

Newton's Second Law to Lagrangian and Hamiltonian

Newton's Second Law

$$\mathbf{F} = \frac{d}{dt}(m\mathbf{v}) = m\mathbf{a}$$

$$\mathbf{F} - m\mathbf{a} = 0$$

D'Alembert's Principle

$$(\mathbf{F} - m\mathbf{a}) \cdot \delta\mathbf{r} = 0$$

Principle of Least Action

$$\int_{t_1}^{t_2} (\mathbf{F} - m\mathbf{a}) \cdot \delta\mathbf{r} dt = 0$$

$$\int_{t_1}^{t_2} \mathbf{F} \cdot \delta\mathbf{r} dt - \int_{t_1}^{t_2} m\mathbf{a} \cdot \delta\mathbf{r} dt = 0$$

$$\int_{t_1}^{t_2} \mathbf{F} \cdot \delta\mathbf{r} dt := \int_{t_1}^{t_2} -\delta V dt = \delta \int_{t_1}^{t_2} -V dt$$

$$- \int_{t_1}^{t_2} m\mathbf{a} \cdot \delta\mathbf{r} dt = - \int_{t_1}^{t_2} m\dot{\mathbf{v}} \cdot \delta\mathbf{r} dt$$

$$= -[m\mathbf{v} \cdot \delta\mathbf{r}]_{t_1}^{t_2} + \int_{t_1}^{t_2} m\mathbf{v} \cdot \frac{d}{dt}(\delta\mathbf{r}) dt$$

$$\delta \mathbf{r}(t_1) = \delta \mathbf{r}(t_2) = 0 \Rightarrow [m \mathbf{v} \cdot \delta \mathbf{r}]_{t_1}^{t_2} = 0$$

$$\Rightarrow - \int_{t_1}^{t_2} m \mathbf{a} \cdot \delta \mathbf{r} dt = \int_{t_1}^{t_2} m \mathbf{v} \cdot \delta \mathbf{v} dt$$

$$\delta(v^2) = \delta(\mathbf{v} \cdot \mathbf{v}) = 2\mathbf{v} \cdot \delta \mathbf{v}$$

$$\Rightarrow \int_{t_1}^{t_2} m \mathbf{v} \cdot \delta \mathbf{v} dt = \int_{t_1}^{t_2} \frac{m}{2} \delta(\mathbf{v} \cdot \mathbf{v}) dt$$

$$= \delta \int_{t_1}^{t_2} \frac{m}{2} v^2 dt := \delta \int_{t_1}^{t_2} T dt$$

$$\Rightarrow \int_{t_1}^{t_2} (\mathbf{F} - m \mathbf{a}) \cdot \delta \mathbf{r} dt = \delta \int_{t_1}^{t_2} (T - V) dt = 0$$

$$\delta \int_{t_1}^{t_2} (T - V) dt := \delta \int_{t_1}^{t_2} \mathcal{L} dt := \delta S = 0$$

$$\delta \int_{t_1}^{t_2} \mathcal{L} dt = \int_{t_1}^{t_2} (\mathcal{L}(\mathbf{q} + \boldsymbol{\varepsilon}, \dot{\mathbf{q}} + \dot{\boldsymbol{\varepsilon}}, t) - \mathcal{L}(\mathbf{q}, \dot{\mathbf{q}}, t)) dt$$

$$= \sum_i \int_{t_1}^{t_2} (\varepsilon_i \partial_{q_i} \mathcal{L} + \dot{\varepsilon}_i \partial_{\dot{q}_i} \mathcal{L}) dt$$

$$= \sum_i \left([\varepsilon_i \partial_{\dot{q}_i} \mathcal{L}]_{t_1}^{t_2} + \int_{t_1}^{t_2} (\varepsilon_i \partial_{q_i} \mathcal{L} - \varepsilon_i \dot{\partial}_{\dot{q}_i} \mathcal{L}) dt \right)$$

$$\boldsymbol{\varepsilon}(t_1) = \boldsymbol{\varepsilon}(t_2) = 0 \Rightarrow [\varepsilon_i \partial_{\dot{q}_i} \mathcal{L}]_{t_1}^{t_2} = 0$$

$$\Rightarrow \delta S = \sum_i \int_{t_1}^{t_2} \varepsilon_i (\partial_{q_i} \mathcal{L} - \dot{\partial}_{\dot{q}_i} \mathcal{L}) dt = 0$$

$$\delta S = 0 \text{ for all } \boldsymbol{\varepsilon} \Rightarrow \dot{\partial}_{\dot{q}_i} \mathcal{L} = \partial_{q_i} \mathcal{L}$$

Lagrangian to Hamiltonian

$$\partial_{\dot{q}_i} \mathcal{L} := p_i, \quad \partial_{q_i} \mathcal{L} = \frac{d}{dt} (\partial_{\dot{q}_i} \mathcal{L}) = \dot{p}_i$$

$$\delta \mathcal{L} = \sum_i \left((\partial_{q_i} \mathcal{L}) \delta q_i + (\partial_{\dot{q}_i} \mathcal{L}) \delta \dot{q}_i \right) + (\partial_t \mathcal{L}) \delta t$$

$$= \sum_i (\dot{p}_i \delta q_i + p_i \delta \dot{q}_i) + (\partial_t \mathcal{L}) \delta t$$

$$= \sum_i (\dot{p}_i \delta q_i + \delta(p_i \dot{q}_i) - \dot{q}_i \delta p_i) + (\partial_t \mathcal{L}) \delta t$$

$$\delta \mathcal{L} - \sum_i \delta(p_i \dot{q}_i) = \sum_i (\dot{p}_i \delta q_i - \dot{q}_i \delta p_i) + (\partial_t \mathcal{L}) \delta t$$

$$\delta \left(\sum_i p_i \dot{q}_i - \mathcal{L} \right) := \delta \mathcal{H} = \sum_i (\dot{q}_i \delta p_i - \dot{p}_i \delta q_i) - (\partial_t \mathcal{L}) \delta t$$

$$\partial_{p_i} \mathcal{H} = \dot{q}_i, \quad \partial_{q_i} \mathcal{H} = -\dot{p}_i, \quad \partial_t \mathcal{H} = -\partial_t \mathcal{L}$$

Standard Hamiltonian

$$\mathcal{L}(\mathbf{q}, \dot{\mathbf{q}}, t) = T(\dot{\mathbf{q}}) - V(\mathbf{q}, t) = \sum_i \frac{m_i}{2} \dot{q}_i^2 - V(\mathbf{q}, t)$$

$$p_i = \partial_{\dot{q}_i} \mathcal{L} = m_i \dot{q}_i \Rightarrow \dot{q}_i = \frac{p_i}{m_i}$$

$$\mathcal{H}(\mathbf{q}, \mathbf{p}, t) = \sum_i p_i \dot{q}_i - \mathcal{L} = \sum_i \frac{p_i^2}{2m_i} + V(\mathbf{q}, t) = T(\mathbf{p}) + V(\mathbf{q}, t)$$

Poisson Bracket

$$\{A, B\} := \sum_i \left((\partial_{q_i} A)(\partial_{p_i} B) - (\partial_{p_i} A)(\partial_{q_i} B) \right)$$

$$\{A, B\} = -\{B, A\}$$

$$\{A + B, C\} = \{A, C\} + \{B, C\}$$

$$\{AB, C\} = B\{A, C\} + A\{B, C\}$$

$$\{A, \{B, C\}\} + \{B, \{C, A\}\} + \{C, \{A, B\}\} = 0$$

$$\dot{A}(\mathbf{q}, \mathbf{p}, t) = \sum_i \left((\partial_{q_i} A) \dot{q}_i + (\partial_{p_i} A) \dot{p}_i \right) + \partial_t A$$

$$= \sum_i \left((\partial_{q_i} A)(\partial_{p_i} \mathcal{H}) - (\partial_{p_i} A)(\partial_{q_i} \mathcal{H}) \right) + \partial_t A = \{A, \mathcal{H}\} + \partial_t A$$