# Bayesian model comparison with informative hypotheses

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Consider the test scores from students in three different treatment conditions:

- Treatment 1 read and reread
- Treatment 2 read, then answer prepared questions
- Treatment 3 read, then create and answer questions

Treatment 1	Treatment 2	Treatment 3
2	5	8
3	9	6
8	10	12
6	13	11
5	8	11
6	9	12
M=5	M=9	M = 10

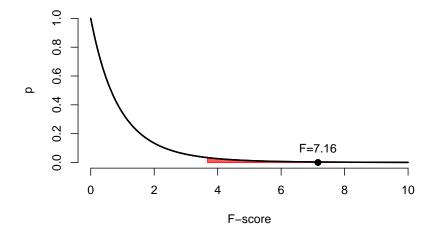
Typical question – are there differences among these condition means?

Standard approach - analysis of variance (ANOVA)

- model  $Y_{ij} = \mu + \alpha_j + \varepsilon_{ij}$ , where  $\varepsilon_{ij} \sim \mathcal{N}(0, \sigma^2)$
- assume "null hypothesis"  $\mathcal{H}_0: \alpha_j = 0$
- ullet compute probability of observing data  $Y_{ij}$  under  $\mathcal{H}_0$
- if data is rare under  $\mathcal{H}_0$ , reject  $\mathcal{H}_0$

#### ANOVA computations

source	SS	df	MS	F
between treatments	84	2	42	7.16
within treatments	88	15	5.87	
total	172	17		



Since our data  $Y_{ij}$  is rare under  $\mathcal{H}_0$ , we reject  $\mathcal{H}_0$  as an implausible model restriction.

What does this tell us?

If we reject  $\mathcal{H}_0: \alpha_j = 0$ , this tells us that  $\alpha_j \neq 0$  for some j.

- which values of *j*?
- are they positive / negative?
- the alternative is rather uninformative

## Informative hypotheses

Consider instead defining competing *informative* models:

• 
$$\mathcal{M}_1: \mu_1 < \mu_2 < \mu_3$$

#### • $\mathcal{M}_2: \mu_2 < \mu_1 < \mu_3$

• 
$$\mathcal{M}_3: \mu_1 < \mu_3 < \mu_2$$

$$\bullet \ \mathcal{M}_e: \mu_1, \mu_2, \mu_3$$

#### Note:

- 1. each model tells a different story about effective study methods
- 2. typical ANOVA cannot differentiate between  $\mathcal{M}_1$ ,  $\mathcal{M}_2$ ,  $\mathcal{M}_3$

Goal - evaluate relative evidence for each model  $\mathcal{M}_j$ , in light of observed data  $oldsymbol{y}$ 

Bayes' Theorem:

$$\underbrace{\frac{p(\mathcal{M}_{j} \mid \boldsymbol{y})}{p(\mathcal{M}_{k} \mid \boldsymbol{y})}}_{\text{posterior odds}} = \underbrace{\frac{p(\mathcal{M}_{j})}{p(\mathcal{M}_{k})}}_{\text{prior odds}} \times \underbrace{\frac{p(\boldsymbol{y} \mid \mathcal{M}_{j})}{p(\boldsymbol{y} \mid \mathcal{M}_{k})}}_{\text{predictive updating factor}}$$

The predictive updating factor, or **Bayes factor**, tells us how much better  $\mathcal{M}_i$  predicts our observed data compared to  $\mathcal{M}_k$ .

#### Computing Bayes factors for informative hypotheses

**Theorem 1.** (Klugkist et al., 2005) Consider a model  $\mathcal{M}_1$  nested within an encompassing model  $\mathcal{M}_e$  via an inequality constraint. Then

$$B_{1e} = \frac{F}{C}$$

where F and C represent the proportions of the posterior and prior of the encompassing model, respectively, that are in agreement with the inequality constraint imposed by the nested model  $\mathcal{M}_1$ .

# Sample from prior:

	Prior					
Iteration	$\overline{\mu_1}$	$\mu_2$	$\mu_3$	$\overline{\mathcal{M}_1}$	$\mathcal{M}_2$	$\overline{\mathcal{M}_3}$
1	6.54	10.15	-1.78	0	0	0
2	22.60	-0.28	8.03	0	0	0
3	3.37	3.01	-0.63	0	0	0
4	-6.13	11.54	12.33	1	0	0
5	13.68	-0.61	1.50	0	0	0
6	27.83	7.43	6.79	0	0	0
<b>:</b>	i	÷	i	i	i	:
5000	11.00	13.07	23.91	1	0	0
Sum				847	876	807
Proportion $(C)$				0.169	0.175	0.161

# Sample from posterior:

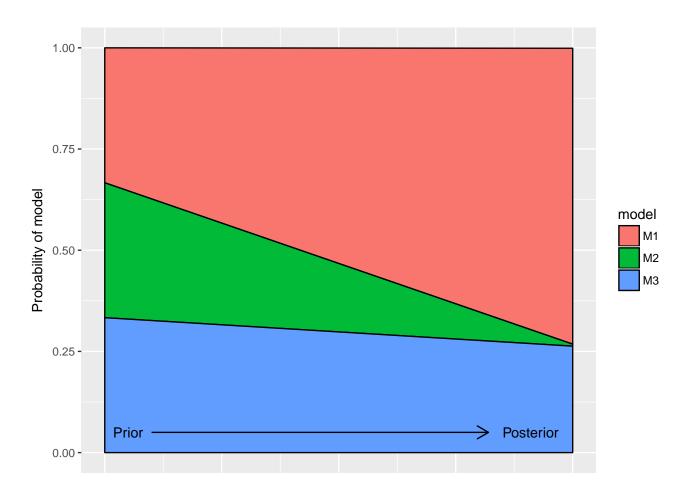
	Posterior					
Iteration	$\overline{\mu_1}$	$\mu_2$	$\mu_3$	$\overline{\mathcal{M}_1}$	$\mathcal{M}_2$	$\overline{\mathcal{M}_3}$
1	5.59	9.90	12.83	1	0	0
2	2.90	8.86	8.35	0	0	1
3	2.63	10.43	10.44	1	0	0
4	5.55	10.17	9.61	0	0	1
5	4.61	7.24	10.24	1	0	0
6	4.72	8.95	9.78	1	0	0
ŧ	i	i	i	i	:	:
5000	5.61	8.72	9.99	1	0	0
Sum				3674	29	1286
Proportion $(F)$				0.735	0.006	0.257
Proportion $(C)$				0.169	0.175	0.161
$B_{je}$				4.43	0.03	1.59

From these Bayes factors, we can compute  $posterior\ model\ probabilities$  (PMPs).

$$p(\mathcal{M}_j \mid \boldsymbol{y}) = \frac{B_{je}}{B_{1e} + B_{2e} + B_{3e}}$$

Model	F	C	$B_{je}$	PMP
$\mathcal{M}_1: \mu_1 < \mu_2 < \mu_3$	0.735	0.169	4.43	0.731
$\mathcal{M}_2: \mu_2 < \mu_1 < \mu_3$	0.006	0.175	0.03	0.005
$\mathcal{M}_3: \mu_1 < \mu_3 < \mu_2$	0.257	0.161	1.59	0.263

## "flow of model belief"



#### Thank you!

- Thanks to Tarleton Office of Research and Innovation for funding!
- slides available at github.com/tomfaulkenberry/talks
- more details in Faulkenberry, T. J. (2019). A tutorial on generalizing the default Bayesian t-test via posterior sampling and encompassing priors. Communications for Statistical Applications and Methods, 26(2), 1-22.
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