# The Hidden Geometry of Singular Matrices: How Non-Singular Matrices Are "Born" from Their Singular Core

This paper explores the hidden relationship between **singular matrices** and their corresponding **non-singular matrices**, showing that **non-singular matrices** are **not independent entities but are closely tied to singular structures through shared eigenvectors**. We demonstrate that for every singular matrix, there exists an infinite family of non-singular matrices that share the same eigenvectors. These non-singular matrices can be generated through small perturbations of the eigenvalues of the singular matrix, with the transformation behavior governed by the underlying **column space and null space geometry**.

This relationship provides insight into the numerical stability of near-singular matrices, the role of eigenvectors in governing transformations, and the geometric constraints imposed by singular matrices on non-singular behavior.

### 1. Introduction

The concept of **singular matrices** is typically associated with their lack of invertibility, but their role in defining the behavior of **non-singular matrices** is less explored. In this paper, we reveal that singular

matrices are not just degenerate cases—they act as **the structural cores** of non-singular matrices, providing the **eigenvector framework** that governs transformation dynamics.

By perturbing a singular matrix's eigenvalues, we generate an infinite family of **non-singular matrices** that share the same eigenvector directions. This discovery provides a **new perspective** on matrix transformations and their sensitivity, showing that **the eigenvector structure of a singular matrix is the key to understanding the behavior of nearby non-singular matrices.** 

# 2. Singular Matrices and Their Eigenvector Structure

A matrix (A) is **singular** if its determinant is zero:

$$\det(A) = 0$$

This occurs when at least one eigenvalue ( \lambda\_i = 0 ). The eigenvector corresponding to the zero eigenvalue defines the **null space** of the matrix, while the eigenvector corresponding to any nonzero eigenvalue defines the **column space**. For example, consider the singular matrix:

$$A_{
m singular} = egin{bmatrix} 1 & 2 \ 4 & 8 \end{bmatrix}$$

Its eigenvalues are:

$$\lambda_1 = 0, \quad \lambda_2 = 10$$

The corresponding eigenvectors are:

$$\mathbf{v}_1 = egin{bmatrix} -2 \\ 1 \end{bmatrix}$$
 (null space direction)

$$\mathbf{v}_2 = egin{bmatrix} 1 \\ 4 \end{bmatrix}$$
 (column space direction)

The **key observation** is that the eigenvector structure of the singular matrix remains intact when perturbing the eigenvalues to generate a non-singular matrix.

# 3. Generating Non-Singular Matrices from Singular Matrices

To generate a family of **non-singular matrices** from a given singular matrix, we apply a small perturbation to its eigenvalues. Consider the perturbation:

$$A_{\text{non-singular}} = A_{\text{singular}} + aI$$

where (a) is a small perturbation and (I) is the identity matrix:

$$A_{ ext{non-singular}} = egin{bmatrix} 1-a & 2 \ 4 & 8-a \end{bmatrix}$$

### 3.1 Eigenvalues of the Non-Singular Matrix

The eigenvalues of the non-singular matrix become:

$$\lambda_i' = \lambda_i + a$$

For the zero eigenvalue of the singular matrix ( \lambda\_1 = 0 ), we now have:

$$\lambda_1' = a$$

This small perturbation lifts the eigenvalue from zero, making the matrix invertible.

# 4. Why the Eigenvector Structure Is Preserved

The eigenvector structure remains the same because perturbing the eigenvalues **does not alter the underlying geometry of the column and null spaces.** The eigenvectors of the non-singular matrix ( A\_{\text{singular}}) are the same as those of the singular matrix ( A\_{\text{singular}}), meaning:

$$A_{ ext{non-singular}}\mathbf{v} = \lambda'\mathbf{v}$$

Thus, the non-singular matrix inherits its transformation directions from the singular matrix.

# 5. The "Born Pair" Concept: Two Families of Non-Singular Matrices

Each singular matrix gives rise to **two distinct families of non-singular matrices**, corresponding to perturbations along its **two eigenvector directions**:

1. **Family 1:** Perturb the eigenvalue corresponding to the null space direction (typically the smaller eigenvalue).

Example:

$$A_{\mathrm{family}_1} = egin{bmatrix} 1-a & 2 \ 4 & 8-a \end{bmatrix}$$

2. **Family 2:** Perturb the eigenvalue corresponding to the column space direction (typically the larger eigenvalue).

Example:

$$A_{\mathrm{family}_2} = egin{bmatrix} 1+b & 2 \ 4 & 8+b \end{bmatrix}$$

# 6. Implications of the Born Pair Concept

## **6.1 Geometric Understanding of Matrix Dynamics**

The eigenvector structure of the singular matrix dictates how the non-singular matrix transforms vectors. The **column space direction** defines the primary scaling direction, while the **null space direction** governs collapse and sensitivity to perturbations.

### **6.2 Numerical Stability**

Near-singular matrices are prone to instability because small perturbations in their eigenvalues lead to large changes in their inverses. This instability arises because the **small eigenvalue (\lambda\_1') introduces** large scaling factors in the inverse transformation:

$$A^{-1} = \frac{1}{\lambda_1'}$$

### **6.3 Regularization Techniques**

Regularization methods, such as adding ( \lambda I ) in machine learning, work by artificially increasing the small eigenvalue, effectively stabilizing the inverse:

$$(X^TX + \lambda I)^{-1}$$

# 7. Numerical Example

Consider the singular matrix:

$$A_{
m singular} = egin{bmatrix} 1 & 2 \ 4 & 8 \end{bmatrix}$$

We generate a non-singular matrix by perturbing the diagonal:

$$A_{ ext{non-singular}} = egin{bmatrix} 1-0.1 & 2 \ 4 & 8-0.1 \end{bmatrix} = egin{bmatrix} 0.9 & 2 \ 4 & 7.9 \end{bmatrix}$$

The eigenvectors of both matrices remain:

$$\mathbf{v}_1 = egin{bmatrix} -2 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = egin{bmatrix} 1 \\ 4 \end{bmatrix}$$

## 8. Conclusion

The discovery that **non-singular matrices are "born" from singular matrices through shared eigenvectors** provides a new way of understanding matrix dynamics. Rather than viewing singular matrices as degenerate cases, we see them as **structural cores** that govern the behavior of nearby non-singular matrices.

By perturbing the eigenvalues of singular matrices, we generate non-singular matrices that retain the **same geometric transformation directions**. This discovery has implications for **numerical stability**, **regularization techniques**, **and control systems**, offering a unified view of matrix transformations through their singular cores.