracy:", accuracy score(y test, y pred tree))
        print("Precision (macro):", precision_score(y_test, y_pred_tree, average='ma
        print("Recall (macro):", recall_score(y_test, y_pred tree, average='macro'))
        # 1(e) Plot the decision tree
        plt.figure(figsize=(16, 10))
        plot tree(tree, feature names=feature names, class names=data.target names,
```

```
plt.title("Decision Tree (max_depth=3)")
plt.show()
```

Explained variance ratio of first two components: [0.99809123 0.00173592]

SVM Classifier Metrics:

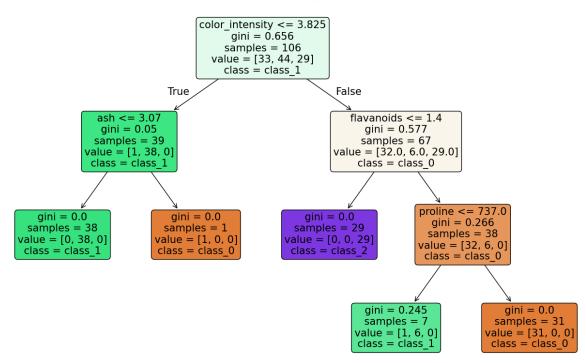
Accuracy: 0.7083333333333334

Precision (macro): 0.6882332643202208 Recall (macro): 0.6934822812015794

Decision Tree Classifier Metrics:

Accuracy: 0.93055555555556

Decision Tree (max_depth=3)



```
In [2]: #Problem 2
# Problem 2: Feature Importance on CIFAR-10 using Random Forest

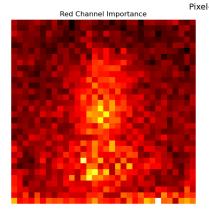
from sklearn.ensemble import RandomForestClassifier
from tensorflow.keras.datasets import cifar10

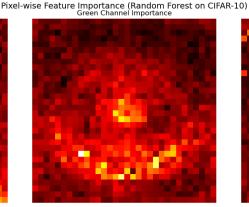
# Load CIFAR-10 dataset
(x_train, y_train), (x_test, y_test) = cifar10.load_data()
y_train = y_train.ravel()
y_test = y_test.ravel()

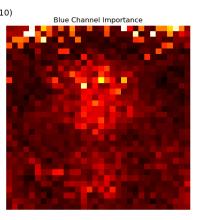
# Combine train and test sets
X = np.concatenate((x_train, x_test), axis=0)
Y = np.concatenate((y_train, y_test), axis=0)

# Flatten the images (32x32x3 -> 3072 features)
X_flat = X.reshape(X.shape[0], -1)
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```

```
# Train a Random Forest Classifier
rf = RandomForestClassifier(n estimators=50, random state=42, n jobs=-1)
rf.fit(X flat, Y)
# Extract feature importances and reshape to image dimensions
importances = rf.feature importances
importances image = importances.reshape(32, 32, 3)
# Plot feature importance heatmaps per channel
fig, axs = plt.subplots(1, 3, figsize=(15, 5))
channels = ['Red', 'Green', 'Blue']
for i in range(3):
    axs[i].imshow(importances image[:, :, i], cmap='hot')
   axs[i].set title(f'{channels[i]} Channel Importance')
   axs[i].axis('off')
plt.suptitle("Pixel-wise Feature Importance (Random Forest on CIFAR-10)", fo
plt.tight layout()
plt.show()
```







```
In [6]: # Problem 3
            from tensorflow.keras.models import Sequential
            from tensorflow.keras.layers import LSTM, Dense
            from sklearn.preprocessing import MinMaxScaler
            # Load temperature data
            temp data = surface temp.reshape(-1, 1)
            # Normalize data
            scaler = MinMaxScaler()
            temp scaled = scaler.fit transform(temp data)
            # Prepare data for RNN
            def create sequences(data, window size, pred size):
                X, y = [], []
                for i in range(len(data) - window size - pred size + 1):
                    X.append(data[i:i+window size])
                    y.append(data[i+window size:i+window size+pred size])
                return np.array(X), np.array(y)
            window size = 20 # how many past steps to look at
Loading [MathJax]/extensions/Safe.js = 10
                             # predict next 10 steps
```

```
X, y = create sequences(temp scaled, window size, pred size)
# Split into training and validation sets
split = int(0.8 * len(X))
X train, y train = X[:split], y[:split]
X val, y val = X[split:], y[split:]
# Build the RNN model
model = Sequential([
    LSTM(64, activation='tanh', input shape=(window size, 1)),
    Dense(pred size)
])
model.compile(optimizer='adam', loss='mse')
# Train the model
history = model.fit(X train, y train, epochs=30, validation data=(X val, y \
# Predict the next 10 timesteps using the last available window
last window = temp scaled[-window size:].reshape(1, window size, 1)
predicted scaled = model.predict(last window)
# Inverse transform predictions
predicted = scaler.inverse transform(predicted scaled.reshape(-1, 1)).flatte
# Plot the results
plt.figure(figsize=(10, 5))
plt.plot(range(1000), temp data.flatten(), label='Original Data')
plt.plot(range(1000, 1010), predicted, label='Predicted (next 10)', marker='
plt.xlabel('Timestep')
plt.ylabel('Surface Temperature')
plt.title('RNN Prediction of Surface Temperature')
plt.legend()
plt.grid(True)
plt.show()
```

Epoch 1/30

C:\Users\Tom\anaconda3\Lib\site-packages\keras\src\layers\rnn\rnn.py:200: Us
erWarning: Do not pass an `input_shape`/`input_dim` argument to a layer. Whe
n using Sequential models, prefer using an `Input(shape)` object as the firs
t layer in the model instead.
 super().__init__(**kwargs)

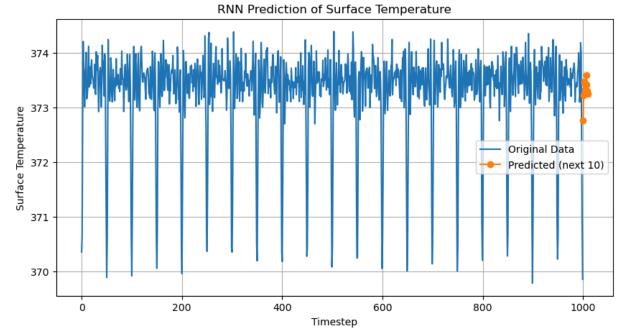
| 25/25 | | 7 c | 10ms/sten | _ | 1000 | 0 4678 | _ | val loss: | 0 0338 |
|----------------|--------|------------|---------------------|---|-------|--------|---|-----------|--------|
| Epoch | | , , | 4511137 3 CCP | | | 0.4070 | | vac_coss. | 0.0550 |
| | , | 1 s | 20ms/step | - | loss: | 0.0397 | - | val_loss: | 0.0299 |
| Epoch | | | | | | | | | |
| | 4.720 | 1 s | 20ms/step | - | loss: | 0.0328 | - | val_loss: | 0.0283 |
| Epoch | 4/30 | 1.0 | 20mc/cton | | 10001 | 0 0334 | | val locci | 0 0203 |
| Epoch | | 12 | Zuiis/step | - | 1055. | 0.0324 | - | vai_tuss. | 0.0203 |
| 25/25 | | 1s | 20ms/step | _ | loss: | 0.0300 | _ | val loss: | 0.0278 |
| Epoch | 6/30 | | | | | | | | |
| | | 1 s | 20ms/step | - | loss: | 0.0298 | - | val_loss: | 0.0280 |
| | 7/30 | 1. | 20mc/c+on | | 10001 | 0 0222 | | val locci | 0 0277 |
| | 8/30 | 12 | Zuiis/step | - | (055; | 0.0322 | - | vat_tuss: | 0.0277 |
| | | 0s | 16ms/step | - | loss: | 0.0316 | _ | val loss: | 0.0273 |
| Epoch | 9/30 | | | | | | | _ | |
| | | 1 s | 22ms/step | - | loss: | 0.0325 | - | val_loss: | 0.0267 |
| | 10/30 | 0.5 | 17mc/cton | | 10001 | 0 0212 | | val locci | 0 0277 |
| | 11/30 | US | 1/1115/3 CCP | _ | 1055. | 0.0312 | - | vat_tuss. | 0.0277 |
| | | 1 s | 19ms/step | - | loss: | 0.0321 | - | val_loss: | 0.0266 |
| Epoch | 12/30 | _ | | | | | | | |
| 25/25 Enach | 12/20 | 1s | 22ms/step | - | loss: | 0.0299 | - | val_loss: | 0.0264 |
| 25/25 | 13/30 | 1s | 20ms/step | _ | loss: | 0.0291 | _ | val loss: | 0.0265 |
| Epoch | 14/30 | | | | | | | | |
| | | 1 s | 21ms/step | - | loss: | 0.0288 | - | val_loss: | 0.0268 |
| | 15/30 | 1.0 | 20mc/cton | | 10001 | 0 0279 | | val locci | 0 0262 |
| | 16/30 | 13 | 20113/3 Cep | _ | 1055. | 0.0270 | - | vat_tuss. | 0.0202 |
| | | 0s | 17ms/step | - | loss: | 0.0280 | - | val_loss: | 0.0268 |
| | 17/30 | _ | | | | | | | |
| | 18/30 | IS | 19ms/step | - | loss: | 0.0284 | - | val_loss: | 0.0264 |
| | | 1s | 19ms/step | _ | loss: | 0.0279 | _ | val loss: | 0.0262 |
| Epoch | 19/30 | | | | | | | | |
| | 22 /22 | 1 s | 21ms/step | - | loss: | 0.0293 | - | val_loss: | 0.0262 |
| | 20/30 | 1 c | 21ms/step | | 10001 | 0 0278 | | val locci | 0 0250 |
| - | 21/30 | 13 | 211113/3CCP | | | 0.0270 | | vac_coss. | 0.0233 |
| | | 1 s | 20ms/step | - | loss: | 0.0288 | - | val_loss: | 0.0259 |
| | 22/30 | _ | 20 () | | - | | | | 0 0050 |
| | 23/30 | ls | 20ms/step | - | loss: | 0.0284 | - | val_loss: | 0.0259 |
| | 23/30 | 1s | 21ms/step | _ | loss: | 0.0293 | _ | val loss: | 0.0259 |
| Epoch | 24/30 | | | | | | | _ | |
| | 25.422 | 1 s | 20ms/step | - | loss: | 0.0300 | - | val_loss: | 0.0258 |
| | 25/30 | 1 e | 20mc/ctan | _ | 1000 | 0 0200 | _ | val loss: | 0 0257 |
| | 26/30 | 13 | 20113/31 c β | _ | .033. | 0.0233 | _ | var_1033. | 0.0237 |
| | | 1 s | 20ms/step | - | loss: | 0.0276 | - | val_loss: | 0.0256 |
| | 27/30 | | 21 / | | 1 | 0.0000 | | | 0.0001 |
| | 28/30 | TS | 21ms/step | - | LOSS: | U.U268 | - | val_loss: | 0.0261 |
| | 20/ 30 | 1s | 20ms/step | - | loss: | 0.0291 | - | val loss: | 0.0257 |
| | 20 /20 | | | | | | | _ | |

```
25/25 ______ 1s 20ms/step - loss: 0.0265 - val_loss: 0.0256

Epoch 30/30

25/25 _____ 1s 17ms/step - loss: 0.0296 - val_loss: 0.0255

1/1 _____ 0s 441ms/step
```



In []: