

Inteligencia Artificial

Redes Neuronales Feedforward Ejemplo de implementación

Martin Marchetta

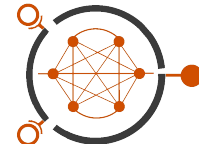
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Ejemplo de implementación

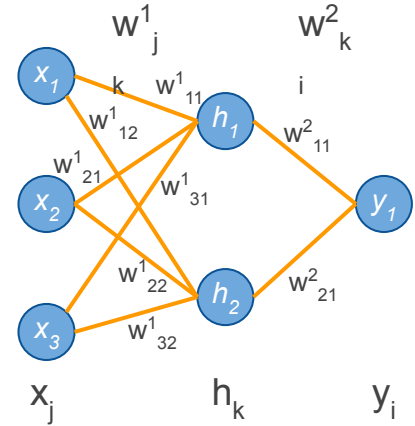


- Implementación Matricial

- m ejemplos
- n entradas
- p neuronas ocultas
- q salidas

$$H = f(XW^1 + B^1) = f(Z)$$

$$XW^1 + B^1 = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1n} \\ x_{21} & x_{22} & \dots & x_{2n} \\ \vdots & & \ddots & \\ x_{m1} & x_{m2} & \dots & x_{mn} \end{bmatrix} \begin{bmatrix} w_{11}^1 & w_{12}^1 & \dots & w_{1p}^1 \\ w_{21}^1 & w_{22}^1 & \dots & w_{2p}^1 \\ \vdots & & \ddots & \\ w_{n1}^1 & w_{n2}^1 & \dots & w_{np}^1 \end{bmatrix} + \begin{bmatrix} b_1^1 & b_2^1 & \dots & b_p^1 \\ b_1^1 & b_2^1 & \dots & b_p^1 \\ \vdots & & \ddots & \\ b_1^1 & b_2^1 & \dots & b_p^1 \end{bmatrix}$$



Ejemplo de implementación



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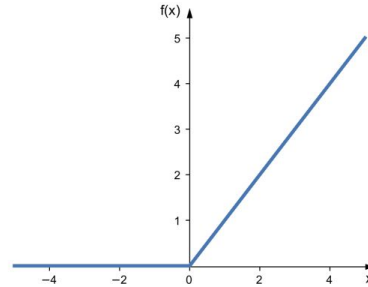
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● Implementación Matricial

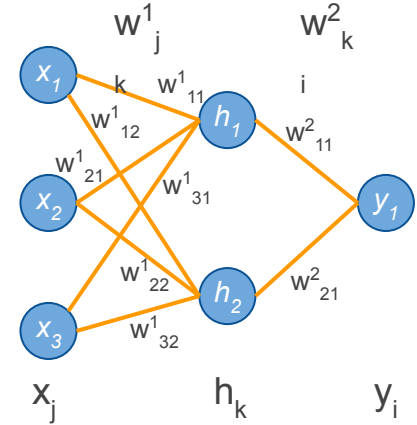
- m ejemplos
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$$H = f(XW^1 + B^1) = f(Z)$$

$$\text{relu}(x) = \max(0, x)$$



$$XW^1 + B^1 = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1n} \\ x_{21} & x_{22} & \dots & x_{2n} \\ \vdots & & \ddots & \\ x_{m1} & x_{m2} & \dots & x_{mn} \end{bmatrix} \begin{bmatrix} w_{11}^1 & w_{12}^1 & \dots & w_{1p}^1 \\ w_{21}^1 & w_{22}^1 & \dots & w_{2p}^1 \\ \vdots & & \ddots & \\ w_{n1}^1 & w_{n2}^1 & \dots & w_{np}^1 \end{bmatrix} + \begin{bmatrix} b_1^1 & b_2^1 & \dots & b_p^1 \\ b_1^1 & b_2^1 & \dots & b_p^1 \\ \vdots & & \ddots & \\ b_1^1 & b_2^1 & \dots & b_p^1 \end{bmatrix}$$



Ejemplo de implementación



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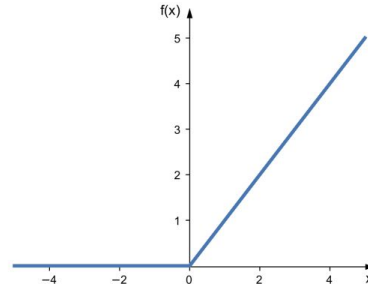
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● Implementación Matricial

- m ejemplos
- n entradas
- p neuronas ocultas
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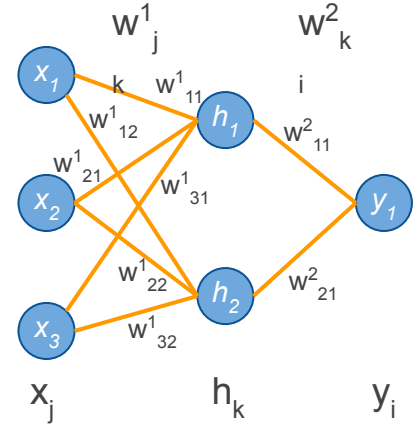
$$H = f(XW^1 + B^1) = f(Z)$$

$$\text{relu}(x) = \max(0, x)$$



$$XW^1 + B^1 = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1n} \\ x_{21} & x_{22} & \dots & x_{2n} \\ \vdots & & \ddots & \\ x_{m1} & x_{m2} & \dots & x_{mn} \end{bmatrix} \begin{bmatrix} w_{11}^1 & w_{12}^1 & \dots & w_{1p}^1 \\ w_{21}^1 & w_{22}^1 & \dots & w_{2p}^1 \\ \vdots & & \ddots & \\ w_{n1}^1 & w_{n2}^1 & \dots & w_{np}^1 \end{bmatrix} + \begin{bmatrix} b_1^1 & b_2^1 & \dots & b_p^1 \\ b_1^1 & b_2^1 & \dots & b_p^1 \\ \vdots & & \ddots & \\ b_1^1 & b_2^1 & \dots & b_p^1 \end{bmatrix}$$

$$Y = g(HW^2 + B^2) \rightarrow g(x) = x \quad (\text{función identidad})$$



Ejemplo de implementación

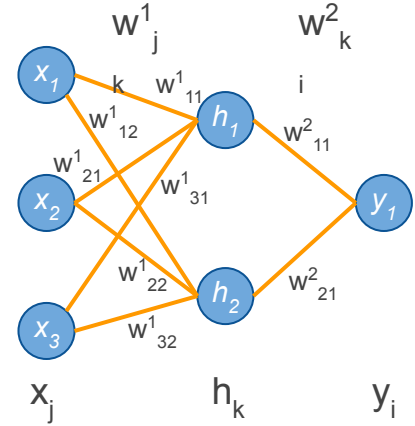
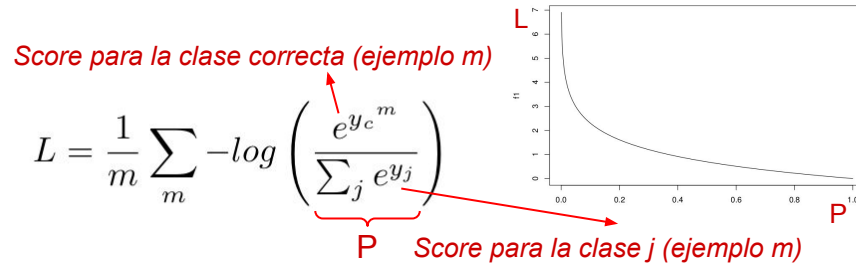


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- Loss Function: Softmax



Ejemplo de implementación



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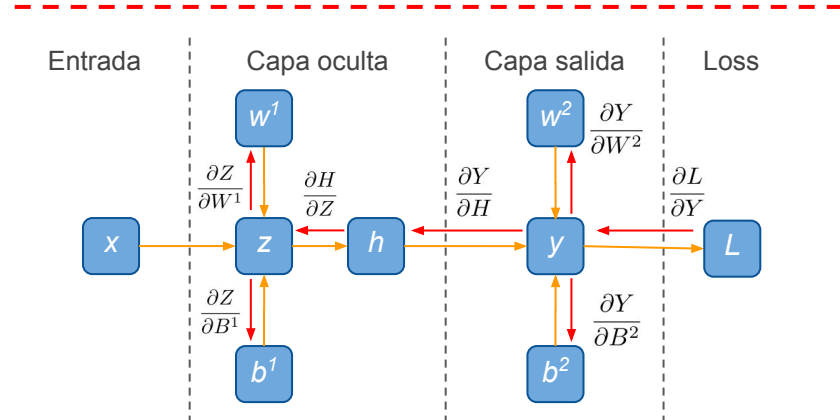
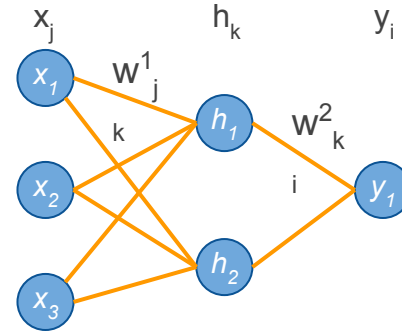
- Aprendizaje: Backpropagation
 - Aplicando la *regla de la cadena*

$$\frac{\partial L}{\partial W^2} = \frac{\partial L}{\partial Y} \frac{\partial Y}{\partial W^2}$$

$$\frac{\partial L}{\partial B^2} = \frac{\partial L}{\partial Y} \frac{\partial Y}{\partial B^2}$$

$$\frac{\partial L}{\partial W^1} = \frac{\partial L}{\partial Y} \frac{\partial Y}{\partial H} \frac{\partial H}{\partial Z} \frac{\partial Z}{\partial W^1}$$

$$\frac{\partial L}{\partial B^1} = \frac{\partial L}{\partial Y} \frac{\partial Y}{\partial H} \frac{\partial H}{\partial Z} \frac{\partial Z}{\partial B^1}$$



Ejemplo de implementación



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- Aprendizaje: Backpropagation
 - Aplicando la *regla de la cadena*

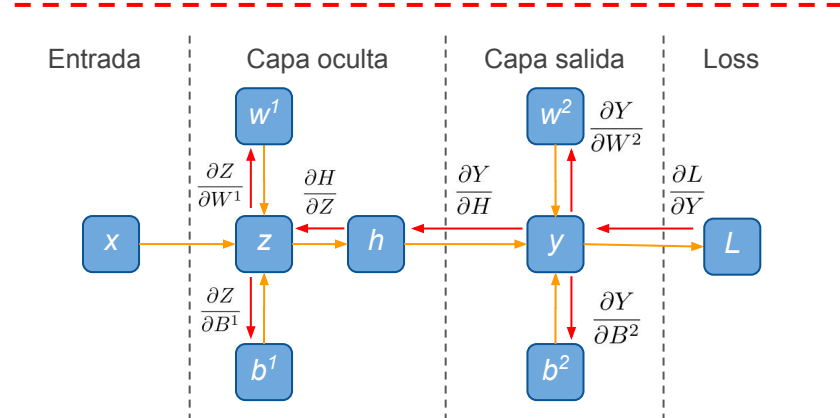
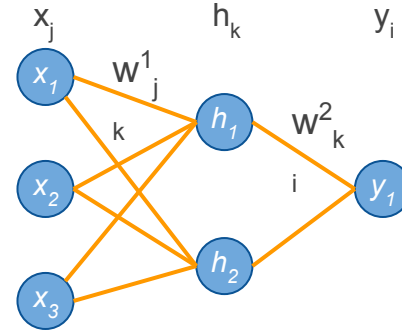
$$\frac{\partial L}{\partial W^2} = \frac{\partial L}{\partial Y} \frac{\partial Y}{\partial W^2}$$

$$\frac{\partial L}{\partial Y} = \begin{cases} \frac{1}{m}(P_i - 1) & \text{(clase correcta)} \\ \frac{1}{m}(P_i) & \text{(otras clases)} \end{cases}$$

$$L = \frac{1}{m} \sum_m -\log \left(\frac{e^{y_c^m}}{\sum_j e^{y_j^m}} \right)$$

$$P_i = \frac{e^{y_i}}{\sum_j e^{y_j}}$$

$$\frac{\partial Y}{\partial W^2} = H$$



Ejemplo de implementación



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- Aprendizaje: Backpropagation
 - Aplicando la *regla de la cadena*

$$\frac{\partial L}{\partial B^2} = \frac{\partial L}{\partial Y} \frac{\partial Y}{\partial B^2}$$

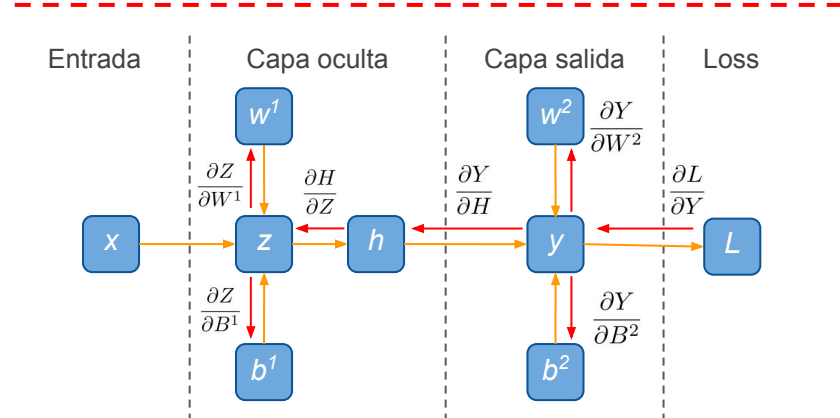
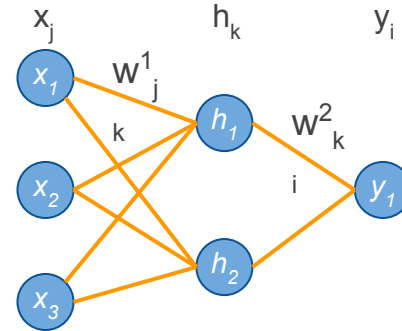
$$\frac{\partial L}{\partial Y} = \begin{cases} \frac{1}{m}(P_i - 1) & \text{(clase correcta)} \\ \frac{1}{m}(P_i) & \text{(otras clases)} \end{cases}$$

$$L = \frac{1}{m} \sum_m -\log \left(\frac{e^{y_c^m}}{\sum_j e^{y_j^m}} \right)$$

$$P_i = \frac{e^{y_i}}{\sum_j e^{y_j}}$$

$$\frac{\partial Y}{\partial B^2} = 1$$

(se suma verticalmente a lo largo de m)



Ejemplo de implementación



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- Aprendizaje: Backpropagation
 - Aplicando la *regla de la cadena*

$$\frac{\partial L}{\partial W^1} = \frac{\partial L}{\partial Y} \frac{\partial Y}{\partial H} \frac{\partial H}{\partial Z} \frac{\partial Z}{\partial W^1}$$

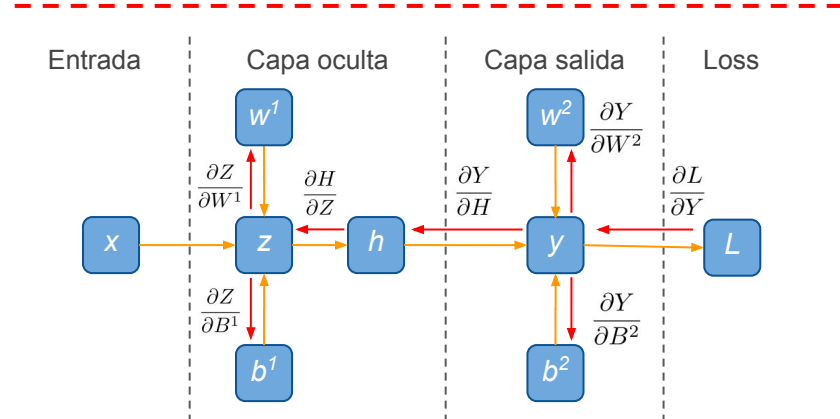
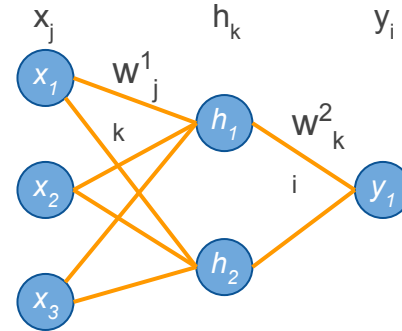
$$\frac{\partial Y}{\partial H} = W^2$$

$$Y = HW^2 + B^2$$

$$\frac{\partial H}{\partial Z} = 1(z > 0)$$

$$\frac{\partial Z}{\partial W^1} = X$$

$$Z = XW^1 + B^1$$



Ejemplo de implementación

- Aprendizaje: Backpropagation

- Aplicando la *regla de la cadena*

$$\frac{\partial L}{\partial B^1} = \frac{\partial L}{\partial Y} \frac{\partial Y}{\partial H} \frac{\partial H}{\partial Z} \frac{\partial Z}{\partial B^1}$$

$$\frac{\partial Y}{\partial H} = W^2$$

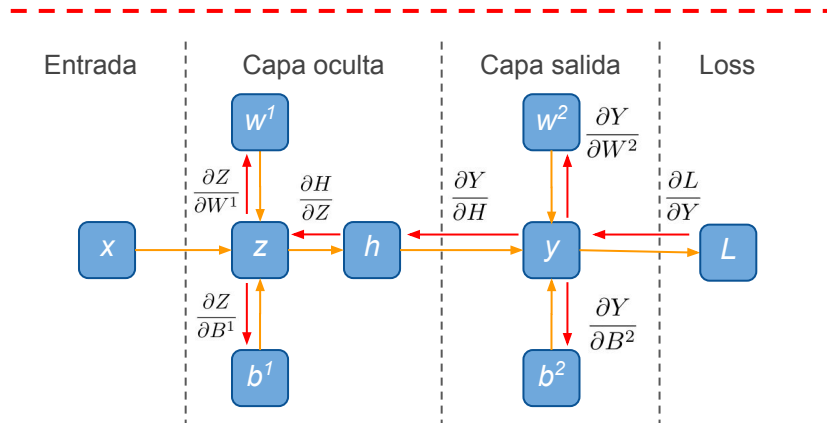
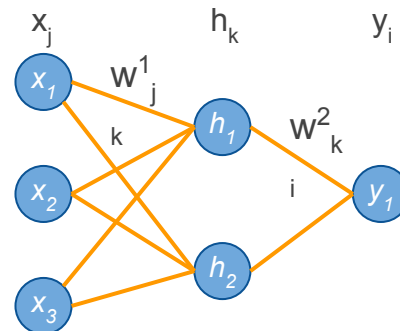
$$Y = HW^2 + B^2$$

$$\frac{\partial H}{\partial Z} = 1(z > 0)$$

$$\frac{\partial Z}{\partial B^1} = 1$$

$$Z = XW^1 + B^1$$

(se suma verticalmente
a lo largo de m)



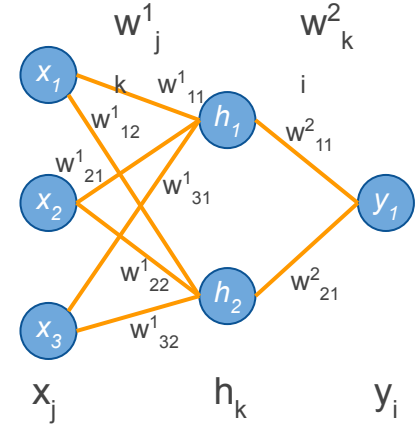
Ejemplo de implementación



- Aprendizaje: Backpropagation
 - Descenso por el gradiente

$$W_{t+1} = W_t - \varepsilon \nabla L_W$$

$$\left\{ \begin{array}{l} W^2(t+1) = W^2(t) - \varepsilon \frac{\partial L}{\partial W^2} \\ B^2(t+1) = B^2(t) - \varepsilon \frac{\partial L}{\partial B^2} \\ W^1(t+1) = W^1(t) - \varepsilon \frac{\partial L}{\partial W^1} \\ B^1(t+1) = B^1(t) - \varepsilon \frac{\partial L}{\partial B^1} \end{array} \right.$$



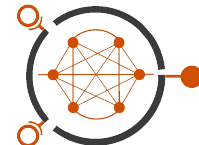
Preguntas? Opiniones?



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