



Northwestern University

Jan 11, 2024

Tom Palamattam

has successfully completed

Modern Robotics, Course 4: Robot Motion Planning and Control

an online non-credit course authorized by Northwestern University and offered through
Coursera

A handwritten signature in black ink that reads "Kevin M. Lynch".

Kevin M. Lynch
Professor of Mechanical Engineering
Northwestern University

COURSE CERTIFICATE



Verify at:

<https://coursera.org/verify/DFWLDPGZBL2C>

Coursera has confirmed the identity of this individual and their
participation in the course.