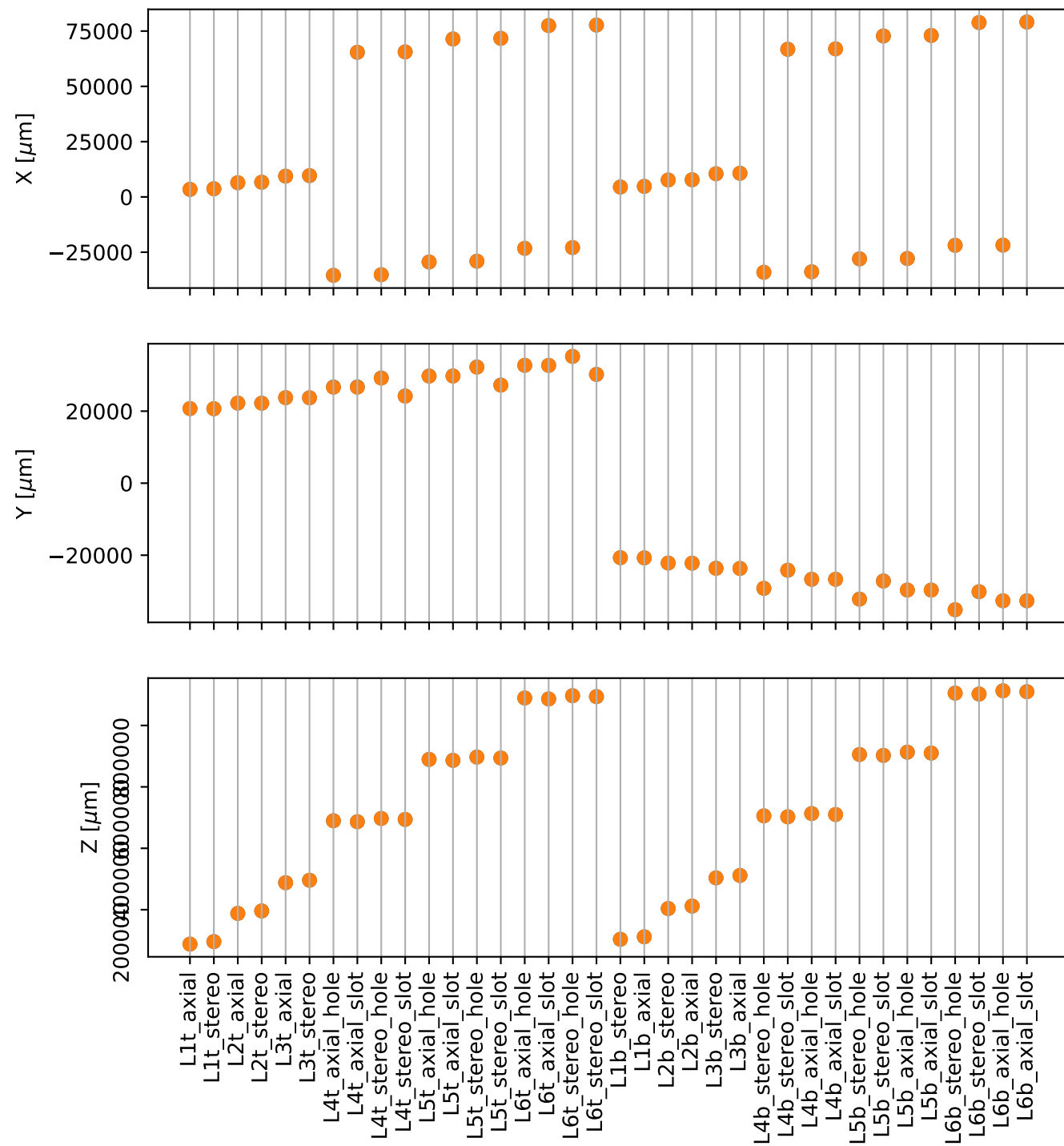


Absolute Position and Orientation

- Original
- Aligned

HPS Global Position



Expected Axis Angles

$\theta_x = \text{acos}(\pm v_x)$ $\theta_y = \text{acos}(\pm u_y)$ $\theta_z = \text{acos}(\pm w_z)$

