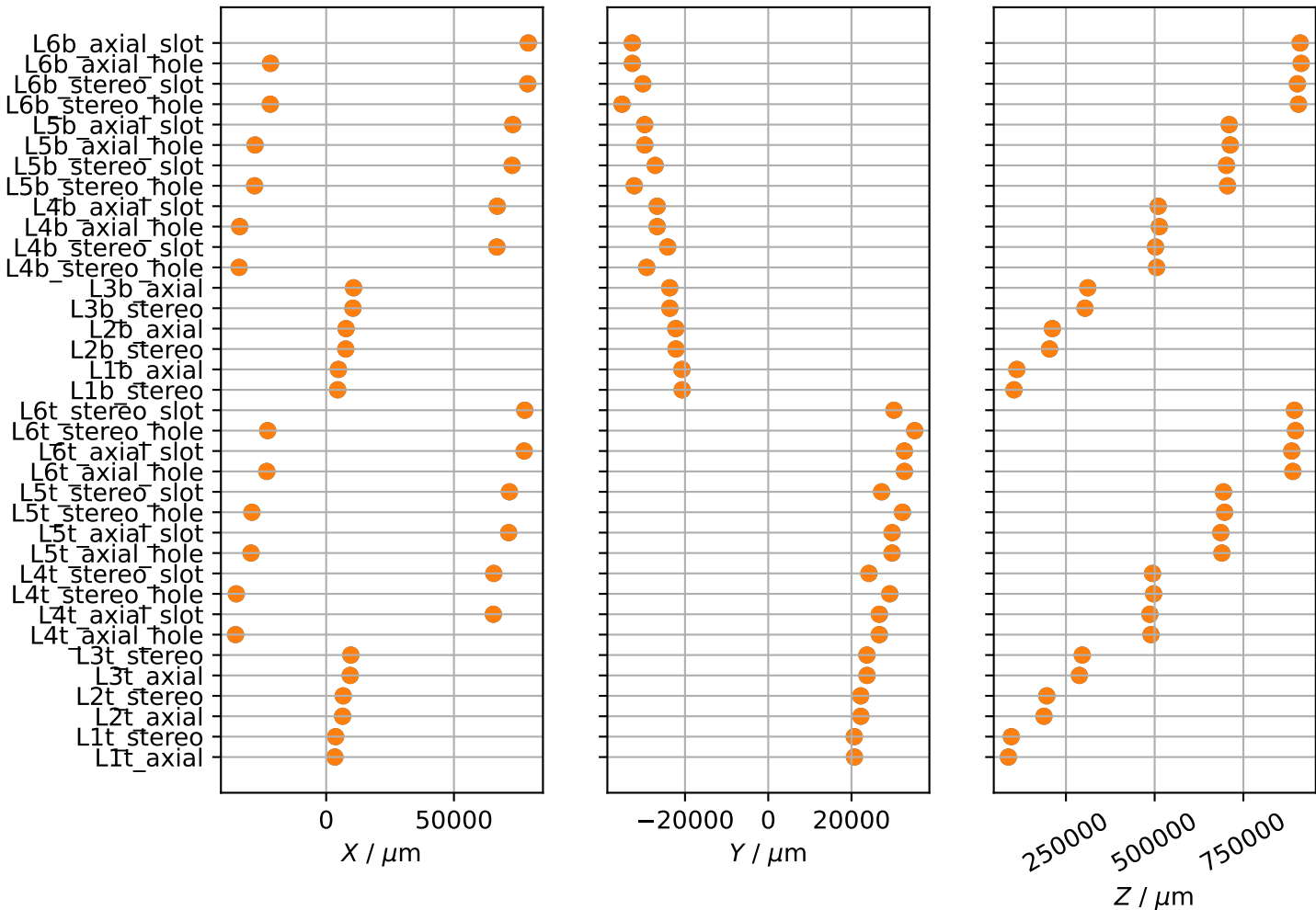


Absolute Position and Orientation

- Original
- Aligned

HPS Global Position



Expected Axis Angles

$$\theta_x = \text{acos}(\pm v_x) \quad \theta_y = \text{acos}(\pm u_y) \quad \theta_z = \text{acos}(\pm w_z)$$

