

Notes for Tom: Kalman filter phase formulation

①

Equations of motion (continuous space)

$$\frac{d\Phi}{dt} = f, \quad (1)$$

$$\frac{df}{dt} = -\gamma(f - f_{em}) + \dot{f}_{em} + \xi \quad (2).$$

Consider (2)

$$\frac{d}{dt} \{f - f_{em}\} = -\gamma(f - f_{em}) + \xi, \quad (2A)$$

$$\text{Let } f^* \equiv f - f_{em}$$

Equation (2) becomes

$$\frac{df^*}{dt} = -\gamma f^* + \xi. \quad (2B)$$

Consider (1)

$$\frac{d\Phi}{dt} = f^* + \frac{d}{dt} \Phi_{em} \quad (1A)$$

$$\text{Let } \Phi^* = \Phi - \Phi_{em}$$

Equation (1) becomes

$$\frac{d\Phi^*}{dt} = f^* \quad (1B)$$

(2)

(Shifted) Equations of motion (continuous).

$$\frac{d\Phi^*}{dt} = f^*$$

Beautifully (3)

$$\frac{df^*}{dt} = -\gamma f^* + \xi$$

simple. (4)

$$\frac{d}{dt} \begin{pmatrix} \Phi^* \\ f^* \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & -\gamma \end{pmatrix} \begin{pmatrix} \Phi^* \\ f^* \end{pmatrix} + \begin{pmatrix} 0 \\ \xi \end{pmatrix}$$

$$\underline{\dot{X}} = \underline{A} \underline{X} + \underline{\xi}$$

✓ looks good.

Solution given by

$$\underline{X}(t_1) = e^{\underline{A}(t_1-t_0)} \underline{X}(t_0) + \int_{t_0}^{t_1} e^{\underline{A}(t_1-t_0')} \underline{\xi}(t_0') dt_0'$$

Integrating factor!

$$e^{\underline{A}(t_1-t_0)} = e^{\underline{A}\Delta t} = \begin{pmatrix} 1 & (1-e^{-\gamma\Delta t})/\gamma \\ 0 & e^{-\gamma\Delta t} \end{pmatrix}$$

i.e. the components are 1,  $\frac{1-e^{-\gamma\Delta t}}{\gamma}$ , 0,  $e^{-\gamma\Delta t}$ .

→ Same as Nicholas' results, as expected.

Note: Even with heterodyning, the formal structure

in the terms multiplying the state-space variables is equivalent, i.e.  $\underline{Q}$  will be the same. To see this:

$$\underline{Q}_n = \int_0^{At} e^{\underline{A}s} \underline{\Sigma} e^{\underline{A}^T s} ds,$$

where  $\underline{\Sigma} = \begin{pmatrix} 0 & 0 \\ 0 & \sigma^2 \end{pmatrix}$

The term inside the integrand, i.e., is given

by  $e^{\underline{A}s} \underline{\Sigma} e^{\underline{A}^T s}$  (ce it is a projection)

$$= \sigma^2 e^{-2\gamma s} \begin{pmatrix} \frac{[e^{\gamma s} - 1]^2}{\gamma^2} & \frac{[e^{\gamma s} - 1]}{\gamma} \\ \frac{[e^{\gamma s} - 1]}{\gamma} & 1 \end{pmatrix} \quad (*)$$

→ Integrate  $(*)$  between 0 &  $At$  to get  
(discrete)  $\underline{Q}_n$ .

→ Integrate each component between  $0 \rightarrow At$ .

$$Q_{00} = \frac{\sigma^2}{\gamma^2} \int_0^{At} e^{-2gs} (e^{gs} - 1)^2 ds, \quad g = \gamma \quad \text{bad notation sorry!!}$$

$$= \frac{\sigma^2}{\gamma^2} \int_0^{At} \{ e^{-2gs} [e^{2gs} - 2e^{gs} + 1] \} ds$$

$$= \frac{\sigma^2}{\gamma^2} \int_0^{At} [1 - 2e^{-gs} + e^{-2gs}] ds$$

$$= \frac{\sigma^2}{\gamma^2} \left[ s + \frac{2}{g} e^{-gs} - \frac{e^{-2gs}}{2g} \right]_0^{At}$$

$$= \frac{\sigma^2}{\gamma^2} \left[ (At - 0) + \frac{2}{g} (e^{-gAt} - 1) - \frac{1}{2g} (e^{-2gAt} - 1) \right]$$

$$= \frac{\sigma^2}{\gamma^3} \left[ \gamma At + 2(e^{-gAt} - 1) + \frac{1}{2}(1 - e^{-2gAt}) \right]$$

Note  $g = \gamma$ , sorry for the bad notation.

Same as Nicholas  $Q_{00}$  ✓

$$Q_{01} = Q_{10} = \frac{\sigma^2}{\gamma} \int_0^{4t} [e^{-gs} - e^{-2gs}] ds$$

$$= \frac{\sigma^2}{\gamma} \left[ \frac{1}{2g} e^{-2gs} - \frac{1}{g} e^{-gs} \right]_0^{4t}$$

$$= \frac{\sigma^2}{\gamma^2} \left[ \frac{1}{2} (e^{-2g4t} - 1) - (e^{-g4t} - 1) \right]$$

$$= \frac{\sigma^2}{2\gamma^2} \left[ (e^{-2g4t} - 1) + 2(1 - e^{-g4t}) \right]$$

$$= \frac{\sigma^2}{2\gamma^2} [1 - 2e^{-g4t} + e^{-2g4t}]$$

$$= \frac{\sigma^2}{2\gamma^2} (1 - e^{-g4t})^2 \quad \checkmark$$

(6)

$$Q_{22} = \sigma^2 \int_0^{At} e^{-2gs} ds$$

$$= -\frac{\sigma^2}{2\gamma} e^{-2gs} \Big|_0^{At}$$

$$= -\frac{\sigma^2}{2\gamma} (e^{-2gs} - 1)$$

$$= \frac{\sigma^2}{2\gamma} (1 - e^{-2gs})$$

Model Summary:

$$\frac{d\Phi^*}{dt} = f^*, \quad \frac{df^*}{dt} = -\gamma f^* + \xi.$$

$$F_n = \begin{pmatrix} 1 & \gamma^{-1} [1 - e^{-\gamma At}] \\ 0 & e^{-\gamma At} \end{pmatrix}$$

$Q_n \equiv$  same as Nicholas Eq (54)

$$\Phi_M^* = \Phi^* - (f^* + f_{em}) At_{aw}.$$